

1 0 주 차 교 육

ToBig's 9기 임소정

Deep Learning

Neural Network - 1

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Unit 01 | 딥러닝이란?

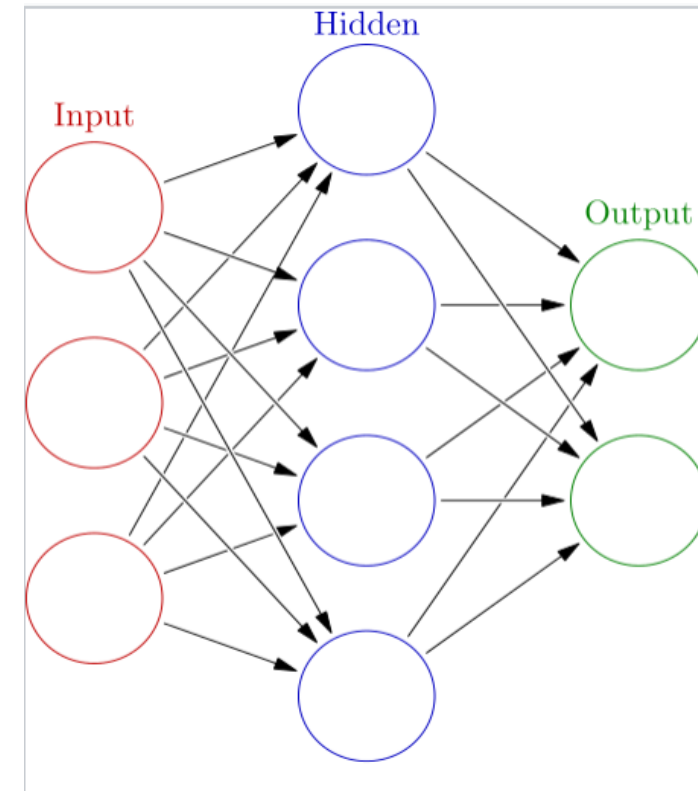
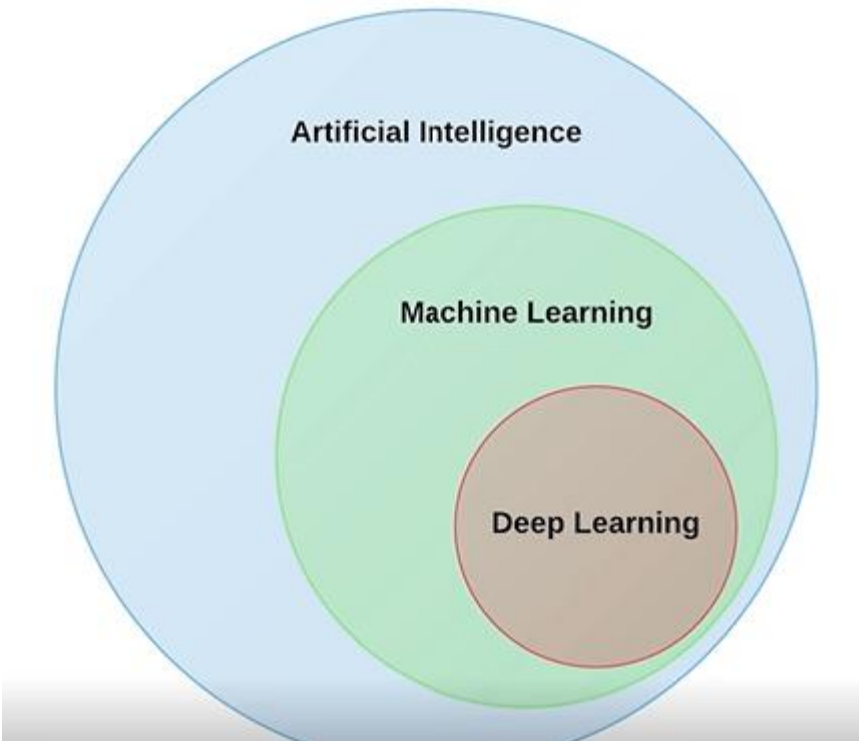
Unit 02 | Perceptron

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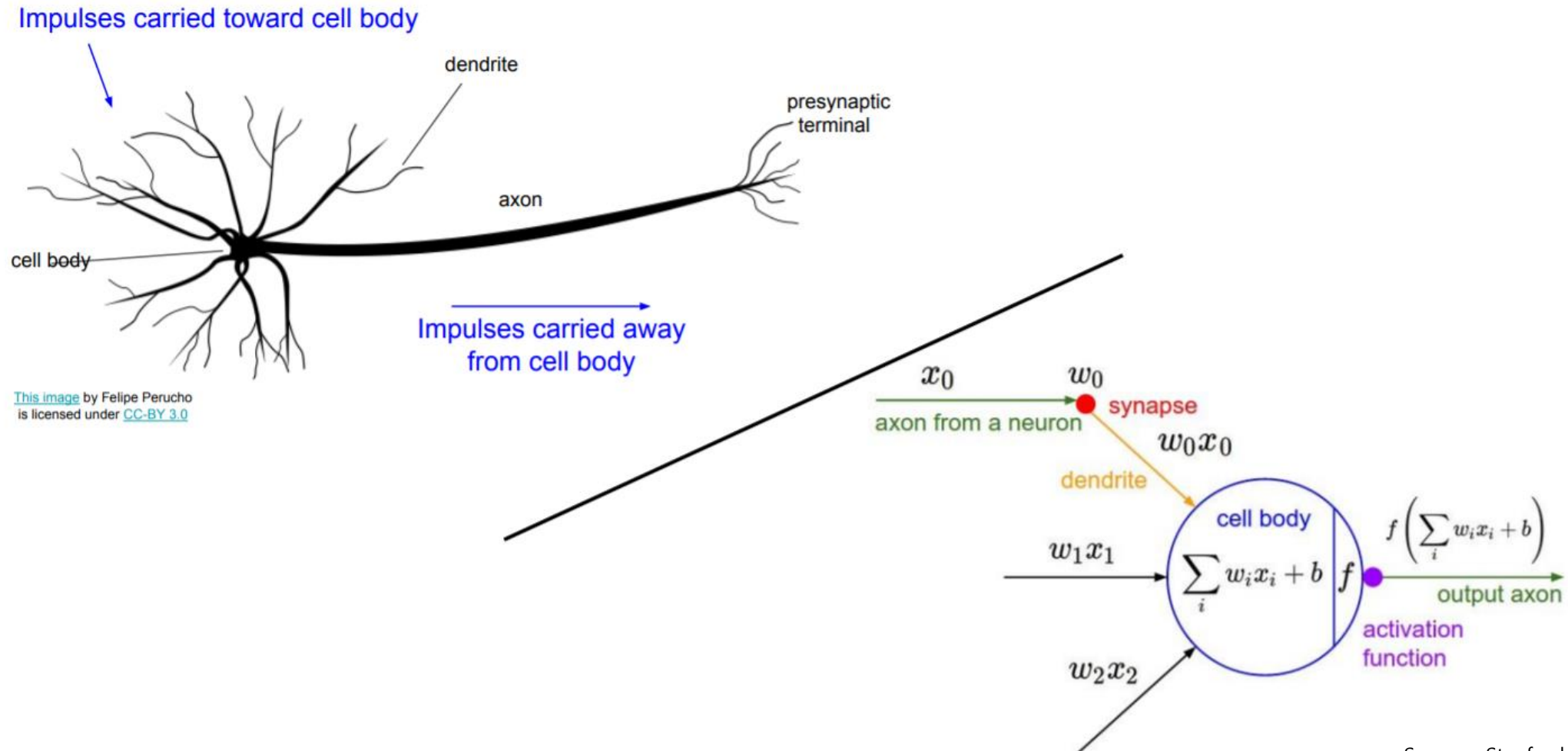
Unit 01 | 딥러닝이란?



Artificial Neural Network

Source : <https://www.youtube.com/watch?v=aF03asAmQbY&feature=youtu.be>
https://en.wikipedia.org/wiki/Artificial_neural_network

Unit 01 | 딥러닝이란?



Unit 01 | 딥러닝이란?

Be very careful with your brain analogies!

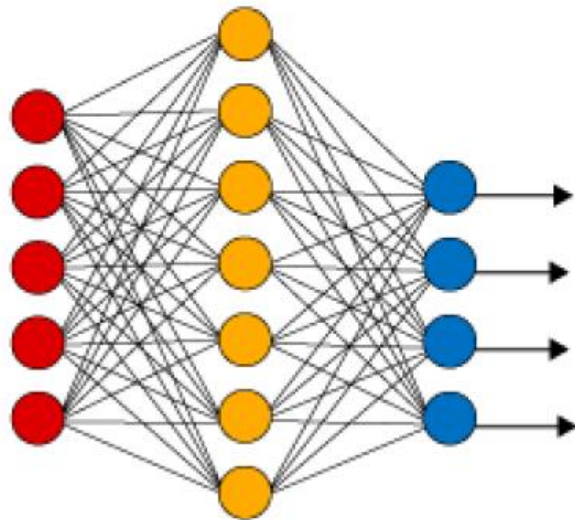
Biological Neurons:

- Many different types
- Dendrites can perform complex non-linear computations
- Synapses are not a single weight but a complex non-linear dynamical system
- Rate code may not be adequate


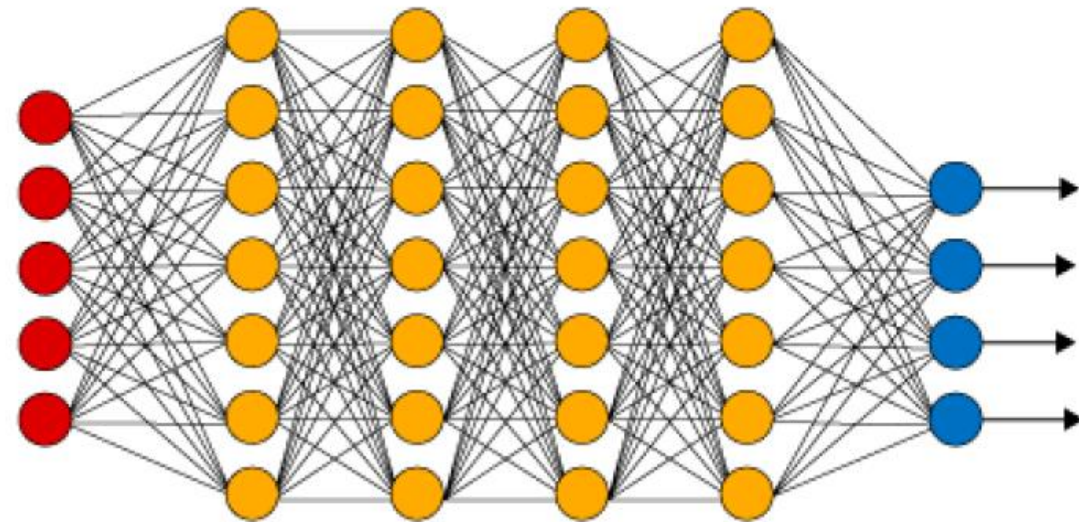
[Dendritic Computation. London and Hausser]

Unit 01 | 딥러닝이란?

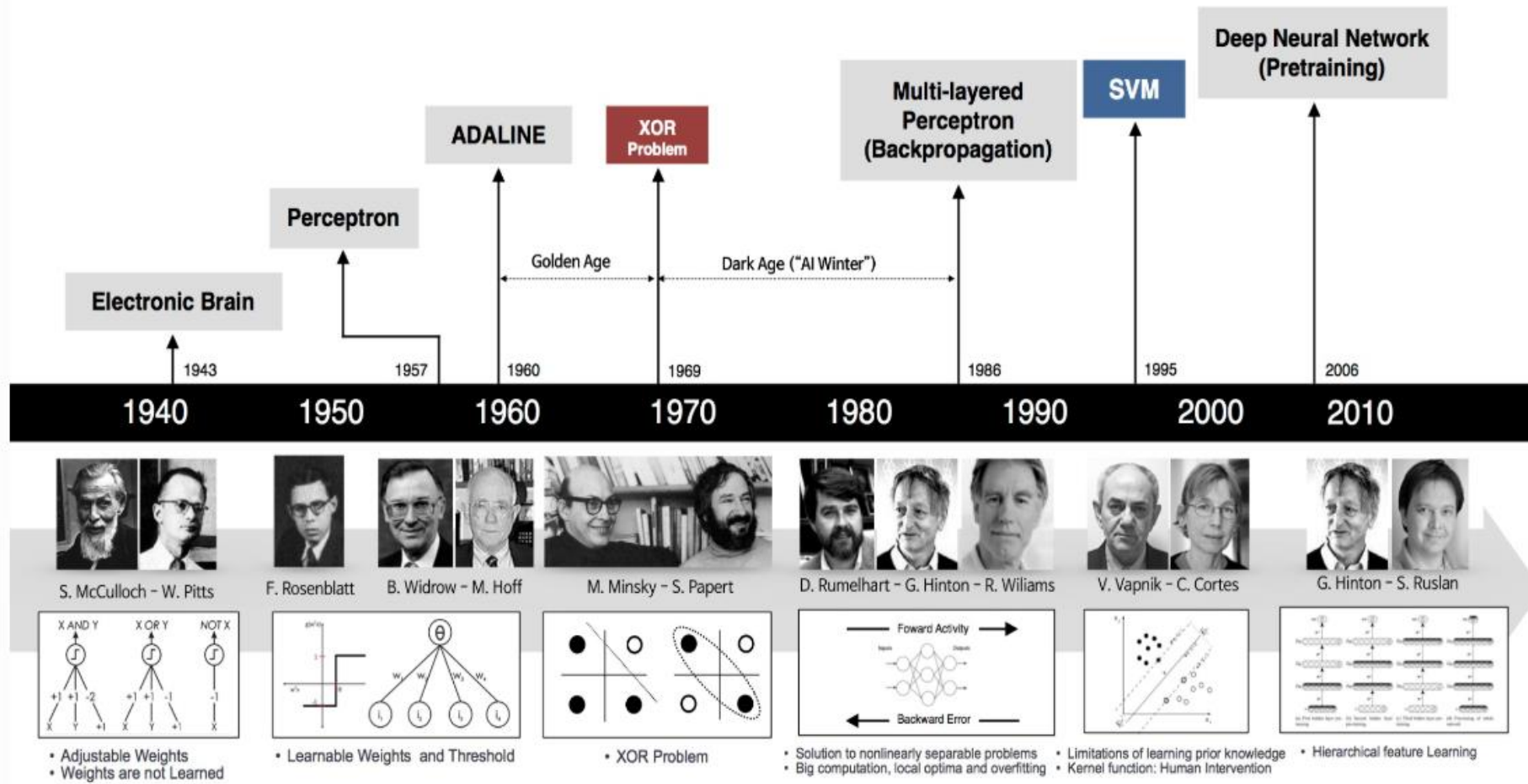
Simple Neural Network



Deep Learning Neural Network

 Input Layer Hidden Layer Output Layer

Unit 01 | 딥러닝이란?



Unit 01 | 딥러닝이란?

Why is Deep Learning Hot **Now**?

1. Big Data

- Larger Datasets
- Easier Collection & Storage

IMAGENET



2. Hardware

- Graphics Processing Units (GPUs)
- Massively Parallelizable



3. Software

- Improved Techniques
- New Models
- Toolboxes



Unit 01 | 딥러닝이란?

Deep Learning Success: Vision

Image Recognition



Unit 01 | 딥러닝이란?

Deep Learning Success: Vision

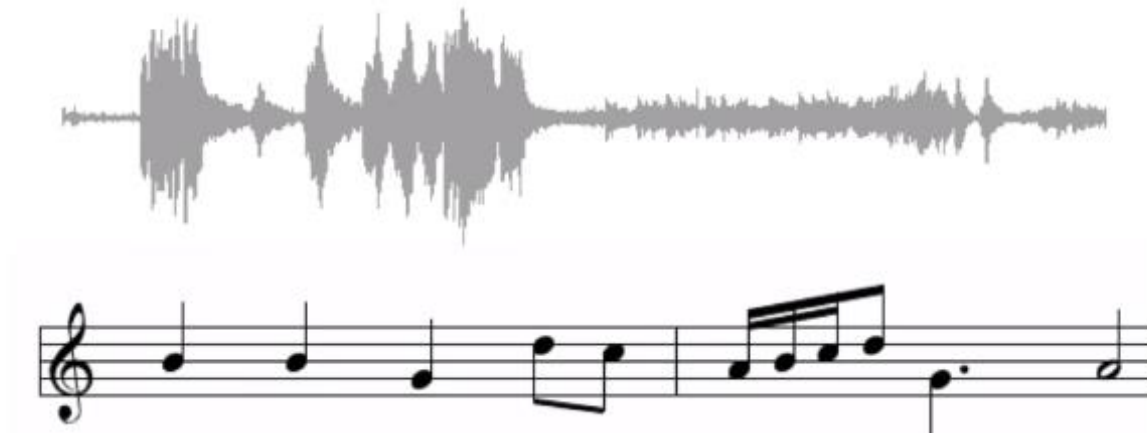
Detect pneumothorax in real X-Ray scans



Unit 01 | 딥러닝이란?

Deep Learning Success: Audio

Music Generation



Unit 01 | 딥러닝이란?

Deep Learning Success

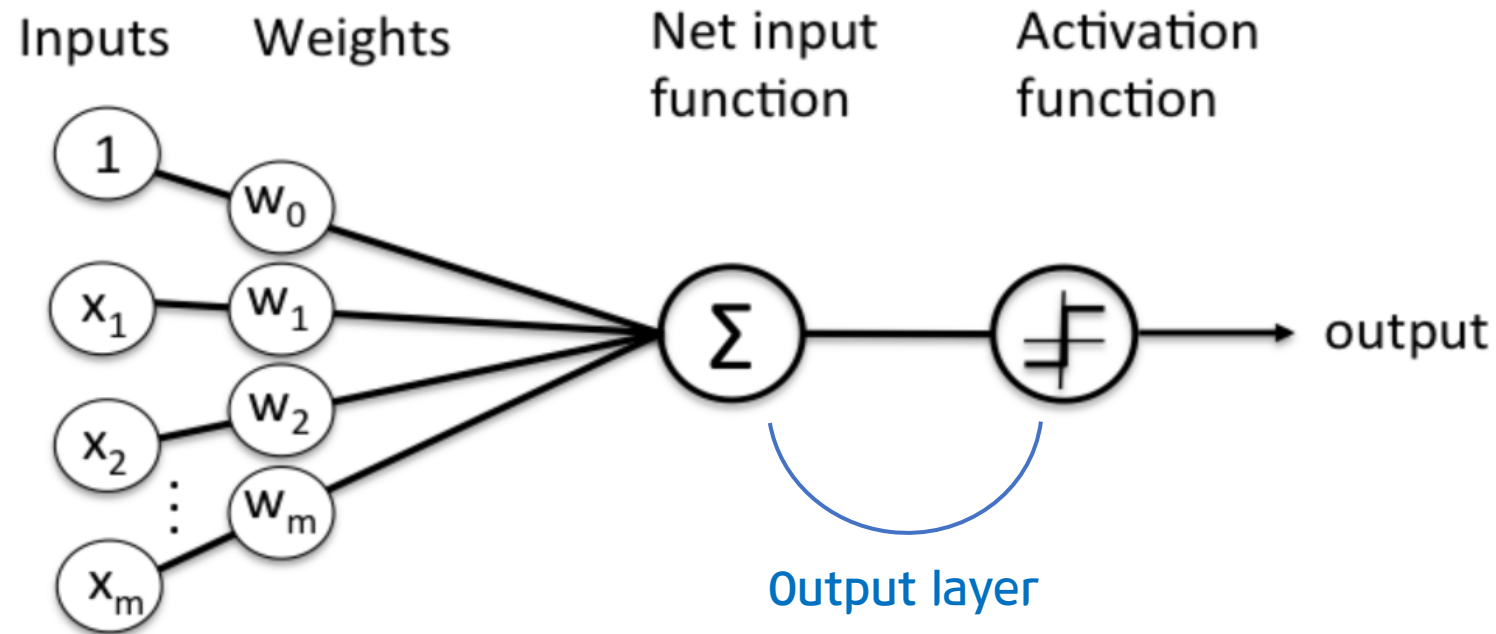
And so many more...



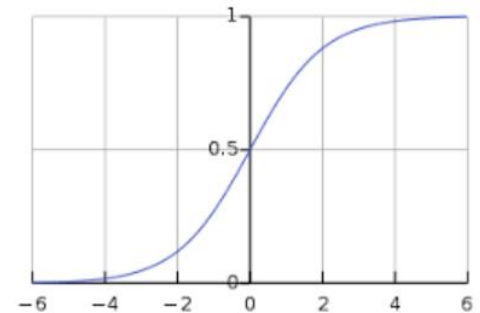
Unit 02 | Perceptron

Perceptron (단층신경망)

- 신경망의 기원이 되는 단층 신경망 알고리즘
- 선형 분류를 수행할 수 있는 피드포워드 뉴럴 네트워크



Input layer

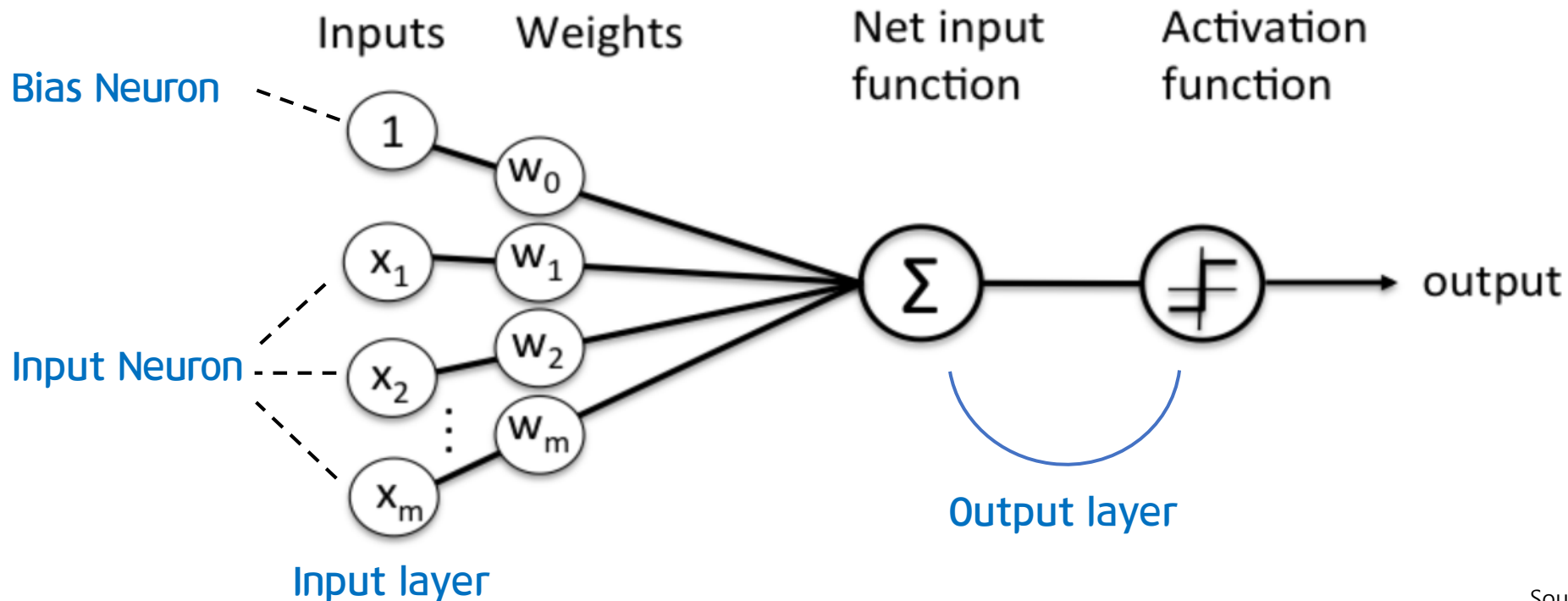


Activation Function

Unit 02 | Perceptron

Perceptron (단층신경망)

- 신경망의 기원이 되는 단층 신경망 알고리즘
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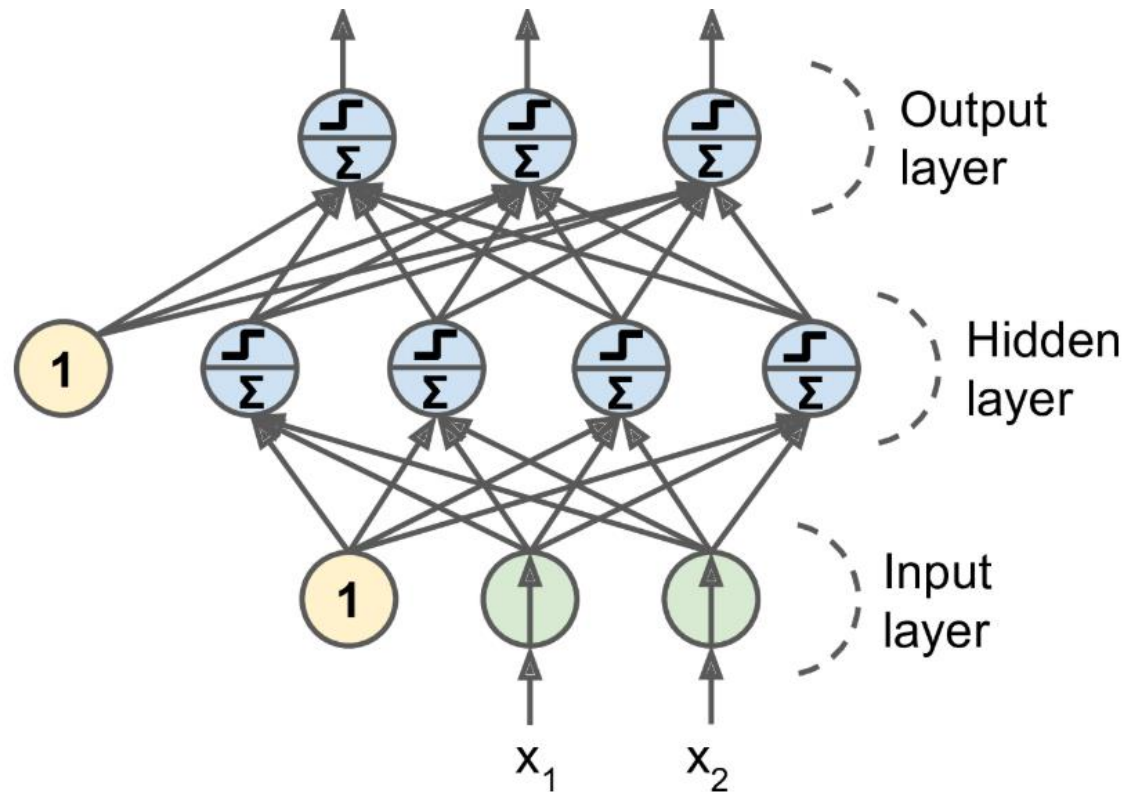


Input Neuron : m
Output Neuron : 1
Bias Neuron : 1
Weights : $m+1$

Unit 03 | Multi Layer Perceptron

Multi Layer Perceptron

Input layer, Output layer 외에도 한 개 이상의 hidden layer 로 구성된 신경망



Unit 03 | Multi Layer Perceptron

Softmax Classifier (Multinomial Logistic Regression)



scores = unnormalized log probabilities of the classes.

$$P(Y = k|X = x_i) = \frac{e^{s_k}}{\sum_j e^{s_j}} \quad \text{where} \quad s = f(x_i; W)$$

Softmax function

cat

3.2

car

5.1

frog

-1.7

Unit 03 | Multi Layer Perceptron

Softmax Classifier (Multinomial Logistic Regression)



scores = unnormalized log probabilities of the classes.

$$P(Y = k|X = x_i) = \frac{e^{s_k}}{\sum_j e^{s_j}}$$

where

$$s = f(x_i; W)$$

Softmax function

Want to maximize the log likelihood, or (for a loss function) to minimize the negative log likelihood of the correct class:

$$L_i = -\log P(Y = y_i|X = x_i) = -\log\left(\frac{e^{s_{y_i}}}{\sum_j e^{s_j}}\right)$$

Loss function

cat

3.2

car

5.1

frog

-1.7

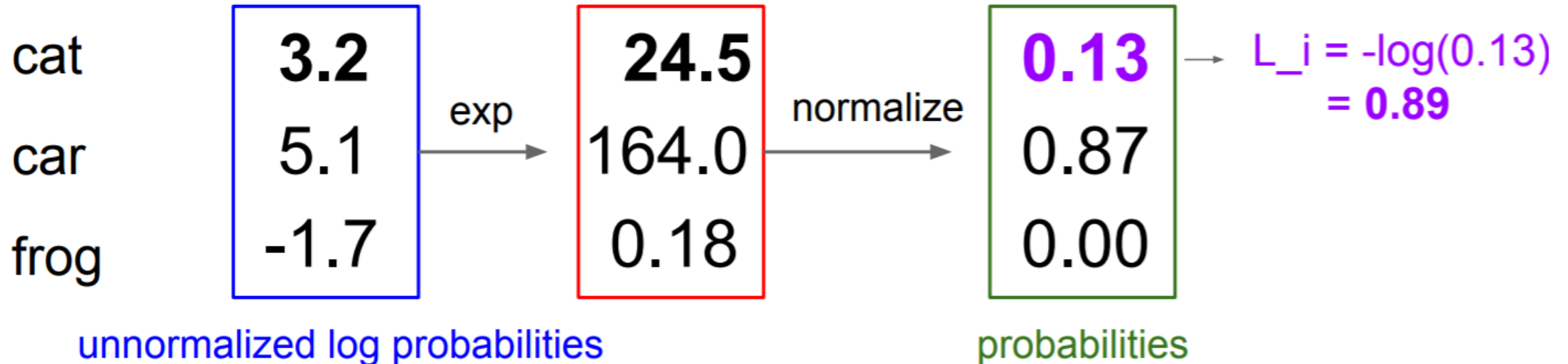
Unit 03 | Multi Layer Perceptron

Softmax Classifier (Multinomial Logistic Regression)

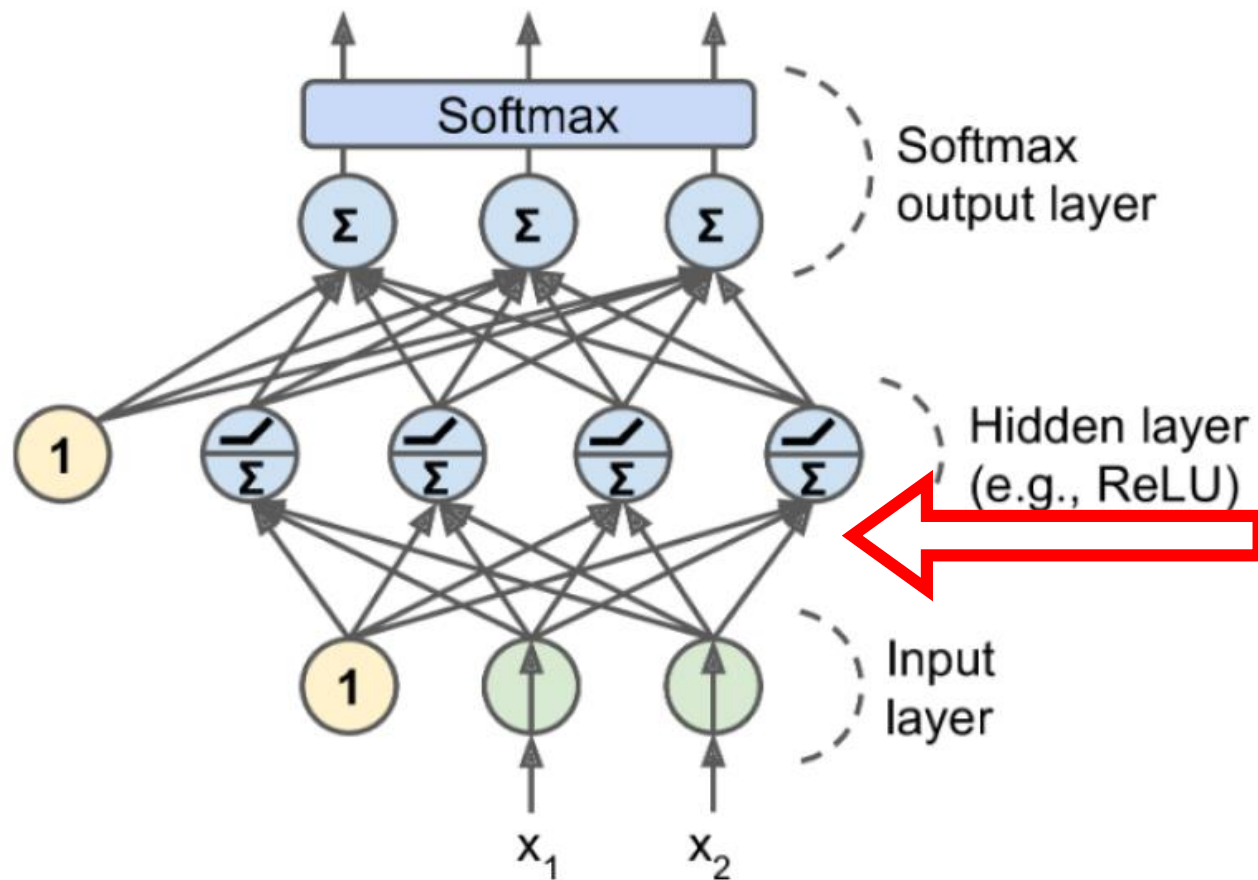


$$L_i = -\log\left(\frac{e^{sy_i}}{\sum_j e^{s_j}}\right)$$

unnormalized probabilities

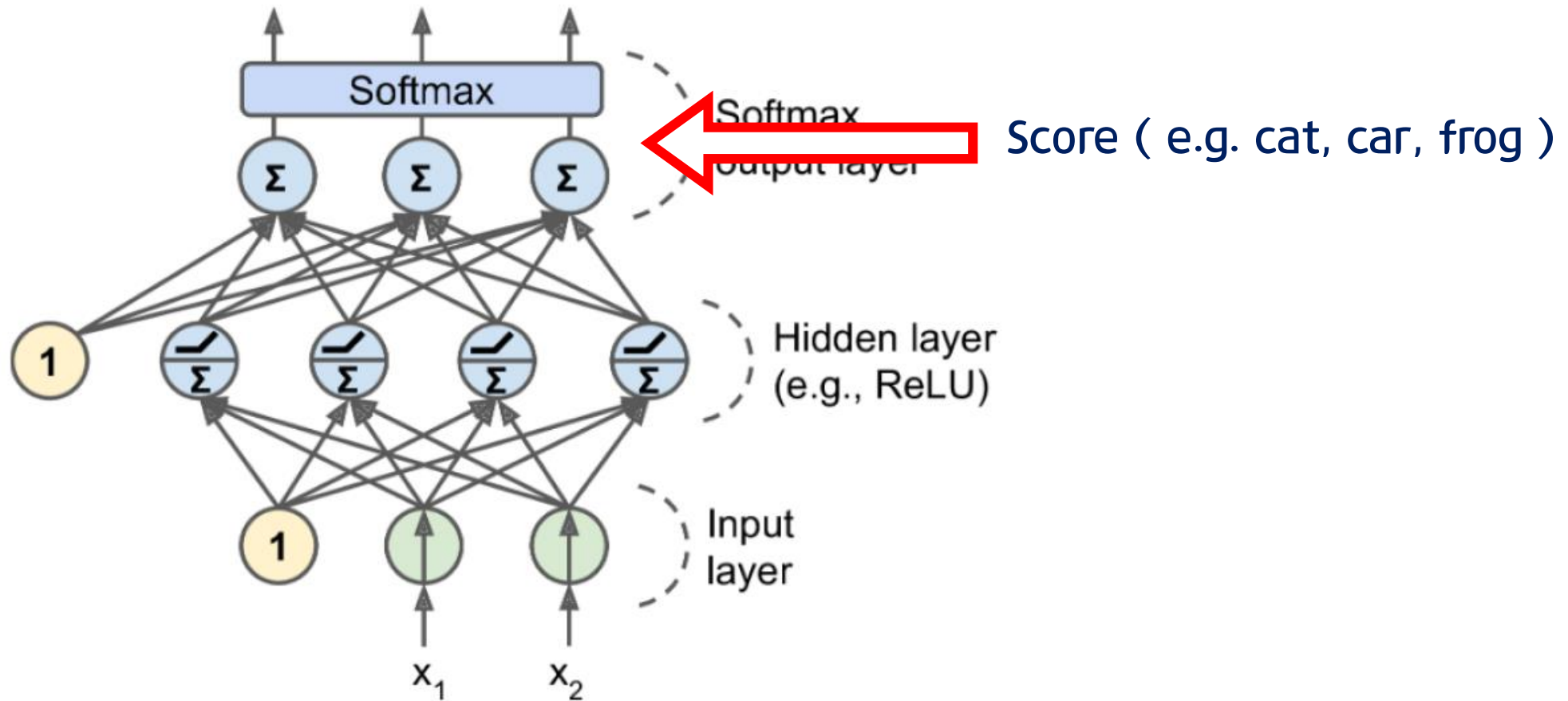


Unit 03 | Multi Layer Perceptron

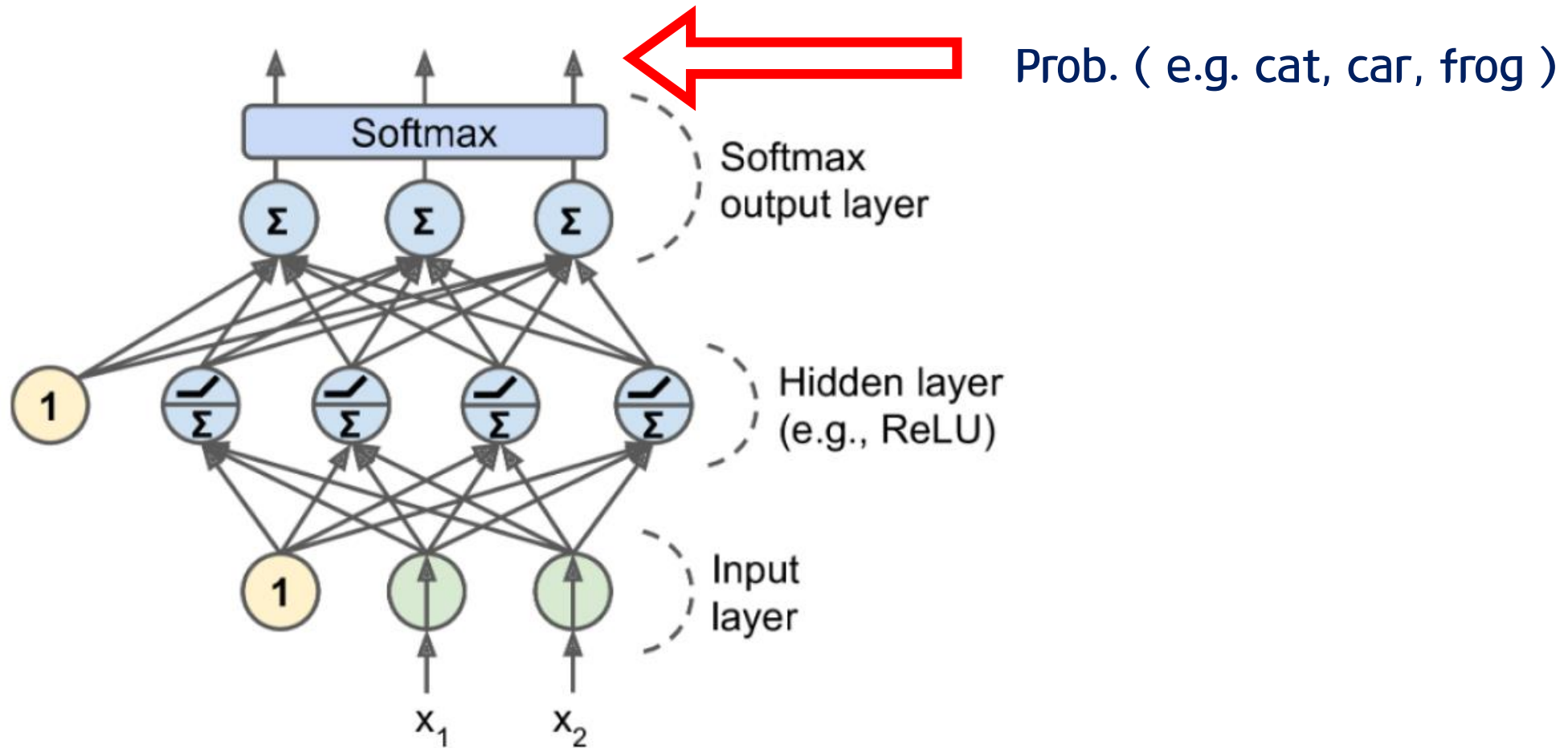


```
W1 = tf.Variable(tf.random_normal([2, 4]))  
b1 = tf.Variable(tf.random_normal([4]))  
Layer1 = tf.nn.relu(tf.matmul(X, W1) + b1)
```

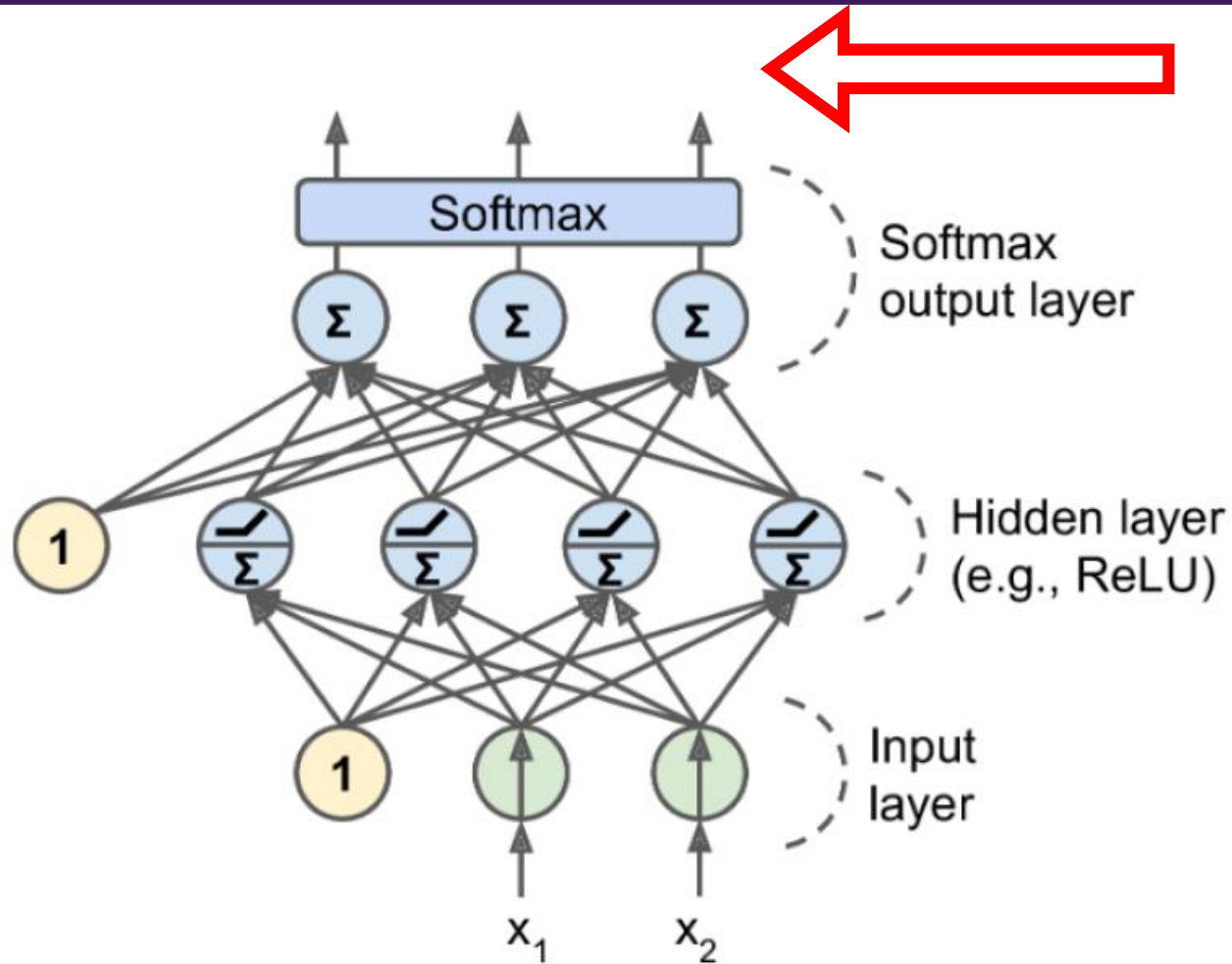
Unit 03 | Multi Layer Perceptron



Unit 03 | Multi Layer Perceptron

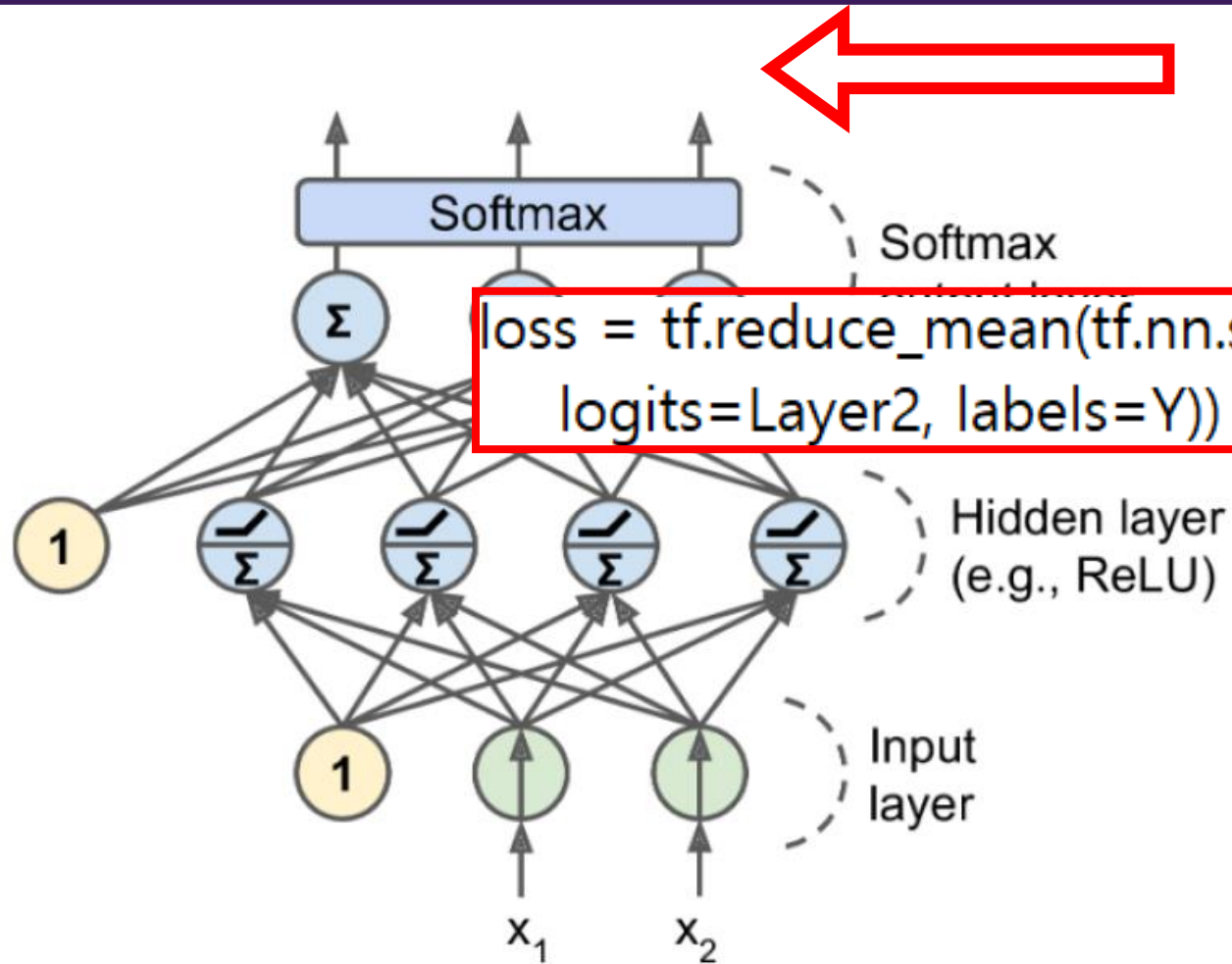


Unit 03 | Multi Layer Perceptron



Loss (per example)
+ called 'cross-entropy loss'

Unit 03 | Multi Layer Perceptron



Loss (per example)
+ called 'cross-entropy loss'

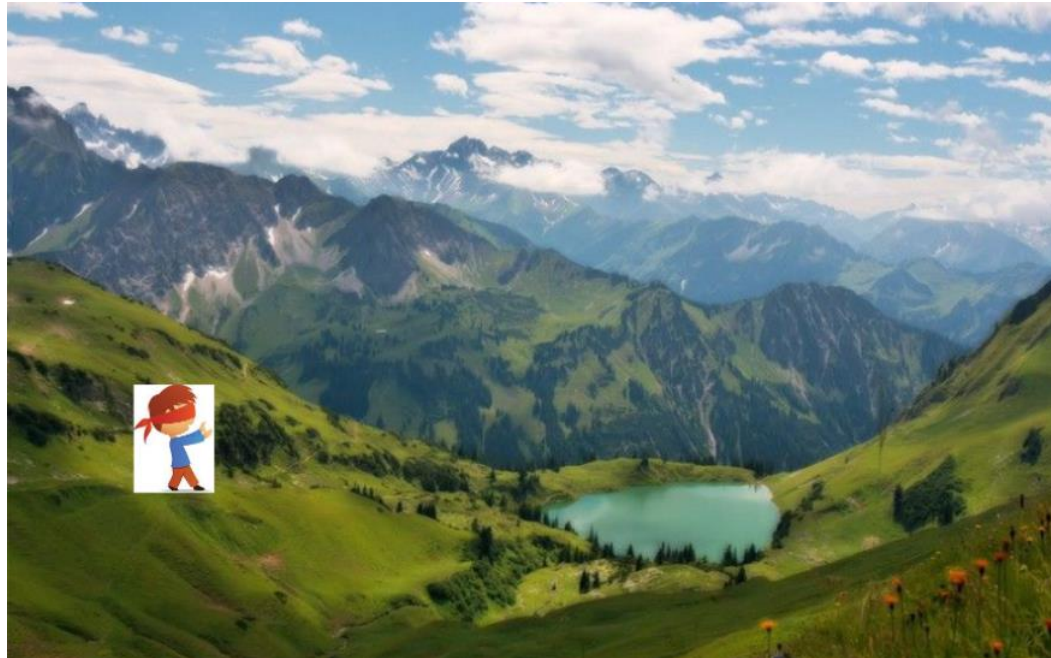
```
loss = tf.reduce_mean(tf.nn.softmax_cross_entropy_with_logits(  
    logits=Layer2, labels=Y))
```

Unit 04 | Backpropagation

그럼 어떻게 MLP, NN를 잘 학습시킬까???

-> **Back Propagation & Gradient Descent**

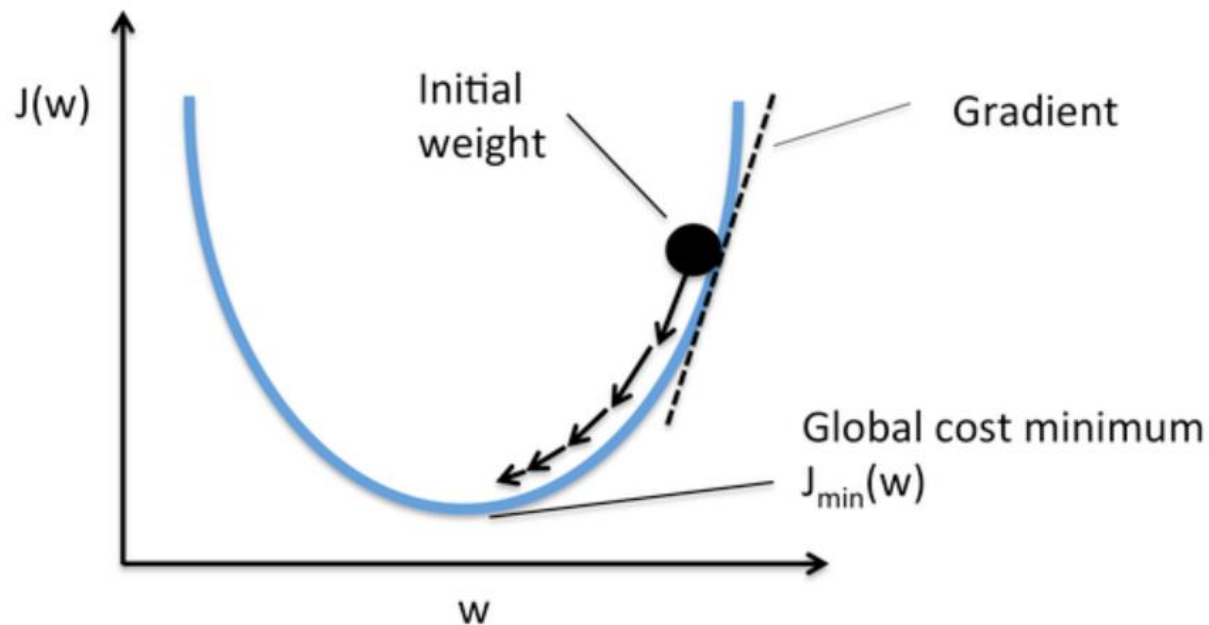
Gradient Descent : loss function을 최소화 하기 위해 사용하는 알고리즘



Unit 04 | Backpropagation

Gradient Descent : loss function을 최소화 하기 위해 사용하는 알고리즘

- 1) Weight에 random 한 숫자로 초기값 부여
- 2) Loss를 minimize 하는 방향으로 w를 업데이트 !

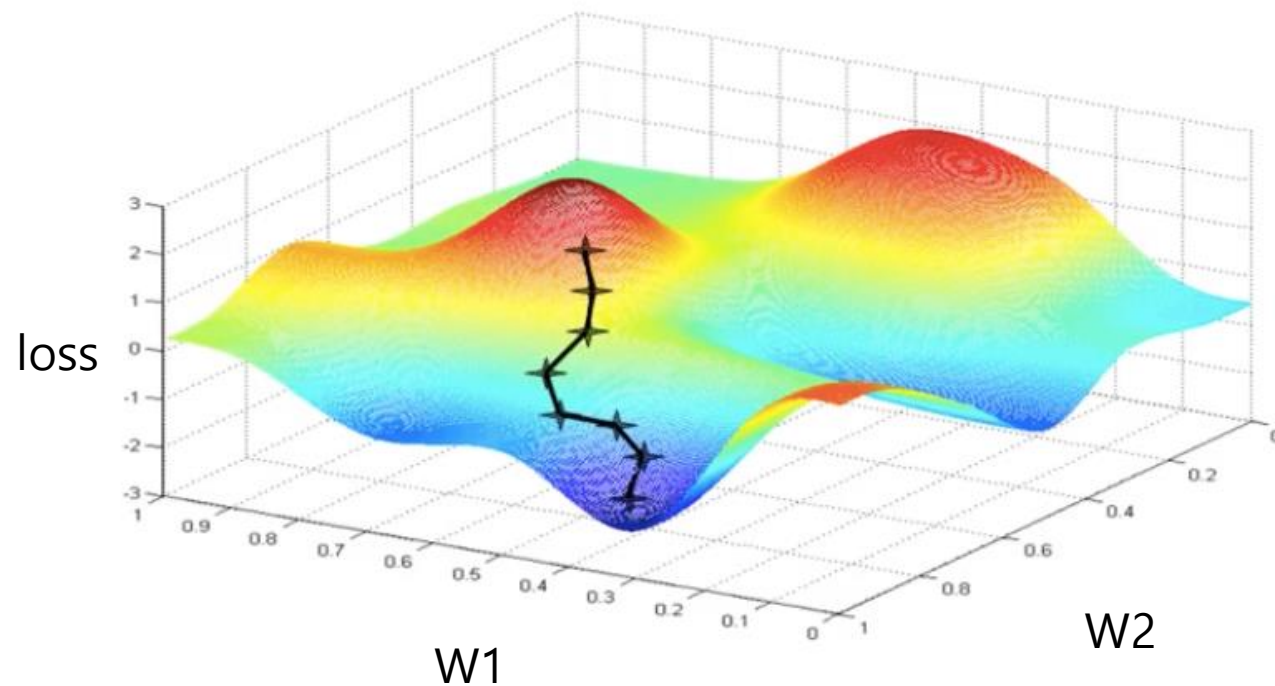


$$W := W - \alpha \frac{d}{dw} \text{loss}(W)$$

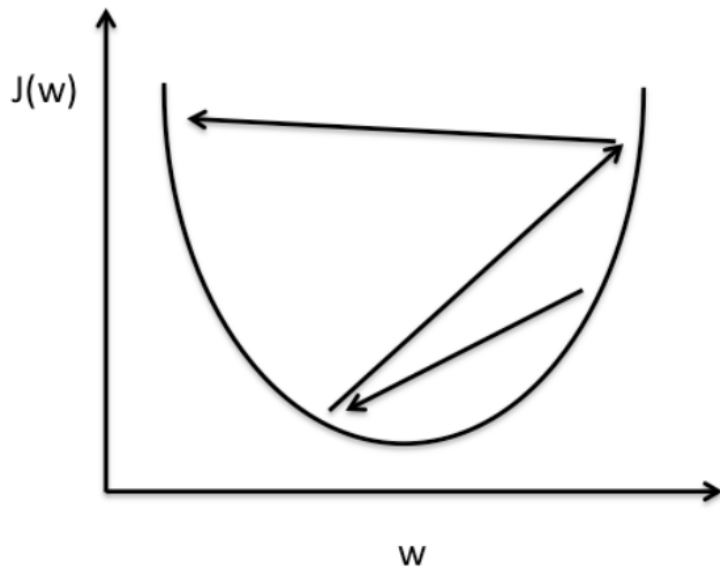
learning rate

Unit 04 | Backpropagation

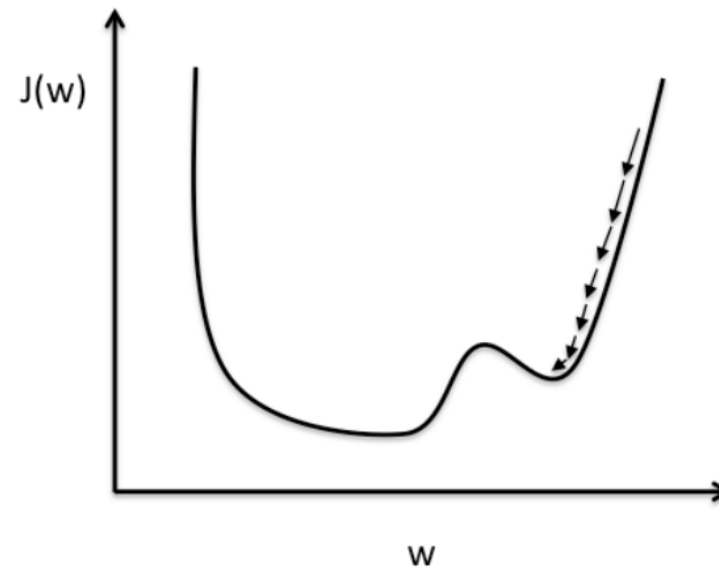
Gradient Descent : loss function을 최소화 하기 위해 사용하는 알고리즘



Unit 04 | Backpropagation

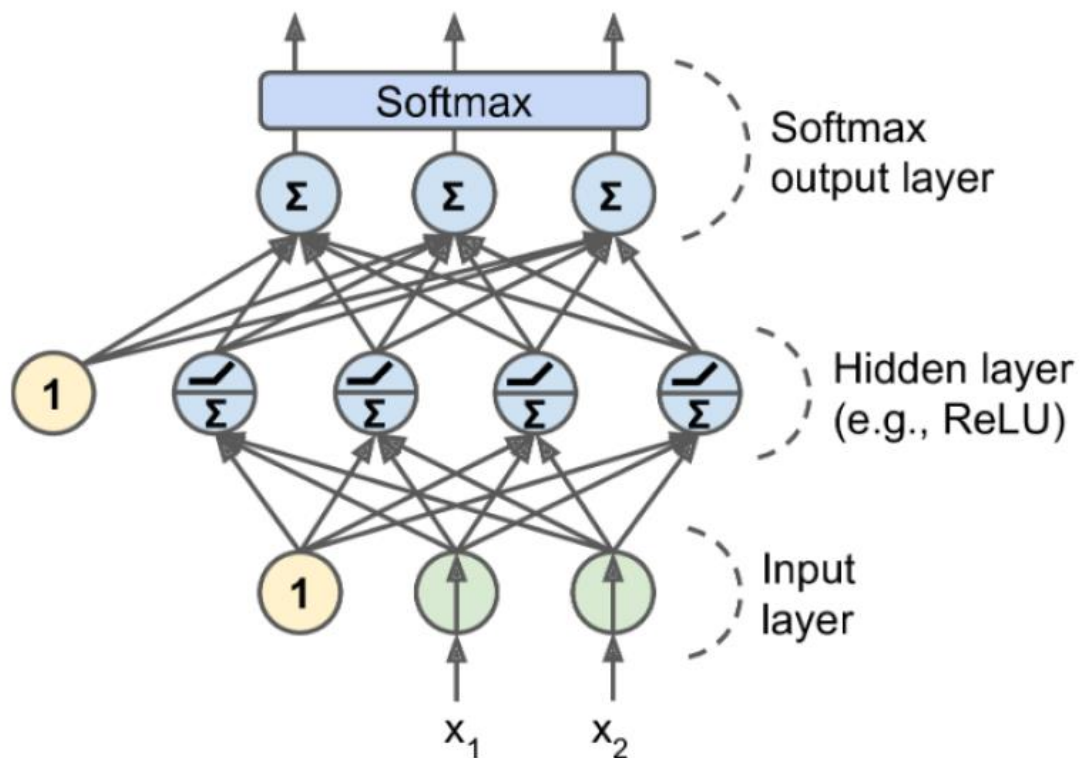
Learning rate (α)

Learning rate 가 **큰** 경우
-> overshooting



Learning rate 가 **작은** 경우
-> 학습하는데 시간이 오래 걸린다
최저점이 아닌 데서 멈추거나,
local minimum에 빠진다.

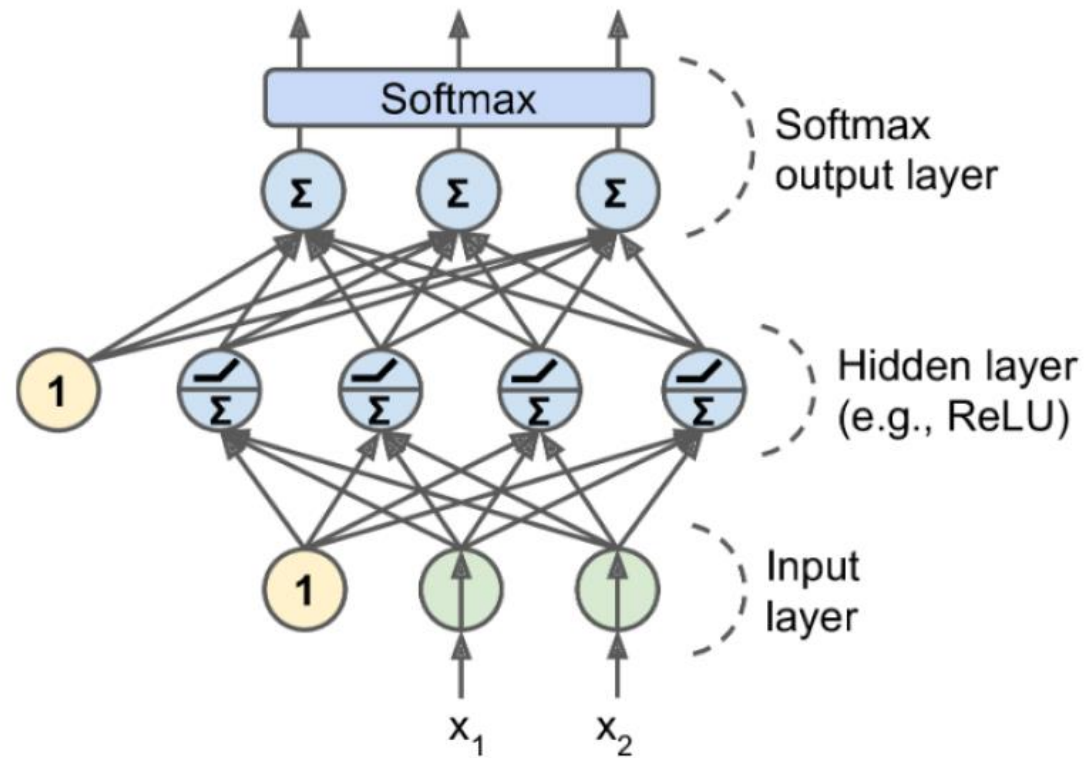
Unit 04 | Backpropagation



이때 y 를 이용하여 loss를 구합니다.
우리는 weights를 update해야 합니다.
즉 loss를 최소화하는 방향(gradient)으로
Weights를 update 시켜줘야 합니다.
(\rightarrow Gradient Descent, 미분값필요)

하지만 loss는 y 에 대한 함수입니다. $-\log(\text{softmax}(y))$
즉, loss를 Weights로 직접적인 미분이 불가능하죠!

Unit 04 | Backpropagation



loss는 y 의 함수이고, y 는 weights의 함수이다.

결국 합성함수

합성 함수의 미분 \rightarrow Chain Rule!

Unit 04 | Backpropagation

The Chain Rule

$$f = f(g) ; g = g(x)$$

$$\frac{df}{dx} = \frac{df}{dg} \frac{dg}{dx}$$

결국 합성함수
합성함수의 미분 -> Chain Rule!

Unit 04 | Backpropagation

Backpropagation: a simple example

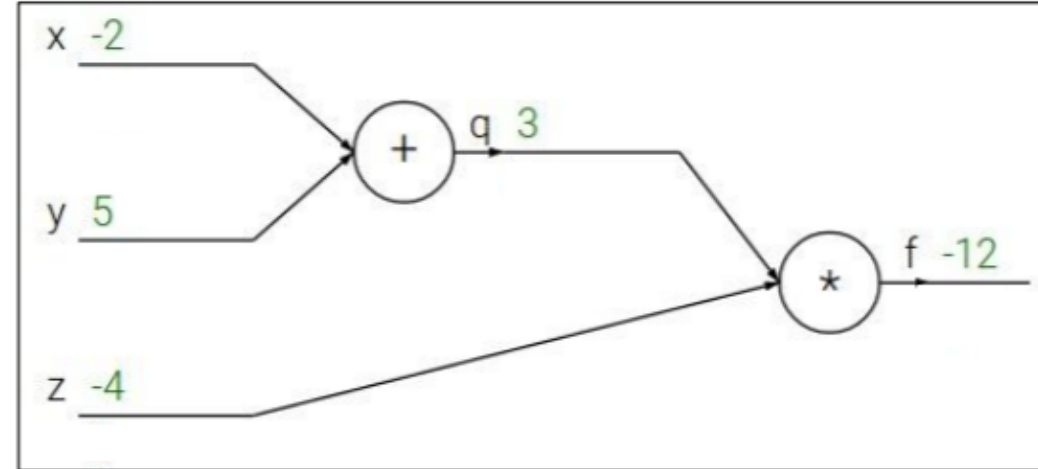
$$f(x, y, z) = (x + y)z$$

e.g. $x = -2, y = 5, z = -4$

$$q = x + y \quad \frac{\partial q}{\partial x} = 1, \frac{\partial q}{\partial y} = 1$$

$$f = qz \quad \frac{\partial f}{\partial q} = z, \frac{\partial f}{\partial z} = q$$

Want: $\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z}$



Unit 04 | Backpropagation

Backpropagation: a simple example

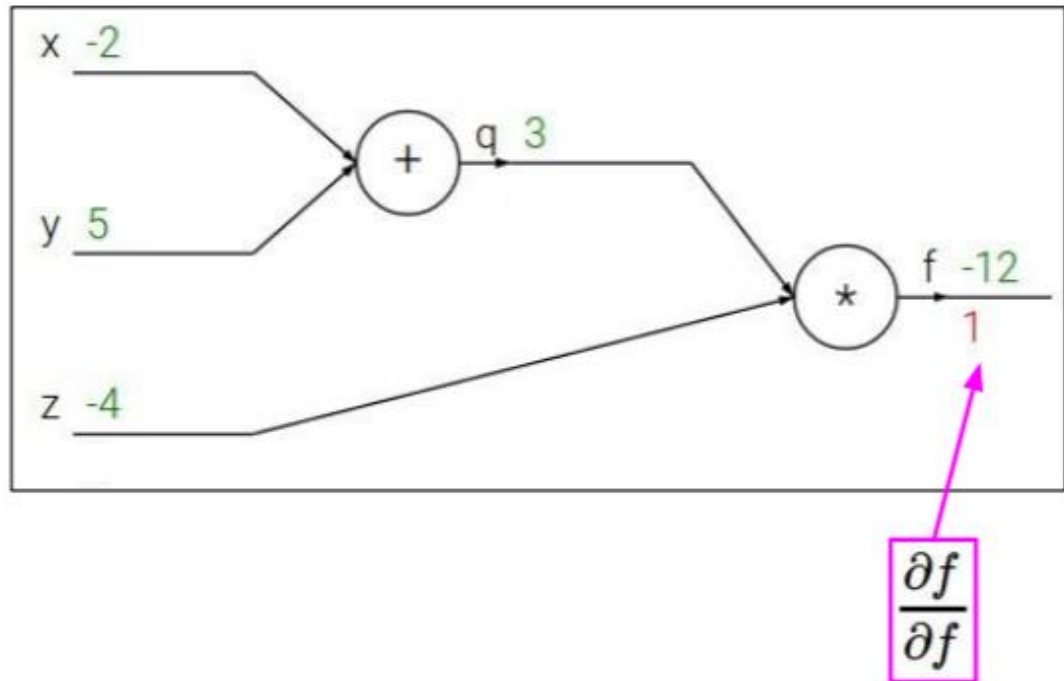
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Unit 04 | Backpropagation

Backpropagation: a simple example

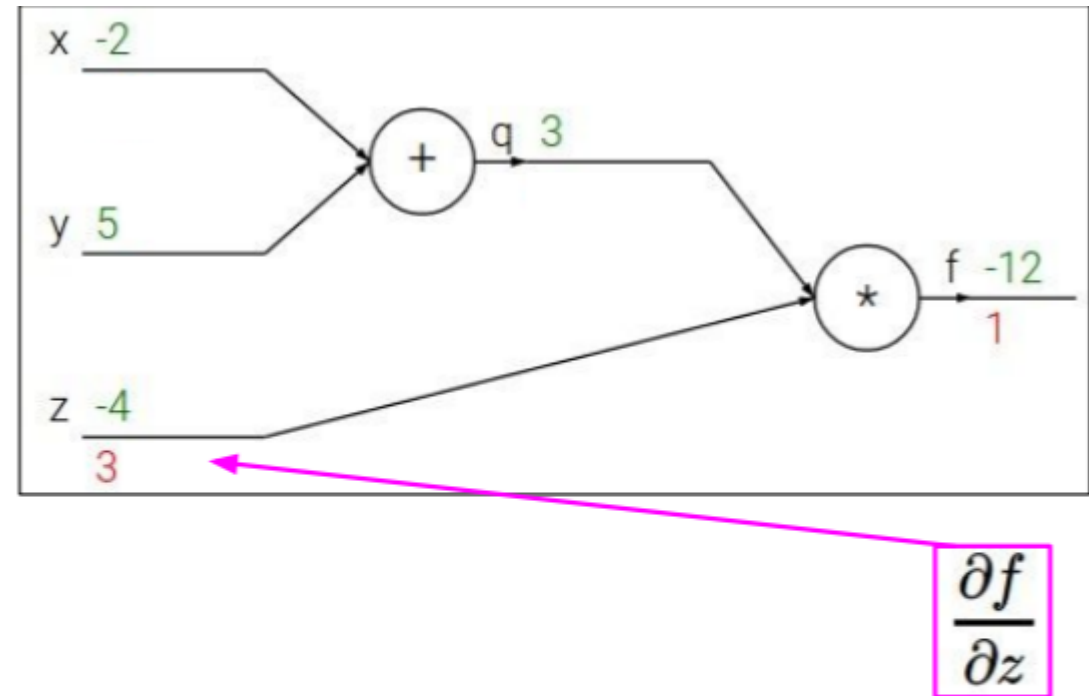
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Unit 04 | Backpropagation

Backpropagation: a simple example

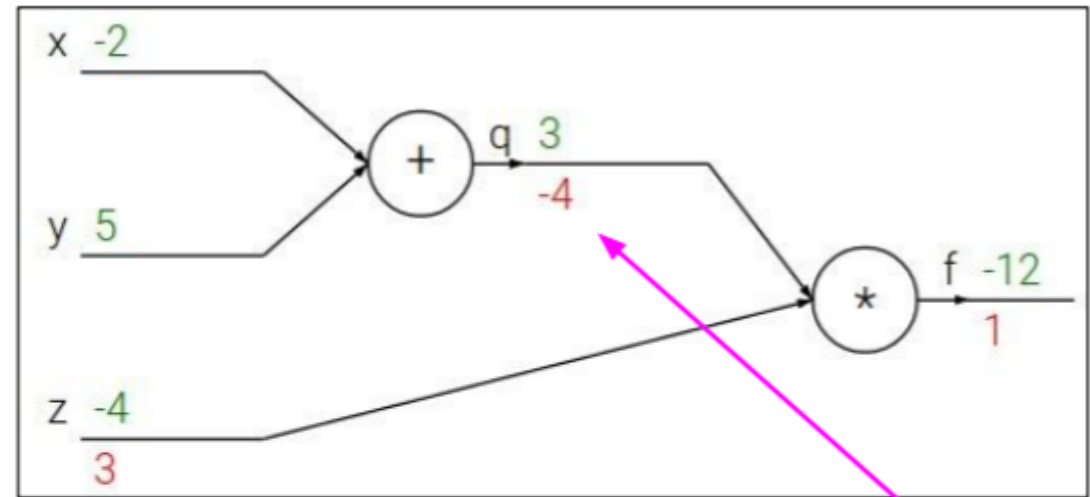
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Want: $\frac{\partial f}{\partial x}$, $\frac{\partial f}{\partial y}$, $\frac{\partial f}{\partial z}$



$$\frac{\partial f}{\partial q}$$

Unit 04 | Backpropagation

Backpropagation: a simple example

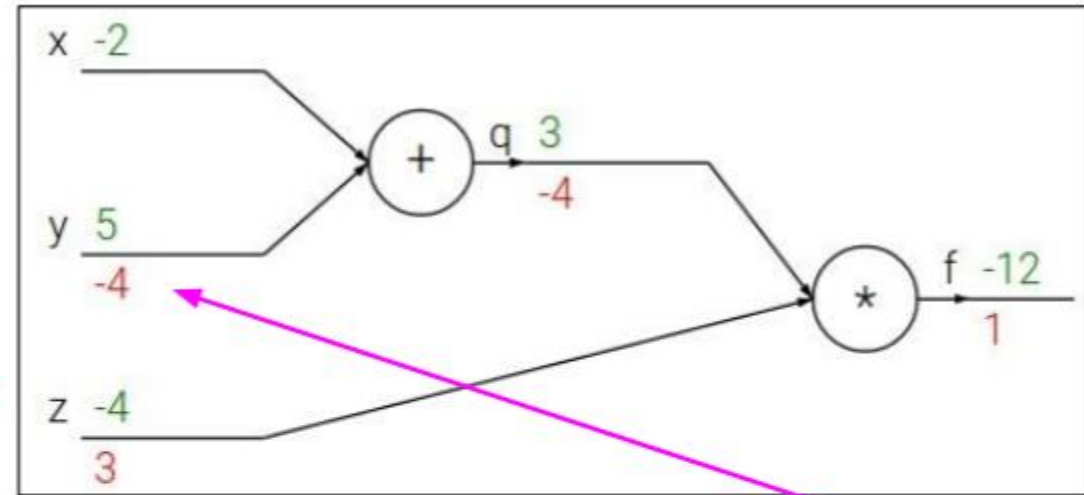
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$$f = qz \quad \frac{\partial f}{\partial q} = z, \frac{\partial f}{\partial z} = q$$

Want: $\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z}$



Chain rule:

$$\frac{\partial f}{\partial y} = \frac{\partial f}{\partial q} \frac{\partial q}{\partial y}$$

$$\frac{\partial f}{\partial y}$$

Unit 04 | Backpropagation

Backpropagation: a simple example

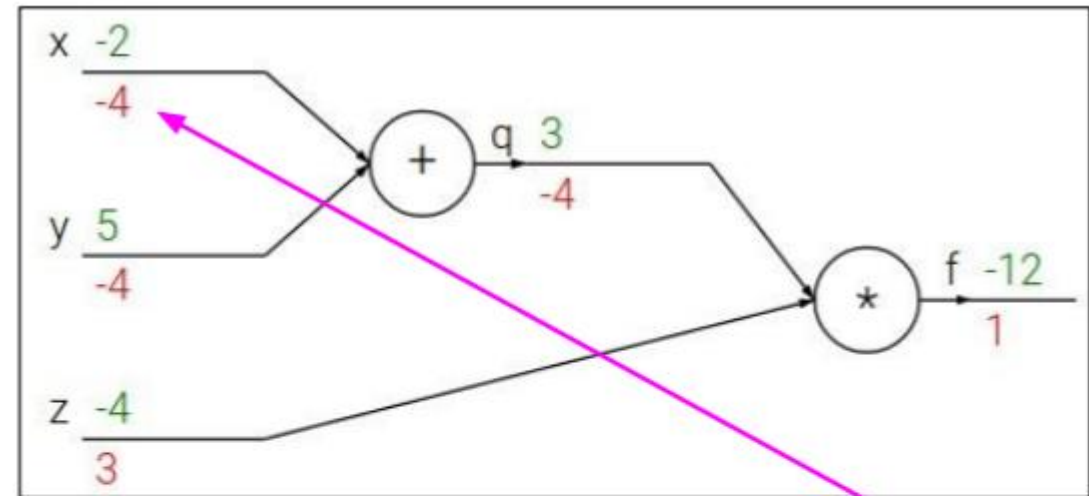
$$f(x, y, z) = (x + y)z$$

e.g. $x = -2, y = 5, z = -4$

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$$f = qz \quad \frac{\partial f}{\partial q} = z, \frac{\partial f}{\partial z} = q$$

Want: $\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z}$

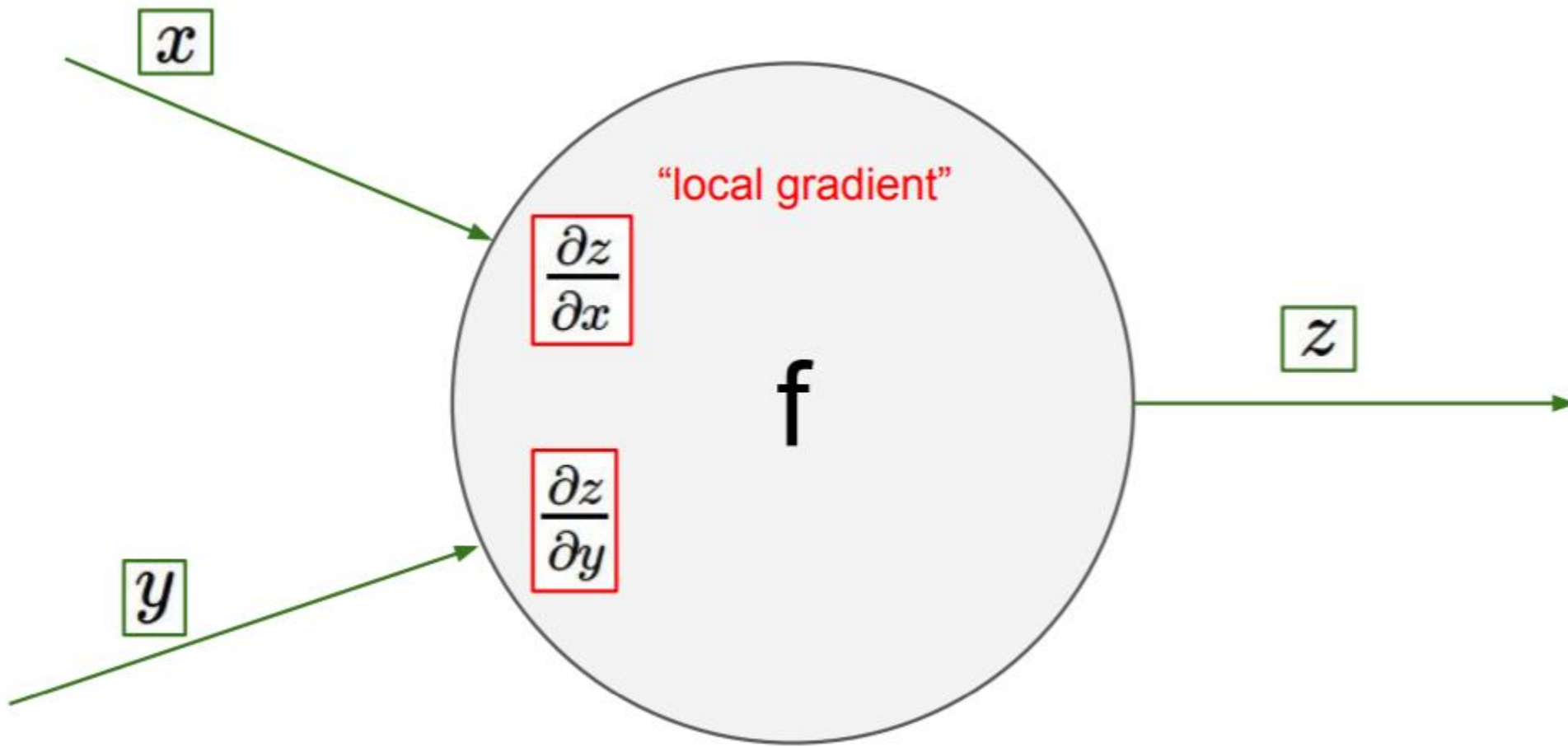


$$\frac{\partial f}{\partial x}$$

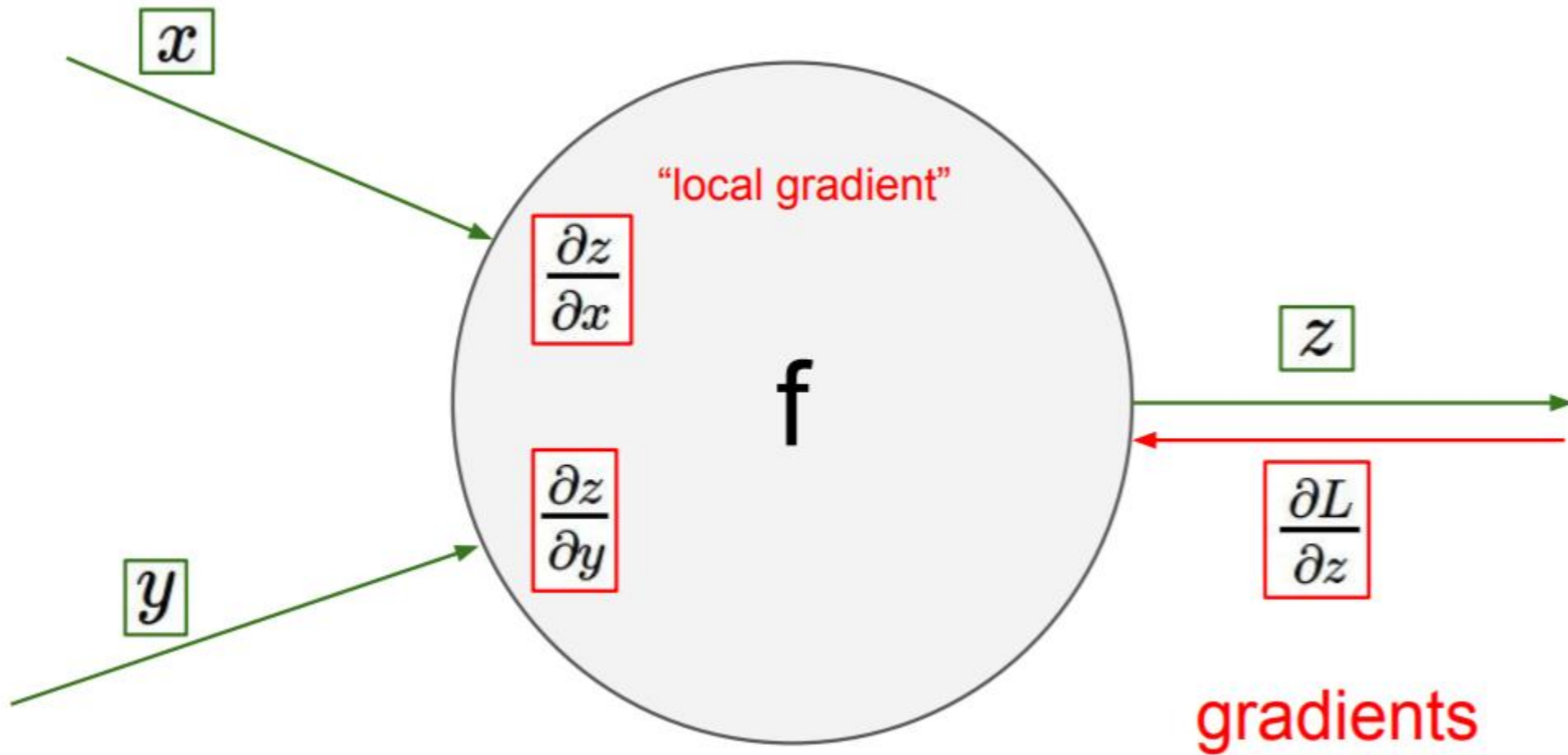
Feed forward

Back Propagation

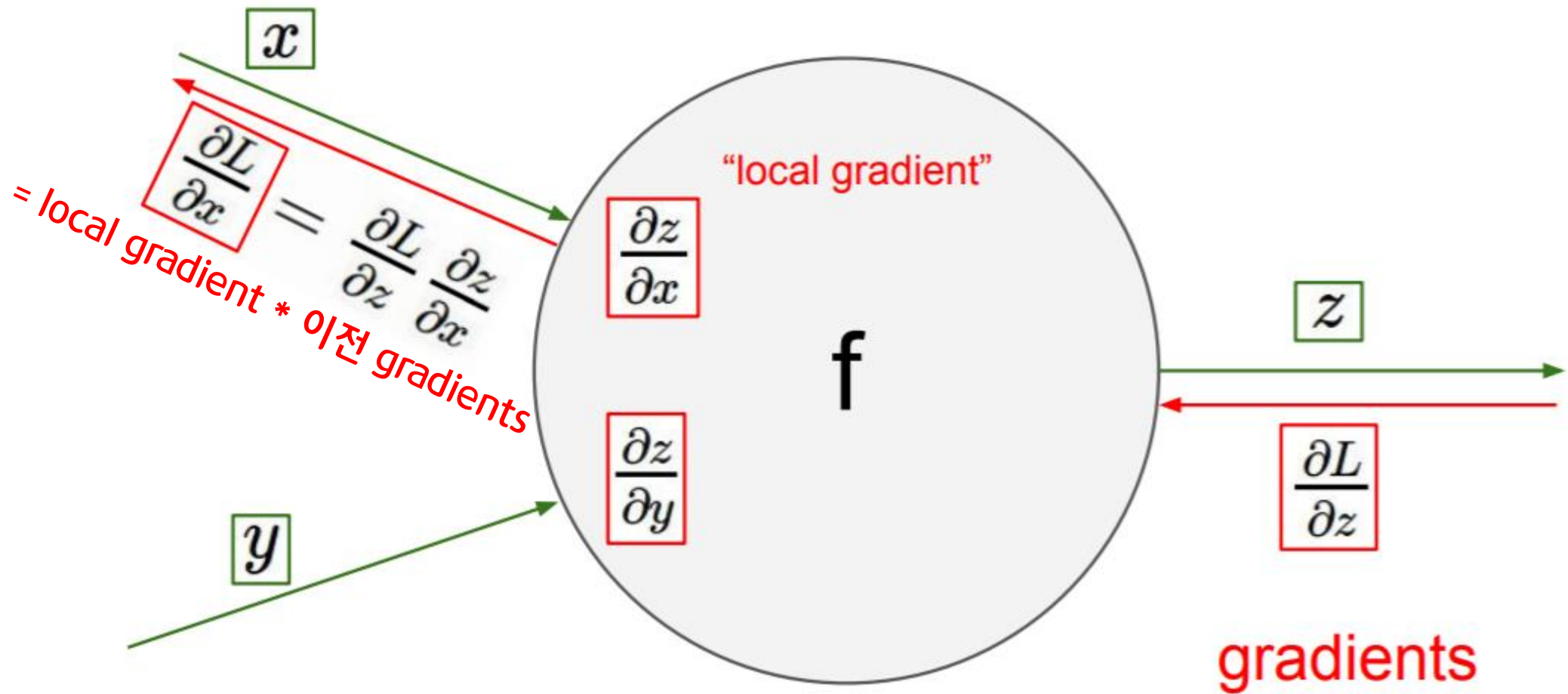
Unit 04 | Backpropagation



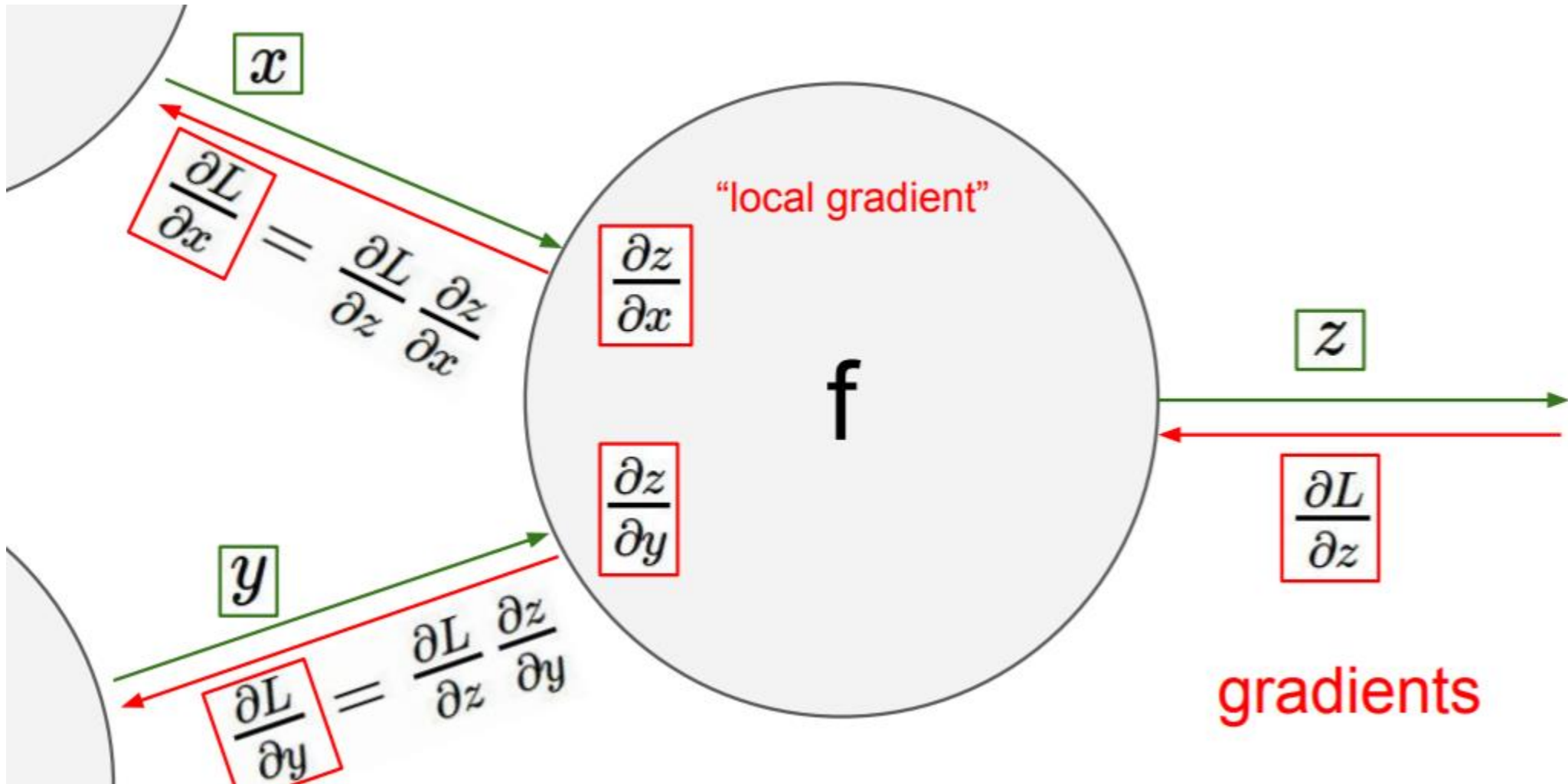
Unit 04 | Backpropagation



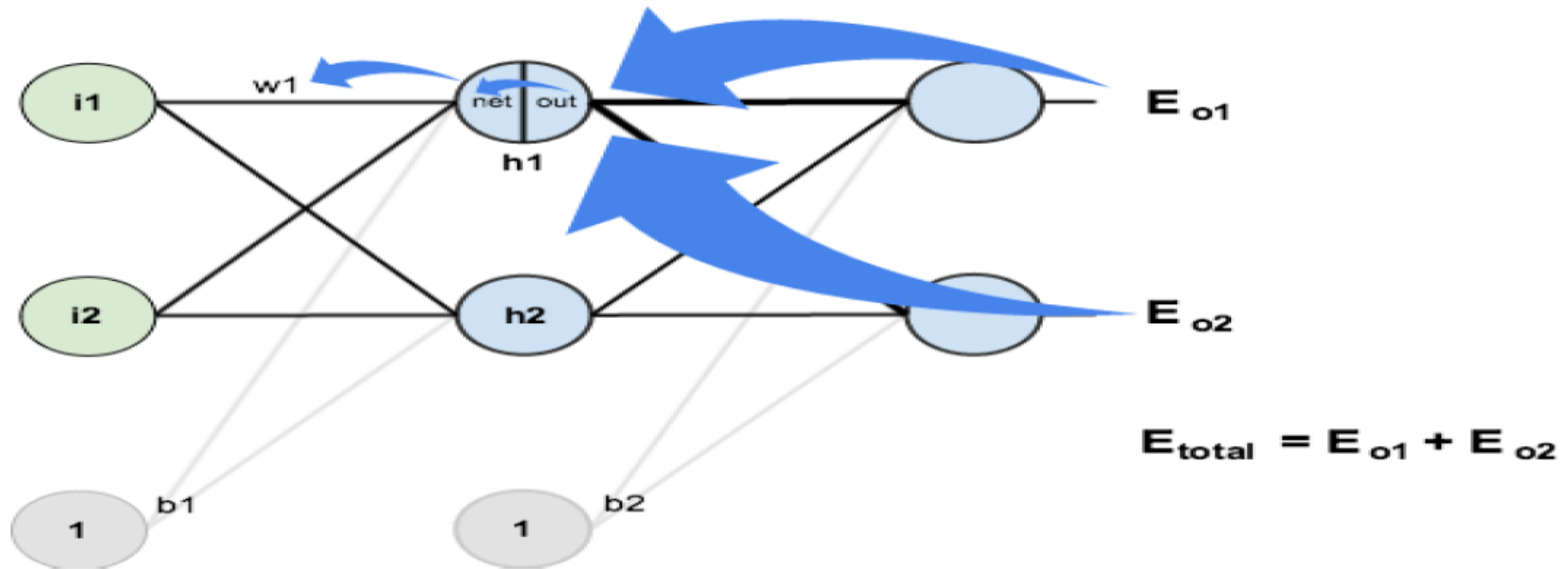
Unit 04 | Backpropagation



Unit 04 | Backpropagation

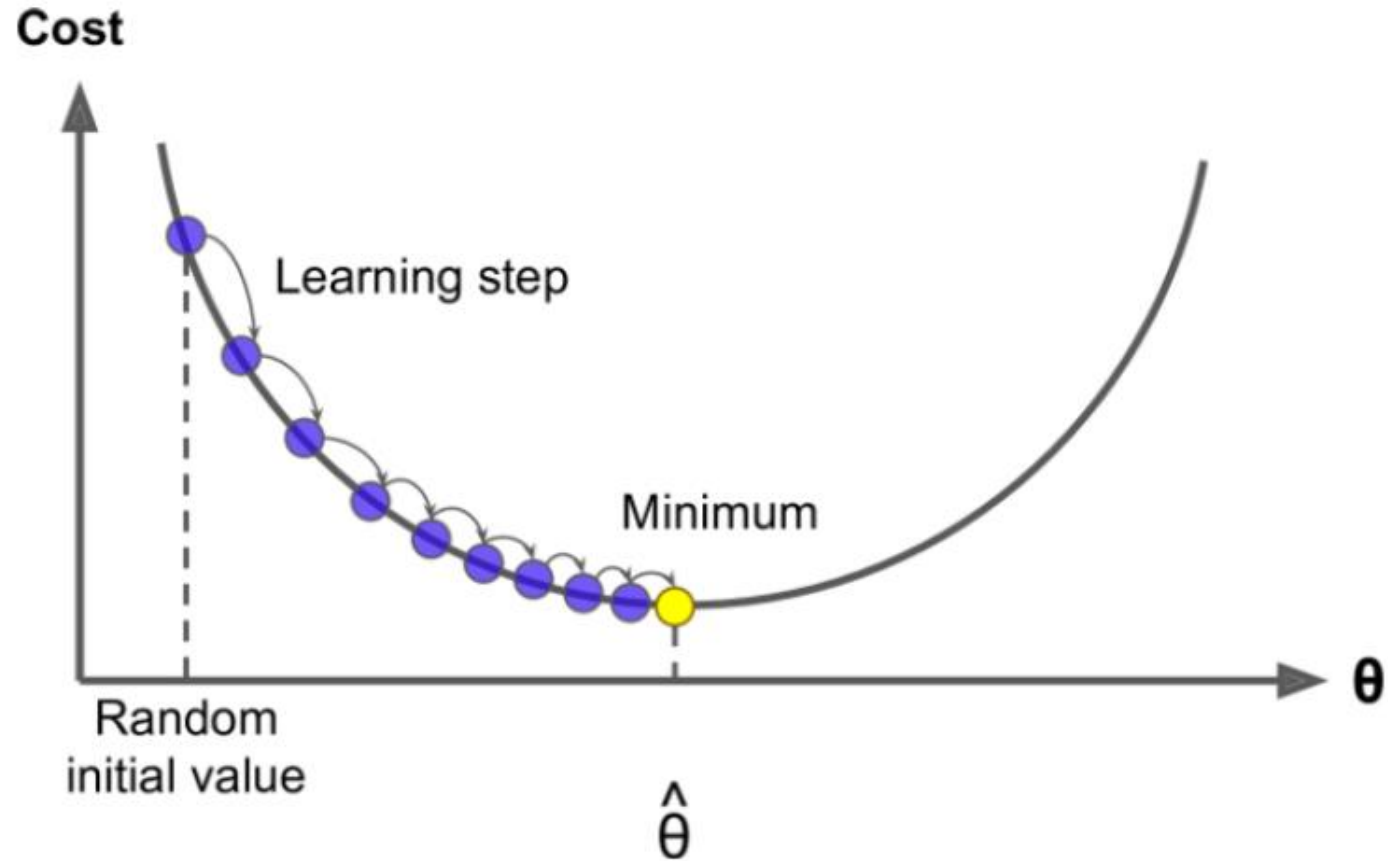


Unit 04 | Backpropagation



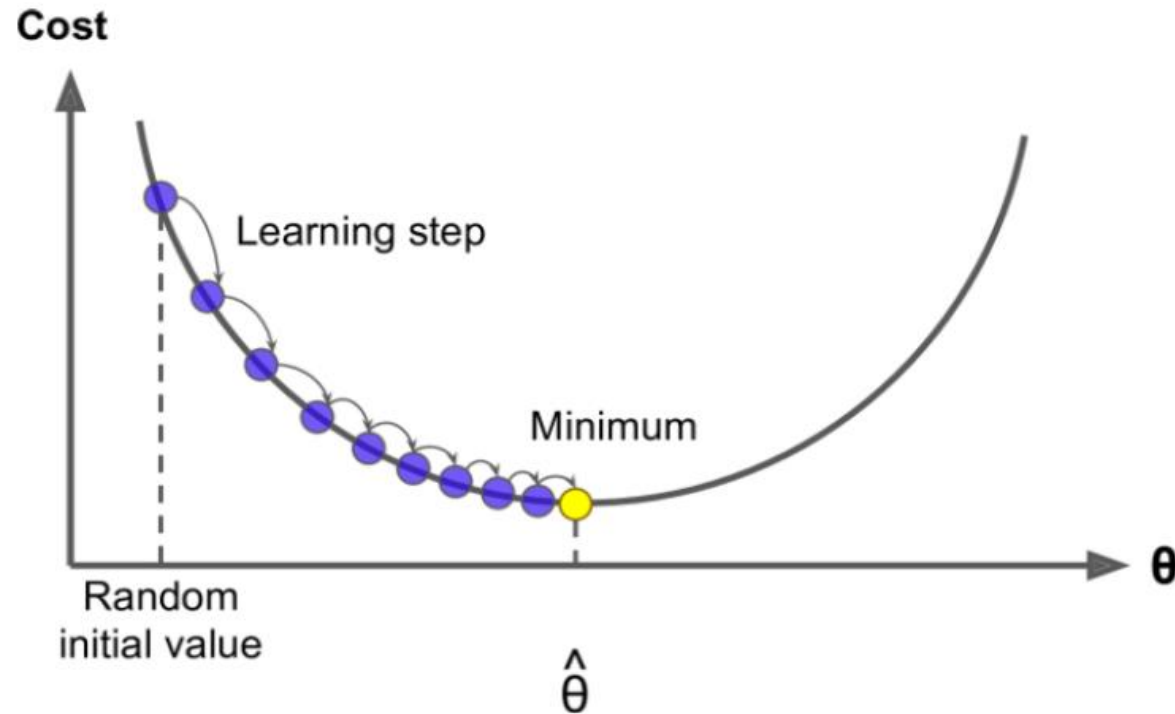
Loss와 멀리 떨어져있는 $w1$ 에 대한 미분 계산이 가능!

Unit 04 | Backpropagation



이제 모든 weights에 Gradient Descent를 적용시켜서 Update!

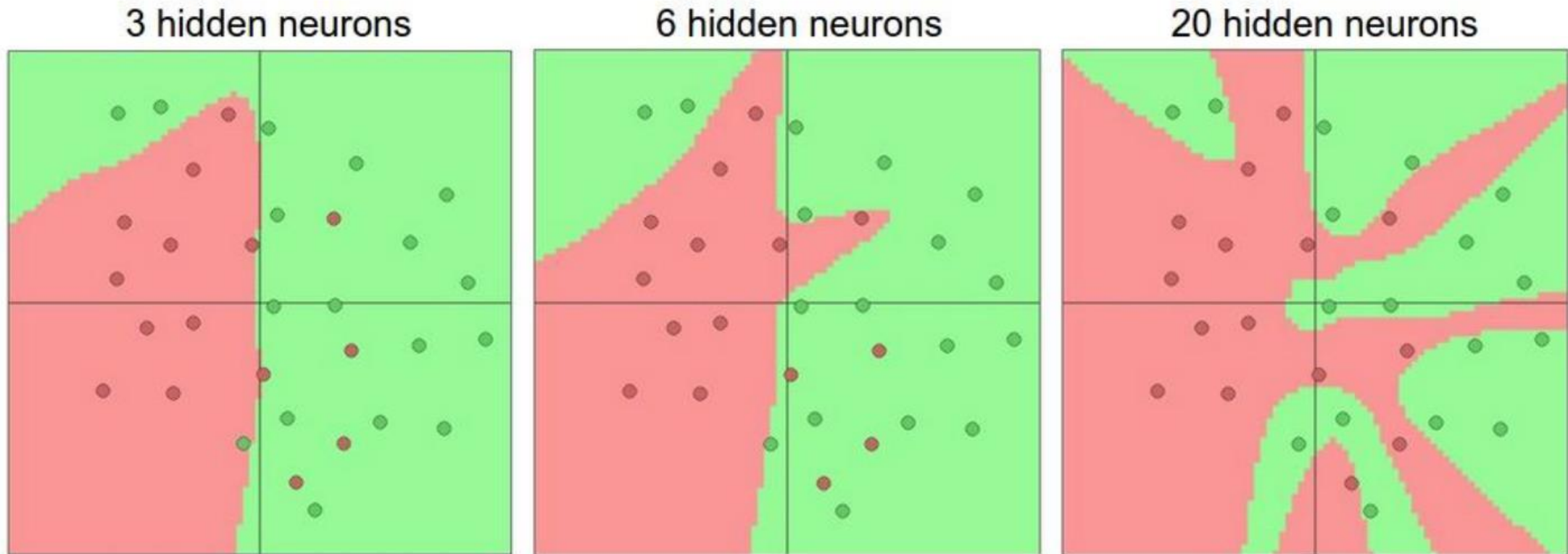
Unit 04 | Backpropagation



이제 모든 weights에 Gradient Descent를 적용시켜서 Update!

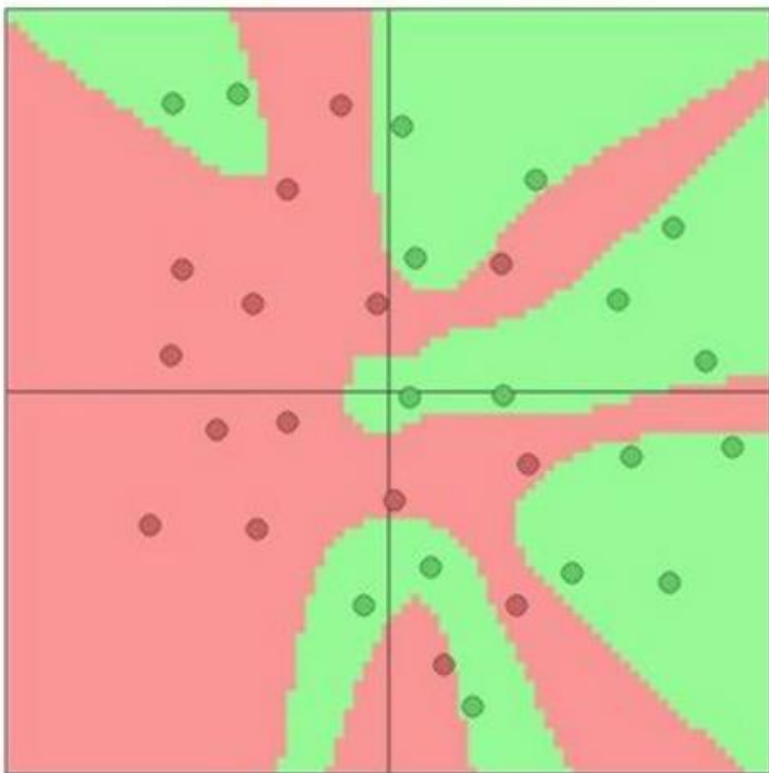
```
optimizer = tf.train.GradientDescentOptimizer(learning_rate=learning_rate)
train_op=optimizer.minimize(loss)
```


Unit 05 | Regularization



Unit 05 | Regularization

20 hidden neurons


**Overfit!!**

Layer / Node 줄여? No!!

Regularization!

Unit 05 | Regularization

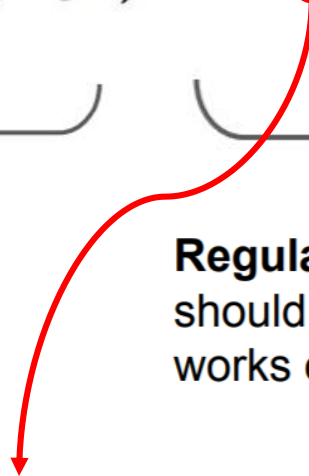
Regularization : weight 클수록 패널티 부여하는 것

$$L(W) = \frac{1}{N} \sum_{i=1}^N L_i(f(x_i, W), y_i)$$


Data loss: Model predictions
should match training data

Unit 05 | Regularization

Regularization : weight 클수록 패널티 부여하는 것

$$L(W) = \underbrace{\frac{1}{N} \sum_{i=1}^N L_i(f(x_i, W), y_i)}_{\text{Data loss: Model predictions should match training data}} + \underbrace{\lambda R(W)}_{\text{Regularization: Model should be "simple", so it works on test data}}$$


* Regularization strength : 얼마나 테스트셋에 일반화 할 것인지
(0과1사이의 값)

Unit 05 | Regularization

In common use:

L2 regularization	$R(W) = \sum_k \sum_l W_{k,l}^2$
L1 regularization	$R(W) = \sum_k \sum_l W_{k,l} $
Elastic net (L1 + L2)	$R(W) = \sum_k \sum_l \beta W_{k,l}^2 + W_{k,l} $

Max norm regularization (might see later)

Dropout (will see later)

Fancier: Batch normalization, stochastic depth

Unit 05 | Regularization

L2 Regularization (Weight Decay)

$$x = [1, 1, 1, 1]$$

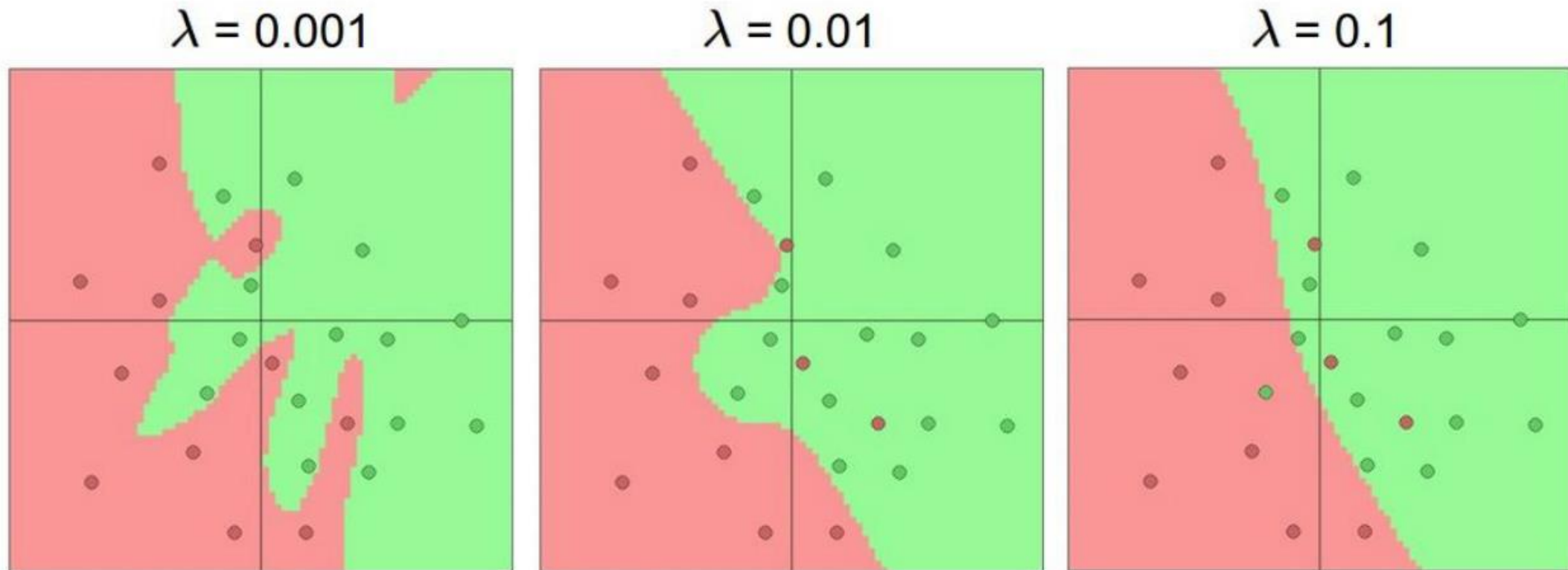
$$R(W) = \sum_k \sum_l W_{k,l}^2$$

$$w_1 = [1, 0, 0, 0]$$

$$w_2 = [0.25, 0.25, 0.25, 0.25]$$

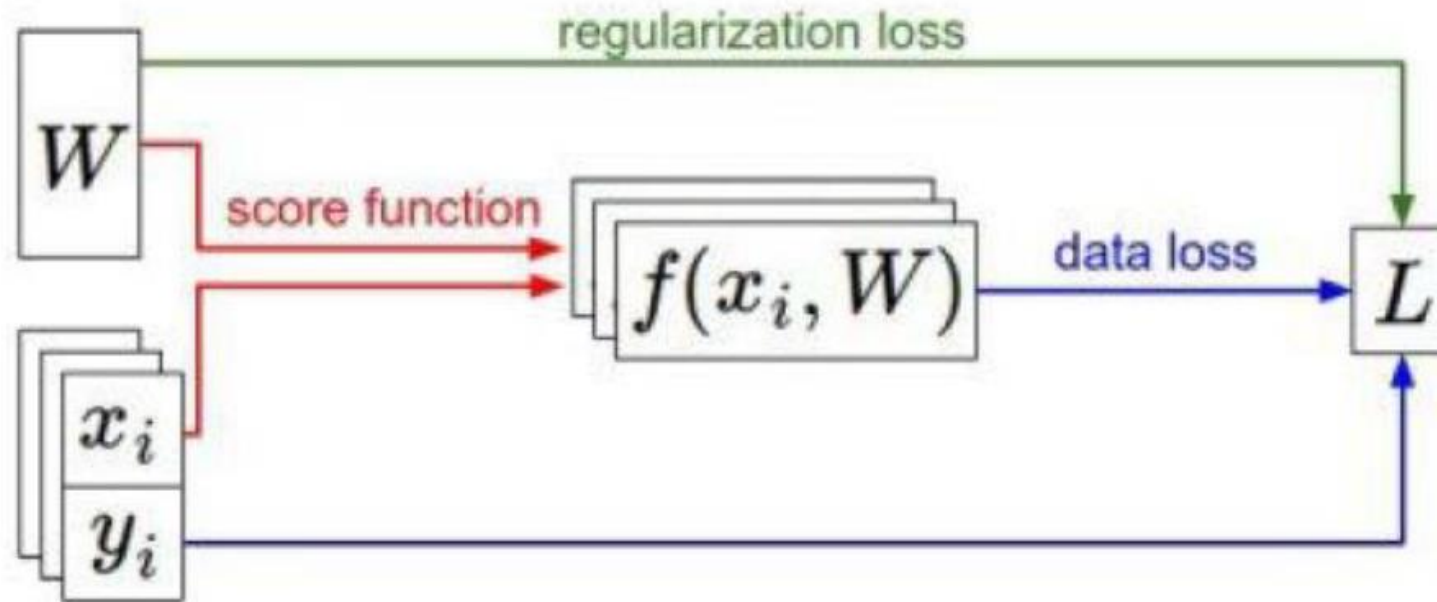
$$w_1^T x = w_2^T x = 1$$

Unit 05 | Regularization



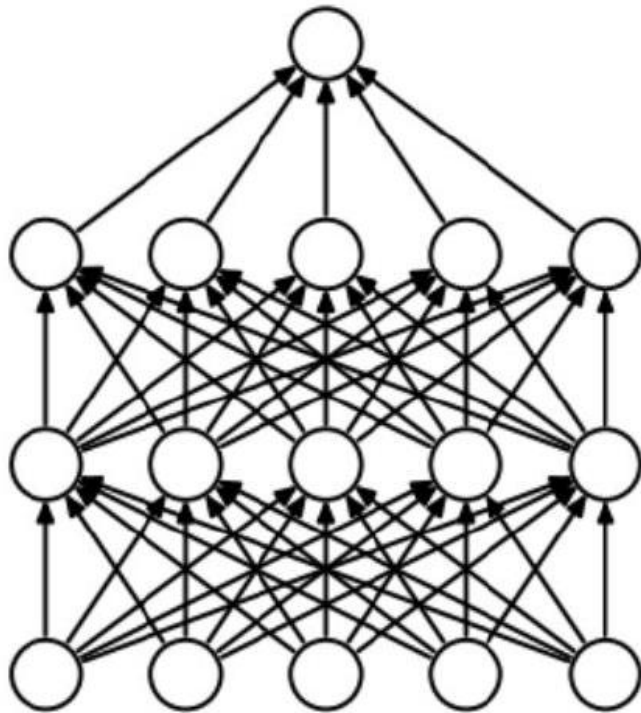
L2 -> Weight를 작게 & 균등하게

Unit 05 | Regularization

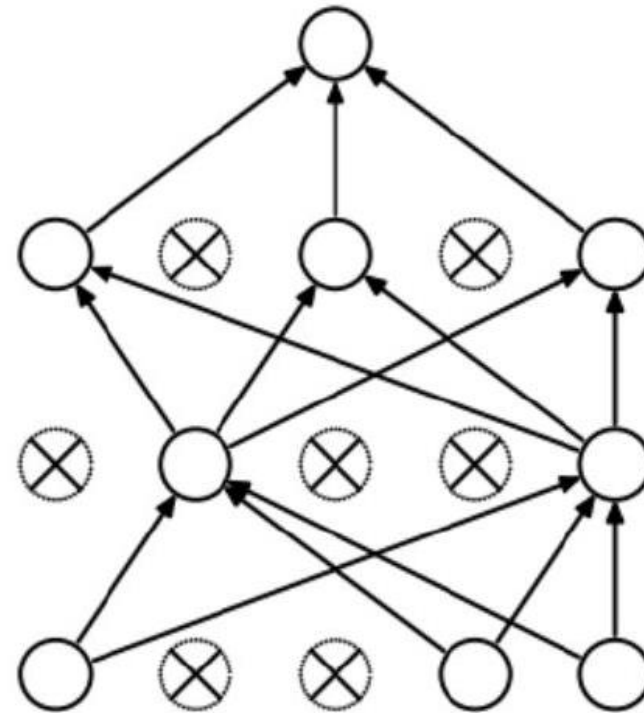


Unit 05 | Regularization

Dropout : layer에 포함된 뉴런 중에서 일부만 참여 시키는 것



(a) Standard Neural Net



(b) After applying dropout.

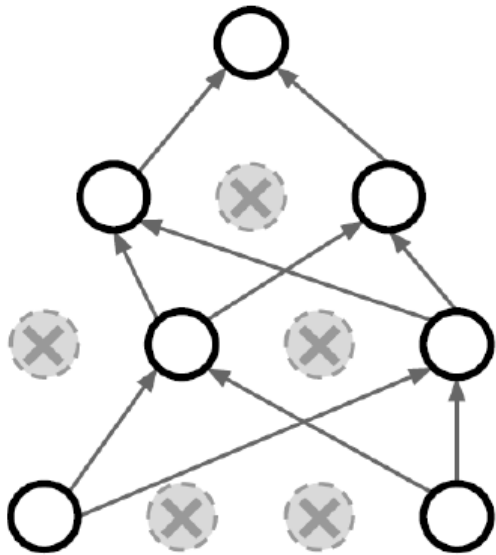
Dropout: A Simple Way to Prevent Neural Networks from Overfitting , N Srivastava et al. 2014

Unit 05 | Regularization

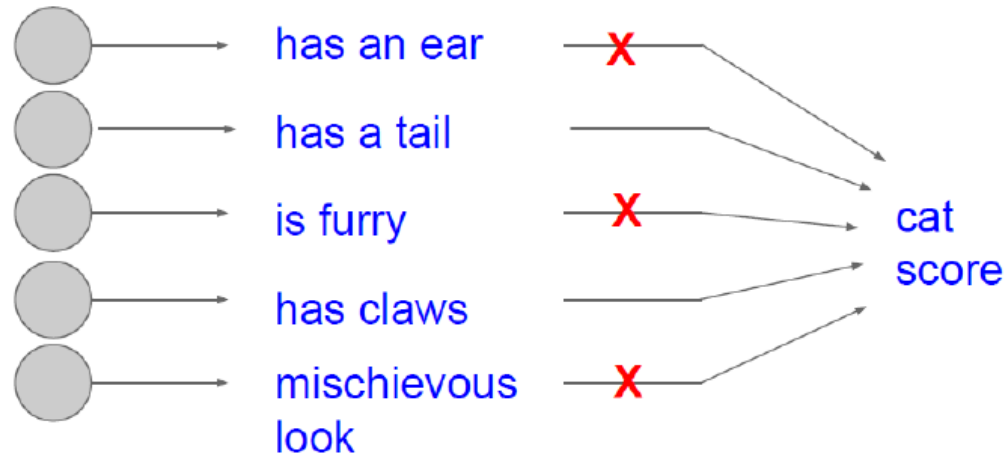
Dropout : layer에 포함된 뉴런 중에서 일부만 참여 시키는 것

Regularization: Dropout

How can this possibly be a good idea?



Forces the network to have a redundant representation;
Prevents co-adaptation of features

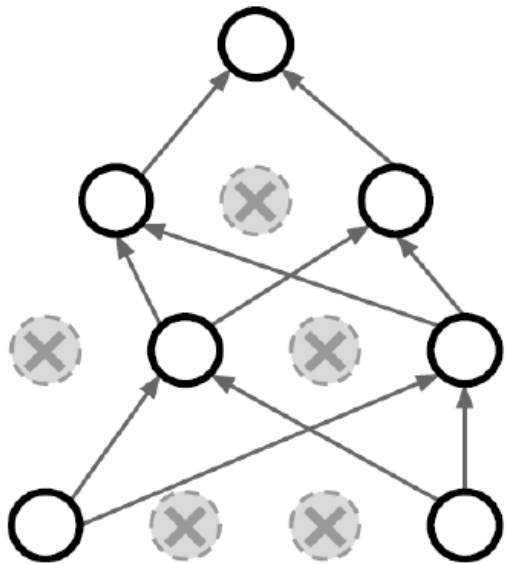


Unit 05 | Regularization

Dropout : layer에 포함된 뉴런 중에서 일부만 참여 시키는 것

Regularization: Dropout

How can this possibly be a good idea?

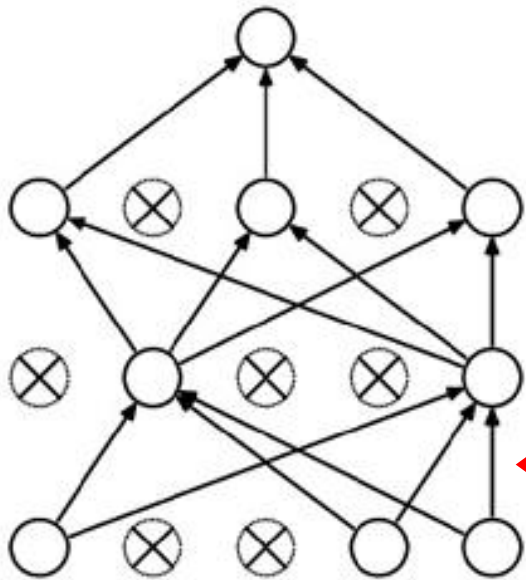


Another interpretation:

Dropout is training a large **ensemble** of models (that share parameters).

Unit 05 | Regularization

Dropout : layer에 포함된 뉴런 중에서 일부만 참여 시키는 것



(b) After applying dropout.

Layer1 = tf.nn.dropout(Layer1, keep_prob=keep_prob)

Unit 05 | 과제

< 과제 >

Mnist 데이터셋을 사용 .

layer 3개 이상 쌓아서 학습 시키기.

각 epoch 마다 줄어드는 loss를 프린트 통해 확인하기.

오늘 배운 것들을 사용해 정확도 올려 보기!

Q & A

들어주셔서 감사합니다.