Machine Learning on graphs. Structural Graph Embeddings

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Graph machine learning

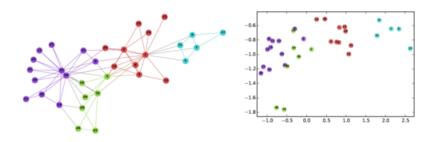
- Node classification (attribute inference)
- Link prediction (missing/hidden links inference)
- Community detection (clustering nodes in graph)
- Graph visualization (cluster projections)

Lecture outline

- Graph Embeddings
 - Problem statement
 - Structural graph embeddings (simple models)
 - Structural graph embeddings (mixed-hop models)
 - Structural graph embeddings (with attributes)

Graph Embeddings

- Necessity to automatically select features
- Reduce domain- and task- specific bias
- Unified framework to vectorize network
- Preserve graph properties in vector space
- ullet Similar nodes o close embeddings

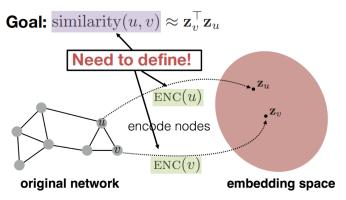


from Leskovec et al., 2018¹

¹http://snap.stanford.edu/proj/embeddings-www/

Graph Embeddings

- Define Encoder
- Define Similarity/graph feature to preserve graph properties
- Define similarity/distance in the embedding space
- Optimize loss to fit embedding with similarity computed on graph

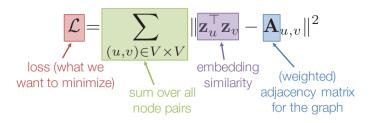


Structural Graph Embeddings

- Embedding look-up (each node separate vector)
- Different similarity measures (adjacency, common neighbours, distances, exact function, etc.)
- Quadratic optimization for MSE loss
- Fast models via random walks

First-order Proximity

- Similarity between u and v is A_{uv}
- MSE Loss
- Variant of Matrix Decomposition



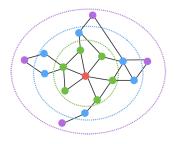
from Leskovec et al., 2018

First-order Proximity

- Pros:
 - Use SGD for scalable optimization
 - Matrix factorization (SVD) or decomposition (QR) may be applicable
- Cons:
 - Quadratic complexity
 - Large embeddings space
 - No indirect graph properties are preserved

Multi-order Proximity

- Similarity of neighborhoods of u and v via indices or k-hop paths
- Direct optimization of exact similarity metric



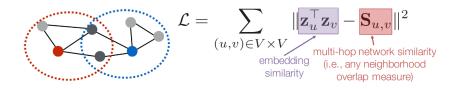
- Red: Target node
- Green: 1-hop neighbors
 - A (i.e., adjacency matrix)
- Blue: 2-hop neighbors
 - A²
- Purple: 3-hop neighbors
 - A³

$$\mathcal{L} = \sum_{(u,v)\in V\times V} \|\mathbf{z}_u^{\top}\mathbf{z}_v - \mathbf{A}_{u,v}^k\|^2$$

from Leskovec et al., 2018

Multi-order Proximity

• Similarity score S_{uv} as Jaccard/Common Neighbours, etc. (HOPE)



Weighted k-hop paths with different k (GraRep)

$$\tilde{\mathbf{A}}_{i,j}^k = \max \left(\log \left(\frac{(\mathbf{A}_{i,j}/d_i)}{\sum_{l \in V} (\mathbf{A}_{l/j}/d_l)^k} \right)^k - \alpha, 0 \right)$$
 node degree constant shift

from Leskovec et al., 2018

Even worse complexity

Random Walks

- Similarity between u and v is probability to co-occur on a random walk
- Sample each vertex u neighborhood $N_R(u)$ (multiset) by short random walks via strategy R
- Optimize similarity considering independent neighbor samples via MLE (remind Word2Vec)

$$\mathcal{L} = \sum_{u \in V} \sum_{v \in N_R(u)} -\log(P(v|\mathbf{z}_u))$$

from Leskovec et al., 2018

Random Walks

• $P(v|z_u)$ is approximated via softmax over similarity $z_u^T \cdot z_v$

$$\mathcal{L} = \sum_{u \in V} \sum_{v \in N_R(u)} -\log \left(\frac{\exp(\mathbf{z}_u^{\top} \mathbf{z}_v)}{\sum_{n \in V} \exp(\mathbf{z}_u^{\top} \mathbf{z}_n)} \right)$$

- Problem in second Σ over all nodes
- Hard to find optimal solution

Negative Sampling

• Use Negative Sampling to approximate denominator

$$\begin{split} &\log\left(\frac{\exp(\mathbf{z}_u^{\top}\mathbf{z}_v)}{\sum_{n\in V}\exp(\mathbf{z}_u^{\top}\mathbf{z}_n)}\right) \quad \text{random distribution} \\ &\approx \log(\sigma(\mathbf{z}_u^{\top}\mathbf{z}_v)) - \sum_{i=1}^k \log(\sigma(\mathbf{z}_u^{\top}\mathbf{z}_{n_i})), n_i \sim P_V \end{split}$$

from Leskovec et al., 2018

- Sample in proportion to node degree
- Experiment with k to impact negative prior and robustness
- No need to sample non-connected edges same as random

Random Walk Strategies

- Finite unbiased random walks (DeepWalk)
- 1-hops & 2-hops for half of the embedding, arbitrary random walks for the second half of the embedding (LINE)
- Diffusion for sampling (Diff2Vec)
- Biased random walks combining BFS and DFS (Node2Vec)

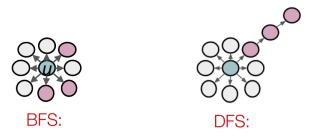
DeepWalk & LINE

- DeepWalk: Unbiased random walks with fixed length and number
- LINE: Combination of first-order and second-order proximity aggregation via concatenation



Node2Vec

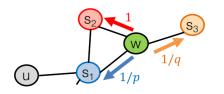
BFS samples local neighborhood, DFS goes for global features



- \bullet Two parameters p and q to control sampling
- Second order Markov process

Node2Vec

 Parameters are multiplied by edge weights and normalized for random walk probabilities



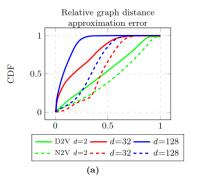
1/p, 1/q, 1 are unnormalized probabilities

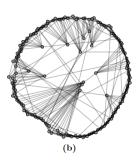
p, q model transition probabilities

- p ... return parameter
- q ... "walk away" parameter

Diff2vec

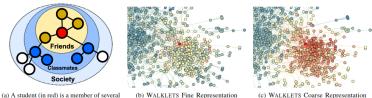
- Sample node according to supervised diffusion
- Efficient initialization and [possibility to control clustering parameters]





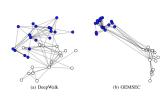
Grarep & Walklets

- Grarep: Approximate normalized A^k efficiently
- Walklets: approximate attention over k-distance neighbors



GEMSEC

- GEMSEC model cluster information adding regularization term over community labels given number of classes
- \bullet parameter γ balance cluster error and cluster structure given model hyper-parameters



$$\mathcal{L} = \underbrace{\sum_{v \in V} \left[\ln \left(\sum_{u \in V} \exp(f(v) \cdot f(u)) \right) - \sum_{n_i \in N_S(v)} f(n_i) \cdot f(v) \right]}_{\text{Embedding cost}} + \underbrace{\gamma \cdot \sum_{v \in V} \min_{c \in C} \|f(v) - \mu_c\|_2}_{\text{Clustering cost}}.$$
 (5)

M-NMF

- Modularized Nonnegative Matrix Factorization (M-NMF) incorporates first-second order proximity together with community structure.
- $S = S_1 + \eta S_2$, S_i goes for *i*-th order proximity.
- C represents community structure.
- H represents nodes community labels.
- B stands for $\left(A_{ij}-\frac{k_ik_j}{2m}\right)$ matrix in modularity function.
- U is our embedding.

$$\min_{\mathbf{M}, \mathbf{U}, \mathbf{H}, \mathbf{C}} \|\mathbf{S} - \mathbf{M}\mathbf{U}^T\|_F^2 + \alpha \|\mathbf{H} - \mathbf{U}\mathbf{C}^T\|_F^2 - \beta tr(\mathbf{H}^T \mathbf{B} \mathbf{H})$$

$$s.t., \mathbf{M} \geqslant 0, \mathbf{U} \geqslant 0, \mathbf{H} \geqslant 0, \mathbf{C} \geqslant 0, tr(\mathbf{H}^T \mathbf{H}) = n,$$

HOPE

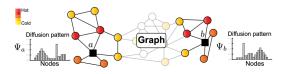
- HOPE is specific asymmetric transitivity preserving graph embedding.
- Asymmetric similarity measures can be formulated as $S = M_g^{-1} M_I$.
- Katz index refers to $M_g = I \beta A$, $M_I = \beta A$.
- Rooted PageRank can be stated as $M_g = I \alpha P, \ M_I = (1 \alpha)P, \ P = D^{-1}A.$
- Common neighbors is represented by $M_g = I$, $M_I = A^2$.
- Adamic-Adar with $M_g = I$, $M_I = ADA$.
- Generalized SVD and directly estimate matrices M_g and M_I .

Other models

- Structural Deep Network Embedding (SDNE) uses autoencoder via Laplacian eigenmaps.
- Watch Your Step: Learning Node Embeddings via Graph Attention attention on random walks aggregation without use on inference
- Metapath2vec adapts random walks on heterogeneous networks
- Discriminative Deep Random Walk (DDRW) includes label regularization to incorporate classification task

Diffusion Wavelets for Structural Similarity

- GraphWave learns heat wavelet diffusion patterns. Nodes with similar neighbors will have similar GraphWave embeddings.
- O(|E|) performance



VERSE for Structural Similarity

- VERSE uses conditional probability not on the embedding, but on the similarity rank.
- O(|E|) performance

$$\begin{split} sim_{\mathbf{E}}(v,\cdot) &= \frac{\exp(W_v W^\top)}{\sum_{i=1}^n \exp\left(W_v \cdot W_i\right)} \\ \mathcal{L} &= -\sum_{v \in V} sim_{\mathbf{G}}(v,\cdot) \log\left(sim_{\mathbf{E}}\left(v,\cdot\right)\right) \\ \mathcal{L}_{NCE} &= \sum_{u \sim \mathcal{P}} \left\lfloor \log \Pr_{W}(D=1|sim_{\mathbf{E}}(u,v)) + \sum_{v \sim sim_{\mathbf{G}}(u,\cdot)} \log \Pr_{W}(D=0|sim_{\mathbf{E}}(u,\widetilde{v})) \right\rfloor \end{split}$$

Short conclusion for structural Graph Embeddings

- Random walks are powerful tool for fast network embedding
- Proximity-aware embeddings, random walks can be modeled in terms of each other (and even deep neural networks!)
- complexity and space are important to choose the embedding model
- provided models are used for transductive learning only, inductive learning require additional regularizations and local optimizations
- large graphs are hard to fit with handcrafted sampling strategies
- no clear way to support features

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