

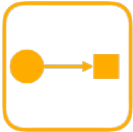
LaCAM[Okumura+AAAI-23]

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MAPF solver which balances optimality and speed

Limitations to address:





**Following-Free
LaCAM**

• **Does not prevent cycling conflict**

Multi-Goal LaCAM



• **Limiting goal**

LaCAM^[Okumura+ AAAI-23]

MAPF  solver which balances optimality and speed

Limitations to address:

- **Limited to single goal**



Multi-Goal
LaCAM

- **Does not prevent cycle or following conflict**



Following-Free
LaCAM

Related Work

This Study

