

## Solving Kinematic Equations for $\theta$

We are trying to aim a projectile at a target. Assume we are in 2 dimensional space (higher dimensional cases can be simplified to the 2 dimensional one.) Then let  $\langle 0, 0 \rangle$  be the initial position of the projectile and let  $\mathbf{x}_t = \langle x_t, y_t \rangle \in [0, \infty)^2$  be the position of the target. The projectile has a launch speed of  $v_i \in \mathbb{R}^{>0}$ , and the acceleration due to gravity is  $a \in \mathbb{R}^{>0}$ . The projectile is launched at some angle  $\theta \in [0, \frac{\pi}{2}]$ . Let  $\mathbf{x}_\theta(t) : [0, \infty) \rightarrow \mathbb{R}^2$  be the path of the projectile. We want the largest theta such that there exists a  $t : \mathbf{x}_\theta(t) = \mathbf{x}_t$ .

The equation for  $\mathbf{x}_\theta(t)$  is below:

$$\mathbf{x}_\theta(t) = \left\langle v_i t \cos \theta, -\frac{a}{2}t^2 + v_i t \sin \theta \right\rangle$$

Letting  $\mathbf{x}_\theta(t) = \mathbf{x}_t$ :

$$\langle x_t, y_t \rangle = \left\langle v_i t \cos \theta, -\frac{a}{2}t^2 + v_i t \sin \theta \right\rangle$$

This gives us two equations. Our two unknowns are  $t$  and  $\theta$ , but we only care about  $\theta$ . So, let's write  $t$  in terms of  $\theta$  using the first equation:

$$t = \frac{x_t}{v_i \cos \theta}$$

Therefore,

$$\begin{aligned} y_t &= -\frac{a}{2} \left( \frac{x_t}{v_i \cos \theta} \right)^2 + x_t \tan \theta \\ y_t \cos^2 \theta &= -\frac{a}{2} \left( \frac{x_t^2}{v_i^2} \right) + x_t \sin \theta \cos \theta \\ y_t \cos^2 \theta - x_t \sin \theta \cos \theta + \frac{ax_t^2}{2v_i^2} &= 0 \end{aligned}$$

Let  $C = \frac{ax_t^2}{2v_i^2}$ . Then the desired value of  $\theta$  is a root of  $f$ , where

$$f(\theta) = y_t \cos^2 \theta - x_t \sin \theta \cos \theta + C$$

## Finding a root

We can approximate the above equation using Taylor polynomials:

$$\begin{aligned} f(\theta) &\approx y_t \left( 1 - \frac{\theta^2}{2} \right)^2 - x_t \theta \left( 1 - \frac{\theta^2}{2} \right) + C \\ &= \frac{y_t}{4} \theta^4 + \frac{x_t}{2} \theta^3 - y_t \theta^2 - x_t \theta + (y_t + C) \end{aligned}$$

This is a quartic equation, which has calculatable roots. We can then use the largest root in  $[0, \frac{\pi}{2}]$  as a guess for the root of  $f$  and use Newton's method to find an approximation within the requested tolerance. If a root is found, we have our angle. If no root is found, the target must be out of range. Either way, we are done.