Operating Systems CSCI 3150

Lecture 3: Processes

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Processes

- This lecture starts a class segment that covers processes, threads, and synchronization
 - These topics are perhaps the most important in this course
 - You can rest assured that they will be covered in the exams
- Today's topics are processes and process management
 - What are the units of execution?
 - How are those units of execution represented in the OS?
 - What are the possible execution states of a process?
 - How does a process move from one state to another?

Users, Programs

- Users have accounts on the system
- Users launch programs
 - Many users may launch the same program
 - One user may launch many instances of the same program
- Then what is a process?

The Process

- The process is the OS's abstraction for execution
 - It is the unit of execution
 - It is the unit of scheduling
 - It is the dynamic execution context of a program, a concrete instantiation of the program
- A process is sometimes called a job or a task or a sequential process
- Real life analogy?

Analogy: A robot taking CSCI3150

- **Program**: steps for attending the lecture
 - Step 1: take a school bus
 - Step 2: enter the classroom
 - Step 3: listen (or sleep)
- **Process**: attending this particular lecture right now
 - Action
 - You are all in the middle of a process

MacOS example: Activity monitor

Process Name	% CPU ~	CPU Time	Threads	Idle Wake-Ups	% GPU	GPU Time	PID	User
Microsoft Edge Helper (Rend	2.8	1:20.50	29	58	0.0	0.00	4283	henry
Activity Monitor	1.7	2:47.08	5	3	0.0	0.00	1706	henry
photolibraryd	0.9	56.12	8	0	0.0	0.00	525	henry
accountsd	0.9	12.62	4	0	0.0	0.00	477	henry
Screenshot	0.8	0.26	5	1	0.0	0.00	5124	henry
Microsoft Edge Helper (GPU)	0.7	2:22.43	13	66	0.1	27.71	1907	henry
Microsoft Edge Helper (Rend	0.7	1.27	16	0	0.0	0.00	1968	henry
♡ Dropbox	0.6	3:30.31	146	26	0.0	0.00	1939	henry
WeChat	0.6	1:34.12	38	23	0.0	0.16	3925	henry
Microsoft Edge	0.5	2:23.11	46	6	0.0	0.00	1697	henry
iStat Menus Status	0.5	3:39.07	4	3	0.0	0.00	1930	henry
Microsoft Edge Helper	0.5	21.75	11	16	0.0	0.00	2062	henry
tccd	0.4	4.11	4	0	0.0	0.00	471	henry
mdworker_shared	0.4	0.06	3	0	0.0	0.00	5121	henry
routined	0.4	10.13	5	0	0.0	0.00	489	henry
System Preferences	0.4	1.51	3	0	0.0	0.00	1696	henry
Microsoft PowerPoint	0.3	29.15	45	4	0.0	0.24	4932	henry

Linux example: ps

0	0	Thanks for flying Vim	
diyuar	n@ug132:~\$ ps −e		6
PID	TTY TIME	CMD	
1	? 00:00:04	init	
2	? 00:00:00	kthreadd	
3	? 00:00:00	migration/0	- 11
4	? 00:00:00	ksoftirqd/0	
5	? 00:00:00	watchdog/0	
6	? 00:00:00	migration/1	
7	? 00:00:00	ksoftirqd/1	
8	? 00:00:00	watchdog/1	
9	? 00:00:00	migration/2	
10	? 00:00:00	ksoftirqd/2	
11	? 00:00:00	watchdog/2	
12	? 00:00:00	migration/3	
13	? 00:00:00	ksoftirqd/3	
14	? 00:00:00	watchdog/3	
15	? 00:00:00	events/0	
16	? 00:00:00	events/1	
17	? 00:00:03	events/2	
18	? 00:00:00	events/3	
19	? 00:00:00	cpuset	
20	? 00:00:00	khelper	A
21	? 00:00:00	netns	₩.
22	? 00:00:00	async/mgr	11.

So what is a process?

- A process is a program in execution
- It is one executing instance of a program
- It is separated from other instances

- It can start ("launch") other processes
- It can be launched by them

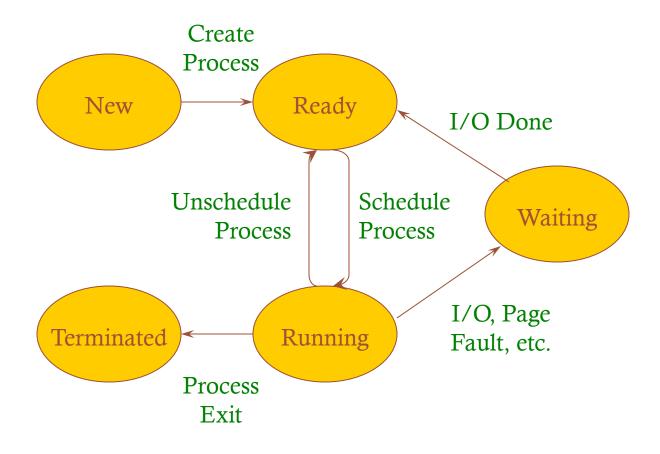
Process State

- A process has an execution state that indicates what it is currently doing
 - Running: Executing instructions on the CPU
 - It is the process that has control of the CPU
 - How many processes can be in the running state simultaneously?
 - Ready: Waiting to be assigned to the CPU
 - Ready to execute, but another process is executing on the CPU
 - Waiting: Waiting for an event, e.g., I/O completion
 - It cannot make progress until event is signaled (disk completes)
- As a process executes, it moves from state to state
 - Unix "ps": STAT column indicates execution state

Questions

- What state do you think a process is in most of the time?
- For a uni-processor machine, how many processes can be in running state?
- Benefit of multi-core?

Process State Graph



Process Components

- Process State
 - new, ready, running, waiting, terminated;
- Program Counter
 - the address of the next instruction to be executed for this process;
- CPU Registers
 - index registers, stack pointers, general purpose registers;
- CPU Scheduling Information
 - process priority;

Process Components (cont.)

- Memory Management Information
 - base/limit information, virtual->physical mapping, etc
- Accounting Information
 - time limits, process number; owner
- I/O Status Information
 - list of I/O devices allocated to the process;
- An Address Space
 - memory space visible to one process

Now how about this?

```
int myval;
int main(int argc, char *argv[])
{
   myval = atoi(argv[1]);
   while (1)
     printf("myval is %d, loc 0x%lx\n", myval, (long) &myval);
}
```

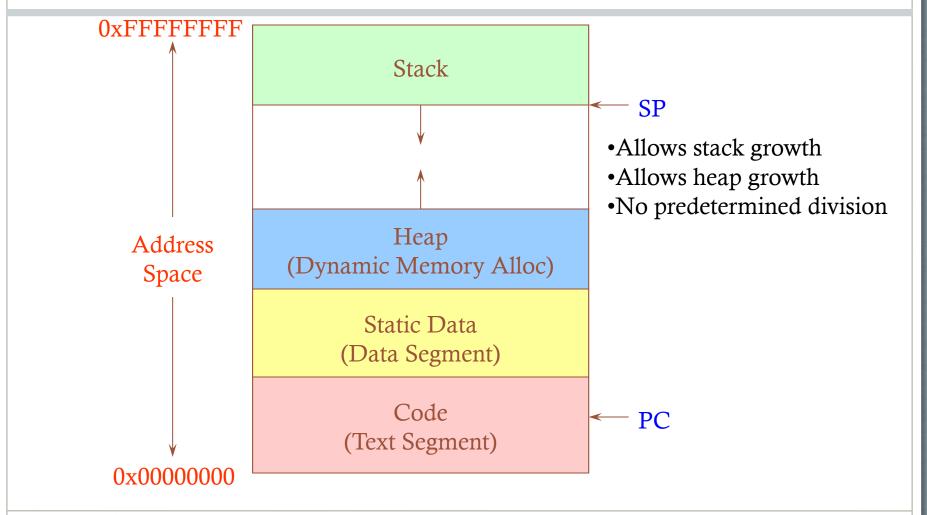
- Now simultaneously start two instances of this program
 - Myval 5
 - Myval 6
 - What will the outputs be?

Default	D \varTheta 🕚 🔘	Thank
myval is 5, loc 0x2030	myval is 6,	loc 0x2030
myval is 5, loc 0x2030	myval is 6,	loc 0x2030
myval is 5, loc 0x2030	myval is 6,	loc 0x2030
myval is 5, loc 0x2030	myval is 6,	loc 0x2030
myval is 5, loc 0x2030	myval is 6,	loc 0x2030
myval is 5, loc 0x2030	myval is 6,	loc 0x2030
myval is 5, loc 0x2030	myval is 6,	loc 0x2030
myval is 5, loc 0x2030	myval is 6,	
myval is 5, loc 0x2030	myval is 6,	loc 0x2030
myval is 5, loc 0x2030	myval is 6,	loc 0x2030
myval is 5, loc 0x2030	myval is 6,	
myval is 5, loc 0x2030	Output differs on myval is 6,	loc 0x2030
myval is 5, loc 0x2030	your machine! myval is 6,	loc 0x2030
myval is 5, loc 0x2030	myval is 6,	loc 0x2030
myval is 5, loc 0x2030	myval is 6,	loc 0x2030
myval is 5, loc 0x2030	myval is 6,	loc 0x2030
myval is 5, loc 0x2030	myval is 6,	loc 0x2030
myval is 5, loc 0x2030	myval is 6,	loc 0x2030
myval is 5, loc 0x2030	myval is 6,	loc 0x2030
myval is 5, loc 0x2030	myval is 6,	loc 0x2030
myval is 5, loc 0x2030	myval is 6,	loc 0x2030
myval is 5, loc 0x2030	myval is 6,	loc 0x2030
myval is 5, loc 0x2030	myval is 6,	loc 0x2030
myval is 5, loc 0x2030		

Instances of Programs

- The address was always the same
 - But the values were different
- Implications?
 - The programs aren't seeing each other
 - But they think they're using the same address
- Conclusions
 - addresses are not the "physical memory"
- How?
 - Memory mapping
- What is the benefit?

Process Address Space



Process Data Structures

How does the OS represent a process in the kernel?

- At any time, there are many processes in the system, each in its particular state
- The OS data structure representing each process is called the Process Control Block (PCB)
- The PCB contains all of the info about a process
- The PCB also is where the OS keeps all of a process' hardware execution state (PC, SP, regs, etc.) when the process is not running
 - This state is everything that is needed to restore the hardware to the same state it was in when the process was switched out of the hardware

PCB Data Structure

- The PCB contains a huge amount of information in one large structure
 - Process ID (PID)
 - Execution state
 - Hardware state: PC, SP, regs
 - Memory management
 - Scheduling
 - Pointers for state queues
 - Etc.

struct proc (Solaris)

```
* One structure allocated per active process. It contains all
* data needed about the process while the process may be swapped
* out. Other per-process data (user.h) is also inside the proc structure.
* Lightweight-process data (lwp.h) and the kernel stack may be swapped out.
typedef struct proc {
     * Fields requiring no explicit locking
    struct vnode *p_exec;
                                  /* pointer to a.out vnode */
    struct as *p_as;
                               /* process address space pointer */
    struct plock *p_lockp;
                                  /* ptr to proc struct's mutex lock */
                                  /* lock for p_cred */
    kmutex_t p_crlock;
    struct cred *p_cred;
                                 /* process credentials */
     * Fields protected by pidlock
    int p_swapcnt;
                                /* number of swapped out lwps */
                             /* status of process */
    char p_stat;
                                /* current wait code */
    char p_wcode;
    ushort_t p_pidflag;
                                 /* flags protected only by pidlock */
                              /* current wait return value */
/* process id of parent */
    int p_wdata;
    pid_t p_ppid;
                                 /* forward link */
    struct proc
                   *p_link;
                                /* ptr to parent process */
/* ptr to first child process */
    struct proc
                   *p parent;
                   *p_child;
    struct proc
                                /* ptr to next sibling proc on chain */
                   *p_sibling;
    struct proc
                   *p_sibling; /* prt to prev sibling proc on chain */
*p_sibling_ns; /* prt to siblings with new state */
    struct proc
    struct proc
                   *p child_ns; /* prt to children with new state */
    struct proc
                                 /* active chain link next */
    struct proc
                   *p_next;
                   *p_prev;
                                 /* active chain link prev */
    struct proc
                   *p_nextofkin; /* gets accounting info at exit */
    struct proc
    struct proc
                   *p_orphan;
    struct proc
                   *p_nextorph:
```

```
*p_pglink;
              /* process group hash chain link next */
             *p_ppglink; /* process group hash chain link prev */
struct proc
                          /* session information */
struct sess
             *p_sessp;
                          /* process ID info */
struct pid
             *p_pidp;
struct pid
            *p_pgidp;
                           /* process group ID info */
* Fields protected by p lock
kcondvar tp cv;
                           /* proc struct's condition variable */
kcondvar t p flag cv;
kcondvar_t p_lwpexit;
                             /* waiting for some lwp to exit */
kcondvar_t p_holdlwps;
                              /* process is waiting for its lwps */
                   /* to to be held */
                          /* unused */
ushort_t p_pad1;
uint_t p_flag;
                        /* protected while set. */
/* flags defined below */
clock_t p_utime;
                          /* user time, this process */
clock_t p_stime;
                          /* system time, this process */
                          /* sum of children's user time */
clock_t p_cutime;
clock tp cstime;
                          /* sum of children's system time */
caddr_t *p_segacct;
                           /* segment accounting info */
caddr_t p_brkbase;
                           /* base address of heap */
size_t p_brksize;
                          /* heap size in bytes */

    Per process signal stuff.

                         /* signals pending to this process */
k sigset tp sig;
k_sigset_t p_ignore;
                           /* ignore when generated */
k_sigset_t p_siginfo;
                           /* gets signal info with signal */
struct sigqueue *p_sigqueue;
                              /* queued siginfo structures */
struct sigghdr *p_sigghdr;
                             /* hdr to sigaueue structure pool */
struct sigghdr *p_signhdr;
                             /* hdr to signotify structure pool */
                          /* jobcontrol stop signal */
uchar_t p_stopsig;
```

struct proc (Solaris) (2)

```
* Special per-process flag when set will fix misaligned memory
     * references.
     char p fixalignment;
     * Per process lwp and kernel thread stuff
                               /* most recently allocated lwpid */
     id t p lwpid;
                               /* number of lwps in this process */
          p lwpcnt;
                               /* number of not stopped lwps */
/* number of lwps in lwp_wait() */
          p_lwprcnt;
          p_lwpwait;
                                /* number of zombie lwps */
          p zombcnt;
         p zomb max;
                                  /* number of entries in p zomb tid */
    id_t *p_zomb_tid;
                                  /* array of zombie lwpids */
     kthread t*p tlist;
                                /* circular list of threads */
     * /proc (process filesystem) debugger interface stuff.
     k sigset tp sigmask;
                                  /* mask of traced signals (/proc) */
     k fltset t p fltmask;
                                 /* mask of traced faults (/proc) */
    struct vnode *p_trace;
struct vnode *p_plist;
                                 /* pointer to primary /proc vnode */
/* list of /proc vnodes for process */
     kthread_t *p_agenttp;
                                   /* thread ptr for /proc agent lwp */
    struct watched_area *p_warea; /* list of watched areas */
    ulong t p nwarea;
                                  /* number of watched areas */
     struct watched page *p wpage: /* remembered watched pages
(vfork) */
                                /* number of watched pages (vfork) */
     int p_nwpage;
                               /* number of active pr_mappage()s */
/* linked list for server */
    int p_mapcnt;
     struct proc *p_rlink;
     kcondvar t p srwchan cv;
                                '* process stack size in bytes */
     size t p stksize;
     * Microstate accounting, resource usage, and real-time profiling
     hrtime t p mstart;
                                 /* hi-res process start time */
                                  /* hi-res process termination time */
     hrtime t p mterm;
```

```
/* elapsed time sum over defunct lwps */
hrtime_t p_mlreal;
hrtime_t p_acct[NMSTATES]; /* microstate sum over defunct lwps */
struct lrusage p_ru;
                          /* lrusage sum over defunct lwps */
struct itimerval p_rprof_timer; /* ITIMER_REALPROF interval timer */
                           /* ITIMER REALPROF cyclic */
uintptr_t p_rprof_cyclic;
uint t p defunct;
                         /* number of defunct lwps */
* profiling. A lock is used in the event of multiple lwp's
* using the same profiling base/size.
kmutex_t p_pflock;
                           /* protects user profile arguments */
struct prof p_prof;
                         /* profile arguments */
 * The user structure
                         /* (see sys/user.h) */
struct user p_user;
* Doors.
kthread t
                  *p server threads:
struct door node
                     *p door list: /* active doors */
struct door_node
                     *p_unref_list;
kcondvar t
                   p_server_cv;
char
                p_unref_thread; /* unref thread created */
* Kernel probes
uchar t
                 p_tnf_flags;
```

struct proc (Solaris) (3)

```
* C2 Security (C2_AUDIT)
      caddr t p audit data;
                                               /* per process audit structure */
kthread t *p_aslwptp; /* thread ptr representing "aslwp" */
#if defined(i386) || defined(_i386) || defined(_ia64)
       * LDT support.
                                              /* protects the following fields */
      kmutex_t p_ldtlock;
                                              /* Pointer to private LDT */
      struct seg_desc *p_ldt;
      struct seg_desc p_ldt_desc; /* segment descriptor for private LDT */
int p_ldtlimit; /* highest selector used */
#endif
                                          /* resident set size before last swap */
      size_t p_swrss;
      struct aio *p_aio; /* pointer to async I/O
struct itimer **p_itimer; /* interval timers */
                                           /* pointer to async I/O struct */
      k_sigset_t p_notifsigs; /* signals in notification set */
      kcondvar_t p_notificy; /* notificy to synchronize with aslwp */
timeout_id_t p_alarmid; /* alarm's timeout id */
uint_t p_sc_unblocked; /* number of unblocked threads */
struct vnode *p_sc_door; /* scheduler activations door */
                      p_usrstack; /* top of the process stack */
p_stkprot; /* stack memory protection */
      caddr t
      model t p_model; /* data model determined at exec time */
struct Iwpchan_data *p_lcp; /* lwpchan cache */
       * protects unmapping and initilization of robust locks.
      kmutex_t p_lcp_mutexinitlock;
      utrap_handler_t *p_utraps; /* pointer to user trap handlers */
refstr_t *p_corefile; /* pattern for core file */
```

```
#if defined( ia64)
    caddr t
                              /* base of the upward-growing stack */
                p_upstack;
                p upstksize; /* size of that stack, in bytes */
    size t
    uchar t
                            /* which instruction set is utilized */
                p_isa;
#endif
                           /* resource control extension data */
    void
                *p rce;
                              /* our containing task */
    struct task *p task;
    struct proc
                 *p_taskprev; /* ptr to previous process in task */
    struct proc *p_tasknext; /* ptr to next process in task */
              p_lwpdaemon; /* number of TP_DAEMON lwps */
              p_lwpdwait; /* number of daemons in lwp_wait() */
    int
    kthread t
                 **p_tidhash; /* tid (lwpid) lookup hash table */
    struct sc_data *p_schedctl; /* available schedctl structures */
} proc t;
```

Context switch

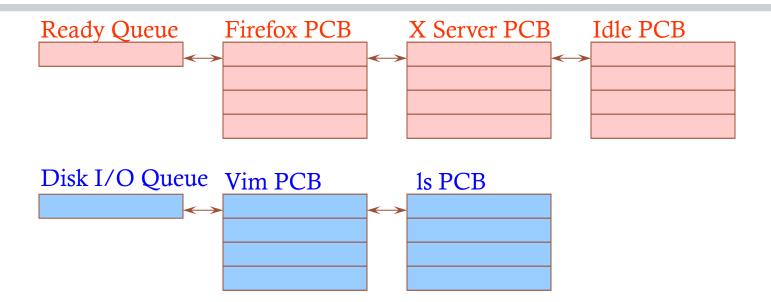
- When a process is running, its hardware state (PC, SP, regs, etc.) is in the CPU
 - The hardware registers contain the current values
- When the OS stops running a process, it saves the current values of the registers into the process' PCB
- When the OS is ready to start executing a new process, it loads the hardware registers from the values stored in that process' PCB
- The process of changing the CPU hardware state from one process to another is called a context switch
 - This can happen 100 or 1000 times a second!

State Queues

How does the OS keep track of processes?

- The OS maintains a collection of queues that represent the state of all processes in the system
- Typically, the OS has one queue for each state
 - Ready, waiting, etc.
- Each PCB is queued on a state queue according to its current state
- As a process changes state, its PCB is unlinked from one queue and linked into another

State Queues



Console Queue Sleep Queue

There may be many wait queues, one for each type of wait (disk, console, timer, network, etc.)

PCBs and State Queues

- PCBs are data structures dynamically allocated in OS memory
- When a process is created, the OS allocates a PCB for it, initializes it, and places it on the ready queue
- As the process computes, does I/O, etc., its PCB moves from one queue to another
- When the process terminates, its PCB is deallocated

Process Creation

- A process is created by another process
 - Parent is creator, child is created (Unix: ps "PPID" field)
 - What creates the first (userspace) process? (Unix: init (PID 1))
- In some systems, the parent defines (or donates) resources and privileges for its children
 - Unix: Process User ID is inherited children of your shell execute with your privileges
- After creating a child, the parent may either wait for it to finish its task or continue in parallel (or both)

Process Creation: Windows

• The system call on Windows for creating a process is called, surprisingly enough, CreateProcess:

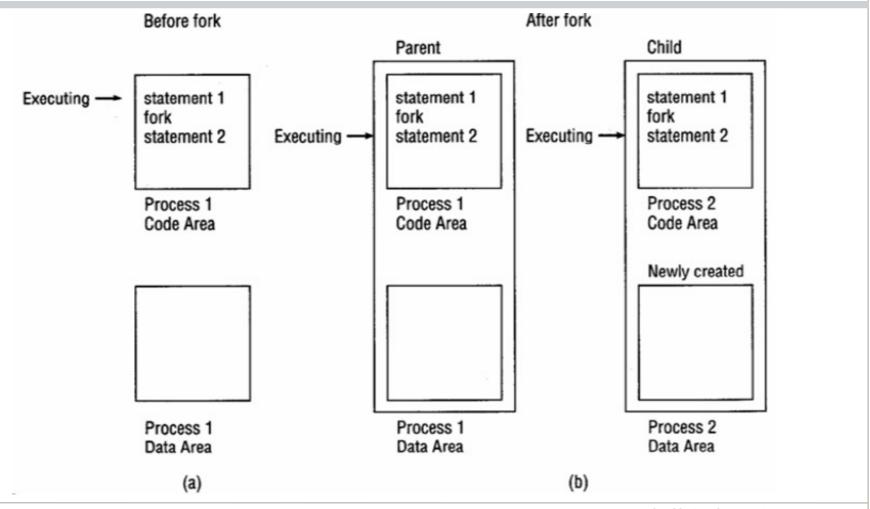
```
BOOL CreateProcess(char *prog, ....) (simplified)
```

- CreateProcess
 - Creates and initializes a new PCB
 - Creates and initializes a new address space
 - Loads the program specified by "prog" into the address space
 - Initializes the hardware context to start execution at main (or wherever specified in the file)
 - Places the PCB on the ready queue

Process Creation: Unix

- In Unix, processes are created using fork()
 int fork (void)
- fork (void)
 - Creates and initializes a new PCB
 - Creates a new address space
 - Initializes the address space with a **copy** of the entire contents of the address space of the parent
 - Initializes the kernel resources to point to the resources used by parent (e.g., open files)
 - Places the PCB on the ready queue
- Fork returns twice
 - Returns the child's PID to the parent, "0" to the child
 - Huh?

fork() semantics



fork()

```
int main(int argc, char *argv[])
{
    char *name = argv[0];
    int child_pid = fork();
    if (child_pid == 0) {
        printf("Child of %s is %d\n", name, getpid());
        return 0;
    } else {
        printf("My child is %d\n", child_pid);
        return 0;
    }
}
```

What does this program print?

Example Output

My child is 486

Child of a out is 486

Duplicating Address Spaces

Parent

Child

Divergence

```
child_pid = 486

child_pid = fork();

if (child_pid == 0) {
    printf("child");
} else {
    printf("parent");
}
PC → PC
printf("parent");
}
```

Parent

Child

Example Continued

> a.out

My child is 486

Child of a out is 486

> a.out

Child of a out is 498

My child is 498

Why is the output in a different order?

Why fork()?

- Very useful when the child...
 - Is cooperating with the parent
 - Relies upon the parent's data to accomplish its task

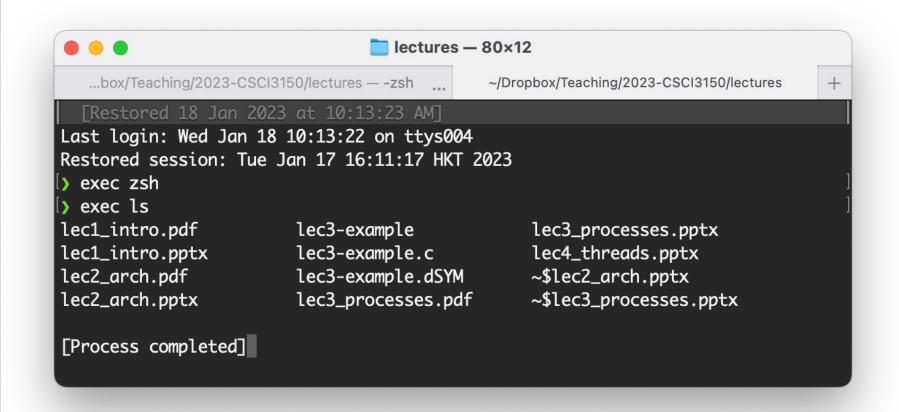
```
• Example: Web server
while (1) {
  int sock = accept();
  if ((child_pid = fork()) == 0) {
    Handle client request
  }
}
```

Process Creation: Unix (2)

- Wait a second. How do we actually start a new program? int exec(char *prog, char *argv[])
- exec()
 - Stops the current process
 - Loads the program "prog" into the process' address space
 - Initializes hardware context and args for the new program
 - Places the PCB onto the ready queue
 - Note: It does not create a new process
- What does it mean for exec to return?
- What does it mean for exec to return with an error?

Process Creation: Unix (3)

- fork() is used to create a new process, exec is used to load a program into the address space
- What happens if you run "exec csh" in your shell?
- What happens if you run "exec ls" in your shell? Try it.
- fork() can return an error. Why might this happen?
 - Cannot create child process (return to parent).



Process Creation: fork or not?

- Why does Windows have CreateProcess while Unix uses fork/exec?
 - Comparing fork() and CreateProcess()?
 - Which is more convenient to use?
 - Which is more efficient?

A fork() in the road

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Orran Krieger Boston University Timothy Roscoe
ETH Zurich

Process Termination

- All good processes must come to an end. But how?
 - Unix: exit(int status), Windows: ExitProcess(int status)
- Essentially, free resources and terminate
 - Terminate all threads (next lecture)
 - Close open files, network connections
 - Allocated memory (and VM pages out on disk)
 - Remove PCB from kernel data structures, delete
- Note that a process does not need to clean up itself
 - Why does the OS have to do it?

Process Termination

- When exit() is called on Unix:
 - Threads are terminated (next lec.)
 - Open files, network connections are closed
 - Address space is de-allocated
 - But the PCB still remains in the Process Table
- Only a parent can remove the PCB
 - Thus completely terminate the process (called reap)
- Died but not yet reaped process is called a zombie

wait() a second...

- Often it is convenient to pause until a child process has finished
 - Think of executing commands in a shell
- Use wait() (WaitForSingleObject)
 - Suspends the current process until a child process ends
 - waitpid() suspends until the specified child process ends
- Unix: Every process must be reaped by a parent
 - What happens if a parent process exits before a child?
 - What do you think a "zombie" process is?

Unix Shells

Process Summary

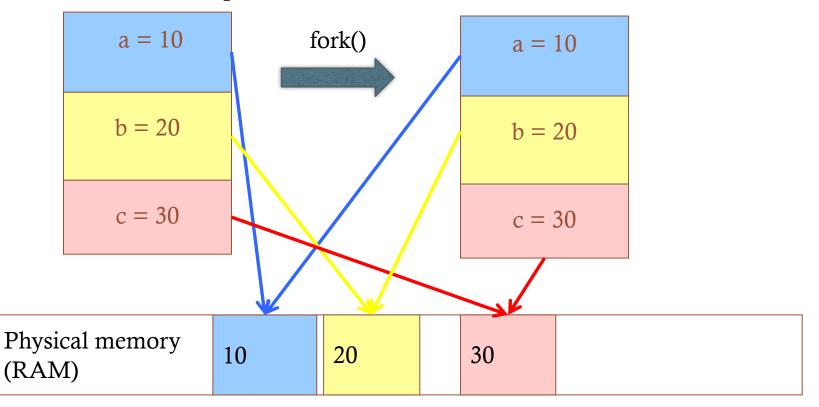
- What are the units of execution?
 - Processes
- How are those units of execution represented?
 - Process Control Blocks (PCBs)
- How is work scheduled in the CPU?
 - Process states, process queues, context switches
- What are the possible execution states of a process?
 - Running, ready, waiting
- How does a process move from one state to another?
 - Scheduling, I/O, creation, termination
- How are processes created?
 - CreateProcess (Windows), fork/exec (Unix)

Copy-On-Write

• *Lazy* copy

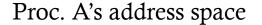
Proc. A's address space

Proc. B's address space



Copy-On-Write

• *Lazy* copy



Proc. B's address space

