

Theoretical Analysis of Complex Systems:

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is the course of course.

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Programming: Python...

Evaluation: 1/2 Project. 11/12.

- 1/2: 1/4 weekly exercises.
- 1/2: exam + practical.
(16/12) (23/10)

Lecture by Werner KRAUTH.
CFP master
takes place every Friday Afternoon.
Statistical Physics & Algorithms.
(LTS)

Lecture 1 28/08:

INTRODUCTION TO STOCHASTIC PROCESSES.

Understand the emerging properties, the emergence process.

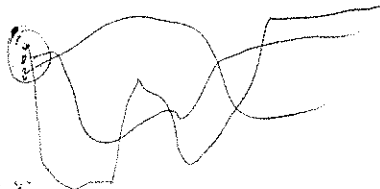
1 - From microscopic to macroscopic description.

N constituents $N \gg 1$.

elementary systems of position $\{\vec{x}_i^{mic}\}$, Newton's law $m_i \ddot{\vec{x}}_i = \vec{F}(\{\vec{x}_j^{mic}\}, t)$.
in 2 mole: $6 \cdot 10^{23}$ constituent \rightarrow impossible.

A sensitivity to initial conditions (if we could solve).

Solution in phase space.



Some systems present arbitrary sensitivity.

CHAOS.

1/ solution of deterministic eq.

we will describe effective paths, from stochastic point of view (complementary: microscopic) \rightarrow random gradients...

Complex Quantum systems are also possible.

Compromise between 2 points of view: \rightarrow individual trajectories.
 \rightarrow distributions. (stochastic).

1st solution (historically): Thermodynamics. (Boltzmann, Gibbs, Einstein, Fermi).
Hypothesis on the distribution after a long time.

x microcanonical point of view: every configuration with the same energy E has the same probability. (equi-).

x canonical p. of view: (not isolated systems) $Prob(conf) \propto e^{-\beta E_{energy}(conf)}$ $\beta = \frac{1}{k_B T}$

Applies only to systems

- x at equilibrium (linked to reversibility).
- x very large systems.
- x to determine mean values.
- x in the steady states.
- x for static observables.

$\overset{0}{P}(x, t)$: probability that the particle is at position x at time t .

• normalized: $\forall t, \sum_x \overset{0}{P}(x, t) = 1$.

• initial condition: $\overset{0}{P}(x, 0) = \delta_{x,0} = \begin{cases} 1 & x=0 \\ 0 & x \neq 0 \end{cases}$.

• Master equation for $\overset{0}{P}(x, t)$

$$\overset{0}{P}(x, t + \delta t) = \overset{0}{P}(x - \delta x, t) + \overset{0}{P}(x + \delta x, t) + (1 - 2B)\overset{0}{P}(x, t).$$

increasing,
discrete space,
rule 24.

"Good" object $\rightarrow B_c$. In continuous, hole densities.

Prob. density $P(x, t)$:

$$\delta_x P(x, t) = \left[\text{probability of being in } \overset{0}{P} \left[x - \frac{\delta x}{2}, x + \frac{\delta x}{2} \right] \text{ at time } t \right] \cdot \delta_x \overset{0}{P}(x, t).$$

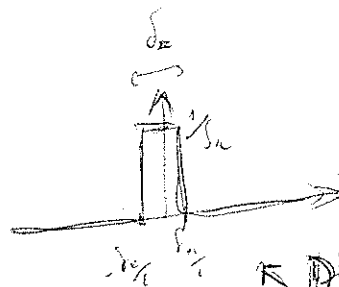
[DEF]

$$P(x, t) = \frac{\overset{0}{P}(x, t)}{\delta_x}$$

\rightarrow norm: $\sum_x \delta_x P(x, t) = 1$

$$\int dx P(x, t) = 1$$

• Initial condition: $\frac{\overset{0}{P}(x, 0)}{\delta_x} = \frac{\delta_{x,0}}{\delta_x}$



\propto Dirac in the limit.

$$P(x, 0) = \delta(x) \text{ : Dirac delta "function".}$$

prop: $\int dx f(x) \delta(x - x_0) = f(x_0)$. \rightarrow more prob. ($\langle \delta, f \rangle = f(0)$).

$$\int dx f(x) P(x, 0) = f(0).$$

\hookrightarrow new value of observable with initial distribution.

Physical interpretation: \rightarrow extremely sharp wave a value. o. a message over

Integration of dirac & derivation:

Exercise: determine $A_{x_0}(x) = \int_{-\infty}^{\infty} dx' \delta(x' - x_0)$.

Consistency of hypothesis? \rightarrow eq only in \hat{x} .

or: $\text{off} = 1 - \{ = -3 \}$, i.e. $\{ = 1/2$.

$\hat{P}(\hat{x}) + \hat{x} \hat{P}'(\hat{x}) = 2D \hat{P}''(\hat{x})$. Recover the same scaling again!

Solving by variation of constants: $\hat{P}(\pm\infty) = 0$.

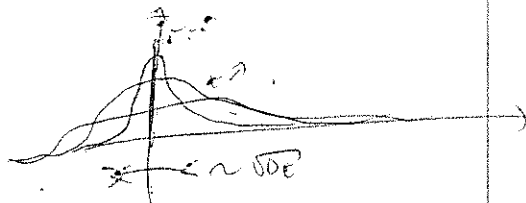
$$\hat{P}(\hat{x}) = \frac{1}{\sqrt{4\pi D}} \exp\left(-\frac{1}{2} \frac{\hat{x}^2}{2D}\right)$$

$$\int d\hat{x} \hat{P}(\hat{x}) = 1$$

$$\forall t, \int dx P(x,t) = 1$$

Solution:

$$P(x,t) = \frac{1}{\sqrt{4\pi D t}} \exp\left(-\frac{1}{2} \frac{x^2}{2D t}\right)$$



$$\lim_{t \rightarrow 0} P(x,t) = \delta(x)$$

Let put many random walkers with interactions.

or add force or potential -

Next goal: put force & interactions:

$$x_{t+\delta t} = x_t + \dot{\eta} \delta t + \tilde{F}(x_t)$$

or rather $\dot{x} = \frac{x_t \delta t - x_t}{\delta t} = \frac{\dot{\eta} \delta t}{\delta t} + \tilde{F}(x_t)$

Mean and variance of the noise?

$$\dot{x}(t) = \eta(t) \quad \text{"lim}_{\delta t \rightarrow 0} \frac{\eta_t}{\delta t}$$

What is the distribution of the continuous noise $\eta(t)$?

Mean: $\langle \eta(t) \rangle = \langle \partial_t x \rangle = \partial_t \langle x \rangle = 0$

from ergodicity & distribution.

"Variance" 2nd moment: $\langle \eta(t_1) \eta(t_2) \rangle = \langle \dot{x}(t_1) \dot{x}(t_2) \rangle$ only $= R(t_1, t_2)$

Let's focus on $C(t_2, t_1) = \langle [x(t_2) - x(t_1)]^2 \rangle$

One uses that $P(x_2, t_2 | x_1, t_1) = \frac{1}{\sqrt{4\pi D(t_2 - t_1)}} \exp\left(-\frac{1}{2} \frac{(x_2 - x_1)^2}{2D(t_2 - t_1)}\right)$ $t_2 > t_1$

use absence of memory & evolution

$$C(x_1, t_1) = \int dx_1 dx_2 (x_2 - x_1)^2 P(x_2, t_2 | x_1, t_1) = 2D |t_2 - t_1|$$

$$C(t_2, t_1) = 2D |t_2 - t_1|$$

$C(t_2, t_1) = C(t_2 - t_1)$
 $x(t_1) - x(t_2) = \int_{t_1}^{t_2} \dot{x}(t) dt$
 $\rightarrow C(t_2 - t_1) = \left\langle \left(\int_{t_1}^{t_2} dt \eta(t) \right)^2 \right\rangle = \left\langle \left(\int_{t_1}^{t_2} dt \int_{t_1}^{t_1} dt' \dot{\eta}(t) \eta(t') \right) \right\rangle$
 $= \int \int dt dt' R(t' - t)$