

Time Series Analysis - Estimation of ARMA models

ECON 722

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For iid data with marginal pdf $f(y_t; \theta)$, the joint density function for a sample $\mathbf{y} = (y_1, \dots, y_T)$ is simply the product of the marginal densities for each observation

$$f(\mathbf{y}; \theta) = f(y_1, \dots, y_T; \theta) = \prod_{t=1}^T f(y_t; \theta)$$

The likelihood function is this joint density treated as a function of the parameters θ given the data \mathbf{y} :

$$L(\theta | \mathbf{y}) = L(\theta | y_1, \dots, y_T) = \prod_{t=1}^T f(y_t; \theta)$$

The log-likelihood then as the simple form

$$\ln L(\theta | \mathbf{y}) = \sum_{t=1}^T \ln f(y_t; \theta)$$

MLE for Dependent Data

- For a sample from a covariance stationary time series $\{y_t\}$, the construction of the log-likelihood give above doesn't work because the random variables in the sample (y_1, \dots, y_T) are not iid.
- One solution is to try to determine the joint density $f(y_1, \dots, y_T; \theta)$ directly, which requires, among other things, the $T \times T$ variancecovariance matrix $\text{var}(\mathbf{y})$. Hamilton describes this approach in detail for Gaussian ARMA processes.
- An alternative approach relies on factorization of the joint density into a series of conditional densities and the density of a set of initial values.

Conditional MLE

Consider the joint density of two adjacent observations $f(y_2, y_1; \theta)$ from a covariance stationary time series. The joint density can always be factored as the product of the conditional density of y_2 given y_1 and the marginal density of y_1 :

$$f(y_2, y_1; \theta) = f(y_2 | y_1; \theta) f(y_1; \theta)$$

For three observations, the factorization becomes

$$f(y_3, y_2, y_1; \theta) = f(y_3 | y_2, y_1; \theta) f(y_2 | y_1; \theta) f(y_1; \theta)$$

In general, the conditional marginal factorization has the form

$$f(y_T, \dots, y_1; \theta) = \left(\prod_{t=p+1}^T f(y_t | l_{t-1}, \theta) \right) \cdot f(y_p, \dots, y_1; \theta)$$

where $l_t = \{y_t, \dots, y_1\}$ denotes the information available at time t , and y_p, \dots, y_1 denotes the initial values.

Conditional MLE

The log-likelihood function may then be expressed as

$$\ln L(\boldsymbol{\theta} \mid \mathbf{y}) = \sum_{t=p+1}^T \ln f(y_t \mid I_{t-1}, \boldsymbol{\theta}) + \ln f(y_p, \dots, y_1; \boldsymbol{\theta})$$

The full log-likelihood function is called the exact log-likelihood. The first term is called the conditional log-likelihood, and the second term is called the marginal loglikelihood for the initial values.

Conditional MLE

$$\hat{\boldsymbol{\theta}}_{\text{CMLE}} = \arg \max_{\boldsymbol{\theta}} \sum_{t=p+1}^T \ln f(y_t \mid I_{t-1}, \boldsymbol{\theta})$$

Exact MLE

$$\hat{\boldsymbol{\theta}}_{\text{MLE}} = \arg \max_{\boldsymbol{\theta}} \sum_{t=p+1}^T \ln f(y_t \mid I_{t-1}, \boldsymbol{\theta}) + \ln f(y_p, \dots, y_1; \boldsymbol{\theta})$$

- For stationary models, $\hat{\theta}_{\text{CMLE}}$ and $\hat{\theta}_{\text{MLE}}$ are consistent and have the same limiting normal distribution. Intuition?
- For non stationary data the initial observation matters (initial conditions).
- In finite samples, however, $\hat{\theta}_{\text{cmle}}$ and $\hat{\theta}_{\text{mle}}$ are generally not equal and may differ by a substantial amount if the data are close to being non-stationary or non-invertible.

Example: MLE for AR(1)

Consider the stationary AR(1) model

$$y_t = c + \phi y_{t-1} + \varepsilon_t, \varepsilon_t \sim iidN(0, \sigma^2), t = 1, \dots, T$$
$$\theta = (c, \phi, \sigma^2)', |\phi| < 1$$

Conditional on y_{t-1}

$$y_t \mid y_{t-1} \sim N(c + \phi y_{t-1}, \sigma^2), t = 2, \dots, T$$

which only depends on y_{t-1} . The conditional density $f(y_t \mid y_{t-1}, \theta)$ is then

$$f(y_t \mid y_{t-1}, \theta) = (2\pi\sigma^2)^{-1/2} \exp\left(-\frac{1}{2\sigma^2} (y_t - c - \phi y_{t-1})^2\right), t = 2, \dots, T$$

Example: MLE for AR(1)

To determine the marginal density for the initial value y_1 , recall that for a stationary AR(1) process

$$E[y_1] = \mu = \frac{c}{1 - \phi}$$
$$\text{var}(y_1) = \frac{\sigma^2}{1 - \phi^2}$$

It follows that

$$y_1 \sim N\left(\frac{c}{1 - \phi}, \frac{\sigma^2}{1 - \phi^2}\right)$$
$$f(y_1; \theta) = \left(2\pi \frac{\sigma^2}{1 - \phi^2}\right)^{-1/2} \exp\left(-\frac{1 - \phi^2}{2\sigma^2} \left(y_1 - \frac{c}{1 - \phi}\right)^2\right)$$

Example: MLE for AR(1)

The conditional log-likelihood function is

$$\begin{aligned} \sum_{t=2}^T \ln f(y_t | y_{t-1}, \theta) &= \frac{-(T-1)}{2} \ln(2\pi) - \frac{(T-1)}{2} \ln(\sigma^2) \\ &\quad - \frac{1}{2\sigma^2} \sum_{t=2}^T (y_t - c - \phi y_{t-1})^2 \end{aligned}$$

Notice that the conditional log-likelihood function has the form of the log-likelihood function for a linear regression model with normal errors. It follows that the conditional mles for c and ϕ are identical to the least squares estimates from the regression

$$y_t = c + \phi y_{t-1} + \varepsilon_t, t = 2, \dots, T$$

and the conditional MLE for σ^2 is

$$\hat{\sigma}_{\text{CMLE}}^2 = (T-1)^{-1} \sum_{t=2}^T \left(y_t - \hat{c}_{\text{CMLE}} - \hat{\phi}_{\text{CMLE}} y_{t-1} \right)^2$$

Example: MLE for AR(1)

The marginal log-likelihood for the initial value y_1 is

$$\ln f(y_1; \theta) = -\frac{1}{2} \ln(2\pi) - \frac{1}{2} \ln \left(\frac{\sigma^2}{1 - \phi^2} \right) - \frac{1 - \phi^2}{2\sigma^2} \left(y_1 - \frac{c}{1 - \phi} \right)^2$$

The exact log-likelihood function is then

$$\begin{aligned} \ln L(\theta \mid \mathbf{y}) = & -\frac{T}{2} \ln(2\pi) - \frac{1}{2} \ln \left(\frac{\sigma^2}{1 - \phi^2} \right) - \frac{1 - \phi^2}{2\sigma^2} \left(y_1 - \frac{c}{1 - \phi} \right)^2 \\ & - \frac{(T - 1)}{2} \ln(\sigma^2) - \frac{1}{2\sigma^2} \sum_{t=2}^T (y_t - c - \phi y_{t-1})^2 \end{aligned}$$

- The exact log-likelihood function is a non-linear function of the parameters θ , and so there is no closed form solution for the exact mles.
- The exact mles must be determined by numerically maximizing the exact log-likelihood function.

CMLE for MA and ARMA models

- For MA and ARMA models, even the conditional Likelihood is a non linear functions of the parameters and has to be numerically maximized.
- See Hamilton Chapter 5, for derivations. Useful review.
- Most time series packages will do this for you.