Survey on Development Practices and Challenges in Robotic Software Engineering

*Required

Instructions and Disclaimer

Are you an industrial practitioner in robotics? We know that software is becoming increasingly important for the robotics domain. However, researchers have a lack of knowledge on how you develop software for robotics and what challenges you face.

The whole questionnaire takes approximately 15 minutes. It elicits industrial engineering practices and challenges. Thank you for your participation.

Robotic platforms and context

| TICK | ch types of robots are used in your projects? * all that apply. |
|------|--|
| | Mobile robots (i.e., ground robots with navigation capabilities) |
| | Mobile manipulators (i.e., mobile robots with manipulation capabilities) |
| | Humanoid robots (i.e., a robot with its body shape built to resemble the human body) |
| huma | Collaborative robots (i.e., robots that are able through some mechanism to collaborate with ans or other robots) |
| | Drones |
| | Underwater robots |
| | Industrial arms |
| | Other: |
| | |
| | ch is the application field of your projects? * all that apply. |
| | |
| | all that apply. |
| | Factory automation |
| | Agriculture |
| | Agriculture Cleaning |
| | Factory automation Agriculture Cleaning Transportation |
| | Factory automation Agriculture Cleaning Transportation Medical |

| Low-level functionalities Planning and orchestra Complete robotic syste Other: tivities and Paradi | tion modul | les | | | | |
|--|--------------|------------------|------------------|----------------|---------------|---------------|
| Planning and orchestra Complete robotic syste Other: | tion modul | les | | | | |
| Complete robotic syste Other: | m (e.g., B0 | | mower) | | | |
| Other: | | OSCH'S lawn | mower) | | | |
| Other: | | | | | | |
| tivities and Paradi | | | | | | |
| Which activities are perform | | ur projects? | * | | | |
| Mark only one oval per row. | | | | | | |
| | 0 (never) | 1 (almost never) | 2 (sometimes) | 3 (very often) | 4 (always) | Doi kno |
| Project management | | | | | | |
| Requirements engineering | | | | | | |
| Architectural and detailed design | | | | | | |
| Implementation (i.e., writing code) | | | | | | |
| Automatic code generation | | | | | | |
| Testing and simulation | | | | | | |
| Real-world | | | | | | |
| experimentation Software | | | | | | $\overline{}$ |
| maintenance/evolution | | | | | | |
| Other (please specify) | | | | | | |
| If applicable, please specify "Other": Which tools do you use for management" in your projection of example, Jira, Excel, Treshouse tool, | r "Project | | | | | |
| Which tools do you use for engineering" in your projec | | | | | | |

| 9. | Which tools do you use fo in your projects? For example, Eclipse, Intellic Sublime, QT-creator, in-house | I, Visual St | | | | | |
|-----|---|-----------------------------------|------------------|------------------|----------------|---------------|---------------|
| 10. | Which tools/languages do "Automatic code generation projects? | | | | | | |
| | For example, Xtend, Xpand, house tool/language, | Acceleo, N | /latlab, in- | | | | |
| 11. | Which tools do you use fo simulation" in your project | ts? | | | | | |
| | For example, JUnit, Gazebo Mindstorms, in-house tool, | | LEGO | | | | |
| 12. | Which tools do you use fo experimentation" in your profession for example, rosbag, roslau multimaster_fkie, in-house to | rojects? | orld | | | | |
| 13. | Which tools do you use for maintenance/evolution" in For example, Eclipse, Intellic Sublime, QT-creator, in-house | your proje I, Visual St | ects? | | | | |
| 14. | Which software developmed Mark only one oval per row. | ent paradi | gms are app | lied in your pro | ojects? * | | |
| | | 0 (never) | 1 (almost never) | 2 (sometimes) | 3 (very often) | 4 (always) | Don't know |
| | Object-oriented | | | | | | |
| | programming Functional programming | | | | | | |
| | Component-based | | | | | | |
| | software engineering Model-based software | | | | | | |
| | development | | | | | | |
| | Software product line engineering | | | | | | |
| | Other (please specify) | | | | | | |
| 15. | If applicable, please specif "Other": | y your ans | swer for | | | | |

Development practices

Other:

| 16. Which of these software e | engineering processes de | o you apply in your | projects? * |
|-------------------------------|--------------------------|---------------------|-------------|
| Mark only one oval per row | | | |

| | 0 (never) | 1 (almost never) | 2 (sometimes) | 3 (very often) | 4 (always) | Don' knov |
|---|--------------|------------------|------------------|----------------|---------------|--------------|
| Waterfall | | | | | | |
| Hybrid (e.g., V-Model, Spiral) | | | | | | |
| Agile (e.g., SCRUM, Extreme Programming |) | | | | | |
| Other (please specify below) | | | | | | |
| If applicable, please spe "Other": | ecify your a | nswer for | | | | |
| Which of these software A Domain Specific Langu domain. Mark only one oval per ro | age (DSL) is | - | | | particular ap | olicatio |
| wark only one oval per ro | 0 (never) | 1 (almost never) | 2 (sometimes) | 3 (very often) | 4 (always) | Don' |
| Java | | | | | | |
| С | | | | | | |
| C++ | | | | | | |
| Python | | | | | | |
| UML | | | | | | |
| MATLAB / Simulink | | | | | | |
| Self-developed DSLs | | | | | | |
| Third-party DSLs | | | | | | |
| Other (please specify below) | | | | | | |
| If applicable, please spe "Other": | ecify your a | nswer for | | | | |
| Which of these robotic to Tick all that apply. | frameworks | s do you use | in your projects | s? * | | |
| ROS 2.0 | | | | | | |
| OROCOS | | | | | | |
| SmartSoft | | | | | | |
| | | | | | | |

| Proprietary | | | | | | |
|---|--|---|------------------------------------|------------------|----------------|---------------|
| Open source | | | | | | |
| Don't know | | | | | | |
| | | | | | | |
| Other: | | | | | | |
| Under which license do | you relea | se your own | software? * | | | |
| Proprietary | | | | | | |
| Open source | | | | | | |
| Don't know | | | | | | |
| Other: | | | | | | |
| Mark only one oval per re | 0 | 1 (almost | 2 | 3 (very | 4 | Don'i |
| Carranada | (never) | never) | (sometimes) | often) | (always) | know |
| Source code Configuration files | | | | | | \rightarrow |
| Software models | | | | | | |
| Libraries (source or binaries) | | | | | | |
| Software components | | | | | | |
| | | | | | | |
| | | | () | | | |
| Test cases | | | | | | |
| binaries) Software components Documentation | | | | | | |
| Other (please specify below) If applicable, please sp "Other": | ed a softwa | are compone | | | an reusing a | an |
| Other (please specify below) If applicable, please sp "Other": | ed a softwa veloped or by and past | are compone third-party) of te" style reuse | one? If yes, why and systematic | /? reuse (e.g | ., creating sh | |

| Tick all that apply. | | | | | | |
|---|----------------------------|------------------|------------------|----------------|---------------|---------------|
| Copy-paste-modify | | | | | | |
| Systematic reuse (e.g. | frameworl | ks componer | nts libraries) | | | |
| | , namowon | ito, componer | 110, 110101100,) | | | |
| Both equally | | | | | | |
| 27. Which mechanisms to faci projects? Leave empty if r Tick all that apply. | | operability a | mong compon | ents are a | applied in y | our |
| We rely on the experie | ence and sk | ills of our tea | m | | | |
| We follow a precise are | | | | | | |
| | | • | | | | |
| We have a clear definition | | | component | | | |
| We follow a standard (| please spe | cify below) | | | | |
| Other (please specify b | below) | | | | | |
| 28. If applicable, please specir "We follow a standard " / " | | swer for | | | | |
| Quality Assurance 29. Which kind of quality assu | | nniques do y | ou perform in y | your proje | ects? * | |
| Mark only one oval per row. | | | | | | |
| iviai k olily olie oval per fow. | 0 (never) | 1 (almost never) | 2 (sometimes) | 3 (very often) | 4 (always) | Don't know |
| Unit testing | 0 | , | - | | | |
| | 0 | , | - | | | |
| Unit testing | 0 | , | - | | | |
| Unit testing Integration testing Performance testing Code reviews | 0 | , | - | | | |
| Unit testing Integration testing Performance testing Code reviews Formal methods (please | 0 | , | - | | | |
| Unit testing Integration testing Performance testing Code reviews | 0 | , | - | | | |
| Unit testing Integration testing Performance testing Code reviews Formal methods (please specify below) | 0 | , | - | | | |
| Unit testing Integration testing Performance testing Code reviews Formal methods (please specify below) Other (please specify below) 30. If applicable, please specify below) 31. From where do you get test Tick all that apply. Manual specification be | o (never) fy your ans r": | never) | (sometimes) | | | |
| Unit testing Integration testing Performance testing Code reviews Formal methods (please specify below) Other (please specify below) 30. If applicable, please specify below) "Formal methods" / "Other "It was a specify below of the specify below" of the specify below of the specify | o (never) fy your ans r": | never) | (sometimes) | | | |
| Unit testing Integration testing Performance testing Code reviews Formal methods (please specify below) Other (please specify below) 30. If applicable, please specify below) 31. From where do you get test Tick all that apply. Manual specification be | o (never) fy your ans r": | never) | (sometimes) | | | |
| Unit testing Integration testing Performance testing Code reviews Formal methods (please specify below) Other (please specify below) 30. If applicable, please specify below) 31. From where do you get test Tick all that apply. Manual specification be Simulation | o (never) fy your ans r": | never) | (sometimes) | | | |
| Unit testing Integration testing Performance testing Code reviews Formal methods (please specify below) Other (please specify below) 30. If applicable, please specify "Formal methods" / "Other "Formal methods" / "Other 31. From where do you get test Tick all that apply. Manual specification be Simulation Runtime monitoring | o (never) fy your ans r": | never) | (sometimes) | | | |

| lission Specificatio | n | | | | | |
|---|-----------------------------------|--------------------------------------|------------------|---------------|--------------------------------|----------------------------|
| mission is a kind of functional r | equiremen | | | | | For |
| xample: "A robot must go the ki | tchen, grat | a cup of cof | fee and go back | to the office | ce". | |
| 33. Who specifies missions fo | r robots ir | your projec | cts? * | | | |
| Tick all that apply. | | | | | | |
| Developer | | | | | | |
| Non-technical end-use | r | | | | | |
| Technically skilled end | -user | | | | | |
| Integrator | | | | | | |
| Don't know | | | | | | |
| Don't know | | | | | | |
| | | | | | | |
| Other: | | | | | | |
| | | | | | | |
| 34. Which mission specification | | - | | | articular anr | olication |
| 34. Which mission specification A Domain Specific Language domain. In this case, mission | e (DSL) is | a computer la | | | articular app | olication |
| 34. Which mission specification A Domain Specific Language | e (DSL) is | a computer la | | | articular app | olication |
| 34. Which mission specification A Domain Specific Language domain. In this case, mission | e (DSL) is | a computer la | | | articular app 4 (always) | olication Don't know |
| A Domain Specific Language domain. In this case, mission Mark only one oval per row. Hard-coded (in the used | e (DSL) is a n specificat 0 | a computer la ion. 1 (almost | inguage speciali | ized to a pa | 4 | Don't |
| A Domain Specific Language domain. In this case, mission Mark only one oval per row. Hard-coded (in the used programming language, | e (DSL) is a n specificat 0 | a computer la ion. 1 (almost | inguage speciali | ized to a pa | 4 | Don't |
| A Domain Specific Language domain. In this case, mission Mark only one oval per row. Hard-coded (in the used programming language, XML file, etc) Use of logical language | e (DSL) is a n specificat 0 | a computer la ion. 1 (almost | inguage speciali | ized to a pa | 4 | Don't |
| A Domain Specific Language domain. In this case, mission Mark only one oval per row. Hard-coded (in the used programming language, XML file, etc) Use of logical language (e.g., LTL, CTL) | e (DSL) is a n specificat 0 | a computer la ion. 1 (almost | inguage speciali | ized to a pa | 4 | Don't |
| A Domain Specific Language domain. In this case, mission Mark only one oval per row. Hard-coded (in the used programming language, XML file, etc) Use of logical language (e.g., LTL, CTL) Use of a third-party DSL | e (DSL) is a n specificat 0 | a computer la ion. 1 (almost | inguage speciali | ized to a pa | 4 | Don't |
| A Domain Specific Language domain. In this case, mission Mark only one oval per row. Hard-coded (in the used programming language, XML file, etc) Use of logical language (e.g., LTL, CTL) | e (DSL) is a n specificat 0 | a computer la ion. 1 (almost | inguage speciali | ized to a pa | 4 | Don't |
| A Domain Specific Language domain. In this case, mission Mark only one oval per row. Hard-coded (in the used programming language, XML file, etc) Use of logical language (e.g., LTL, CTL) Use of a third-party DSL Use of an own DSL | e (DSL) is a n specificat 0 | a computer la ion. 1 (almost | inguage speciali | ized to a pa | 4 | Don't |
| A Domain Specific Language domain. In this case, mission Mark only one oval per row. Hard-coded (in the used programming language, XML file, etc) Use of logical language (e.g., LTL, CTL) Use of a third-party DSL Use of an own DSL Other (please specify) | o (never) | a computer la ion. 1 (almost never) | inguage speciali | ized to a pa | 4 | Don't |
| A Domain Specific Language domain. In this case, mission Mark only one oval per row. Hard-coded (in the used programming language, XML file, etc) Use of logical language (e.g., LTL, CTL) Use of a third-party DSL Use of an own DSL Other (please specify) | o (never) | a computer la ion. 1 (almost never) | inguage speciali | ized to a pa | 4 | Don't |

Challenges and solutions

36. For the following items, to which extent do you agree that they describe a challenge in your projects? A challenge is a task that makes the development difficult. *

| Mark only | one | oval | per | row. |
|-----------|-----|------|-----|------|
|-----------|-----|------|-----|------|

| Specifying missions for robots Software reuse Lack of documentation Lack of standards Interoperability among heterogeneous components Validating the robotic system Safety certification Robustness Dynamic adaptation of robotic behavior Transition from simulation to real world applications Applying artificial intelligence techniques Other (please specify below) 7. If applicable, please specify your answer for "Other": 8. For the encountered challenges, which solutions do you apply to address them? Please, specify solutions together with the challenges they address. * | Software reuse Lack of documentation Lack of standards Interoperability among heterogeneous components Validating the robotic system Safety certification Robustness Dynamic adaptation of robotic behavior Transition from simulation to real world applications Applying artificial intelligence techniques Other (please specify below) 7. If applicable, please specify your answer for "Other": | | 0 (strongly disagree) | 1 (disagree) | 2 (neutral) | 3 (agree) | 4 (strongly agree) | Don' knov |
|---|---|--|-----------------------|---------------------------|------------------------|--------------|--------------------------|--------------|
| Lack of documentation Lack of standards Interoperability among heterogeneous components Validating the robotic system Safety certification Robustness Dynamic adaptation of robotic behavior Transition from simulation to real world applications Applying artificial intelligence techniques Other (please specify below) 7. If applicable, please specify your answer for "Other": | Lack of documentation Lack of standards Interoperability among heterogeneous components Validating the robotic system Safety certification Robustness Dynamic adaptation of robotic behavior Transition from simulation to real world applications Applying artificial intelligence techniques Other (please specify below) 7. If applicable, please specify your answer for "Other": | | | | | | | |
| Lack of standards Interoperability among heterogeneous components Validating the robotic system Safety certification Robustness Dynamic adaptation of robotic behavior Transition from simulation to real world applications Applying artificial intelligence techniques Other (please specify below) 7. If applicable, please specify your answer for "Other": | Lack of standards Interoperability among heterogeneous components Validating the robotic system Safety certification Robustness Dynamic adaptation of robotic behavior Transition from simulation to real world applications Applying artificial intelligence techniques Other (please specify below) 7. If applicable, please specify your answer for "Other": | Software reuse | | | | | | |
| Interoperability among heterogeneous components Validating the robotic system Safety certification Robustness Dynamic adaptation of robotic behavior Transition from simulation to real world applications Applying artificial intelligence techniques Other (please specify below) 7. If applicable, please specify your answer for "Other": | Interoperability among heterogeneous components Validating the robotic system Safety certification Robustness Dynamic adaptation of robotic behavior Transition from simulation to real world applications Applying artificial intelligence techniques Other (please specify below) 7. If applicable, please specify your answer for "Other": | Lack of documentation | | | | | | |
| heterogeneous components Validating the robotic system Safety certification Robustness Dynamic adaptation of robotic behavior Transition from simulation to real world applications Applying artificial intelligence techniques Other (please specify below) 7. If applicable, please specify your answer for "Other": | heterogeneous components Validating the robotic system Safety certification Robustness Dynamic adaptation of robotic behavior Transition from simulation to real world applications Applying artificial intelligence techniques Other (please specify below) 7. If applicable, please specify your answer for "Other": | Lack of standards | | | | | | |
| Validating the robotic system Safety certification Robustness Dynamic adaptation of robotic behavior Transition from simulation to real world applications Applying artificial intelligence techniques Other (please specify below) 7. If applicable, please specify your answer for "Other": | Validating the robotic system Safety certification Robustness Dynamic adaptation of robotic behavior Transition from simulation to real world applications Applying artificial intelligence techniques Other (please specify below) 7. If applicable, please specify your answer for "Other": | heterogeneous | | | | | | |
| Robustness Dynamic adaptation of robotic behavior Transition from simulation to real world applications Applying artificial intelligence techniques Other (please specify below) 7. If applicable, please specify your answer for "Other": | Robustness Dynamic adaptation of robotic behavior Transition from simulation to real world applications Applying artificial intelligence techniques Other (please specify below) 7. If applicable, please specify your answer for "Other": | Validating the robotic | | | | | | |
| Dynamic adaptation of robotic behavior Transition from simulation to real world applications Applying artificial intelligence techniques Other (please specify below) 7. If applicable, please specify your answer for "Other": | Dynamic adaptation of robotic behavior Transition from simulation to real world applications Applying artificial intelligence techniques Other (please specify below) 7. If applicable, please specify your answer for "Other": | • | | | | | | |
| Transition from simulation to real world applications Applying artificial intelligence techniques Other (please specify below) 7. If applicable, please specify your answer for "Other": | Transition from simulation to real world applications Applying artificial intelligence techniques Other (please specify below) 7. If applicable, please specify your answer for "Other": | Robustness | | | | | | |
| simulation to real world applications Applying artificial intelligence techniques Other (please specify below) If applicable, please specify your answer for "Other": | simulation to real world applications Applying artificial intelligence techniques Other (please specify below) If applicable, please specify your answer for "Other": | robotic behavior | | | | | | |
| Other (please specify below) 7. If applicable, please specify your answer for "Other": 8. For the encountered challenges, which solutions do you apply to address them? Please, | Other (please specify below) 7. If applicable, please specify your answer for "Other": 8. For the encountered challenges, which solutions do you apply to address them? Please, | simulation to real world | | | | | | |
| 2. If applicable, please specify your answer for "Other": 3. For the encountered challenges, which solutions do you apply to address them? Please, | 2. If applicable, please specify your answer for "Other": 3. For the encountered challenges, which solutions do you apply to address them? Please, | intelligence techniques | | | | | | |
| 7. If applicable, please specify your answer for "Other": | 7. If applicable, please specify your answer for "Other": | | | | | | | |
| | | . For the encountered challe specify solutions together | enges, which s | solutions do enges they a | you apply ddress. * | to addres | ss them? Pl | ease, |
| | | | | | | | | |
| | | . Is there something you wo software engineering? | ould like to add | d regarding t | ne biggest | challeng | es in roboti | cs |
| | | | | | | | | |
| | | | | | | | | |
| Is there something you would like to add regarding the biggest challenges in robotics software engineering? | | | | | | | | |

General perception

|). How d | lo you think robotics software engineering differs from software engineering in other ins? * |
|----------------------|---|
| | |
| | |
| | u think the practices applied in robotics software engineering should change? If yes, at way? |
| | |
| | |
| | part: Participant background |
| put your ckground | r responses into context, we would appreciate if you could provide us with a bit of your d. |
| | |
| emog | graphics |
| | |
| | is your occupation? only one oval. |
| | Industrial practitioner: Programmer |
| | Industrial practitioner: Leading Technical Role |
| | |
| | Academic/Scientist |
| | Other: |
| | ow long have you been working in cs? Please specify the time in years. |
| | |
| | ich gender identity do you most identify? only one oval. |
| iviai K C | |
| | Female |
| | Male |
| | Diverse |
| | Prefer not to say |
| () | Other: |

| Mark only one | ze of your company? | |
|----------------------------------|---|----------------------------|
| Mark only one | oval. | |
| 1-10 | | |
| 11-30 | | |
| 31-50 | | |
| +50 | | |
| 6. Contact info i | mation | |
| To receive the email address | study results, please enter your | |
| | ct you via this email address for clarification | s and follow-up questions? |
| 7 Can we conta | | o una ronon ap quocnono. |
| 7. Can we conta Mark only one | Uvai. | |
| | ovai. | |

Powered by

