



*Dwight Look College of*

**ENGINEERING**  
TEXAS A&M UNIVERSITY

# **Team 0: Growable Space Habitat**

**Robert Dye**

**Justin Blankenhorn**

**Andrew Yang**

**Adam Pameron**

**Sponsor: Dr. John Lusher II, Dr. Hope Rising**

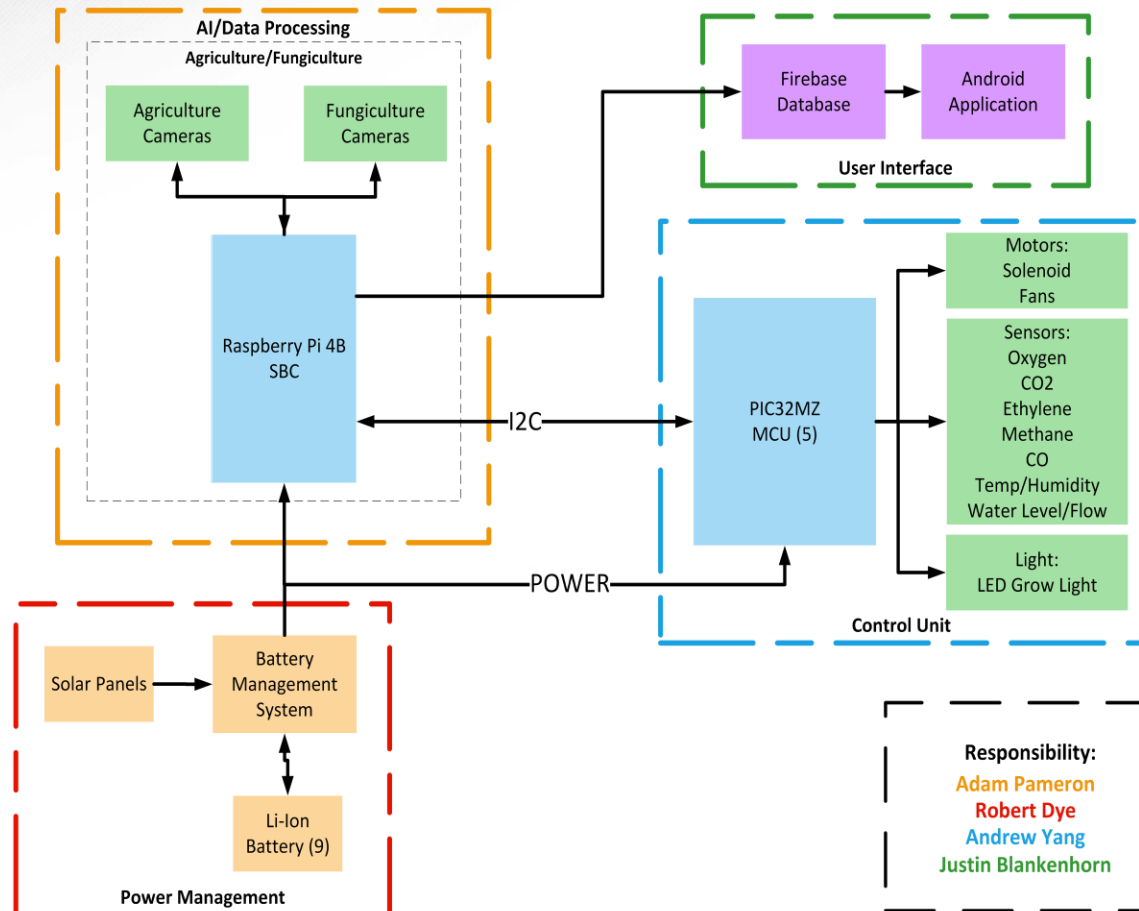
**TA: Rohith Kumar**

# Project Summary

- Current space operations require constant resupply
  - Costly (\$20,000 per kg)
  - Inefficient and wasteful
- Long term space missions need a sustainable food source
- Project provides electrical infrastructure for a self-sustaining system capable of recycling agricultural products



# Project/Subsystem Overview





# Major Project Changes Since Last Time

Power Management:

- None

User Interface:

- Will display data on health of system

AI/Data Processing:

- None

Microcontroller:

- None

# AI/Data Processing Subsystem

Adam Pameron

- Create binary classifier using Convolutional Neural Network (CNN) Model
  - Baby Spinach [Proxy: Tomato Leaves]
- Collect sensor data from microcontrollers
- Send sensor data to database





# AI/Data Processing Subsystem

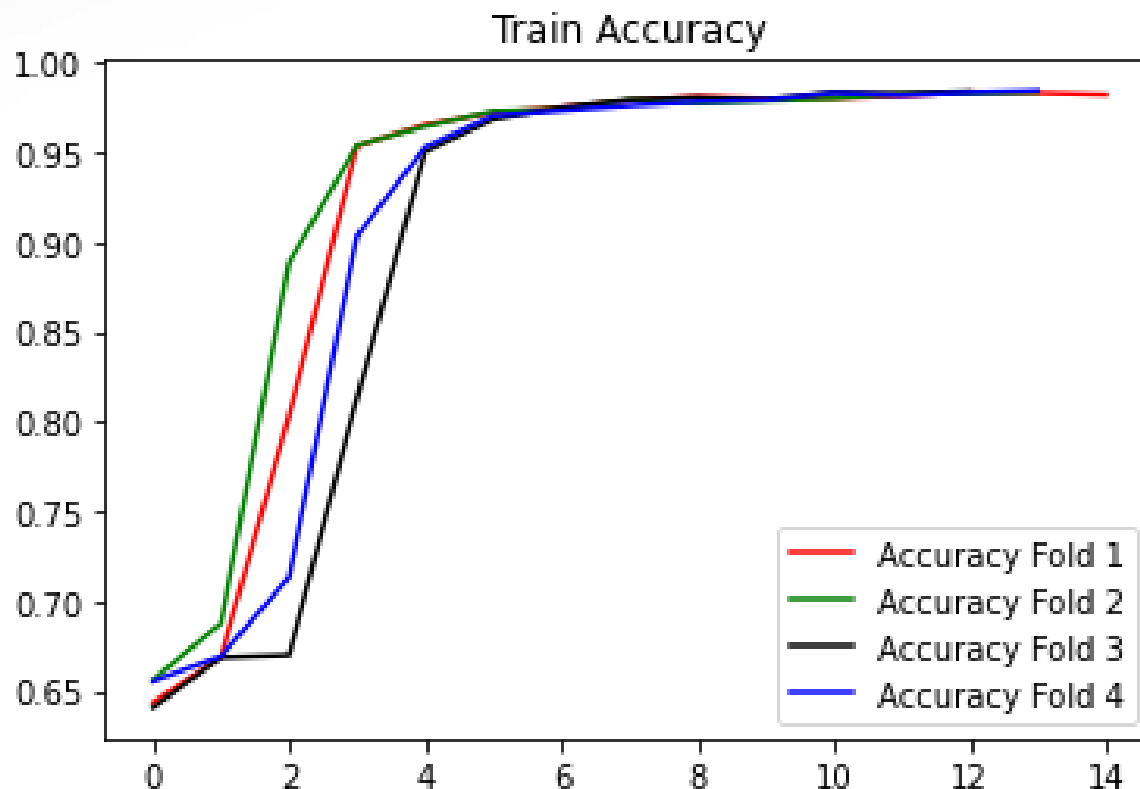
Adam Pameron

Accomplishments since last presentation	Ongoing progress/problems and plans until the next presentation
<ul style="list-style-type: none"><li>• Perform Stratified Cross Validation with augmented RGB Dataset<ul style="list-style-type: none"><li>• Used SGD Optimizer</li></ul></li><li>• Configured UART serial communication<ul style="list-style-type: none"><li>• Validated sensor data with trusted Pi data</li></ul></li><li>• Configured I2C serial communication<ul style="list-style-type: none"><li>• Controller and Peripheral Mode</li><li>• Validated Sensor Data with trusted Arduino data</li></ul></li><li>• Deployed model to Pi to validate classification</li><li>• Built application code to repeat routines (classify, send image and state)<ul style="list-style-type: none"><li>• Created specialized functions to abstract routine</li></ul></li></ul>	<ul style="list-style-type: none"><li>• Further validation of sensor data</li><li>• Build application code for PIC32<ul style="list-style-type: none"><li>• Create specialized functions to abstract routine</li></ul></li></ul>

# AI/Data Processing Subsystem

## – Train Accuracy 4 Folds

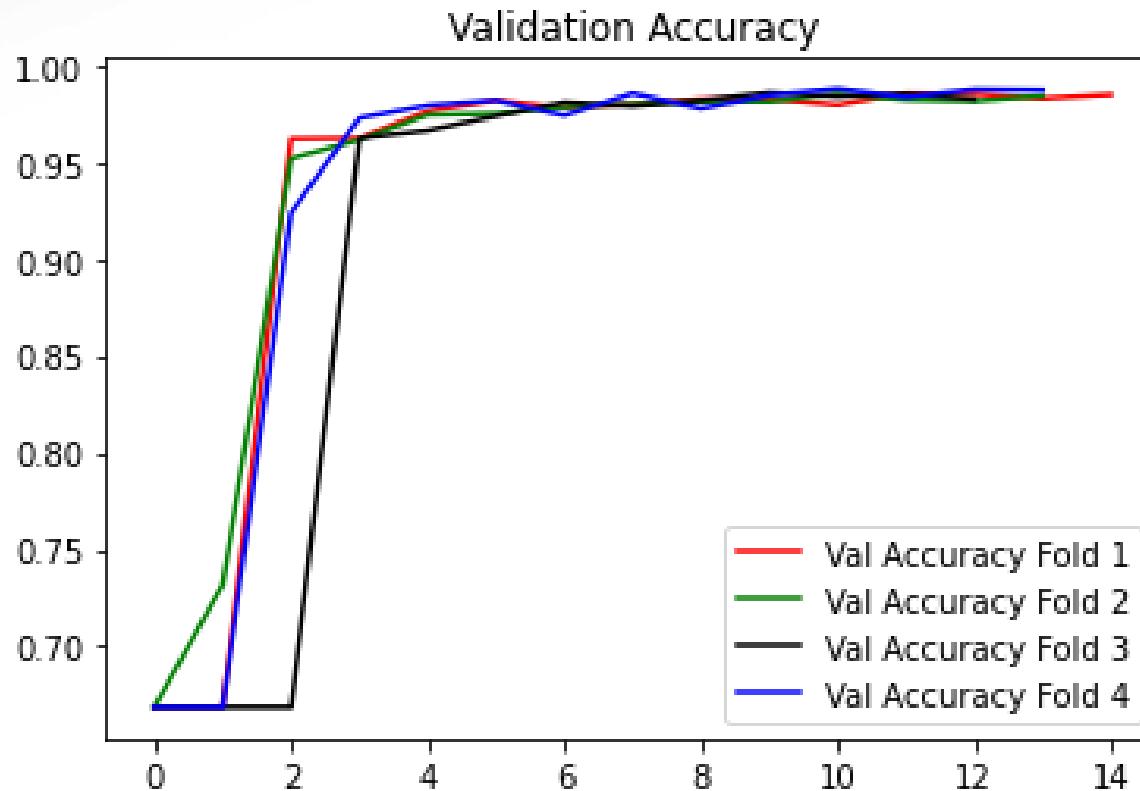
Adam Pameron



# AI/Data Processing Subsystem

## – Validation Accuracy 4 Folds

Adam Pameron

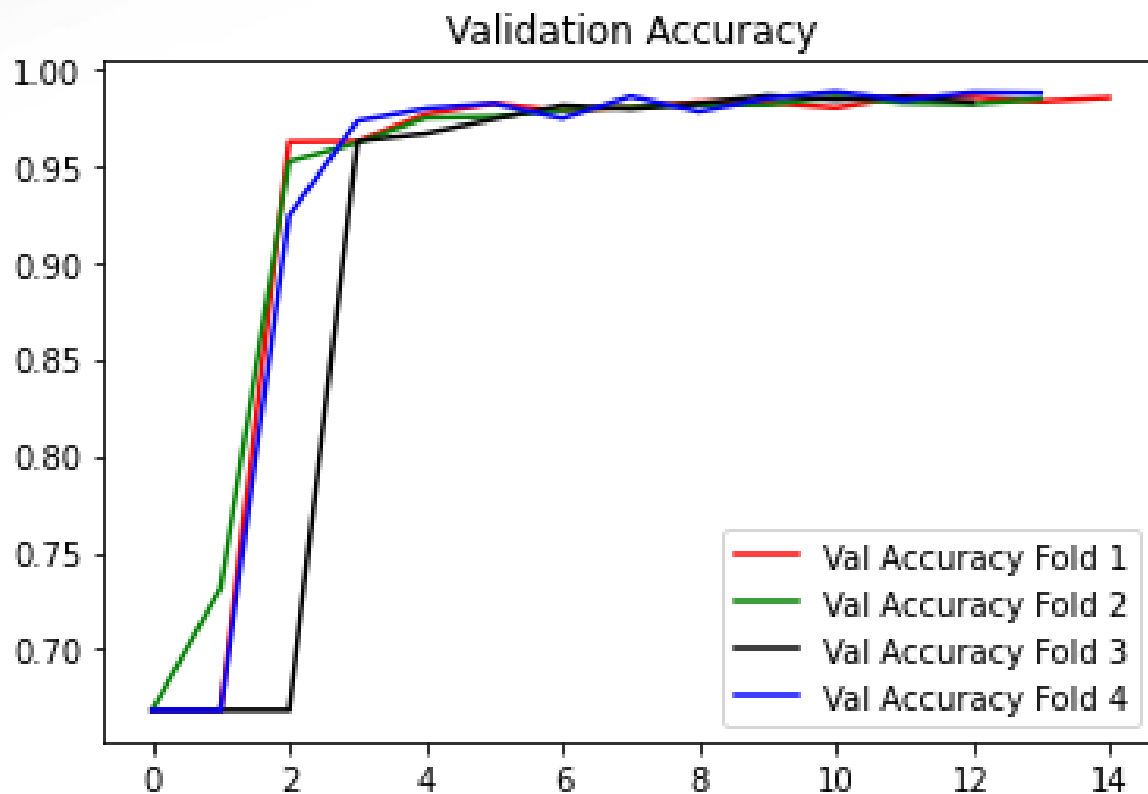




# AI/Data Processing Subsystem

## – Validation Accuracy 4 Folds

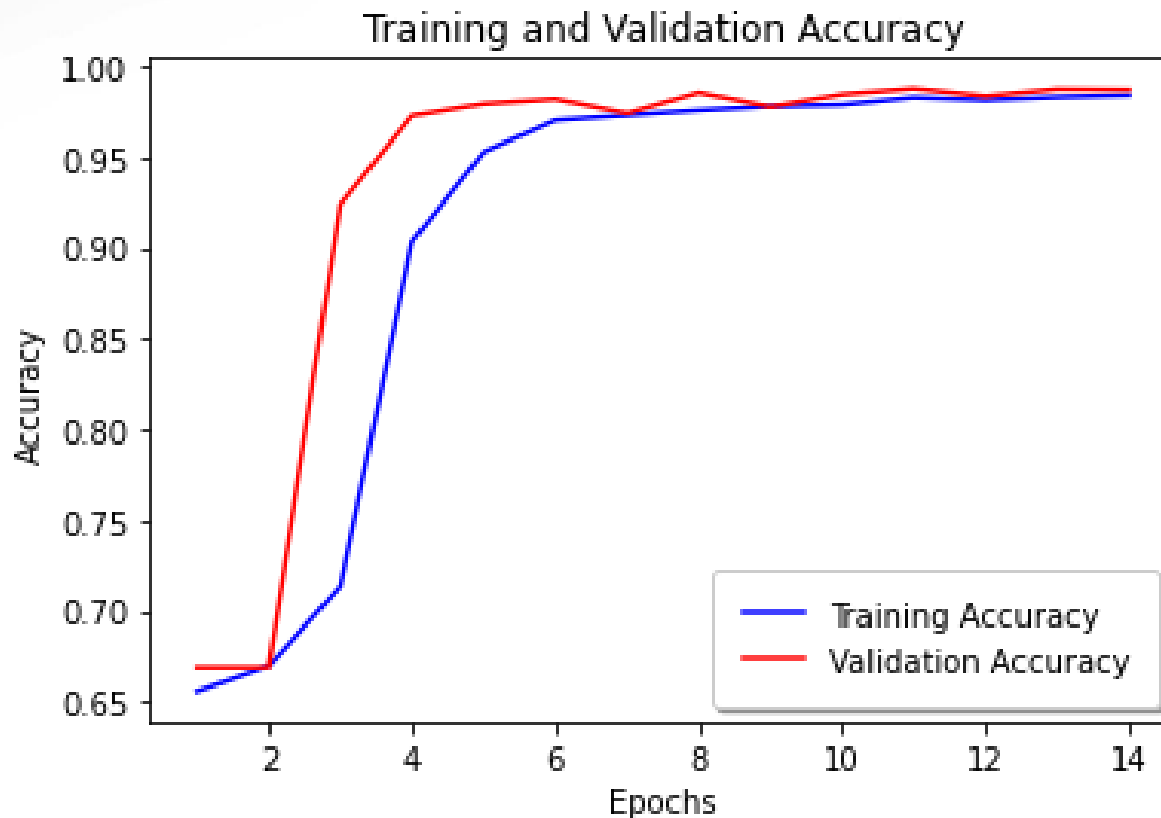
Adam Pameron



# AI/Data Processing Subsystem

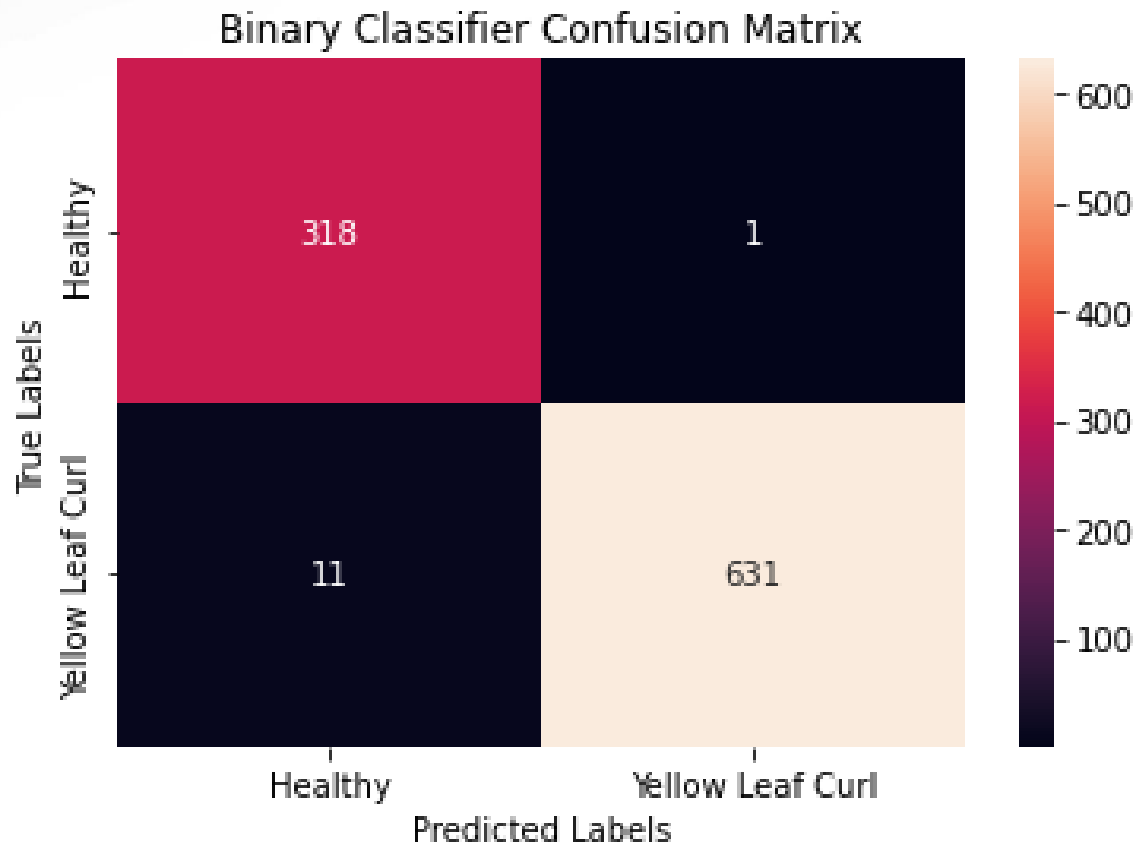
## – Training and Validation Accuracy Fold 4

Adam Pameron



# AI/Data Processing Subsystem – Confusion Matrix Fold 4

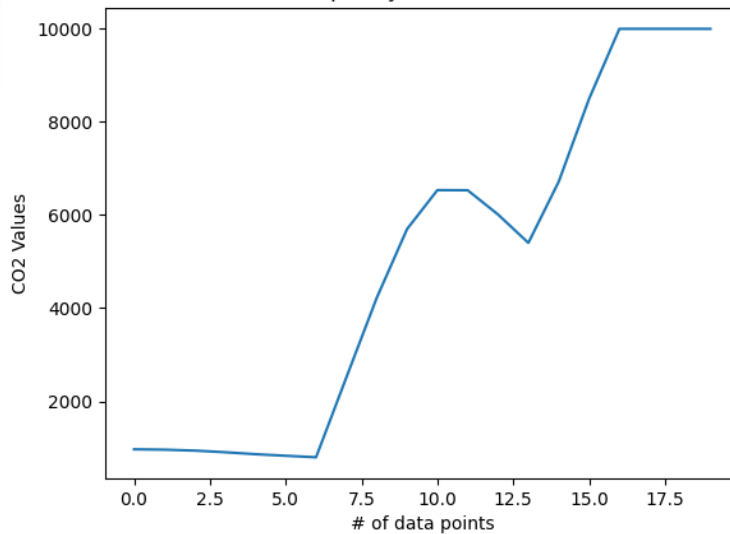
Adam Pameron



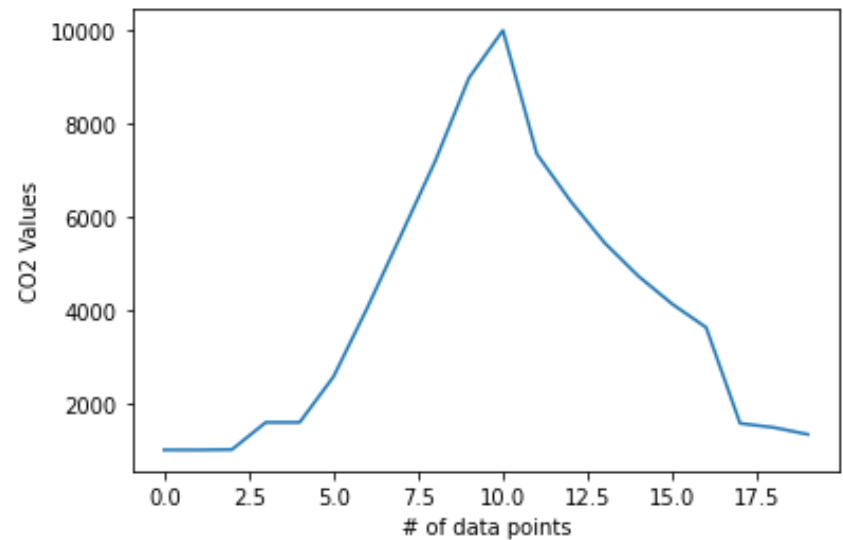
# AI/Data Processing Subsystem – Pi and PIC32 CO2 Values

Adam Pameron

Raspberry Pi CO2 Values



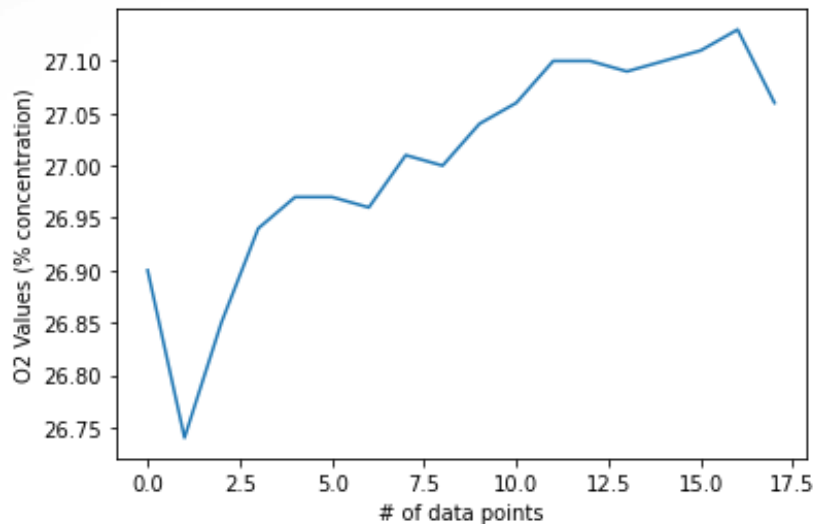
PIC32 CO2 Values



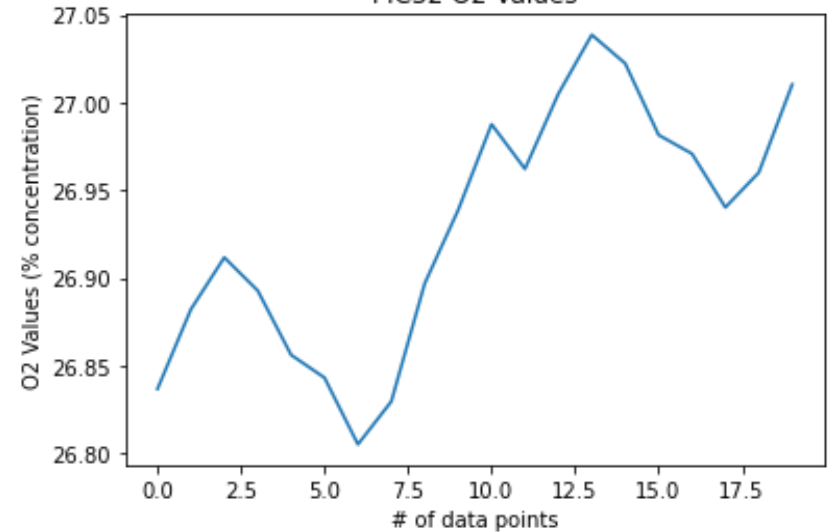
# AI/Data Processing Subsystem – Arduino and PIC32 O<sub>2</sub> Values

Adam Pameron

Arduino O<sub>2</sub> Values

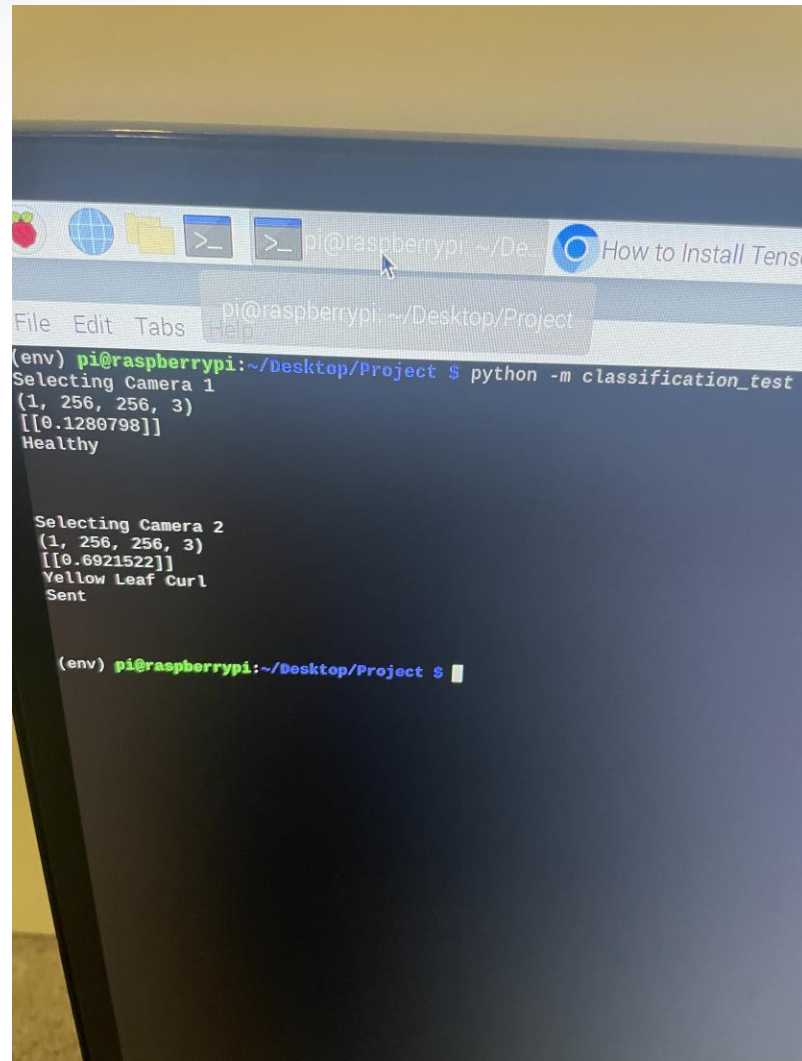


PIC32 O<sub>2</sub> Values



# AI/Data Processing Subsystem

Adam Pameron



```
(env) pi@raspberrypi:~/Desktop/Project $ python -m classification_test
Selecting Camera 1
(1, 256, 256, 3)
[[0.1280798]]
Healthy

Selecting Camera 2
(1, 256, 256, 3)
[[0.6921522]]
Yellow Leaf Curl
Sent

(env) pi@raspberrypi:~/Desktop/Project $
```



# Power Management

Robert Dye

- Provide power to PCBs that house the microcontrollers as well as the pi that will be used to control AI subsystem
- BMS monitoring
- Charging



# Power Management

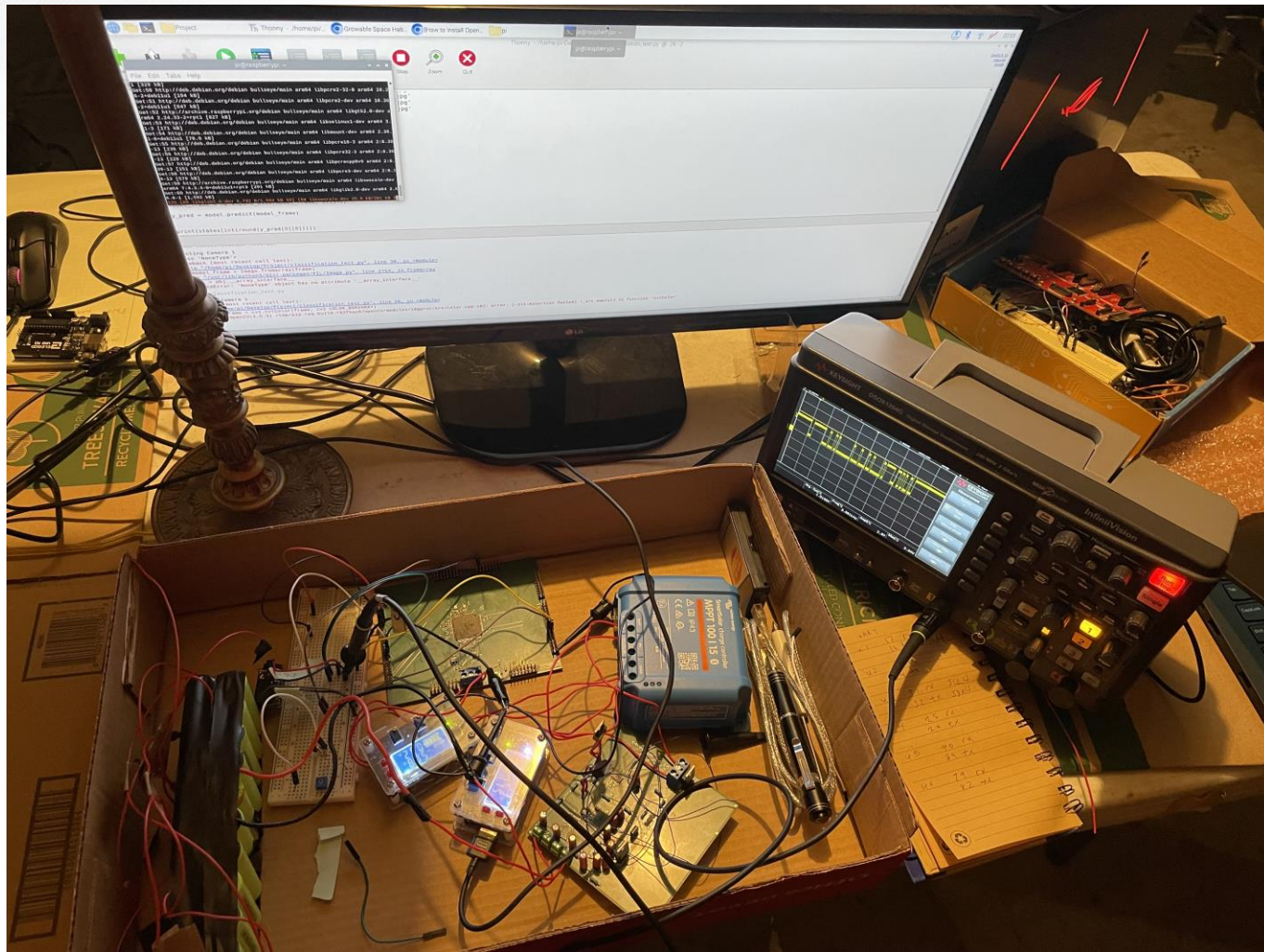
Robert Dye

Accomplishments since last presentation	Ongoing progress/problems and plans until the next presentation
<ul style="list-style-type: none"><li>• Powered all subsystems at the same time</li><li>• Soldered analog Sensor PCBs</li></ul>	<ul style="list-style-type: none"><li>• Keep performing testing on the BMS</li><li>• Code monitoring chips with BQ Studio</li></ul>



# Power Management

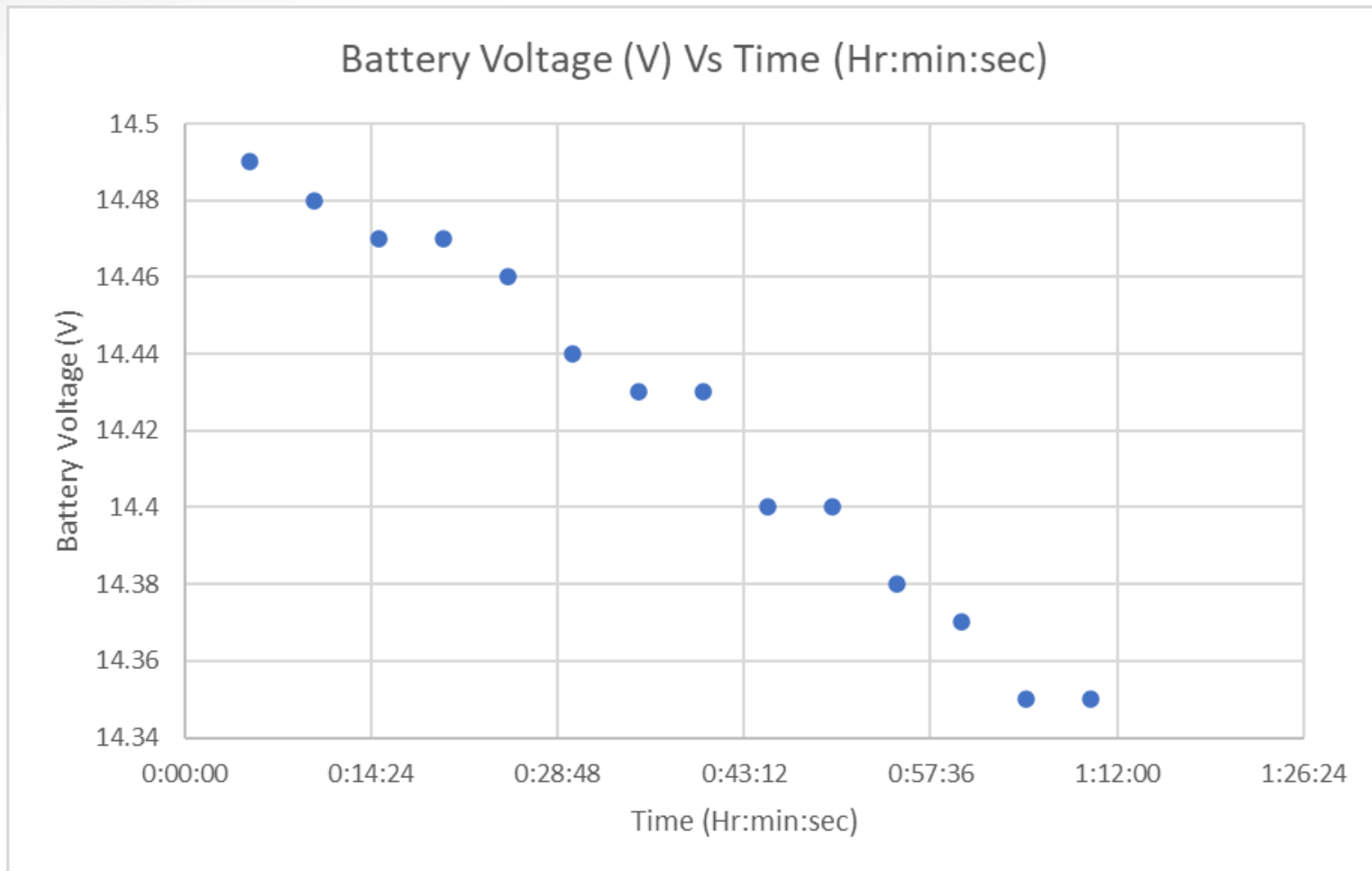
Robert Dye



# Power Management

## - Voltage/Time graph current 1.06/1.25

Robert Dye

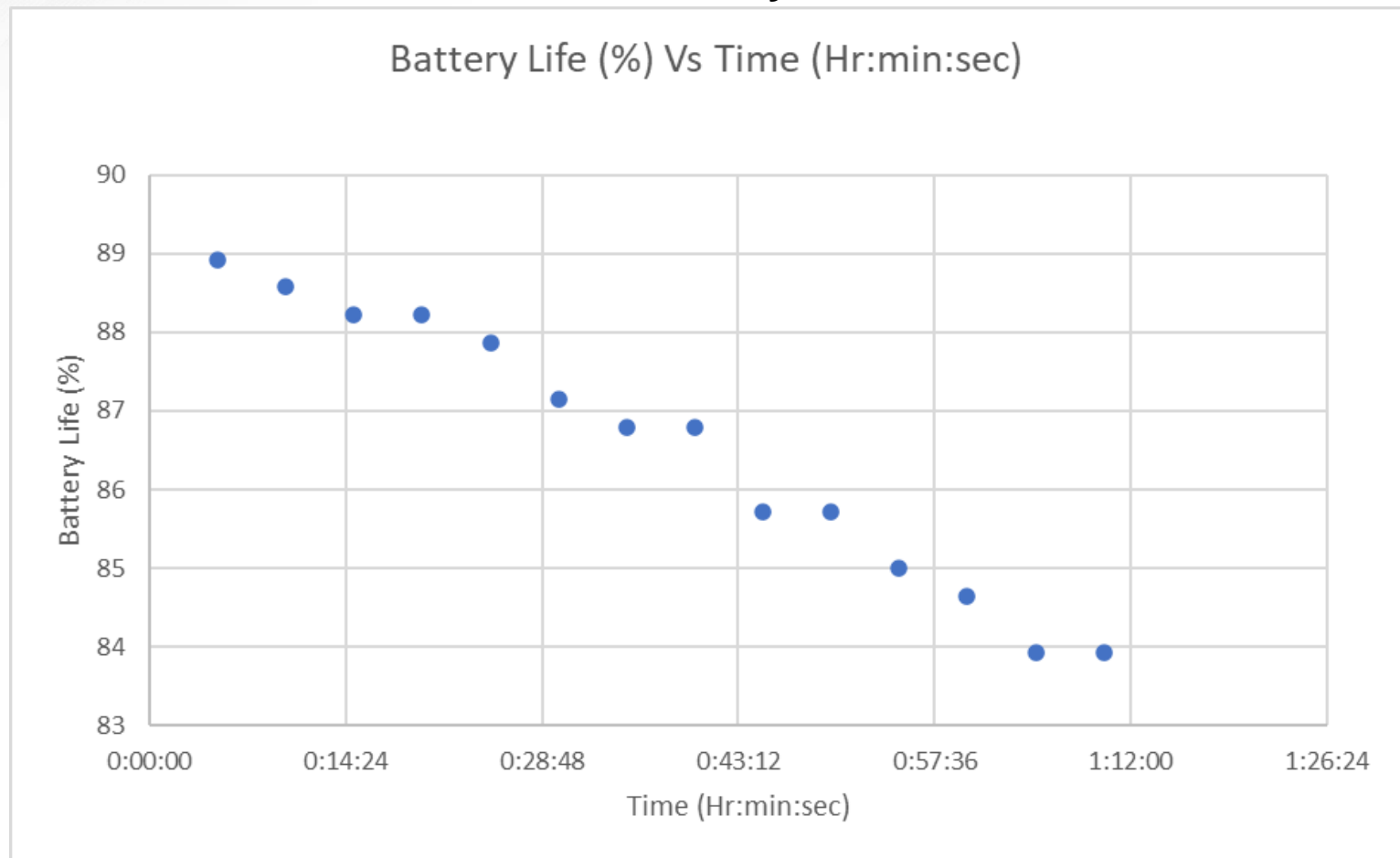




# Power Management

## - % Health/Time graph current 1.06/1.25

Robert Dye





# Microcontroller

Andrew Yang

- 200 Peripherals modularized between 5 microcontrollers
- UART, I2C, Analog, Digital, Digital Counter, GPIO switch



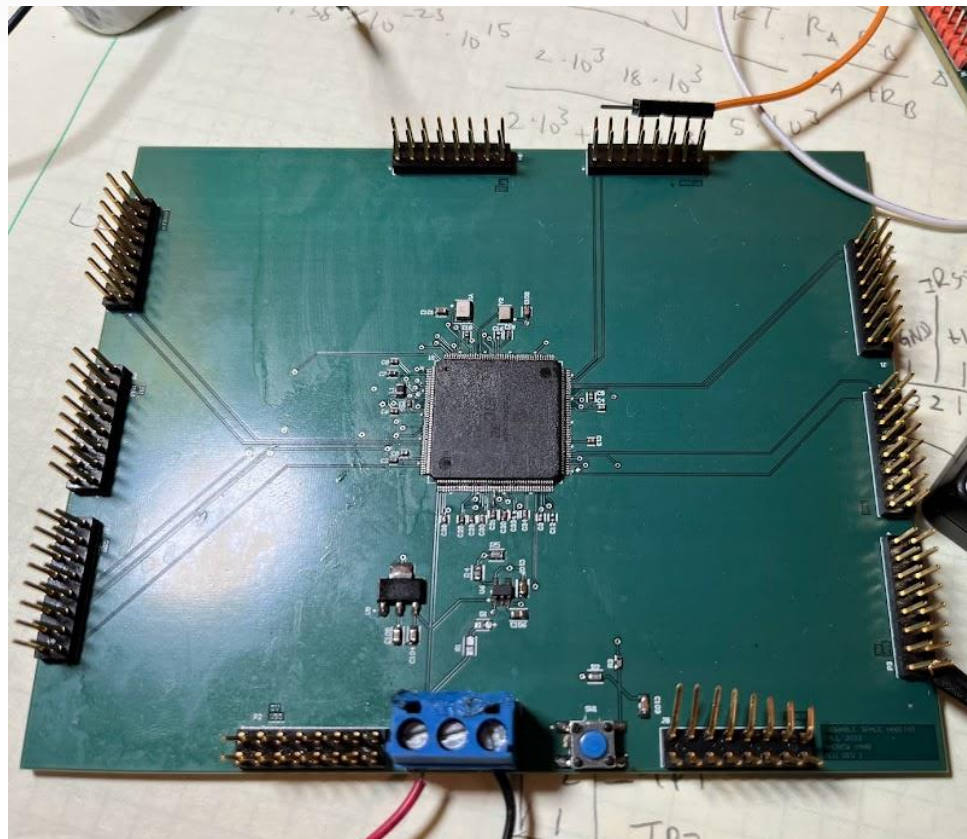


# Microcontroller

Andrew Yang

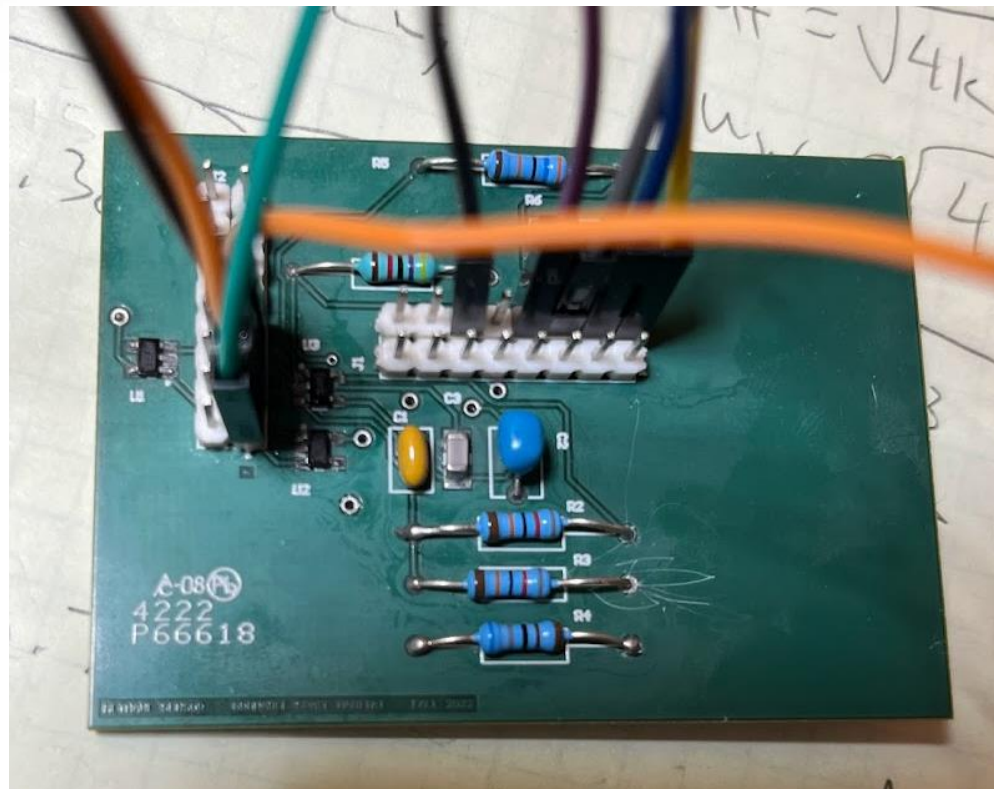
Accomplishments since last presentation	Ongoing progress/problems and plans until the next presentation
<ul style="list-style-type: none"><li>Validated MCU operation</li><li>Ordered Analog Sensor PCBs Rev. 2</li></ul>	<ul style="list-style-type: none"><li>Implement counter logic for water flow sensor</li><li>Solder and validate analog sensor boards</li><li>Flash MCU with dev board code</li></ul>

# Microcontroller Andrew Yang



# Microcontroller

Andrew Yang



# User Interface

- Display Data from MCU sensors on app
- Visualize sensor values over time
- Display camera pictures on app



# User Interface

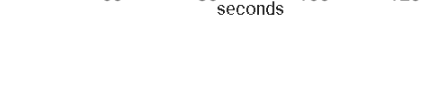
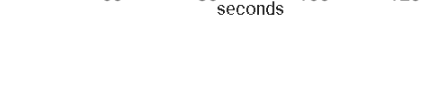
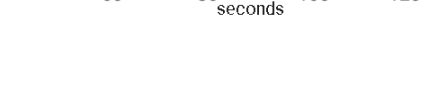
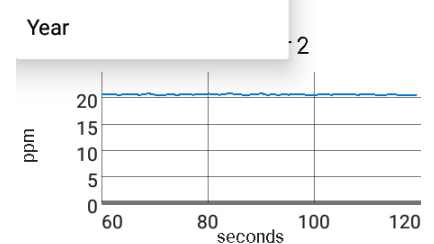
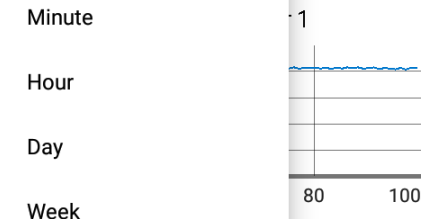
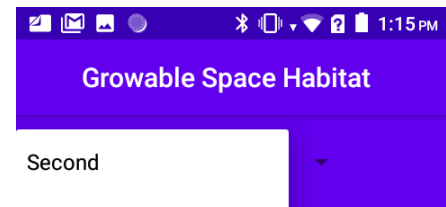
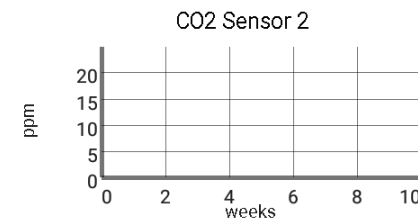
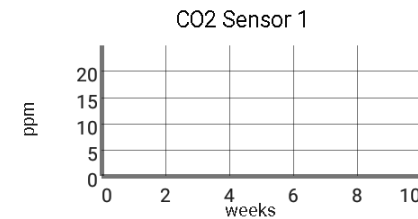
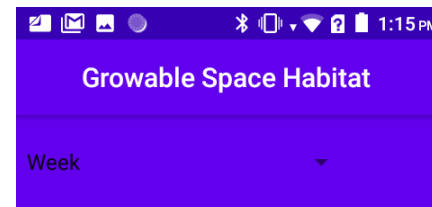
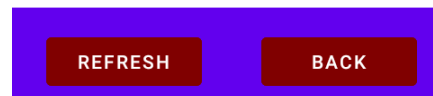
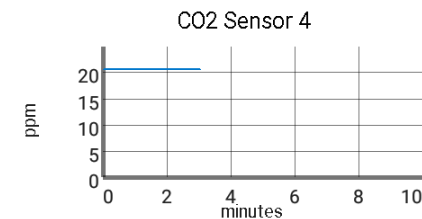
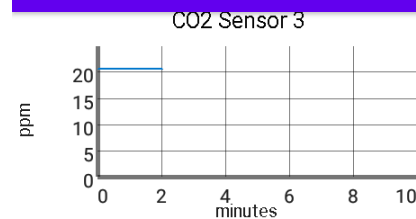
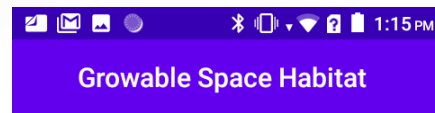
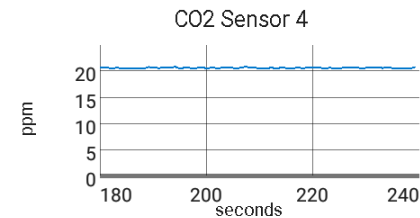
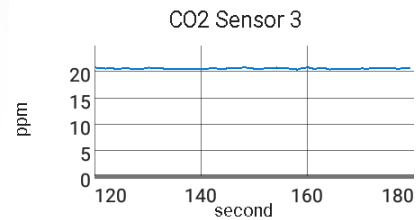
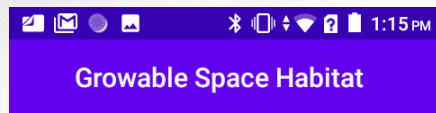
Justin Blankenhorn

Accomplishments since last presentation	Ongoing progress/problems and plans until the next presentation
<ul style="list-style-type: none"> <li>• Configured Graphs in terms of hours, days, weeks, years</li> <li>• Use dropdown button instead of buttons</li> <li>• Included data + graphs on plant health with pictures</li> <li>• Reconfigured graphs to lower noise</li> <li>• Put Camera pictures on separate pages</li> </ul>	<ul style="list-style-type: none"> <li>• Reformat graphs to align with Pi internal clock</li> <li>• Work on formatting</li> </ul>



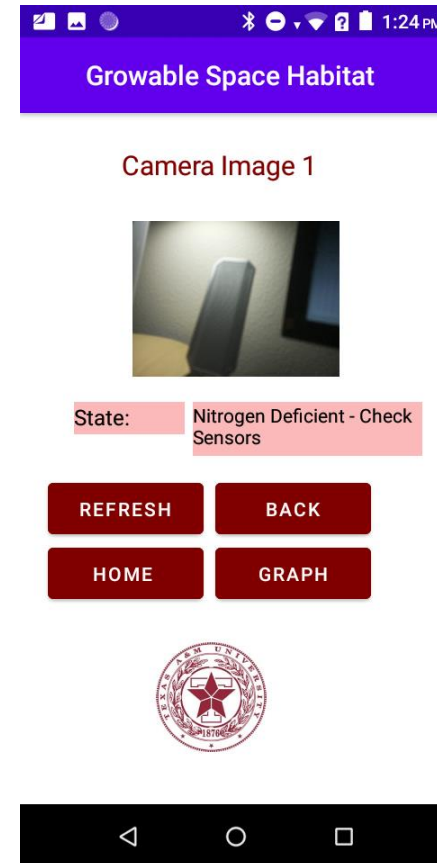
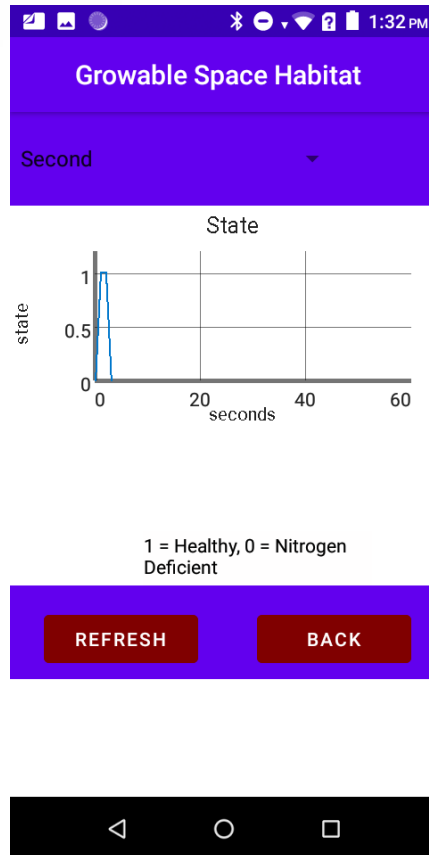
# User Interface - Graphs

Justin Blankenhorn






# User Interface – System Health





# Data Integration

 <https://growable-space-habitat-default-rtdb.firebaseio.com>



Your security rules are defined as public, so anyone can steal, modify,

▶ -NDP00N3Xfjq1UXUK-W0

▶ -NDP000hLwSIvkwqKhK1

▶ -NDP00QHk6m7Niml2w\_z

▶ -NDP00Rsd7Gi6lQ5xgvi

▼ -NDP00TVcjRd4ptakvSH

— concentration: 20.497204605687745

— time: 99

▶ Sensor 2

▼ Sensor 3

▼ -NETjsXWWvaYyVCdIyDf

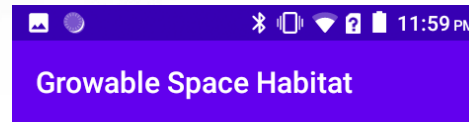
— concentration: 20.546331352745128



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# Data Integration



CO2 Sensors

Sensor 1: 20.497204	Expected Range: NA
Sensor 2: 20.387352	Expected Range: NA
Sensor 3: 20.481132	Expected Range: NA
Sensor 4: 20.556638	Expected Range: NA

BACK

REFRESH

GRAPH  
DATA



# Execution & Plan

[illegible]



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**THANK YOU!**