Introduction to Prolog – Installation and First Exercises

LABWORK 2

2023 - 2024

MDE – Lab2 Objectives and Scheduling

- Lab 2 class 1: Introduction, Installation and Exercises
- Lab 2 class 2: Lab Work Modeling
- Lab 2 class 3: Lab Work Modeling and Implementation
- Lab 2 class 4: Lab Work Implementation

- **Delivery date: 2024/05/27**

MDE – Lab2 (Class 1)

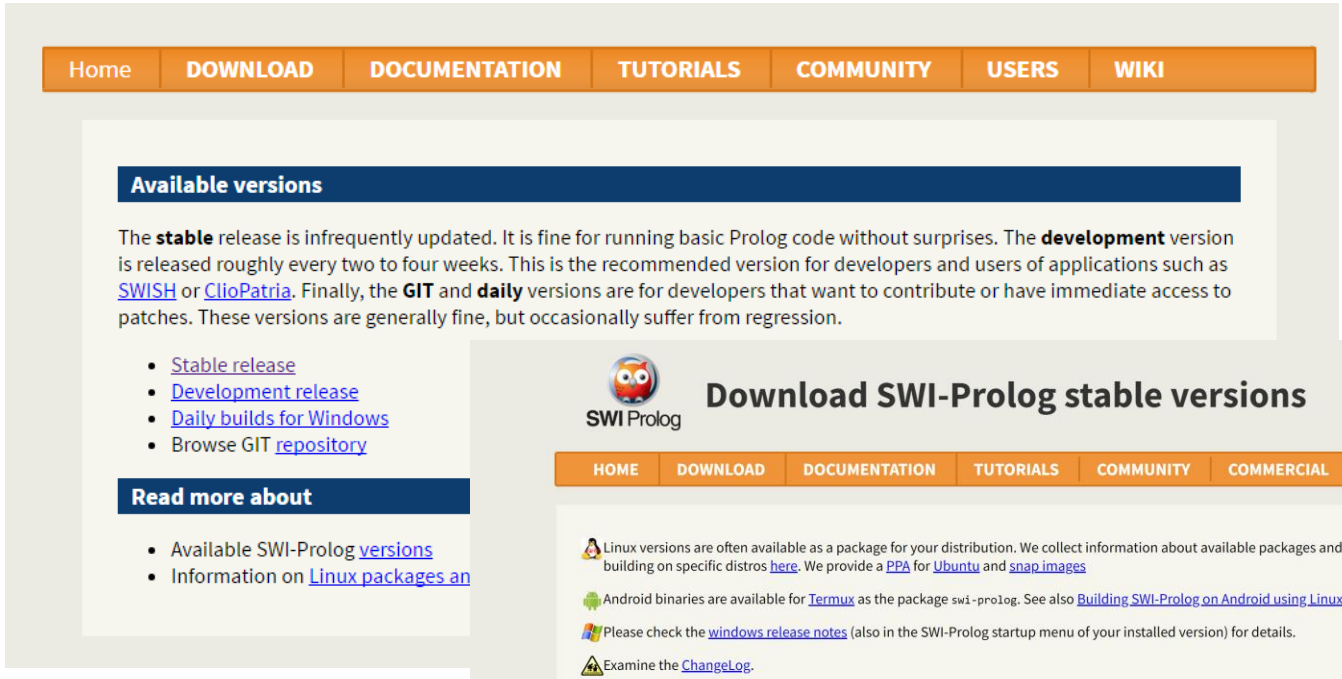
- Swi-prolog installation

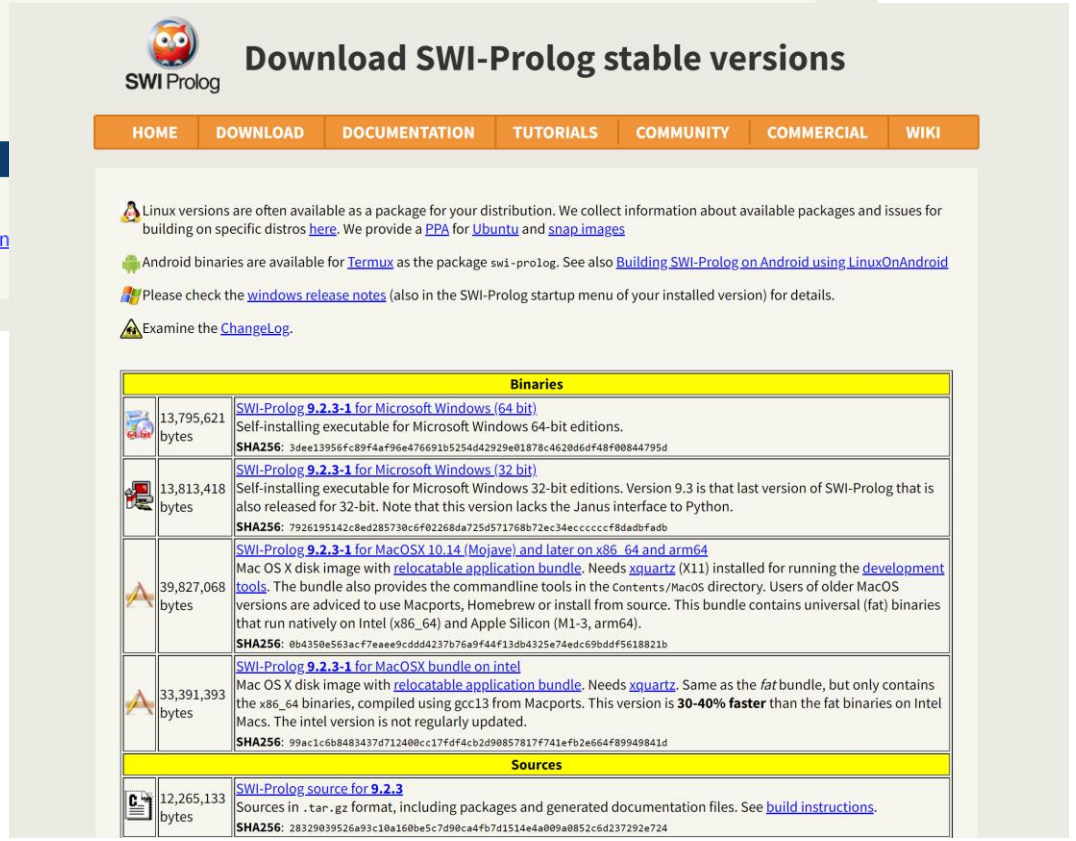
- Examples with:
  - Representation of facts and rules
  - Queries
  - Recursion

MDE – Lab2: Swi-prolog installation

SWI Prolog

http://www.swi-prolog.org



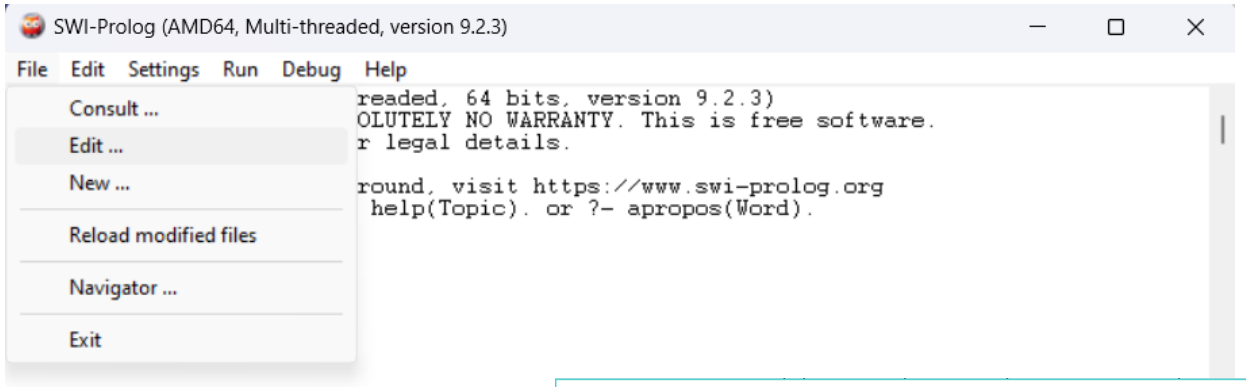


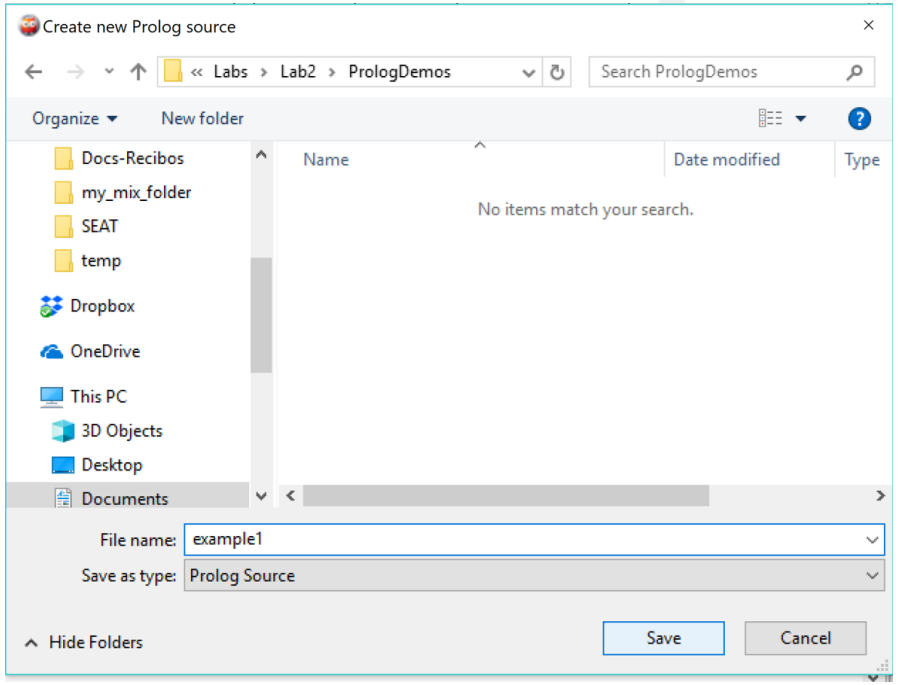
New Stable Version: 9.2.3.1

MDE – Lab2: Using Swi-prolog

SWI Prolog

http://www.swi-prolog.org

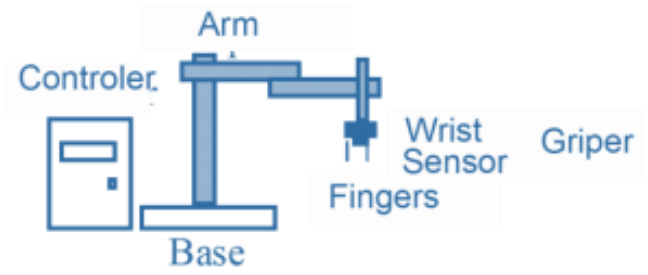




- Execute “swipl-win.exe”
- Create new .pl file
  - File->new

MDE – Lab2: Representation of facts

- Example 1: Model the structure of a robot [Done in the THORETICAL class]



example1.pl

File Edit Browse Compile Prolog Pce Help

example1.pl

```
part(robot,base).
part(robot,arm).
part(robot,griper).
part(robot,controller).

part(griper,wrist).
part(griper,fingers).
part(griper,sensor).
```

example1.pl

File Edit Browse Compile Prolog Pce Help

Make Control-c Control-m

Compile buffer Control-c Control-b

Consult selection

example1.pl

```
part(robot,bas
part(robot,arm
part(robot,gri
part(robot,controller).

part(griper,wrist).
part(griper,fingers).
part(griper,sensor).
```

Line: 8

SWI Prolog

MDE – Lab2: Representation of rules

FROM THEORETICAL CLASSES…

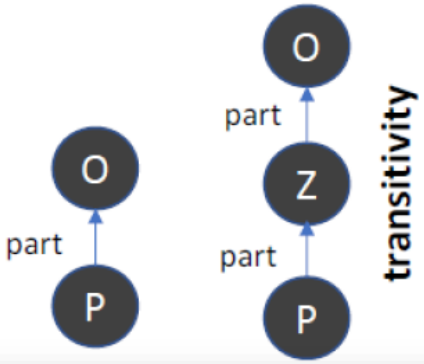
Rules:

Conclusion if Condition: conclusion :- condition.

if → **:-** *and* → **,** *or* → **;** *not* → **not**(…)

includes(O,P) :- part(O,P). /* O includes P if O has a part P */

includes(O, P) :- part(O,Z), part(Z,P). /* O includes P if O has a part Z and Z has a part P*/



mde_tp_prolog.pl [modified]

```
part(robot,griper).
part(robot,controler).

part(griper,wrist).
part(griper,fingers).
part(griper,sensor).

includes(O,P):-part(O,P). /* O includes P if O has a part P */
includes(O,P):-part(O,Z), part(Z,P). /* O includes P if O has a part Z and Z has a part P*/
```

SWI Prolog

MDE – Lab2: Queries

FROM THEORETICAL CLASSES…

SWI-Prolog (AMD64, Multi-threaded, version 9.2.2)

File Edit Settings Run Debug Help

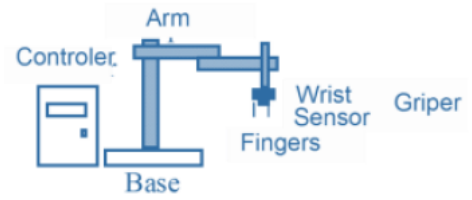
```
?- part(robot,base).
true.

?- part(robot,X).
X = base .

?- part(robot,X).
X = base ;
X = arm ;
X = griper ;
X = controler.

?- part(X,arm).
X = robot.
```

Examples "?-"




```
?- part(O,P).
O = robot,
P = base ;
O = robot,
P = arm ;
O = robot,
P = griper ;
O = robot,
P = controler ;
O = griper,
P = wrist ;
O = griper,
P = fingers ;
O = griper,
P = sensor.

?- part(robot,sensor).
false.

?- includes(robot,sensor).
true .
```

Answer obtained from the first rule:
includes(robot, arm) :- part(robot, arm)

```
?- includes(robot,arm).
true .

?- includes(robot,fingers).
true .
```

Answer obtained from the second rule:
includes(robot, fingers) :- part(Z,fingers),part(robot,Z).

SWI Prolog

MDE – Lab2: Queries

FROM THEORETICAL CLASSES…

SWI-Prolog (AMD64, Multi-threaded, version 9.2.2)

File Edit Settings Run Debug Help

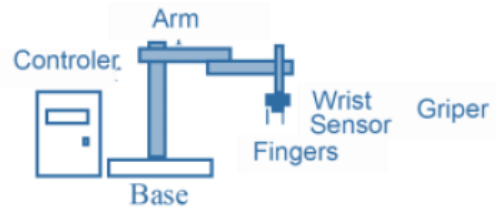
```
?- part(robot,base).
true.

?- part(robot,X).
X = base ,

?- part(robot,X).
X = base ;
X = arm ;
X = griper ;
X = controler.

?- part(X,arm).
X = robot.
```

Multiple results




```
?- part(O,P).
O = robot,
P = base ;
O = robot,
P = arm ;
O = robot,
P = griper ;
O = robot,
P = controler ;
O = griper,
P = wrist ;
O = griper,
P = fingers ;
O = griper,
P = sensor.

?- part(robot,sensor).
false.

?- includes(robot,sensor).
true .
```

Answer obtained from the first rule:
includes(robot, arm) :- part(robot, arm)

```
?- includes(robot,arm).
true .

?- includes(robot,fingers).
true .
```

Answer obtained from the second rule:
includes(robot, fingers) :- part(Z,fingers),part(robot,Z).

SWI Prolog

MDE – Lab2: Some notes

- Facts

```
part(robot,base).
```

- Rules

```
includes(O,P):-part(O,P). /* O includes P if O has a part P */
includes(O,P):-part(O,Z), part(Z,P). /* O includes P if O has a part Z and Z has a part P*/
```

- Variables

```
?- part(robot,X).
X = base ;
X = base ;
X = arm ;
X = griper ;
X = controller.
```

Capital letter

Lower case -> Constants

MDE – Lab2: another example (i)

- Example 2: Robot components [Done in the THORETICAL class]

example2.pl

File Edit Browse Compile Prolog Pce Help

example1.pl | example2.pl

```
/* name, load, opening, power form */
griper(g1,2,5,electric).
griper(g2,1.5,4,pneumatic).
griper(g3,2,6,pneumatic).
%...

/* name, weight, width */
component(p1,1.5,4).
component(p2,2,6).
%...

find_griper(C,G):-
    component(C,P,Lc),
    griper(G,P,Lg,_),
    Lc=<Lg.
```

Buffer saved in file `example2.pl' Line: 3

SWI-Prolog (AMD64, Multi-threaded, version 8.0.3)

File Edit Settings Run Debug Help

```
?- find_griper(P,g1).
false.

?- find_griper(P,g2).
P = p1 .

?- find_griper(P,g3).
P = p2.

?- find_griper(p1,G).
G = g2.

?- find_griper(p2,G).
G = g3.

?-
```

get suitable component

get suitable griper

MDE – Lab2

Exercise 1:

Consider the following predicates:

```
% student_name, unit, shift, grade
student_unit(manuel, mde, p1, 13).
student_unit(alexandra, mde, p1, 16).
student_unit(joana, mde, p3, 12).
student_unit(maria, mde, p3, 17).
student_unit(diogo, mde, p2, 9).
student_unit(jose, mde, p5, 18).
student_unit(rodrigo, mde, p5, 12).
student_unit(manuel,pr, p1, 11).
student_unit(anabela, pr, p1, 13).
student_unit(joana, cee, p2, 18).
student_unit(maria, cee, p2, 8).
student_unit(diogo, cee, p2, 11).

% professor_name, unit, shift
teaches(andre, mde, p4).
teaches(andre, mde, p3).
teaches(filipa, mde, p2).
teaches(filipa, mde, p5).
teaches(anabela, cee, p2).
teaches(anabela, cee, p1).
teaches(joao, pr, p1).
teaches(joao, pr, p2).
```

Write the corresponding rules that would answer the following queries:

a) Which students are enrolled in shift p3?

b) Which students from p5 have a grade > 14?

c) Which units is diogo enrolled in?

d) Who are the students of professor andre?

e) What are the professors of student joana?

MDE – Lab2

Exercise 2:

Given the following facts:

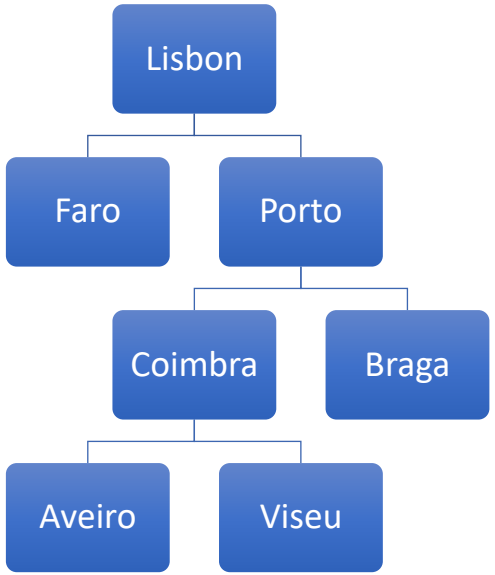
- Maria is fatter than Ana
- Ana is fatter than Luisa
- Luisa is fatter than Diana
- Diana is fatter than Sara

Write the corresponding facts and rules (using recursion) that determine that Maria is heavier that Sara.

MDE – Lab2

Exercise 3:

Consider the following road tree that connects several cities in Portugal (one direction)

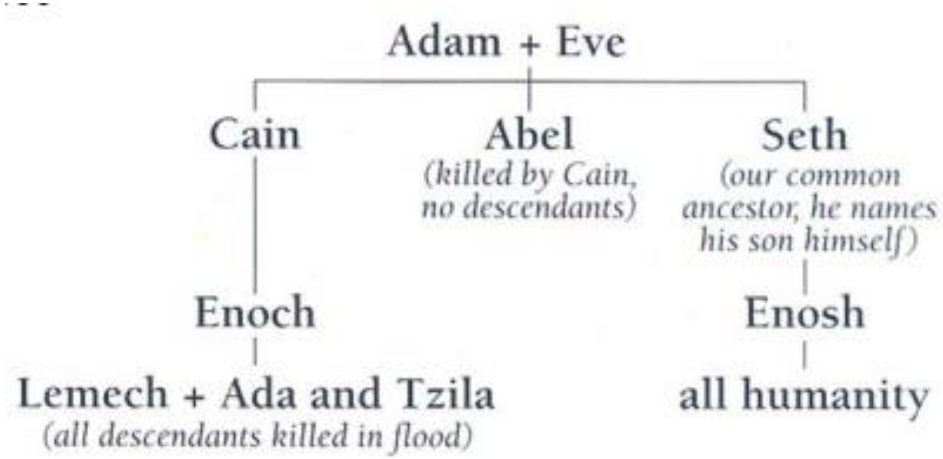


Write the corresponding facts and rules (using recursion) that would answer the following queries:

a) Can I travel from Lisbon to Viseu?
b) Can I travel from Faro to Braga?
c) How many cities I cross between Lisbon and Aveiro?

MDE – Lab2

Exercise 4:



Use the predicates **father/2** and **mother/2** to represent the genealogic tree (in this example we use the Adam and Eve's genealogic tree, but you can use yours!):

```
father(adam,abel).
father(adam,caim).
father(adam,seth).
%...

mother(eve,seth).
%...
```

Create rules to capture the following relationships:

- **son**(Father, Mother)
- **grandfather**(Grandfather, Grandson)
- **brother**(Brother1, Brother2)
- **uncle**(Uncle, Nephew)
- **cousin**(Cousin1, Cousin2)
- **ascendant**(Ascendant, Descendant)
- **descendant**(Descendant, Ascendant)

GOOD WORK!