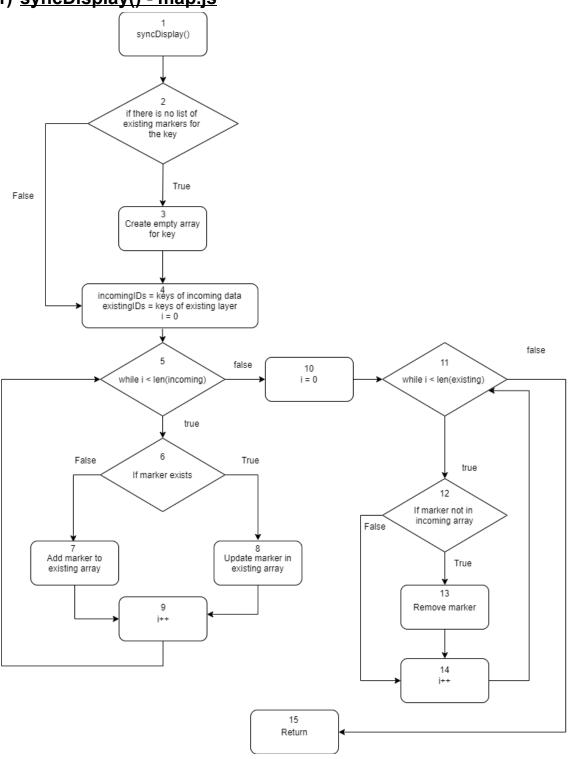
White Box Testing

1) syncDisplay() - map.js



Cyclomatic Complexity

```
CC = |edges| - |nodes| + 2
CC = 19 - 15 + 2 = 6
CC = |decision point| + 1
CC = 5 + 1 = 6
```

Basic Paths

```
I. Baseline: 1, 2, 4, 5, 10, 11, 15
II. 1, 2, 3, 4, 5, 10, 11, 15
III. 1, 2, 4, 5, 6, 7, 9, 5, 10, 11, 15
IV. 1, 2, 4, 5, 6, 8, 9, 5, 10, 11, 15
V. 1, 2, 4, 5, 10, 11, 12, 14, 11, 15 (infeasible)
VI. 1, 2, 4, 5, 10, 11, 12, 13, 14, 11, 15
```

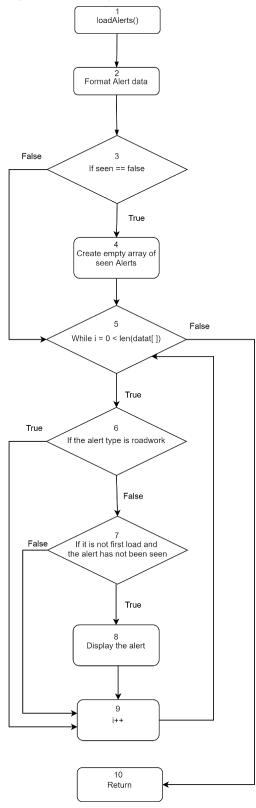
Test Cases

- a. Path 1: incoming = [], existing = []
- b. Path 2: incoming = [], existing = undefined
- c. Path 3: incoming = [id_1], existing = [], id_1 does not exist in the existing array.
- d. Path 4: incoming = [id_1], existing = [id_1], id_1 in incoming array update
- e. Path 6: incoming = [], existing [id_1], id in existing Ds is not in incoming array

Real Execution Paths

- a. 1, 2, 4, 5, 10, 11, 15
- b. 1, 2, 3, 4, 5, 10, 11, 15
- c. 1, 2, 4, 5, 6, 7, 9, 5, 10, 11, 15
- d. 1, 2, 4, 5, 6, 8, 9, 5, 10, 11, 12, 14, 11, 15
- e. 1, 2, 4, 5, 10, 11, 12, 13, 14, 11, 15

2) loadAlerts() - manager_alerts.js



Cyclomatic Complexity

CC = |edges| - |nodes| + 2 CC = 13 - 10 + 2 = 5 CC = |decision point| + 1

CC = 4 + 1 = 5

Basic Paths

I. Baseline: 1, 2, 3, 5, 10

II. 1, 2, 3, <u>4</u>, 5, 10

III. 1, 2, 3, <u>5, 6, 9</u>, 5, 10

IV. 1, 2, 3, <u>5, 6, 7, 9</u>, 5, 10

V. 1, 2, 3, <u>5, 6, 7, 8, 9</u>, 5, 10

Test Cases

I. seenAlertIds = [], data = []

II. seenAlertIds = false, data = []

III. seenAlertIds = [], data = [id_1], id_1 (roadwork) does not need to display alert

IV. seenAlertIds = [id_2], data = [id_2], id_2 (not roadwork & alert has been seen on first load) does not need to display alert

V. seenAlertIds = [id_1], data = [id_2], id_2 (not roadwork & alert has not been seen on first load) need to display alert

Real Execution Paths

I. 1, 2, 3, 5, 10

II. 1, 2, 3, 4, 5, 10

III. 1, 2, 3, 5, 6, 9, 5, 10

IV. 1, 2, 3, 5, 6, 7, 9, 5, 10

V. 1, 2, 3, 5, 6, 7, 8, 9, 5, 10