

conclusion

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Multi-Goal LaCAM

- **Improved throughput** compared to naive (sequential) approach

Following-Free LaCAM

- **Minimal overhead** in low-congestion scenarios

pLaCAM (Multi-Goal + Following-Free)

- **Improved success rate** compared to contemporary work

Generally **positive results in warehouse-like** environment tested

- Results may not generalize to more **complex** environments (e.g. maze)

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