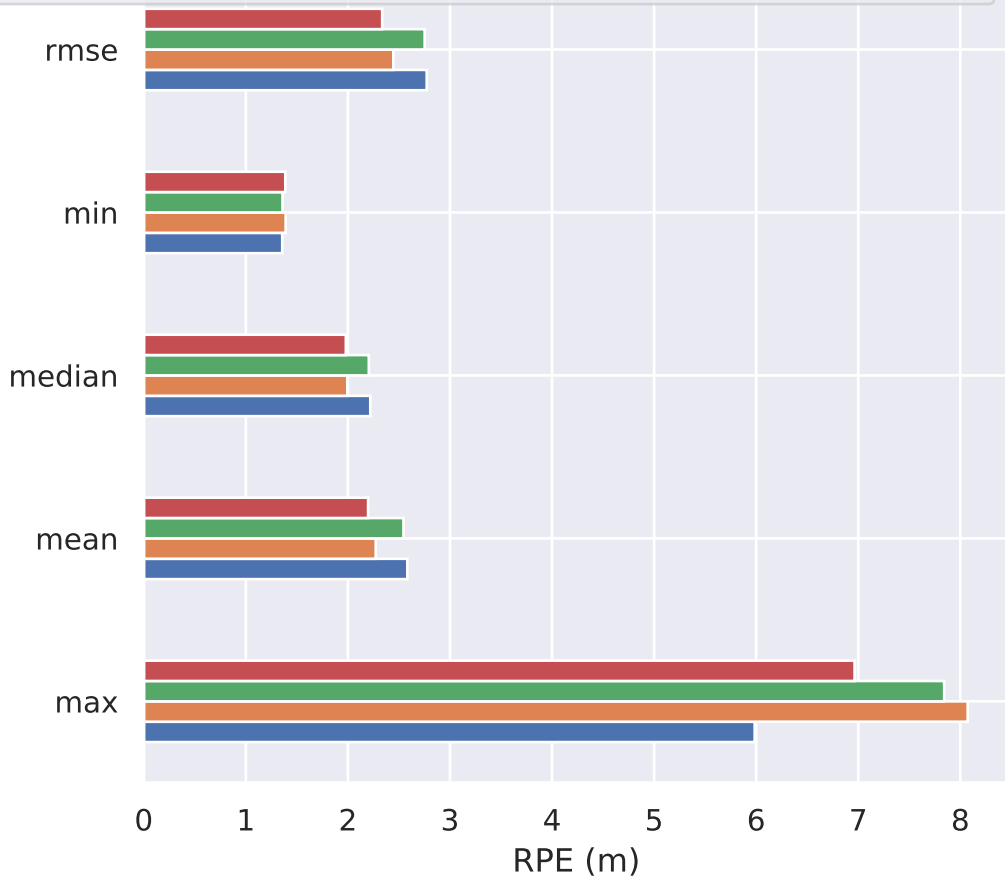


RPE w.r.t. translation part (m)
for $\delta = m$ (frames) using consecutive pairs
(with SE(3) Umeyama alignment)



- Experiment_Results/2018-11-07_12:12:47/rpe_eval/rpe_results.zip
- Experiment_Results/2018-11-07_12:13:21/rpe_eval/rpe_results.zip
- Experiment_Results/2018-11-07_12:13:56/rpe_eval/rpe_results.zip
- Experiment_Results/2018-11-07_12:14:30/rpe_eval/rpe_results.zip



imate = Experiment_Results/2018-11-07_12:13:41/rpe_eval/rpe_results.

2.0

1.5

1.0

0.5

0.0

imate = Experiment_Results/2018-11-07_12:13:56/rpe_eval/rpe_results.

2.0

1.5

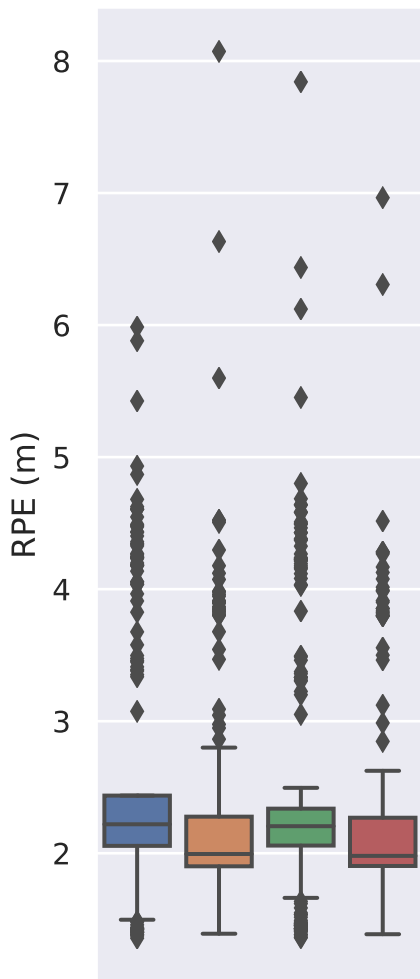
1.0

0.5

0.0

1000

RPE (m)



`performance_report_Rep01_R073_0187204871312072156490pubs_sizeip_ts.zip`

estimate

