Factor Loading Recovery for Smoothed Tetrachoric Correlation Matrices

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Item Factor Analysis

We often want to conduct exploratory factor analysis on binary response data

- The assumption of continuous outcomes required by the common linear factor model is violated when data are binary
- Tetrachoric correlation matrices (Brown & Benedetti, 1977; Divgi, 1979)
 are often used to estimate the correlations between the
 normally-distributed, continuous latent variables often assumed to
 underlie observed binary data

Indefinite Tetrachoric Correlation Matrices

- Tetrachoric correlation matrices can be indefinite, particularly when computed from data sets with:
 - Few subjects
 - · Many items
 - Extreme items (high factor loadings, extreme item difficulties)

Proper Correlation Matrices

A correlation matrix, $\mathbf{R}_{p \times p}$ with elements $r_{ij} = r_{ji}$, $i,j \in \{1,\dots,p\}$, is a symmetric matrix that:

- 1. Has unit diagonal
- 2. Has all $|r_{ij}| \leq 1$
- 3. Is positive semidefinite (PSD), having eigenvalues $\lambda_i \geq 0$ $\forall \ i \in \{1,\dots,p\}$

The Problem with Indefinite Correlation Matrices

 ${f R}_{
m tet}$: The tetrachoric correlation matrix ${f R}_{
m Pop}$: The population correlation matrix estimated by ${f R}_{
m tet}$

Problems:

- \cdot An indefinite $\mathbf{R}_{ ext{tet}}$ is not in the set of possible $\mathbf{R}_{ ext{Pop}}$ matrices
- Some multivariate analysis procedures do not work with indefinite correlation matrices (i.e., maximum likelihood factor analysis)
- Can lead to nonsensical interpretations (e.g., negative component variance in PCA)

Matrix Smoothing Algorithms

A matrix smoothing algorithm is a procedure that modifies an indefinite correlation matrix to produce a correlation matrix that is at least PSD.

- The Higham Alternating Projections algorithm (APA; Higham, 2002)
- The Bentler-Yuan algorithm (BY; Bentler & Yuan, 2011)
- The Knol-Berger algorithm (KB; Knol & Berger, 1991)

The Higham Alternating Projections Algorithm (2002)

Intuition: Find the closest PSD correlation matrix (\mathbf{R}_{APA}) to a given indefinite correlation matrix (\mathbf{R}_{-}) by iteratively projecting between two sets:

- \mathcal{S} : The set containing all possible $p \times p$ symmetric matrices that are PSD
- + \mathcal{U} : The set containing all possible $p \times p$ symmetric matrices that have a unit diagonal

The Higham Alternating Projections Algorithm (2002)

For symmetric matrix $\mathbf{A} \in \mathbb{R}^{p \times p}$, define two projection functions:

- $P_S(\mathbf{A}) = \mathbf{V} \mathrm{diag}(\max(\lambda_i,0)) \mathbf{V}'$: Project \mathbf{A} onto \mathcal{S} by replacing all negative eigenvalues with zero in the eigendecomposition.
- \cdot $P_U({f A})$: Project ${f A}$ onto ${\mathcal U}$ by replacing the diagonal elements of ${f A}$ with ones.

The Higham Alternating Projections Algorithm (2002)

Initialize ${f A}_0$ as the indefinite correlation matrix ${f R}_-$. Repeat the operation

$$\mathbf{A}_{k+1} = P_U(P_S(\mathbf{A}_k))$$

until convergence occurs or the maximum number of iterations is exceeded.

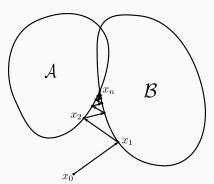


Figure 1: Simplified illustration of the method of alternating projections.

The Bentler-Yuan Algorithm (2011)

Intuition: Shrink the correlations involving variables with minimum trace factor analysis (MTFA; Jamshidian & Bentler, 1998) estimated communalities ≥ 1 .

The Bentler-Yuan Algorithm (2011)

$$\mathbf{R}_{\mathrm{BY}} = \Delta \mathbf{R}_0 \Delta + \mathbf{I}$$

 $\mathbf{R}_0 = \mathbf{R}_- - \mathbf{I}$ $\boldsymbol{\Delta}^2$ is a diagonal matrix with elements δ_i^2 ,

$$\delta_i^2 = \begin{cases} 1 & \text{if } h_i < 1 \\ k/h_i & \text{if } h_i \geq 1. \end{cases}$$

 $k \in (0,1)$ is a constant chosen by the user h_i is the MTFA communality estimate for the ith item

The Knol-Berger Algorithm (1991)

Intuition: Replace all negative eigenvalues with a small positive constant in the eigenvalue decomposition and then scale the result to a correlation matrix.

The Knol-Berger Algorithm (1991)

$$\mathbf{R}_{-} = \mathbf{V} \Lambda \mathbf{V}'$$

$$\Lambda_+ = \mathrm{diag}[\max(\lambda_i,0)], \ i \in \{1,\dots,p\}$$

$$\mathbf{R}_{KB} = [\mathrm{dg}(\mathbf{V}\boldsymbol{\Lambda}_{+}\mathbf{V}')]^{-1/2}\mathbf{V}\boldsymbol{\Lambda}_{+}\mathbf{V}'[\mathrm{dg}(\mathbf{V}\boldsymbol{\Lambda}_{+}\mathbf{V}')]^{-1/2}$$

Example: Matrix Smoothing Algorithms

$$\mathbf{R}_{-} = \begin{bmatrix} 1 & 0.48 & 0.64 & 0.48 & 0.65 & 0.83 \\ 0.48 & 1 & 0.52 & 0.23 & 0.68 & 0.75 \\ 0.64 & 0.52 & 1 & 0.60 & 0.58 & 0.74 \\ 0.48 & 0.23 & 0.60 & 1 & 0.74 & 0.80 \\ 0.65 & 0.68 & 0.58 & 0.74 & 1 & 0.80 \\ 0.83 & 0.75 & 0.74 & 0.80 & 0.80 & 1 \end{bmatrix}$$

Eigenvalues: (4.21, 0.77, 0.52, 0.38, 0.18, -0.06)

Communalities: (1.029, 1.122, 0.557, 1.299, 0.823, 0.997)

Variables 1, 2, and 4 have estimated communalities > 1.

Example: Matrix Smoothing Algorithms

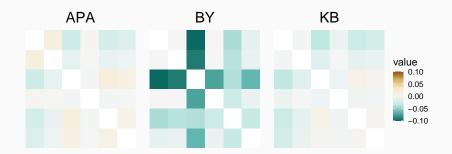


Figure 2: Differences between the elements of the ${f R}_{Sm}$ and ${f R}_-$ matrices for the Higham, Bentler-Yuan, and Knol-Berger algorithms.

Common Factor Model

$$\mathbf{P} = \mathbf{F}\Phi\mathbf{F}' + \Theta^2 \tag{1}$$

- \cdot **P**: $p \times p$ population correlation matrix
- \cdot \mathbf{F} : p imes m factor loading matrix
- Φ : $m \times m$ factor correlation matrix
- $\cdot \ \Theta^2$: $p \times p$ matrix of unique item variances

Common Factor Model with Model Approximation Error

$$\mathbf{P} = \mathbf{F}\Phi\mathbf{F}' + \Theta^2 + \mathbf{W}\mathbf{W}' \tag{2}$$

- \cdot **P**: $p \times p$ population correlation matrix
- \cdot \mathbf{F} : p imes m factor loading matrix
- Φ : $m \times m$ factor correlation matrix
- $\cdot \Theta^2$: $p \times p$ matrix of unique item variances
- \cdot **W**: $p \times q$ minor factor loading matrix for the $q \gg p$ minor common factors

Methods

Simulation Conditions

- Major common factors: $m \in \{1,3,5,10\}$
- Items per factor: $p/m \in \{5, 10\}$
- · Subjects per item: $N/p \in \{5, 10, 15\}$
- Factor Loading: Loading $\in \{0.4, 0.6, 0.8\}$
- · Model Error: $\upsilon_E \in \{0.0, 0.1, 0.3\}$
 - Proportion of uniqueness variance apportioned to minor common factors

Fully-crossed design with 216 unique conditions

Simulation Procedure

For each of the 216 unique conditions, conduct 1,000 replications of the following steps:

- 1. Generate binary response data using Equation (1)
- 2. Compute the tetrachoric correlation matrix
- 3. If the matrix is PSD, next; Else, smooth using:
 - · Higham (2002)
 - · Bentler-Yuan (2011)
 - · Knol-Berger (1991)
- 4. For each of the three smoothed correlation matrices and the unsmoothed matrix, estimate factor loadings using:
 - Principal Axes factor extraction (PA)
 - · Ordinary Least Squares (OLS)
 - Maximum Likelihood (ML)

${ m R}_{ m Pop}$ Recovery Criterion

Given two $p \times p$ symmetric matrices, $\mathbf{A} = \{a_{ij}\}$ and $\mathbf{B} = \{b_{ij}\}$,

$$D_{s}(\mathbf{A}, \mathbf{B}) = \sqrt{\sum_{i=1}^{p-1} \sum_{j=i+1}^{p} \frac{\left(a_{ij} - b_{ij}\right)^{2}}{p(p-1)/2}}.$$

- $\cdot \ \mathbf{R}_{\mathrm{Sm}} \in \{\mathbf{R}_{-}, \mathbf{R}_{\mathrm{APA}}, \mathbf{R}_{\mathrm{BY}}, \mathbf{R}_{\mathrm{KB}}\}$
- $\cdot \mathbf{R}_{Pop} = \mathbf{F} \Phi \mathbf{F}' + \Theta^2 + \mathbf{W} \mathbf{W}'$

Evaluate recovery of ${f R}_{Pop}$ using $D_s({f R}_{Pop},{f R}_{Sm})$

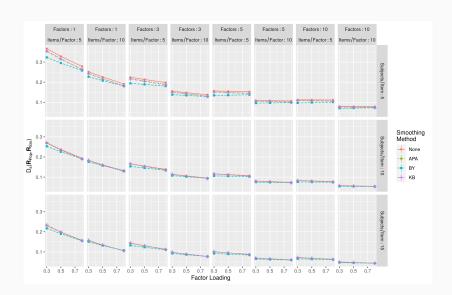
${f F}$ Recovery Criterion

Evaluate how well the factor loading matrix, ${f F}$, was recovered using:

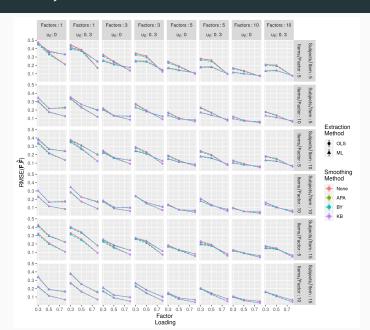
RMSE(
$$\mathbf{F}, \hat{\mathbf{F}}$$
) = $\sqrt{\sum_{i=1}^{p} \sum_{j=1}^{m} \frac{\left(f_{ij} - \hat{f}_{ij}\right)^{2}}{pm}}$

Results

$m R_{Pop}$ Recovery



F Recovery



Appendix

Higham's Algorithm (2002) with Dykstra's Correction

Algorithm 1: For an indefinite correlation matrix ${f R}_-$, find the nearest PSD correlation matrix

$$\begin{split} & \text{Initialize } \mathbf{S}_0 = 0; \mathbf{Y}_0 = \mathbf{R}_- \\ & \text{for } k = 1, 2, \dots \text{ do} \\ & \mathbf{Z}_k = \mathbf{Y}_{k-1} - \mathbf{S}_{k-1} \\ & \mathbf{X}_k = P_S(\mathbf{Z}_k) \\ & \mathbf{S}_k = \mathbf{X}_k - \mathbf{Z}_k \\ & \mathbf{Y}_k = P_U(\mathbf{X}_k) \end{split}$$
 end

The algorithm continues until convergence occurs or the maximum number of iterations is exceeded. If the algorithm converges,

$$\mathbf{R}_{APA} = \mathbf{Y}_{k}$$

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