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Assignment 2: STDR Reactive Controller

**github link:** <https://github.com/Justin-Beiriger/PS2-Reactive-Control-of-STD.R.git>

**youtube link:** <https://youtu.be/yh0BPyEkRvg>

The implementation details of the controller and the lidar alarm can be found in the README file on github. This lab was very interesting, and I am excited to combine this functionality with giving the robot a path to follow or destination to reach.