

MDE

Modeling with PROLOG - Part III -

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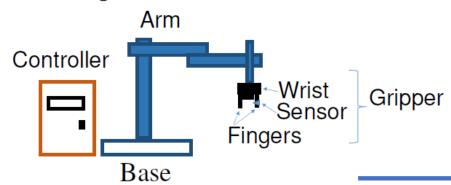
FACTS / RULES / QUERIES

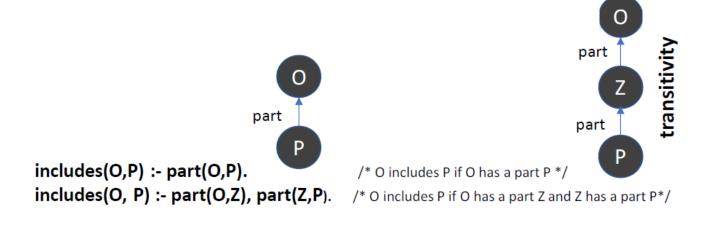


... from previous class ...

Going back to the robot model example:

We can generalize the rule

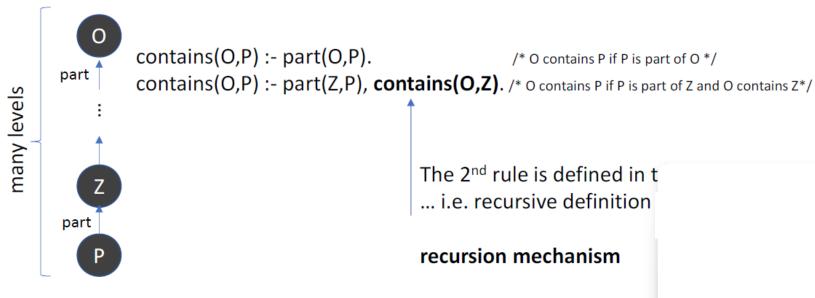




One possible solution:

part(robot, base).
part(robot, arm).
part(robot, gripper).
part(robot, controller).
part(gripper, wrist).
part(gripper, fingers).
part(gripper, sensor).

A more generic solution



STRUCTURES / COMBINED QUERIES



... from previous class ...

```
/* # order, date, product, quantity, delivery address*/
order(305, date(11,10,2022), p45, 20, delivery('R Raul Brandão, 5', 'Almada')).
order(125, date(1,5,2022), p34, 5, delivery('R Fernando Simões, 12', 'Caparica')).
order(235, date(4,2,2023), p34, 16, delivery('R Raul Brandão, 17', 'Almada')).
```

• • •

Identify orders to be delivered in Almada: ?- order(N, _, _, _, delivery(_, 'Almada')). N = 305 ;

N = 235

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Exercises: Write

- 1. Which produ in Caparica?
- 2. Identify 2 pr same city

student(52417, 'Afonso Maria', m, 2). student(52828, 'Alessia Offsas', f, 3). student(53202, 'Alexandre Cardoso', m, 2). student(52431, 'Alexandre Brito', m, 3). student(52993, 'Alexandru Botnari', m, 3). student(52418, 'Americo Alves', m, 3). student(51789, 'Ana Rita Silva', f, 2). student(52751, 'Waner Shan', f, 3).

gender(f, female). gender(m, male).

What is the gender of student no 52993?

?-student(52993, _, G, _), gender(G, Gender). Gender = male

Who is a female student?

?-gender(G, female), student(N, _, G, _).

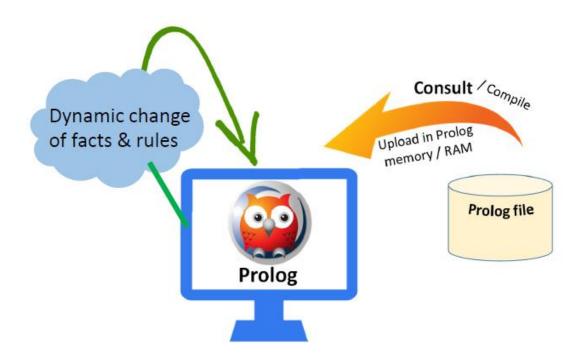
N = 52828 (;) Meaning: try to find a different answer

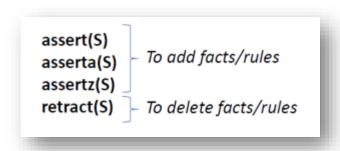
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CHANGING THE MEMORY IN PROLOG



... from previous class ...





Informs the interpreter that the definition of the predicate(s) may change during execution (using assert/1 and/or retract/1)

:-dynamic fact/args



INPUT / OUTPUT



Exercise

Let's get back to the example of fathers and create a menu for a "FATHERS MANAGEMENT SYSTEM ©"

```
FATHERS MANAGEMENT SYSTEM:)
gmenu: - nl, nl, write ('FATHERS MANAGEMENT SYSTEM :)'), nl,
                                                                                 1. List fathers
    menu(Op), execute(Op).
                                                                                 2. Insert father
menu(Op):- write('1. List fathers'), nl,
                                                                                 3. Delete fathers
    write('2. Insert father'), nl,
    write('3. Delete fathers'), nl,
                                                                                 4. Exit
    write('4. Exit'), nl, readoption(Op).
readoption(Op):- read(Op), valid(Op), nl.
readoption(Op): - nl, write('*** Invalid option. Try again: '), readoption(Op).
valid(Op):- Op >=1, Op=<4.
execute(4). % exit condition
                                                              Here we use some pre-defined rules of SWI-Prolog:
execute(Op):- exec(Op),nl,
                                                                read - reads a string ended by "."
    menu (NOp), execute (NOp).
                                                                write - writes a string
                                                                nl - new line
exec(1) :- listing(father).
exec(2) :- read fathers.
exec(3) :- delete fathers.
```



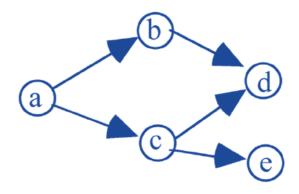
How can we rewrite this code to avoid ending input with.



Recursive definition

Back to modeling....

Examples of application: road maps (one direction), electric circuits, energy distribution, ...



One possible representation:

Facts:

arc(a,b).

arc(a,c).

arc(b,d).

arc(c,d).

arc(c,e).

Rules:

R1 conn

connected(X,Y) :- arc(X,Y).

connected(X,Y) :- arc(X,Z), connected(Z,Y).

?- connected(a,b).

Rule 1: connected(a,b) :- arc(a,b) → succeeds

true

?- connected(a,d).

```
Rule 1: connected(a,d) :- arc(a,d) → fails
Rule 2: connected(a,d) :- arc(a, Z), connected (Z,d)

Z=b Rule 1: connected(b,d) :- arc(b,d)

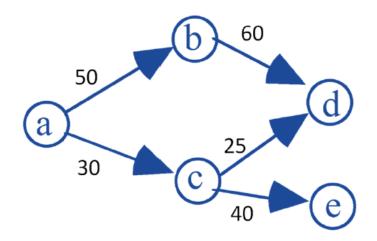
→ succeeds
```

true



Back to modeling....

Arcs with distance



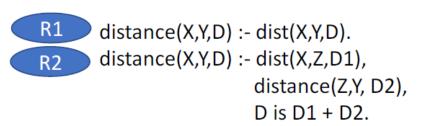
dist(a,b,50).

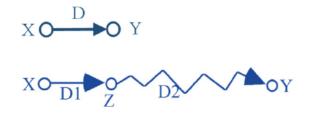
dist(a,c,30).

dist(b,d,60).

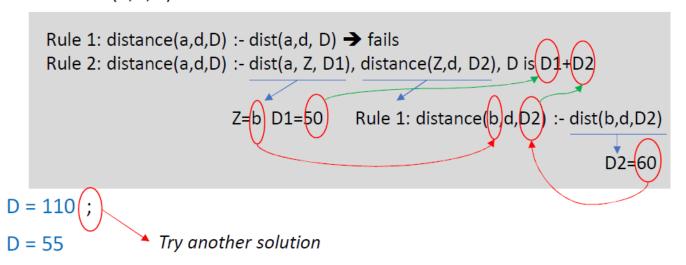
dist(c,d,25).

dist(c,e,40).





?- distance(a,d,D).

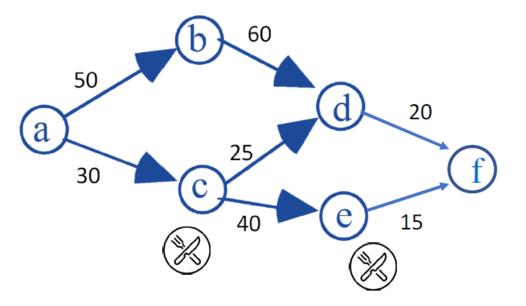




Back to modeling....

Variant:

Imagine that the graph represents a road map (nodes represent cities, arcs represent roads). In order to go from city X to city Y, either there is a direct road, or in case we must pass by intermediate cities we only want to pass by cities with a restaurant. Some cities have restaurants, others not.



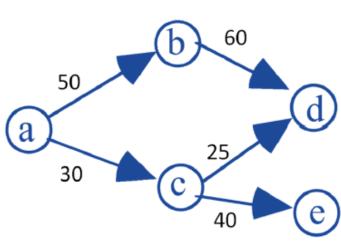
Represent the case illustrated in the figure.

Modify the rule distance in order to consider the constraint indicated above (i.e., only passing by intermediate nodes with a restaurant).

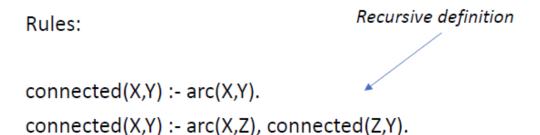
How many valid paths between a and f?



10



Facts:



But what if we want to know the names of all nodes in the path between two nodes X and Y?

The answer can be of a variable length, depending on X, Y and the followed path => thus, we need another data structure to represent such answers with variable length

LISTS in PROLOG



List: a data structure that can contain a variable number of elements

Some notation:

[] empty list

[a] list with 1 element

[a, b] list with 2 elements

[a, [b, c], d] list with 3 elements

[a, date(11,3,94), b] list with 3 elements

[H | R] list with at least 1 element

H – first element (head)

R - list with remaining elements (excluding head)

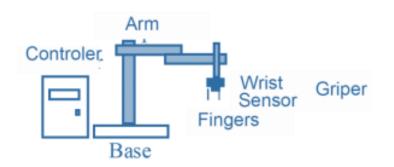
[X1, X2 | R] list with at least 2 elements



Example:

components(robot, [base, arm, gripper, controller]). components(gripper, [wrist, fingers, sensor]).

?-components(robot, L).
L = [base, arm, gripper, controller]
?-components(gripper, [C|R]).
C = wrist
R = [finger, sensor]
?-components(X, [base | _]).
X = robot





```
Example: Is the element E a member of a given list?
```

```
is_member(E, [E|_]).
is_member(E, [_|R]) :- is_member(E,R).
```

```
has(O,C) :- components(O,L), is_member(C,L).
?-has(gripper, fingers).
true
```

```
components(robot, [base, arm, gripper, controller]). components(gripper, [wrist, fingers, sensor]).
```

```
?-components(robot,L), is_member(E,L).
L = [base, arm, gripper, controller],
E = base;
L = [base, arm, gripper, controller],
E = arm;
L = [base, arm, gripper, controller],
E = gripper;
L = [base, arm, gripper, controller],
E = controller;
false.
```



Example: Length or number of elements of a list

- R1 R2
- nelem([], 0).
- $nelem([_|R],N) :- nelem(R, N1), N is N1 + 1.$

?- nelem([a, b, c], N).

Invisible to the user

```
R1 => fails (the 1<sup>st</sup> parameter is not an empty list)
R2 => nelem([a | b,c],N) :- nelem([b,c], N'), N is N' + 1

R1 => fails
R2 => nelem([b|c], N') :- nelem([c], N''), N' s N'' + 1

R1 => fails
R2 => nelem([c | []], N'') :- nelem([], N'''), N'' is N''' + 1

R1 => N'''=0
```



Example: Rule to find the maximum of a list



max([X], X).

max([X | R], X) :- max(R, M), X >= M.

 $max([X \mid R], M) := max(R,M), X < M.$

?- max([4, 3, 8], M).

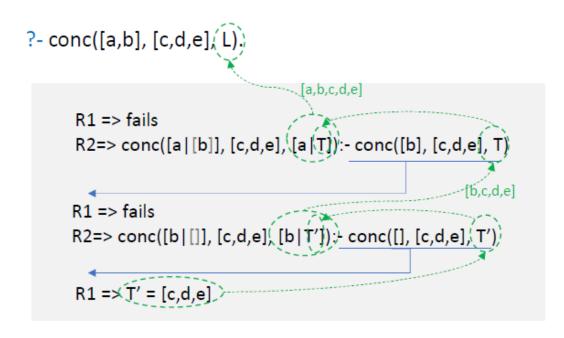


Example: concatenate two lists

$$[a, b] + [c, d, e] => [a, b, c, d, e]$$

conc([], L, L). conc([C|R], L, [C|T]) :- conc(R, L, T).

Example: invert a list



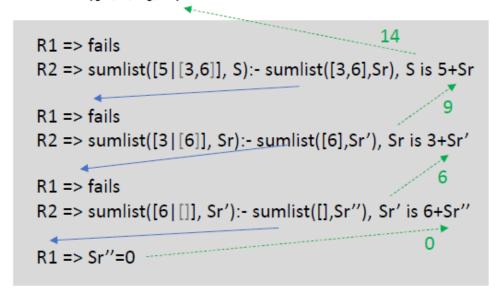
$$L = [a,b,c,d,e]$$



Given a list of numbers, add those numbers.

sumlist([],0).
sumlist([X|R], S):- sumlist(R,Sr), S is X + Sr.

?-sumlist([5,3,6], S).



Given a list of numbers, calculate the **average** of those numbers.

```
?-avglist([6,8,10],A).
A= 8
```





Proposed exercises:

E1: Consider a list in which elements might appear repeated. Write a set of rules to calculate the number of times one element E appears repeated in a given list.

E2: Write a set of rules to find the minimum of a list.

E3: Find the last element of a list.

Example:

?- my_last(X,[a,b,c,d]).

X = d

E4: Duplicate the elements of a list.

Example:

?- dupli([a,b,c,c,d],X).

X = [a,a,b,b,c,c,c,c,d,d]

E5: Extract a slice from a list.

Given two indices, I and K, the slice is the list containing the elements between the I'th and K'th element of the original list (both limits included). Start counting the elements with 1.

Example:

?- slice([a,b,c,d,e,f,g,h,i,k],3,7,L).

X = [c,d,e,f,g]



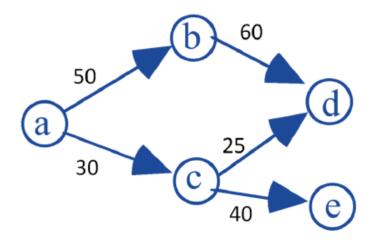


```
E6: Suppose we are given a knowledge base with the following facts:
    tran(um,one).
    tran(dois,two).
    tran(tres,three).
    tran(quatro,four).
    tran(cinco,five).
    tran(seis,six).
    tran(sete,seven).
    tran(oito,eight).
    tran(nove,nine).
Write a predicate listtran(G,E) which translates a list of Portuguese number words to the
corresponding list of English number words. For example:
    listtran([um,nove,dois],X).
should give:
    X = [one, nine, two].
```

LISTS and GRAPHS



Graph revisited:



dist(a,b,50).

dist(a,c,30).

dist(b,d,60).

dist(c,d,25).

dist(c,e,40).

Obtain, in a list, the arcs of the path between two nodes X, Y

Solution 1:

R1 path(X,Y, [dist(X,Y,D)]) :- dist(X,Y,D).
path(X,Y, [dist(X,Z,D) | R]) :- dist(X,Z,D), path(Z,Y,R).

?- path(a, d, P).

R1=> path(a, d, [dist(a, d, D)]) :- dist(a, d, D) => fails

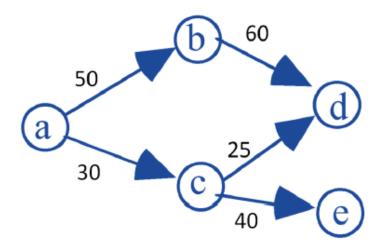
R2=> path(a, d, [dist(a,Z,D) | R]):- dist(a,Z,D), path(Z,d,R) Z = b, D = 50 R1=> path(b, d, [dist(b, d, D')]) :- dist(b, d, D') D' = 60

P = [dist(a,b,50), dist(b,d,60)]; Try another solution P = [dist(a,c,30), dist(c,d,25)]

LISTS and GRAPHS



Graph revisited:



dist(a,b,50). dist(a,c,30). dist(b,d,60). dist(c,d,25). dist(c,e,40). Obtain, in a list, the arcs of the path between two nodes X, Y

Solution 2:

```
path(X,Y, [via(X,Y)]) :- dist(X,Y,_).
path(X,Y, [via(X,Z) | R]) :- dist(X,Z,_), path(Z,Y,R).
?- path(a, d, P).
P = [via(a,b), via(b,d)] ;
P = [via(a,c), via(c,d)]
```

Solution 3:

```
path(X,Y, [(X,Y)]) :- dist(X,Y,_).
path(X,Y, [(X,Z) | R]) :- dist(X,Z,_), path(Z,Y,R).

?- path(a, d, P).

P = [(a,b), (b,d)];
P = [(a, c), (c, d)];
There are no more solutions false.
```

LISTS and GRAPHS



path4(Z,Y, R,D2), DT is D1+D2.

path4(X,Y, [via(X,Y,D)], D) :- dist(X,Y,D).

?-path4(a,d,P, D).

D=110

P = [via(a,b,50), via(b,d,60)].

path4(X,Y, [via(X,Z,D1) | R], DT) :- dist(X,Z,D1),

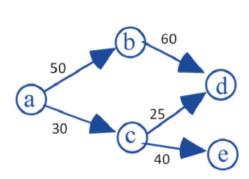
Write another version of path with the following behavior:

?-path3(a,e,P).

P = p([via(a, c, 30), via(c, e, 40)], (70))

Total distance

path3(X,Y, p([via(X,Y,D)], D)) :- dist(X,Y,D).
path3(X,Y, p([via(X,Z,D1) | R], DT)) :- dist(X,Z,D1), path3(Z,Y, p(R,D2)), DT is D1+D2.



```
?- path3(a,d,P).
P = p([via(a, b, 50), via(b, d, 60)], 110);
P = p([via(a, c, 30), via(c, d, 25)], 55);
false.

?- path3(a,e,P).
P = p([via(a, c, 30), via(c, e, 40)], 70);
false.
?- path3(c,e,p([via(c,e,40)],40)).
true
```

LISTS -> Multiple Solutions: findall

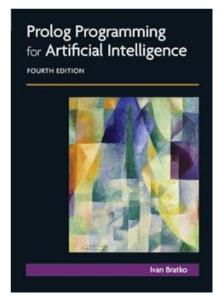


```
Remember the genealogic tree case:
```

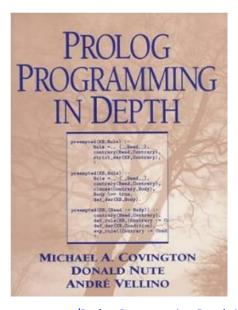
- ?- findall(S, father(_,S), L).
- L = [abel, caim, seth].
- ?- findall(father(P,F),father(P,F),L).
- L = [father(adam, abel), father(adam, caim), father(adam, seth)].
- ?- findall([X,Y],father(X,Y),L).
- L = [[adam, abel], [adam, caim], [adam, seth]].
- ?- findall(p(X,Y), father(X,Y),L).
- L = [p(adam, abel), p(adam, caim), p(adam, seth)].

Further reading

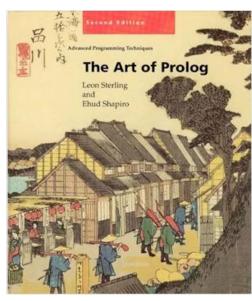




https://www.amazon.com/Programming-Artificial-Intelligence-International-Computer/dp/0321417461



https://www.amazon.com/Prolog-Programming-Depth-Michael-Covington/dp/013138645X/ref=pd_sim_14_4?ie=UTF8&dpID=514M0RXA1WL&dpSr c=sims&preST= AC_UL160_SR122%2C160_&refRID=1TM7A3CEFC2BD4JA77WR



https://mitpress.mit.edu/9780262691635/the-art-of-prolog/



https://www.swi-prolog.org/pldoc/doc_for?object=manual



https://en.wikibooks.org/wiki/Prolog

(...)