

Team 0: Growable Space Habitat
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Project Summary

- Current space operations require constant resupply

 — Costly (\$20,000 per kg)

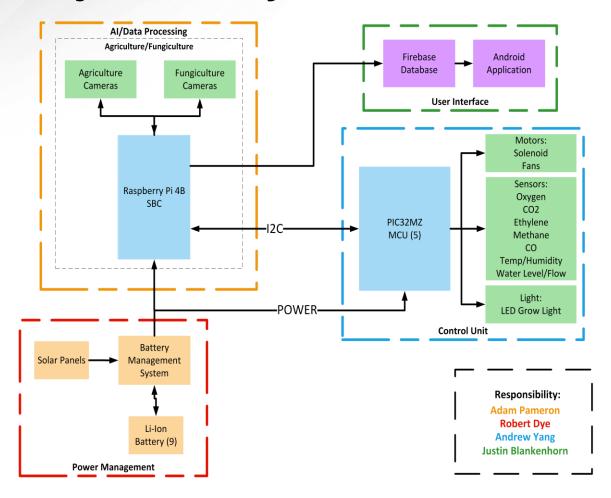
 — Inefficient and wasteful
- Long term space missions need a sustainable food source
- Project provides electrical infrastructure for a selfsustaining system capable of recycling agricultural products







Project/Subsystem Overview





Major Project Changes Since Last Time

Power Management:

None

User Interface:

None

AI/Data Processing:

None

Microcontroller:

None



Al/Data Processing Subsystem

- Create binary classifier using Convolutional Neural Network (CNN) Model
 - Baby Spinach
- Collect sensor data from 5 microcontrollers
- Send sensor data to database

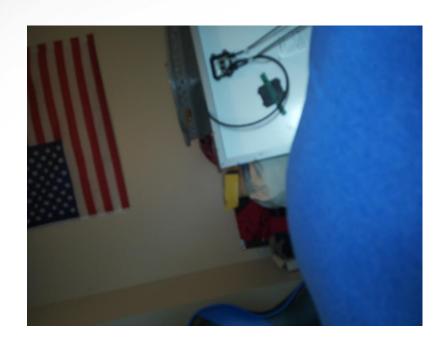


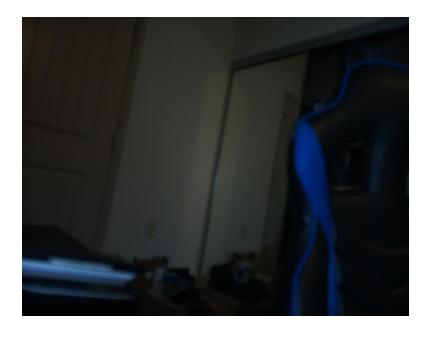
Al/Data Processing Subsystem

Accomplishments since last presentation	Ongoing progress/problems and plans until the next presentation
 Perform Stratified Cross Validation with augmented RGB Dataset Vertical Flip Gaussian Noise Blur Shearing Isolated each cameras to take photos at an interval period Built application code to repeat routines (classify, send image and state) 	Interfacing with microcontrollers using serial communication to request data, and validate all sensors data is collected and accurate



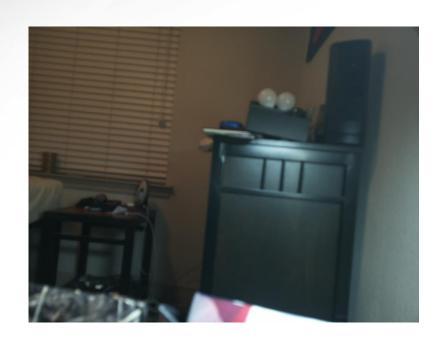
AI/Data Processing Subsystem– Camera 1 and Camera 2 Photos

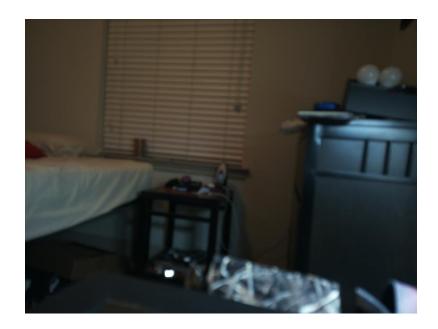






AI/Data Processing Subsystem – Camera 3 and Camera 4 Photos

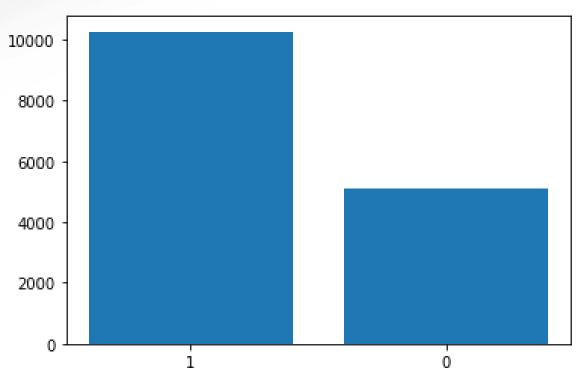






Al/Data Processing Subsystem - Total Size of Dataset

Adam Pameron

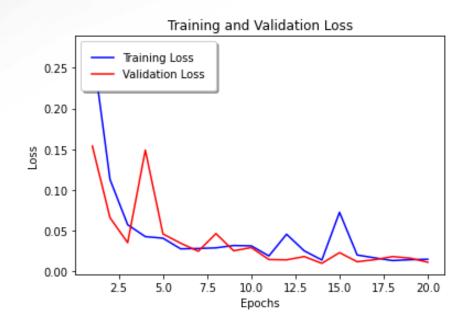


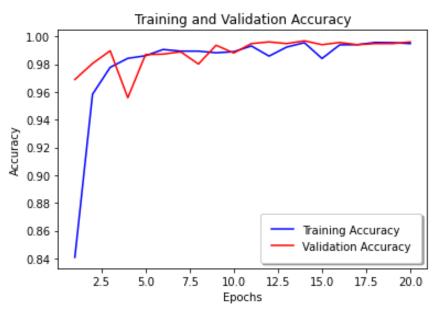
Healthy Set [0]: 5,084

Yellow Leaf Curl Set [1]: 10,264 Total Number of Images: 15,348



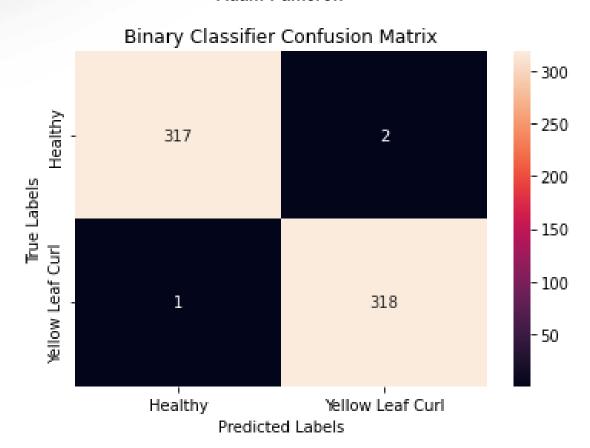
Al/Data Processing Subsystem – with Gaussian Noise







Al/Data Processing Subsystem – with Gaussian Noise



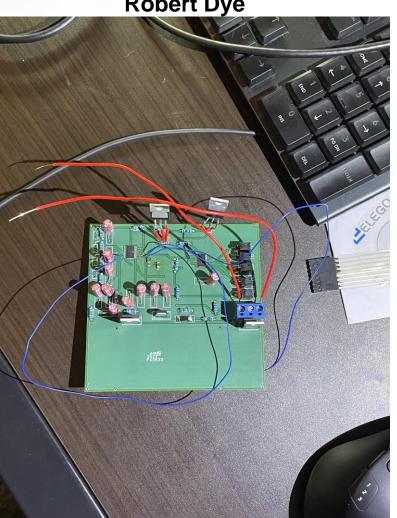


- Provide power to PCBs that house the microcontrollers as well as the pi that will be used to control AI subsystem
- BMS monitoring
- Charging



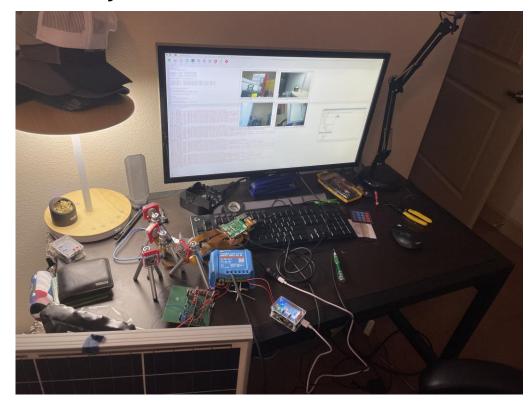
Accomplishments since last presentation	Ongoing progress/problems and plans until the next presentation
 Soldered all components Powered MCU Subsystem Powered Al/Data Processing Subsystem Designed, Routed all 4 analog sensor circuits 	 Keep performing testing on the BMS Code monitoring chips with BQ Studio



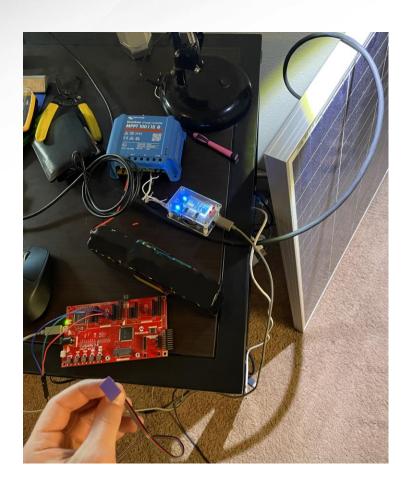


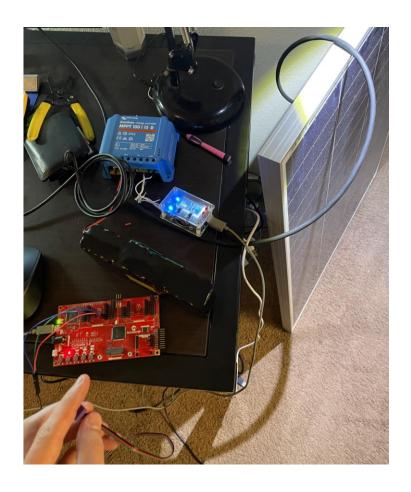












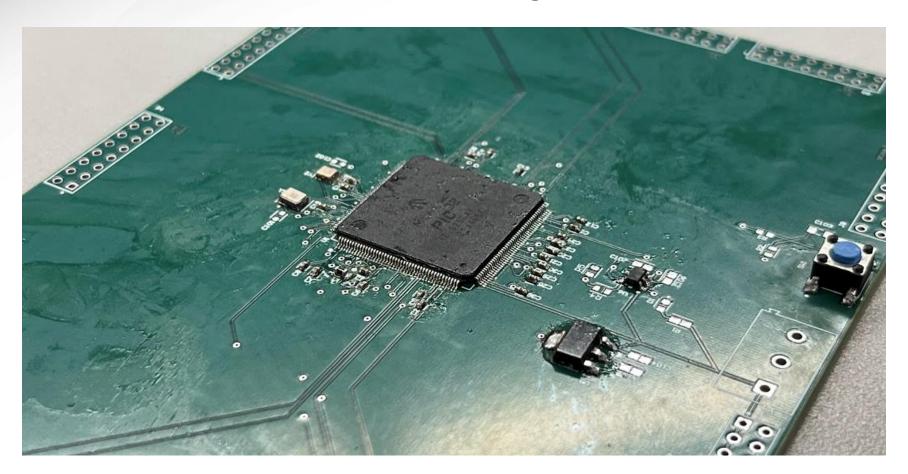


- 200 Peripherals modularized between 5 microcontrollers
- 20 Oxygen, 20 CO2, 20 NO2, 20 Methane, 20 Ethylene, 20 Carbon monoxide, 12 Temp/Humidity, 4 water level, 4 water flow sensors
- 9 types of sensors using I2C, UART, Analog, or digital communication
- 38 solenoids and 26 fans controlled using GPIO + switching circuit

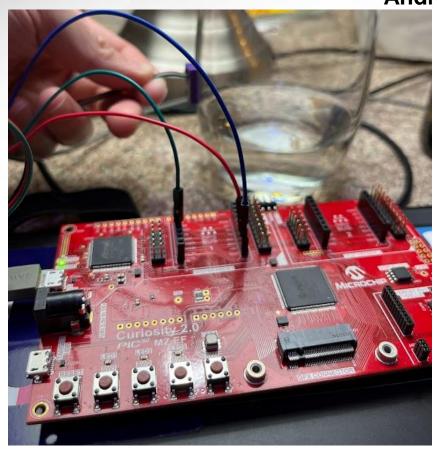


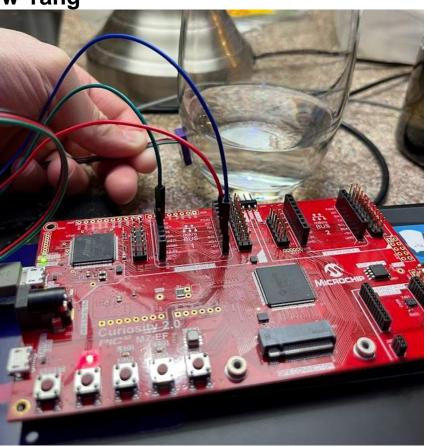
Accomplishments since last presentation	Ongoing progress/problems and plans until the next presentation
 Verified Water Level Sensor operation Designed Analog Sensor circuits Soldered over half of all components for the MCU 	 Verify Temperature/Humidity I2C sensor operation Verify UART sensor operation Implement PWM logic for water flow sensor Design I2C multiplexer circuit for fan and solenoid switching



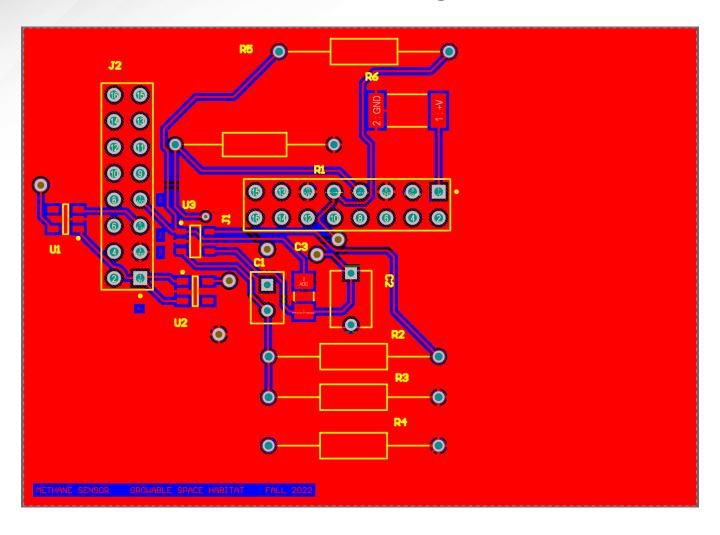




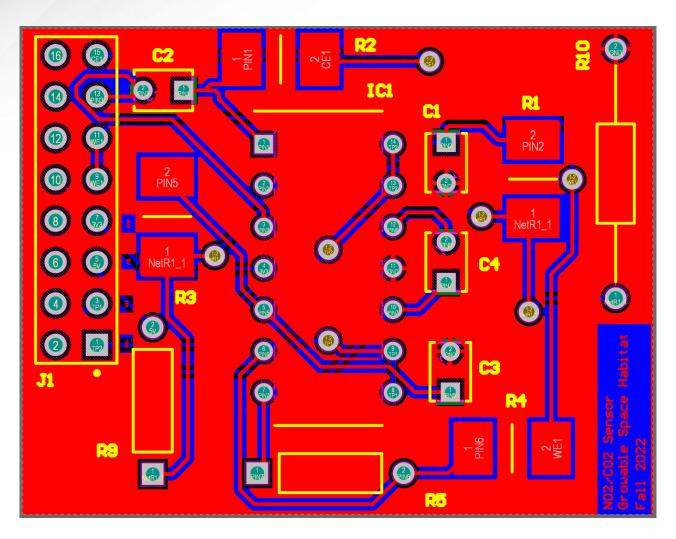




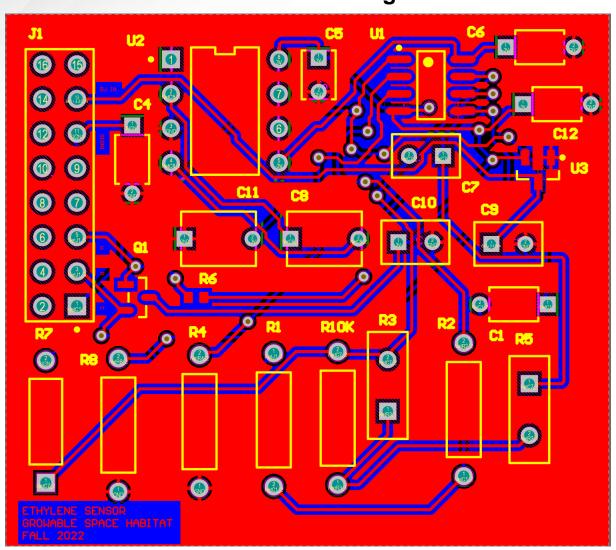














User Interface

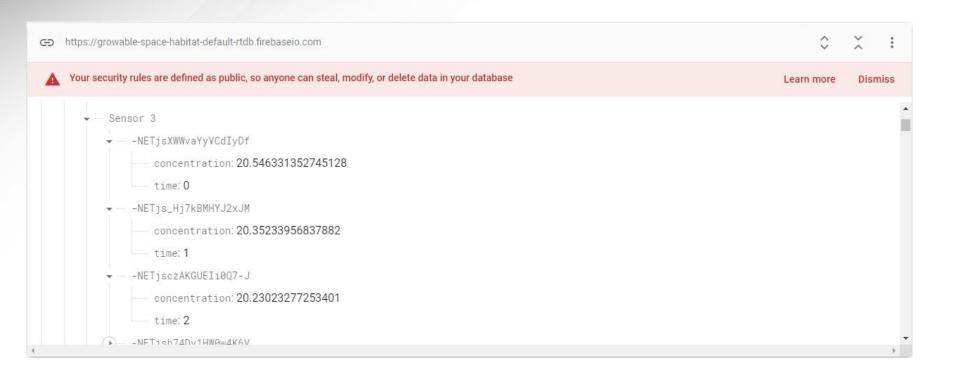
- Display Data from MCU sensors on app
- Visualize sensor values over time
- Display camera pictures on app



User Interface

Justin Blankenhorn

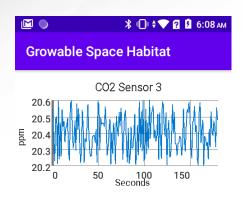
Accomplishments since last presentation	Ongoing progress/problems and plans until the next presentation
 Created Graphs for all sensors Differentiated graphs between Second + Minutes Included Axis's and scroll view for graph 	 Improve formatting on graphs, Help on other subsystems

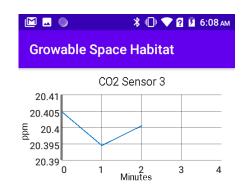




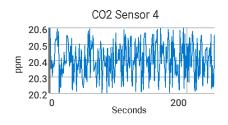
User Interface

Justin Blankenhorn



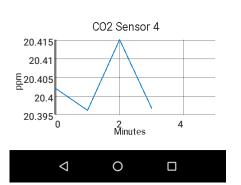


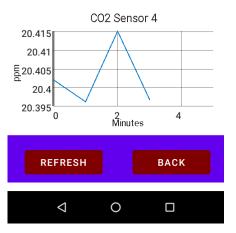




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Execution & Plan



THANK YOU!