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# AdjointTensorMap: lazy adjoint
#=====#
"""
    struct AdjointTensorMap{S<:IndexSpace, N1, N2, ...} <: AbstractTensorMap{S,
N1, N2}

Specific subtype of [AbstractTensorMap](@ref) that is a lazy wrapper for
representing the
adjoint of an instance of [TensorMap](@ref).
"""

struct AdjointTensorMap{S<:IndexSpace, N1, N2, G<:Sector, A, F1, F2} <:
    AbstractTensorMap{S,
N1, N2}
    parent::TensorMap{S,N2,N1,G,A,F2,F1}
end

const AdjointTrivialTensorMap{S<:IndexSpace, N1, N2, A<:DenseMatrix} =
    AdjointTensorMap{S, N1, N2, Trivial, A, Nothing, Nothing}

# Constructor: construct from taking adjoint of a tensor
Base.adjoint(t::TensorMap) = AdjointTensorMap(t)
Base.adjoint(t::AdjointTensorMap) = t.parent

# Properties
codomain(t::AdjointTensorMap) = domain(t.parent)
domain(t::AdjointTensorMap) = codomain(t.parent)

blocksectors(t::AdjointTensorMap) = blocksectors(t.parent)

Base.@pure storagetype(::Type{<:AdjointTensorMap{<:IndexSpace,N1,N2,Trivial,A}})
where {N1,N2,A<:DenseMatrix} = A
Base.@pure
storagetype(::Type{<:AdjointTensorMap{<:IndexSpace,N1,N2,G,<:SectorDict{G,A}}})
where {N1,N2,G<:Sector,A<:DenseMatrix} = A

dim(t::AdjointTensorMap) = dim(t.parent)

# Indexing
#-----
hasblock(t::AdjointTensorMap, s::Sector) = hasblock(t.parent, s)
block(t::AdjointTensorMap, s::Sector) = block(t.parent, s)
blocks(t::AdjointTensorMap) = (c=>b' for (c,b) in blocks(t.parent))

fusiontrees(::AdjointTrivialTensorMap) = ((nothing, nothing),)
fusiontrees(t::AdjointTensorMap) = TensorKeyIterator(t.parent.colr, t.parent.rowr)

function Base.getindex(t::AdjointTensorMap{S,N1,N2,G},
    f1::FusionTree{G,N1}, f2::FusionTree{G,N2}) where
{S,N1,N2,G}
    c = f1.coupled
    @boundscheck begin
        c == f2.coupled || throw(SectorMismatch())
        hassector(codomain(t), f1.uncoupled) && hassector(domain(t), f2.uncoupled)
    end
end

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        return sreshape(
            (StridedView(t.parent.data[c])[t.parent.rowr[c][f2],
t.parent.colr[c][f1]]),
            (dims(codomain(t), f1.uncoupled)..., dims(domain(t), f2.uncoupled)...))
        end
    @propagate_inbounds Base.setindex!(t::AdjointTensorMap{S,N1,N2}, v,
        f1::FusionTree{G,N1}, f2::FusionTree{G,N2}) where
        {S,N1,N2,G} =
            copyto!(getindex(t, f1, f2), v)

    @inline Base.getindex(t::AdjointTrivialTensorMap) =
        sreshape(StridedView(t.parent.data)', (dims(codomain(t))...,
        dims(domain(t))...))
    @inline Base.setindex!(t::AdjointTrivialTensorMap, v) = copyto!(getindex(t), v)

    @inline Base.getindex(t::AdjointTrivialTensorMap, ::Tuple{Nothing,Nothing}) =
        getindex(t)
    @inline Base.setindex!(t::AdjointTrivialTensorMap, v, ::Tuple{Nothing,Nothing}) =
        setindex!(t, v)

    # For a tensor with trivial symmetry, allow direct indexing
    @inline function Base.getindex(t::AdjointTrivialTensorMap, I::Vararg{Int})
        data = t[]
        @boundscheck checkbounds(data, I)
        @inbounds v = data[I...]
        return v
    end
    @inline function Base.setindex!(t::AdjointTrivialTensorMap, v, I::Vararg{Int})
        data = t[]
        @boundscheck checkbounds(data, I)
        @inbounds data[I...] = v
        return v
    end

    # Show
    #-----
    function Base.summary(t::AdjointTensorMap)
        print("AdjointTensorMap(", codomain(t), " ← ", domain(t), ")")
    end
    function Base.show(io::IO, t::AdjointTensorMap{S}) where {S<:IndexSpace}
        if get(io, :compact, false)
            print(io, "AdjointTensorMap(", codomain(t), " ← ", domain(t), ")")
            return
        end
        println(io, "AdjointTensorMap(", codomain(t), " ← ", domain(t), "):")
        if sectortype(S) == Trivial
            Base.print_array(io, t[])
            println(io)
        elseif FusionStyle(sectortype(S)) isa Abelian
            for (f1,f2) in fusiontrees(t)
                println(io, "* Data for sector ", f1.uncoupled, " ← ", f2.uncoupled,
                    ":")
                Base.print_array(io, t[f1,f2])
                println(io)
            end
        end
    end

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    end
else
    for (f1,f2) in fusiontrees(t)
        println(io, "* Data for fusiontree ", f1, " ← ", f2, ":")
        Base.print_array(io, t[f1,f2])
        println(io)
    end
end
end
end
```