## Problem Set 4

Due: 3/30

## Part One: Hand-Written Exercise

- 1. Answer the following questions with "True" or "False". Briefly explain if your answer is True, provide a counter example if your answer is False.
  - (a) A biased estimator must be inconsistent.
  - (b) An unbiased estimator must be consistent.
  - (c) Central Limit Theorem(CLT) always works no matter what the original distribution of random sample is as long as the sample size is sufficiently large.
  - (d) If an estimator is weakly consistent, then with proper normalization, it is also asymptotically normal distributed.
  - (e) If  $\sqrt{n}(\hat{\beta} \beta_o)$  is asymptotically normal distributed, then  $\hat{\beta}$  is weakly consistent for  $\beta_o$ .
- 2. Verify the statement on slide 18, Lecture 4. That is, for the simple linear regression:  $y_i = b_0 + b_1 x_i + u_i$ , we have  $\hat{\beta}_0 \stackrel{p}{\rightarrow} b_0$  under Modern Assumption 0.
- 3. Consider the model without intercept

$$y_i = \beta_1 x_i + u_i$$

that satisfies the Modern Assumptions and  $\mathbb{E}(x_i) = 0$ ,  $\operatorname{Var}(x_i) = \sigma_x^2$ . Now suppose  $x_i$  can't be observed directly, instead, we observe  $w_i$ , which is  $x_i$  plus a random error  $\epsilon_i$ :

$$w_i = x_i + \epsilon_i$$

with  $\mathbb{E}(\epsilon_i) = \mathbb{E}(\epsilon_i x_i) = \mathbb{E}(\epsilon_i u_i) = 0$ , and  $\operatorname{Var}(\epsilon_i) = \sigma_{\epsilon}^2$ . So instead of estimating the model  $y_i = \beta_1 x_i + u_i$ , which is impossible due to the fact that  $x_i$  is unobservable, we now estimate

$$y_i = \gamma_1 w_i + u_i,$$

which is known as the model with measurement errors.

(a) Please find the probability limit of the OLS estimator  $\hat{\gamma}_1$ .

- (b) Is  $\hat{\gamma}_1$  consistent for  $\beta_1$ ? If not, then as the sample size  $n \to \infty$ , does  $\hat{\gamma}_1$  over- or under-estimates  $\beta_1$ ? By how much?
- (c) As  $n \to \infty$ , what would happen to  $\hat{\gamma}_1$  if  $\sigma_x^2 \to \infty$ ? Please briefly explain the intuition behind your results.
- (d) As  $n \to \infty$ , what would happen to  $\hat{\gamma}_1$  if  $\sigma_{\epsilon}^2 \to \infty$ ? Please briefly explain the intuition behind your results.
- 4. Consider the model

$$y_i = \beta_0 + \beta_1 x_{1i} + \beta_2 x_{2i} + u_i$$

that satisfies the Modern Assumptions. Moreover, let  $Var(x_1) = \sigma_{x_1}^2$  and  $Cov(x_1, x_2) = \sigma_{x_1x_2}$ . Suppose we exclude an important variable  $x_2$  and obtain the corresponding OLS estimator  $\tilde{\alpha}_1$ . That is, we obtain  $\tilde{\alpha}_1$  from the model  $y_i = \alpha_0 + \alpha_1 x_{1i} + u_i$ .

- (a) Is  $\tilde{\alpha}_1$  consistent for  $\beta_1$ ?
- (b) As the sample size  $n \to \infty$  and  $\sigma_{x_1 x_2} > 0$ , does  $\tilde{\alpha}_1$  over- or under-estimates  $\beta_1$ ? By how much?
- (c) As the sample size  $n \to \infty$  and  $\sigma_{x_1x_2} > 0$ , does  $\sqrt{n}(\tilde{\alpha}_1 \beta_1)$  converge to a normal distribution, or any other distributions?
- 5. Verify the statement on slide 41, Lecture 4. That is, write down the  $3 \times 3$  matrix  $\mathbf{R}\tilde{\mathbf{D}}\mathbf{R}'$  using the notation  $d_{ij}$ , where

$$\mathbf{R} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & \cdots & 0 \\ 0 & 0 & 1 & 0 & 0 & \cdots & 0 \\ 0 & 0 & 0 & 1 & 0 & \cdots & 0 \end{bmatrix}$$

and

$$\tilde{\mathbf{D}} = \begin{bmatrix} d_{11} & d_{12} & \cdots & d_{1(k+1)} \\ d_{21} & d_{22} & \cdots & d_{2(k+1)} \\ \vdots & \vdots & \ddots & \vdots \\ d_{(k+1)1} & d_{(k+1)2} & \cdots & d_{(k+1)(k+1)} \end{bmatrix}.$$

## Part Two: Monte Carlo Simulation (Due: 3/30)

- Simulation design:
  - Sample sizes N:

- (i) 10
- (ii) 500
- Number of replications: 1000
- Data generating process (DGP):
  - (i)  $y_i \sim N(0, 1)$
  - (ii)  $y_i \sim t(4)$
  - (iii)  $y_i \sim t(1)$
- The statistics:

$$M_N = \frac{1}{\hat{\sigma}_N \sqrt{N}} \sum_{i=1}^N \phi(y_i), \text{ where } \hat{\sigma}_N^2 = \frac{1}{N} \sum_{i=1}^N \left( \phi(y_i) - \frac{1}{N} \sum_{i=1}^N \phi(y_i) \right)^2,$$

with the moment functions:

- (i)  $\phi(y_i) = y_i$
- (ii)  $\phi(y_i) = y_i^3$
- (iii)  $\phi(y_i) = \sin(y_i)$
- (iv)  $\phi(y_i) = \cos(y_i)$
- For the total 24 different ways of constructing  $M_N$ , please plot their corresponding histogram using 1000 replications. Open a new window and combine the 24 graphs on a single plot and place them as  $6 \times 4$ .
- Please compute the empirical frequencies of the events:  $M_N > Z_{.99} = 2.3$  and  $M_N > Z_{.95} = 1.6$  for each simulations ( $Z_q$  is the  $q^{th}$  quantile of standard normal distribution). Record them under their corresponding graphs, see if the frequencies are, respectively, sufficiently close to the 5% and 1% nominal levels.
- Please add the Gaussian kernel density estimate (KDE) of  $M_N$  as well as the probability density function (PDF) of N(0,1) for each simulation graphs.