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# TensorKit.jl
# Main file for module TensorKit, a Julia package for working with
# with tensors, tensor operations and tensor factorizations
module TensorKit
# Exports
# Types:
export Sector, Irrep, FusionStyle, BraidingStyle
export Abelian, NonAbelian, SimpleNonAbelian, DegenerateNonAbelian,
        SymmetricBraiding, Bosonic, Fermionic, Anyonic # sector properties
export Parity, ZNIrrep, U1Irrep, SU2Irrep, CU1Irrep
        #FermionParity, FermionNumber, FermionSpin # specific sectors
export FibonacciAnyon
export VectorSpace, Field, ElementarySpace, InnerProductSpace, EuclideanSpace #
    abstract vector spaces
export ComplexSpace, CartesianSpace, GeneralSpace, RepresentationSpace, ZNSpace,
    Rep # concrete spaces
export Z2Space, Z3Space, Z4Space, U1Space, CU1Space, SU2Space
export CompositeSpace, ProductSpace # composite spaces
export FusionTree
export IndexSpace, TensorSpace, AbstractTensorMap, AbstractTensor, TensorMap,
    Tensor # tensors and tensor properties
export TruncationScheme
export SpaceMismatch, SectorMismatch, IndexError # error types
# general vector space methods
export space, field, dual, dim, dims, fuse, flip, isdual
# partial order for vector spaces
export infinum, supremum, isisomorphic, ismonomorphic, isepimorphic
# methods for sectors and properties thereof
export sectortype, sectors, hassector, Nsymbol, Fsymbol, Rsymbol, Bsymbol,
        frobeniusschur, twist
export Trivial, ZNSpace, SU2Irrep, U1Irrep, CU1Irrep # Fermion
export fusiontrees, braid, permute#, artin_braid, repartition, insertat, merge
# some unicode
export ⊕, ⊗, ×, ℂ, ℝ, ←, →, ≾, ≿, ≅, ≺, ≻
export \mathbb{Z}_2, \mathbb{Z}_3, \mathbb{Z}_4, U_1, SU_2, CU_1
export \mathbb{Z}_2Space, \mathbb{Z}_3Space, \mathbb{Z}_4Space, \mathbb{U}_1Space, \mathbb{U}_1Space, \mathbb{S}\mathbb{U}_2Space
# tensor maps
export domain, codomain, numind, numout, numin, spacetype, storagetype, eltype
export blocksectors, blockdim, block, blocks
# random methods for constructor
export randuniform, randnormal, randisometry, randhaar
# special purpose constructors
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  export zero, one, one!, id, isomorphism, unitary, isometry
  # tensor algebra and factorizations
  export dot, norm, normalize, normalize!, tr
  export mul!, lmul!, rmul!, adjoint!, pinv, axpy!, axpby!
  export leftorth, rightorth, leftnull, rightnull,
          leftorth!, rightorth!, leftnull!, rightnull!,
          tsvd!, tsvd, eigen, eigen!, eig, eig!, eigh, eigh!, exp, exp!,
          isposdef, isposdef!, ishermitian, sylvester
  export braid!, permute!, transpose, transpose!, twist!
  export catdomain, catcodomain
  export OrthogonalFactorizationAlgorithm, QR, QRpos, QL, QLpos, LQ, LQpos, RQ,
  RQpos,
          SVD, SDD, Polar
  # tensor operations
  export @tensor, @tensoropt, @ncon, ncon
  export scalar, add!, contract!
  # truncation schemes
  export notrunc, truncerr, truncdim, truncspace, truncbelow
  # Imports
  #----
  using TupleTools
  using TupleTools: StaticLength
  using Strided
  using TensorOperations: TensorOperations, @tensor, @tensoropt
  const T0 = TensorOperations
  using LRUCache
  using HalfIntegers
  using WignerSymbols
  using Base: @boundscheck, @propagate_inbounds, OneTo, tail, front,
               tuple_type_head, tuple_type_tail, tuple_type_cons,
              SizeUnknown, HasLength, HasShape, IsInfinite, EltypeUnknown, HasEltype
  using Base.Iterators: product, filter
  import LinearAlgebra
  using LinearAlgebra: norm, dot, normalize, normalize!, tr,
                           axpy!, axpby!, lmul!, rmul!, mul!,
                           adjoint, adjoint!, transpose, transpose!,
                           pinv, sylvester,
                           eigen, eigen!, svd, svd!,
                           isposdef, isposdef!, ishermitian,
                           Diagonal, Hermitian
  import Base.Meta
  const IndexTuple{N} = NTuple{N,Int}
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# Auxiliary files
include("auxiliary/auxiliary.jl")
include("auxiliary/dicts.jl")
include("auxiliary/linalg.jl")
include("auxiliary/random.jl")
# experiment with different dictionaries
const SectorDict{K,V} = SortedVectorDict{K,V}
const FusionTreeDict{K,V} = Dict{K,V}
# Exception types:
abstract type TensorException <: Exception end</pre>
# Exception type for all errors related to sector mismatch
struct SectorMismatch{S<:Union{Nothing,String}} <: TensorException</pre>
    message::S
SectorMismatch()=SectorMismatch{Nothing}(nothing)
Base.show(io::I0, ::SectorMismatch(Nothing)) = print(io, "SectorMismatch()")
Base.show(io::I0, e::SectorMismatch) = print(io, "SectorMismatch(", e.message, ")")
# Exception type for all errors related to vector space mismatch
struct SpaceMismatch{S<:Union{Nothing,String}} <: TensorException</pre>
    message::S
end
SpaceMismatch()=SpaceMismatch{Nothing}(nothing)
Base.show(io::I0, ::SpaceMismatch(Nothing)) = print(io, "SpaceMismatch()")
Base.show(io::I0, e::SpaceMismatch) = print(io, "SpaceMismatch(", e.message, ")")
# Exception type for all errors related to invalid tensor index specification.
struct IndexError{S<:Union{Nothing,String}} <: TensorException</pre>
    message::S
end
IndexError() = IndexError{Nothing}(nothing)
Base.show(io::I0, ::IndexError{Nothing}) = print(io, "IndexError()")
Base.show(io::I0, e::IndexError) = print(io, "IndexError(", e.message, ")")
# Definitions and methods for superselection sectors (quantum numbers)
include("sectors/sectors.jl")
# Constructing and manipulating fusion trees and iterators thereof
include("fusiontrees/fusiontrees.jl")
# Definitions and methods for vector spaces
include("spaces/vectorspaces.jl")
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# # Definitions and methods for tensors
# #------
# # general definitions
include("tensors/abstracttensor.jl")
include("tensors/tensortreeiterator.jl")
include("tensors/tensor.jl")
include("tensors/adjoint.jl")
include("tensors/linalg.jl")
include("tensors/tensoroperations.jl")
include("tensors/indexmanipulations.jl")
include("tensors/truncation.jl")
include("tensors/factorizations.jl")
```