

Poppy

Documentation

release 1.1.0

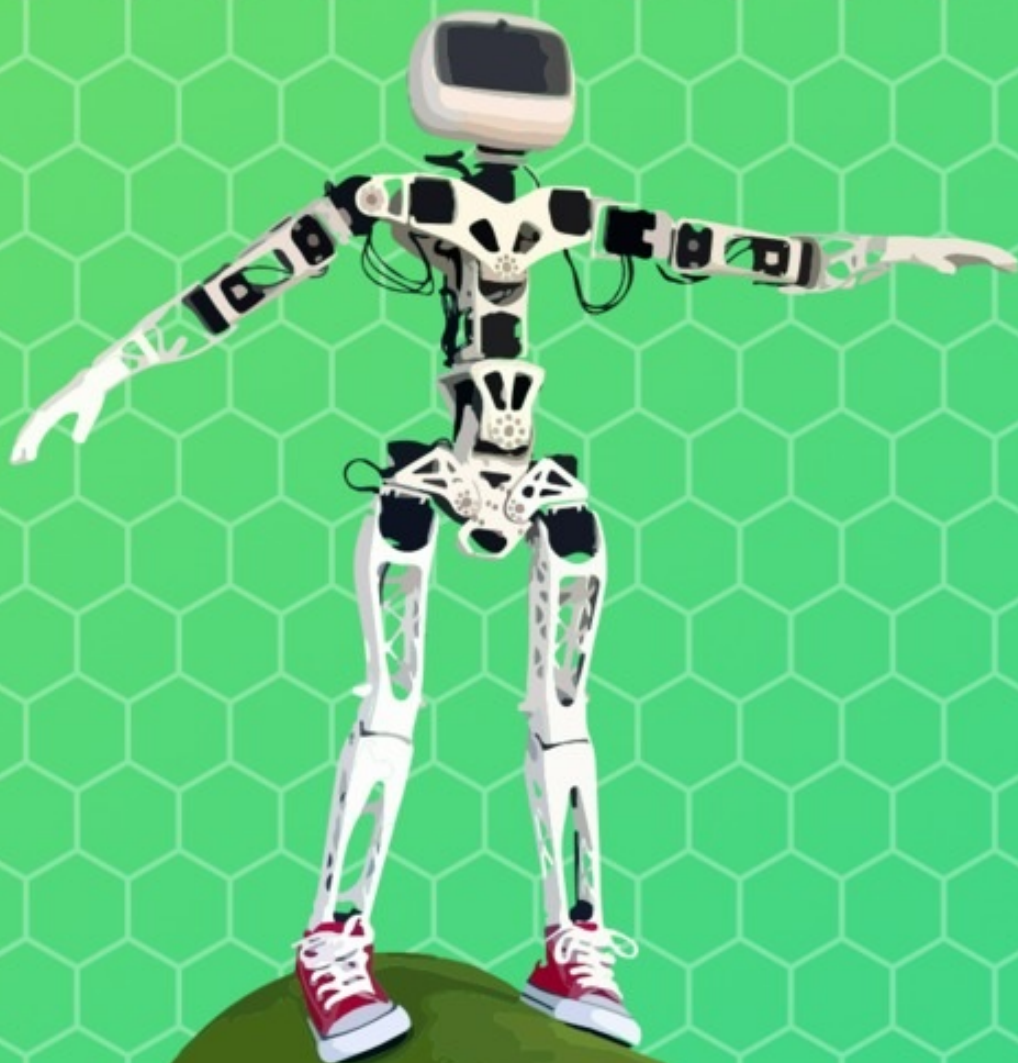


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0Introduction

0.1About

Welcome to the manual of the [Poppy-Project](#), an open-source robotic platform.

In this documentation, we will try to cover everything from the short overview of what is possible within the project to the details on how you can build a Poppy robot or reproduce one of the pedagogical activity.

In the first chapter, we will give you a simple but exhaustive overview of what you can do within this project, so you can quickly focus on the following chapters that cover what you are really interested in. While some advanced chapters may require a good understanding of mechanics, electronics or computer sciences, the [Getting Started](#) section is intended to be easily accessible by all readers.

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0.2Version

This is the version 1.0 of the Poppy documentation.

It contains the documentation for:

- Poppy Humanoid 1.0.1 hardware
- Poppy Torso 1.0.1 hardware
- Poppy ErgoJr beta 6 hardware
- poppy_humanoid library version 1.1.1
- poppy_torso library version 1.1.5
- poppy_ergo_jr library version 1.4.0
- poppy.creatures library version 1.7.1
- pypot library version 2.10.0