



NOVA SCHOOL OF
SCIENCE & TECHNOLOGY

Introduction to Prolog – Installation and First Exercises

LABWORK 2

2023 - 2024

- ☐ Lab 2 class 1: Introduction, Installation and Exercises
- ☐ Lab 2 class 2: Lab Work Modeling
- ☐ Lab 2 class 3: Lab Work Modeling and Implementation
- ☐ Lab 2 class 4: Lab Work Implementation

☐ **Delivery date: 2024/05/27**

- ☐ Swi-prolog installation
- ☐ Examples with:
 - ☐ Representation of facts and rules
 - ☐ Queries
 - ☐ Recursion

MDE – Lab2: Swi-prolog installation



SWI Prolog

<http://www.swi-prolog.org>



New Stable Version: 9.2.3.1

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Available versions

The **stable** release is infrequently updated. It is fine for running basic Prolog code without surprises. The **development** version is released roughly every two to four weeks. This is the recommended version for developers and users of applications such as [SWISH](#) or [ClioPatria](#). Finally, the **GIT** and **daily** versions are for developers that want to contribute or have immediate access to patches. These versions are generally fine, but occasionally suffer from regression.

- [Stable release](#)
- [Development release](#)
- [Daily builds for Windows](#)
- Browse [GIT repository](#)

Read more about

- Available SWI-Prolog [versions](#)
- Information on [Linux packages](#) an

SWI Prolog

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Linux versions are often available as a package for your distribution. We collect information about available packages and issues for building on specific distros [here](#). We provide a [PPA](#) for [Ubuntu](#) and [snap images](#)

Android binaries are available for [Termux](#) as the package `swi-prolog`. See also [Building SWI-Prolog on Android using LinuxOnAndroid](#)

Please check the [windows release notes](#) (also in the SWI-Prolog startup menu of your installed version) for details.

Examine the [ChangeLog](#).

Binaries		
	13,795,621 bytes	SWI-Prolog 9.2.3.1 for Microsoft Windows (64 bit) Self-installing executable for Microsoft Windows 64-bit editions. SHA256: 3dee13956fc89f4af96e476691b5254d42929e01878c4620d6df48f00844795d
	13,813,418 bytes	SWI-Prolog 9.2.3.1 for Microsoft Windows (32 bit) Self-installing executable for Microsoft Windows 32-bit editions. Version 9.3 is that last version of SWI-Prolog that is also released for 32-bit. Note that this version lacks the Janus interface to Python. SHA256: 7926195142c8ed285730c6f02268da725d571768b72ec34ecccccf8dadbfadb
	39,827,068 bytes	SWI-Prolog 9.2.3.1 for MacOSX 10.14 (Mojave) and later on x86_64 and arm64 Mac OS X disk image with relocatable application bundle . Needs xquartz (X11) installed for running the development tools . The bundle also provides the commandline tools in the <code>Contents/MacOS</code> directory. Users of older MacOS versions are adviced to use Macports, Homebrew or install from source. This bundle contains universal (fat) binaries that run natively on Intel (x86_64) and Apple Silicon (M1-3, arm64). SHA256: 0b4350e563acf7eae9cddd4237b76a9f44f13db4325e74edc69bddf5618821b
	33,391,393 bytes	SWI-Prolog 9.2.3.1 for MacOSX bundle on intel Mac OS X disk image with relocatable application bundle . Needs xquartz . Same as the <code>fat</code> bundle, but only contains the <code>x86_64</code> binaries, compiled using <code>gcc13</code> from Macports. This version is 30-40% faster than the fat binaries on Intel Macs. The intel version is not regularly updated. SHA256: 99ac1c6b8483437d712400cc17fd4cb2d90857817f741e7b2e664f89949841d
Sources		
	12,265,133 bytes	SWI-Prolog source for 9.2.3 Sources in <code>.tar.gz</code> format, including packages and generated documentation files. See build instructions . SHA256: 28329039526a93c10a160be5c7d90ca4fb7d1514e4a009a0852c6d2372926724

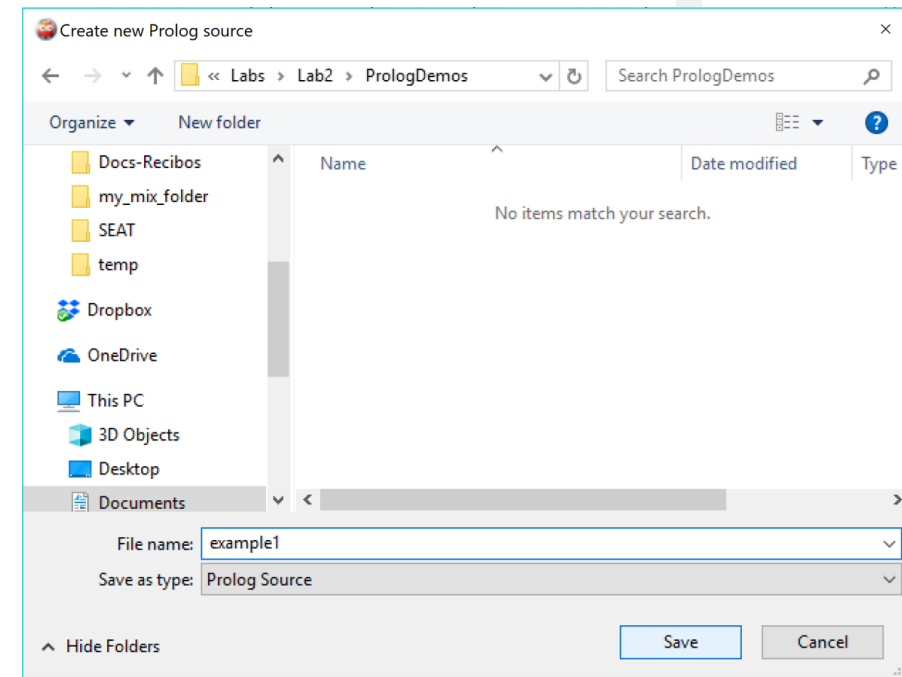
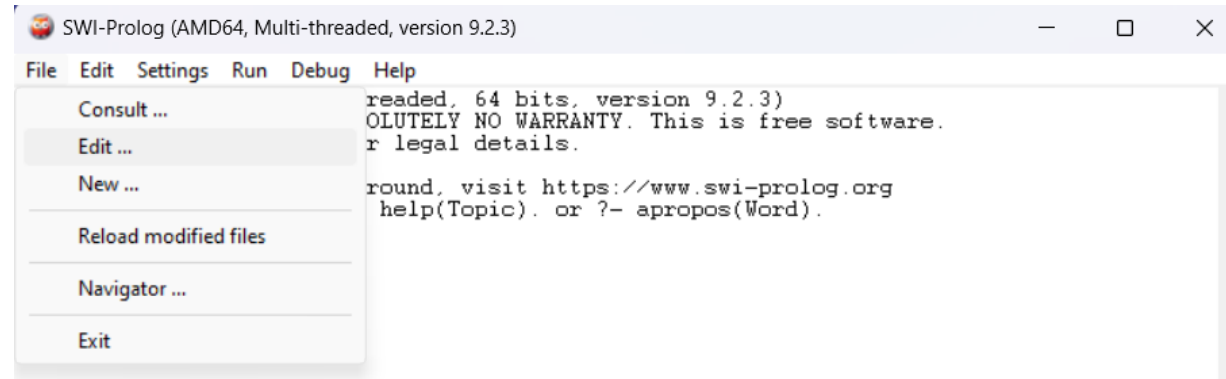
MDE – Lab2: Using Swi-prolog



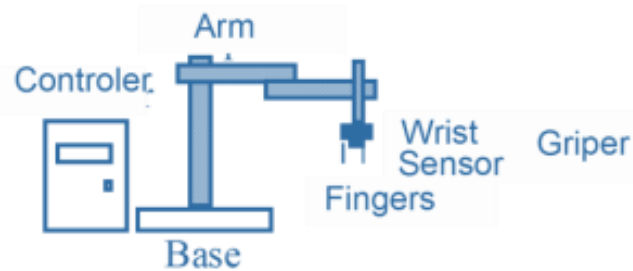
SWI Prolog

<http://www.swi-prolog.org>

- ☐ Execute “swipl-win.exe”
- ☐ Create new .pl file
 - ☐ File->new

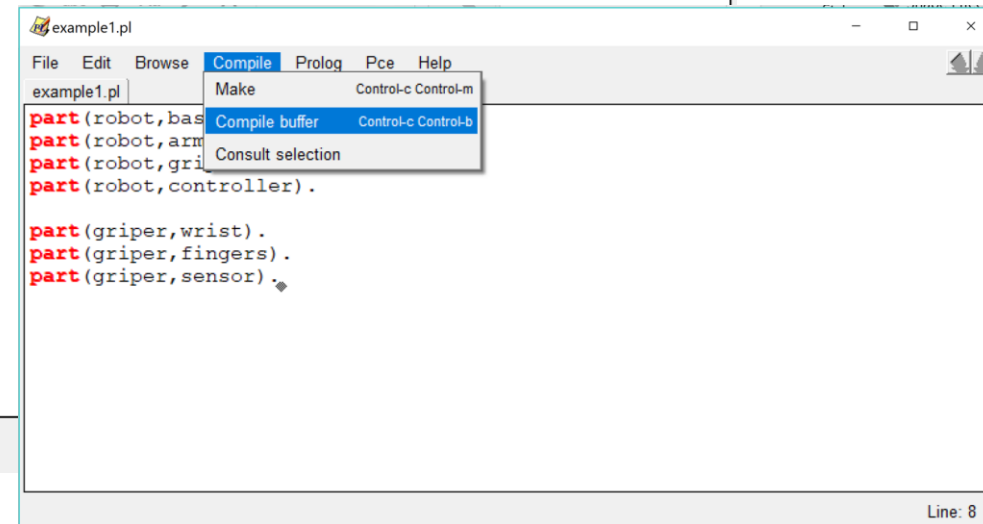


- Example 1: Model the structure of a robot [Done in the THORETICAL class]



```
example1.pl
File Edit Browse Compile Prolog Pce Help
example1.pl
part(robot,base).
part(robot,arm).
part(robot,griper).
part(robot,controller).

part(griper,wrist).
part(griper,fingers).
part(griper,sensor).
```



A screenshot of the Prolog IDE showing the 'Compile' menu open. The menu options are: 'Make' (Control-c Control-m), 'Compile buffer' (Control-c Control-b), and 'Consult selection'. The code in the background is the same as the previous block.



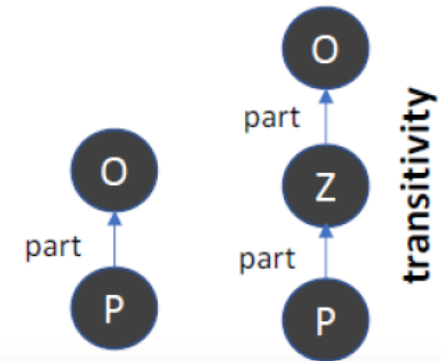
FROM THEORETICAL CLASSES...

Rules:

Conclusion if Condition: conclusion :- condition.
if \rightarrow :- and \rightarrow , or \rightarrow ; not \rightarrow not(...)

`includes(O,P) :- part(O,P).` /* O includes P if O has a part P */

`includes(O, P) :- part(O,Z), part(Z,P).` /* O includes P if O has a part Z and Z has a part P*/



```
mde_tp_prolog.pl [modified]
part(robot,griper).
part(robot,controler).

part(griper,wrist).
part(griper,fingers).
part(griper,sensor).

includes(O,P):-part(O,P). /* O includes P if O has a part P */
includes(O,P):-part(O,Z), part(Z,P). /* O includes P if O has a part Z and Z has a part P*/
```



FROM THEORETICAL CLASSES...

```
SWI-Prolog (AMD64, Multi-threaded, version 9.2.2)
File Edit Settings Run Debug Help

?- part(robot,base).
true.

?- part(robot,X).
X = base ;

?- part(robot,X).
X = base ;
X = arm ;
X = griper ;
X = controler.

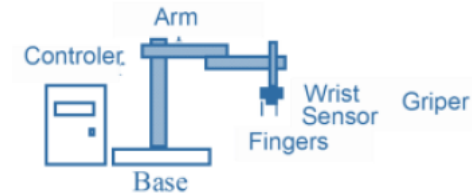
?- part(X,arm).
X = robot.
```

Examples “?-”

```
?- part(O,P).
O = robot,
P = base ;
O = robot,
P = arm ;
O = robot,
P = griper ;
O = robot,
P = controler ;
O = griper,
P = wrist ;
O = griper,
P = fingers ;
O = griper,
P = sensor.

?- part(robot,sensor).
false.

?- includes(robot,sensor).
true.
```



Answer obtained from the first rule:
`includes(robot, arm) :- part(robot, arm)`

```
?- includes(robot,arm).
true.

?- includes(robot,fingers).
true.
```

Answer obtained from the second rule:
`includes(robot, fingers) :- part(Z,fingers),part(robot,Z).`

FROM THEORETICAL CLASSES...

```
SWI-Prolog (AMD64, Multi-threaded, version 9.2.2)
File Edit Settings Run Debug Help

?- part(robot,base).
true.

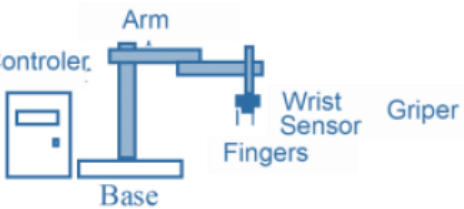
?- part(robot,X).
X = base ;

?- part(robot,X).
X = base ;
X = arm ;
X = griper ;
X = controler.

?- part(X,arm).
X = robot.
```

Multiple results

```
?- part(O,P).
O = robot,
P = base ;
O = robot,
P = arm ;
O = robot,
P = griper ;
O = robot,
P = controler ;
O = griper,
P = wrist ;
O = griper,
P = fingers ;
O = griper,
P = sensor.
```



Answer obtained from the first rule:
`includes(robot, arm) :- part(robot, arm)`

```
?- includes(robot,arm).
true.

?- includes(robot,fingers).
true.
```

Answer obtained from the second rule:
`includes(robot, fingers) :- part(Z,fingers),part(robot,Z).`

```
?- part(robot,sensor).
false.

?- includes(robot,sensor).
true.
```



□ Facts

```
part(robot,base) .
```

□ Rules

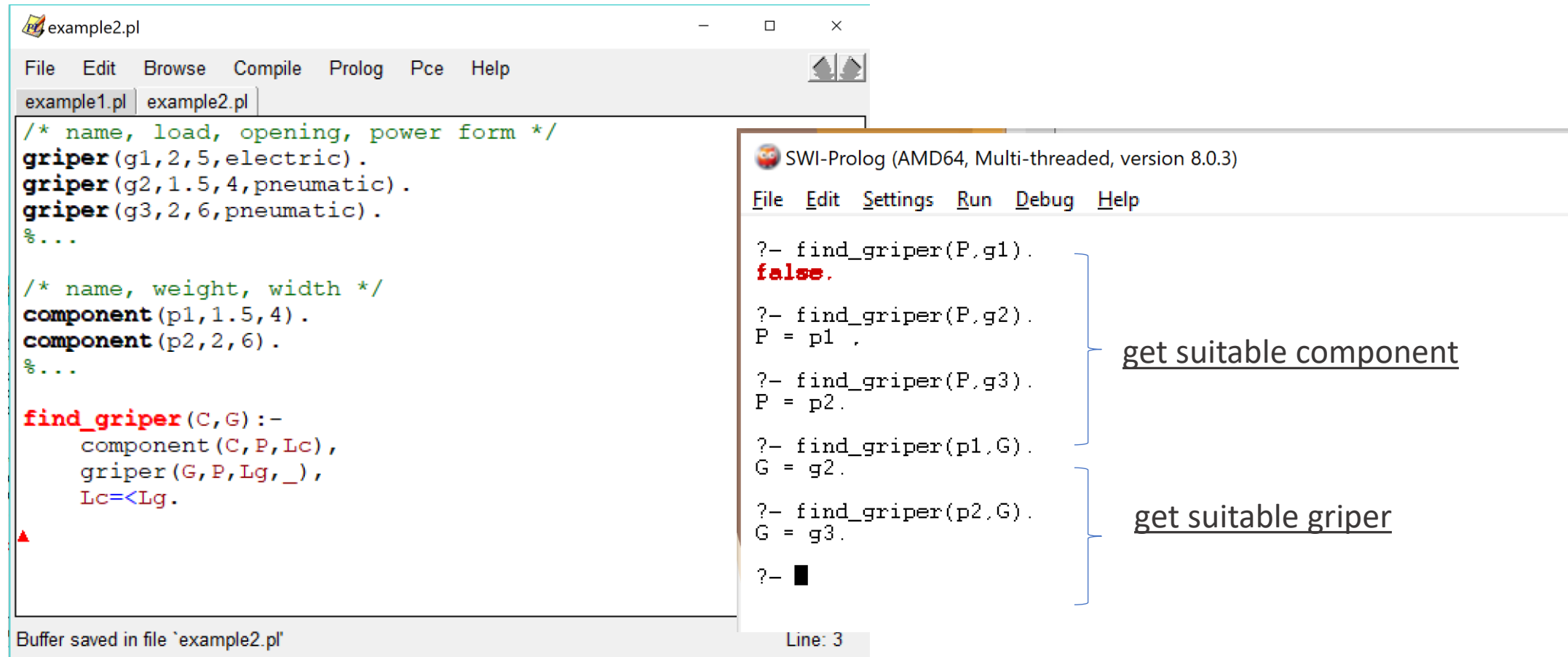
```
includes(O,P):-part(O,P). /* O includes P if O has a part P */  
includes(O,P):-part(O,Z), part(Z,P). /* O includes P if O has a part Z and Z has a part P*/
```

□ Variables

```
?- part(robot,X) . Capital letter  
X = base ;  
X = base ;  
X = arm ;  
X = griper ;  
X = controller .
```

Lower case -> Constants

□ Example 2: Robot components [Done in the THORETICAL class]



The screenshot shows a Prolog IDE with two windows. The left window, titled 'example2.pl', contains the following code:

```
/* name, load, opening, power form */
griper(g1,2,5,electric).
griper(g2,1.5,4,pneumatic).
griper(g3,2,6,pneumatic).
%...

/* name, weight, width */
component(p1,1.5,4).
component(p2,2,6).
%...

find_griper(C,G):-
    component(C,P,Lc),
    griper(G,P,Lg,_),
    Lc<Lg.
```

The right window, titled 'SWI-Prolog (AMD64, Multi-threaded, version 8.0.3)', shows the following queries and results:

```
?- find_griper(P,g1).
false.

?- find_griper(P,g2).
P = p1 .

?- find_griper(P,g3).
P = p2 .

?- find_griper(p1,G).
G = g2 .

?- find_griper(p2,G).
G = g3 .

?-
```

Annotations on the right side of the console window indicate the purpose of the queries:

- A bracket groups the first three queries (`find_griper(P,g1)`, `find_griper(P,g2)`, `find_griper(P,g3)`) with the label get suitable component.
- A bracket groups the next three queries (`find_griper(p1,G)`, `find_griper(p2,G)`, and the final `?-`) with the label get suitable griper.

At the bottom of the IDE, a status bar shows 'Buffer saved in file `example2.pl`' and 'Line: 3'.

□ Exercise 1:

Consider the following predicates:

```
% student_name, unit, shift, grade
student_unit(manuel, mde, p1, 13).
student_unit(alexandra, mde, p1, 16).
student_unit(joana, mde, p3, 12).
student_unit(maria, mde, p3, 17).
student_unit(diogo, mde, p2, 9).
student_unit(jose, mde, p5, 18).
student_unit(rodriago, mde, p5, 12).
student_unit(manuel, pr, p1, 11).
student_unit(anabela, pr, p1, 13).
student_unit(joana, cee, p2, 18).
student_unit(maria, cee, p2, 8).
student_unit(diogo, cee, p2, 11).

% professor_name, unit, shift
teaches(andre, mde, p4).
teaches(andre, mde, p3).
teaches(filipa, mde, p2).
teaches(filipa, mde, p5).
teaches(anabela, cee, p2).
teaches(anabela, cee, p1).
teaches(joao, pr, p1).
teaches(joao, pr, p2).
```

Write the corresponding rules that would answer the following queries:

- a) Which students are enrolled in shift p3?
- b) Which students from p5 have a grade > 14?
- c) Which units is diogo enrolled in?
- d) Who are the students of professor andre?
- e) What are the professors of student joana?

□ Exercise 2:

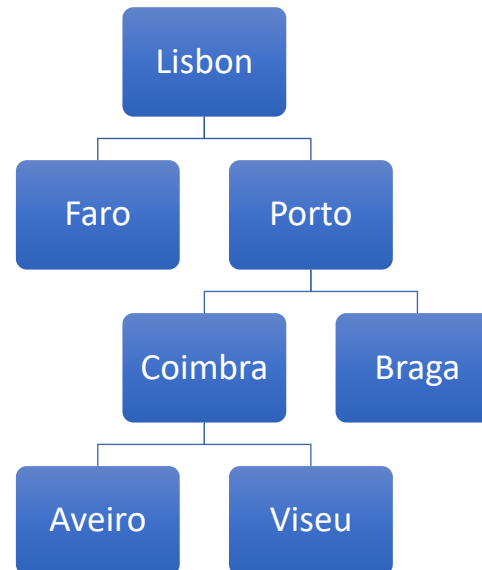
Given the following facts:

- Maria is fatter than Ana
- Ana is fatter than Luisa
- Luisa is fatter than Diana
- Diana is fatter than Sara

Write the corresponding facts and rules (using recursion) that determine that Maria is heavier than Sara.

□ Exercise 3:

Consider the following road tree that connects several cities in Portugal (one direction)

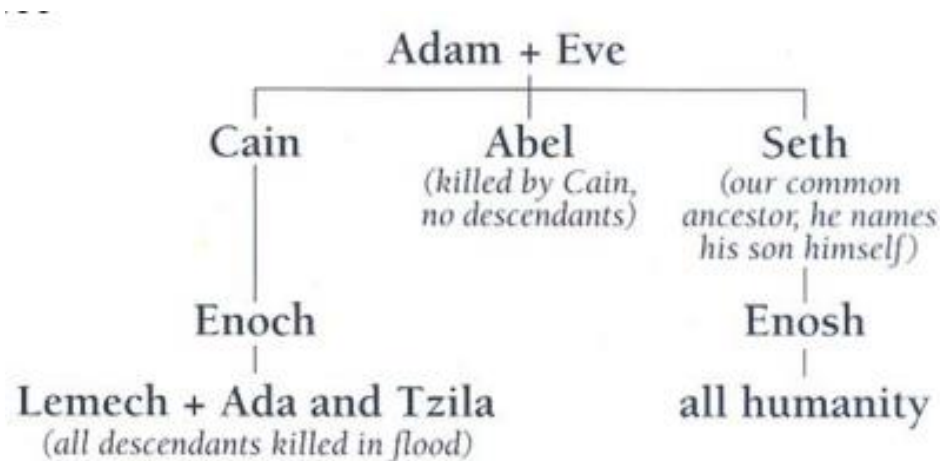


Write the corresponding facts and rules (using recursion) that would answer the following queries:

- a) Can I travel from Lisbon to Viseu?
- b) Can I travel from Faro to Braga?
- c) How many cities I cross between Lisbon and Aveiro?

□ Exercise 4:

Use the predicates **father/2** and **mother/2** to represent the genealogic tree (in this example we use the Adam and Eve's genealogic tree, but you can use yours!):



```

father(adam, abel) .
father(adam, caim) .
father(adam, seth) .
%...

mother(eve, seth) .
%...
  
```

Create rules to capture the following relationships:

- **son**(Father, Mother)
- **grandfather**(Grandfather, Grandson)
- **brother**(Brother1, Brother2)
- **uncle**(Uncle, Nephew)
- **cousin**(Cousin1, Cousin2)
- **ascendant**(Ascendant, Descendant)
- **descendant**(Descendant, Ascendant)



GOOD
WORK!