

```

package cpsc331.assignment3;

import cpsc331.assignment3.Array;

/**
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 * Provides a method to sort the given array.
 * <br />
 *
 * <p>
 * <strong>Array Invariant:</strong>
 * </p>
 * <ol style="list-style-type: lower-alpha">
 * <li> this.LENGTH is an integer </li>
 * <li> Heapsize is an integer </li>
 * <li> i is an integer to check if the array sorted completely.
 * </li>
 * </ol>
 */
public class ArrayUtils<T extends Comparable<T>> {

    public void sort(Array<T> A){

        int heapSize = 1; // heap-size(A) = 1
        int i = 1; // integer i = 1

        while (i < A.length()){ // while(i < A.length)
            //insert(...)
            insert(A.get(i),A,heapSize); // insert (A[i])
            heapSize = heapSize + 1; //update heapSize after insertion
            i = i + 1; // i ++
        }
        i = A.length() - 1; // i = A.length - 1

        while (i > 0){ // while(i > 0)
            T largest = deleteMax(A, heapSize); // int largest = DeleteMax()
            //System.out.println(largest);
            heapSize = heapSize - 1; //update heapSize after deletion
            A.set(i,largest); // A[i] = largest
            i = i - 1; // i = i - 1
        }

    }

    /**
     * A method to insert the elements to the heap:
     * @param key The elements will be inserted
     * @param A The elements will be inserted in this array
     * @param heapSize the sizes of the heap ( will change every time when the elements has been
     inserted successfully)
     */
    public void insert(T key, Array<T> A, int heapSize){
        int x = heapSize; //int x = heap-size(A)
        A.set(x,key); // A[x] = key
        bubbleup(x,A); // bubbleup(x)
    }

    /**
     * After the heap has been added, this method can ensure it is a completed tree and it is a max-heap:
     * @param x The positions of elements in the heap
     * @param A The elements will be inserted in this array
     */
    public void bubbleup(int x, Array<T> A){
        if (!isroot(x) && (A.get(x).compareTo(A.get(parent(x))) > 0)){

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        T temp = A.get(x);           // T tmp = value(x)
        A.set(x,A.get(parent(x)));   // set the value of x to be value(parent(x))
        A.set(parent(x), temp);      // set the value of parent(x) to be tmp
        bubbleup(parent(x),A);       // bubbleup(parent(x))
    }
}

/**
 * A method to check whether the leaf is a root. :
 * @param x      The positions of elements in the heap
 */
public boolean isroot(int x){
    return x == 0; // index of root is 0, when heap is represented using an array.
}

/**
 * To get the parental position of the leaf :
 * @param x      The positions of elements in the heap
 */
public int parent (int x){
    return (x-1)/2; // index of parent of node x is (x-1)/2, when heap is represented using an array.
}

/**
 * A method to delete the top element( The maximum number) in the heap:
 * @param A      The elements will be inserted in this array
 * @param heapSize the sizes of the heap ( will change every time when the elements has been deleted
successfully)
 */
public T deleteMax(Array<T> A, int heapSize){
    T v = A.get(heapSize-1);

    if ((heapSize-1) == 0){
        return v;
    } else{
        //System.out.println(A.get(0));
        T key = A.get(0);
        A.set(0,v);
        // heapSize is not a global data, we do not modified it in this method,
        //but bubbleDown needs a updated one, so we pass heapSize -1 as argument instead.
        bubbleDown(0, A, heapSize - 1);
        return key;
    }
}

/**
 * A method to ensure the heap is a completed tree and max-heap in deletion processes:
 * @param x      the position ( node) of the heap
 * @param A      The elements will be inserted in this array
 * @param heapSize the sizes of the heap ( will change every time when the elements has been deleted
successfully)
 */
public void bubbleDown(int x, Array<T> A, int heapSize){
    if (hasRight(x, heapSize)){ //node x has two children
        if (A.get(left(x)).compareTo(A.get(right(x))) >= 0){
            if (A.get(left(x)).compareTo(A.get(x)) > 0){
                T t = A.get(left(x));           //T tep = value(left(x))
                A.set(left(x), A.get(x));       //set the value of left(x) to be value(x)
                A.set(x, t);                     // set the value of x to be tmp
                bubbleDown(left(x), A, heapSize); // bubbledown(left(x))
            }
        } else if (A.get(right(x)).compareTo(A.get(x)) > 0){
            T t = A.get(right(x));              //T tep = value(right(x))
            A.set(right(x), A.get(x));          //set the value of right(x) to be value(x)
        }
    }
}

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        A.set(x, t); // set the value of x to be tmp
        bubbleDown(right(x), A, heapSize); // bubbledown(right(x))
    }

    } else if (hasLeft(x, heapSize)){ //node has one child.
        if(A.get(left(x)).compareTo(A.get(x)) > 0){
            T t = A.get(left(x)); //T tep = value(right(x))
            A.set(left(x), A.get(x)); //set the value of right(x) to be value(x)
            A.set(x, t); // set the value of x to be tmp
            bubbleDown(left(x), A, heapSize); // bubbledown(right(x))
        }
    }
}

/**
 * To check weather the leaf has left child :
 * @param x      The positions of elements in the heap
 * @param heapSize  The sizes of the heap
 */
public boolean hasLeft(int x, int heapSize){
    return (2*x + 1) < heapSize;
}

/**
 * To check weather the leaf has right child :
 * @param x      The positions of elements in the heap
 * @param heapSize  The sizes of the heap
 */
public boolean hasRight(int x, int heapSize){
    return (2*x + 2) < heapSize;
}

/**
 * A method to get the left child node. :
 * @param x      The positions of elements in the heap
 */
public int left(int x){
    return (2*x + 1); // index of left child of node x is (2*x + 1), when heap is represented
using an array.
}

/**
 * A method to get the right child node. :
 * @param x      The positions of elements in the heap
 */
public int right(int x){
    return (2*x + 2); // index of right child of node x is (2*x + 2), when heap is represented
using an array.
}

}

```

CPSC331A3Report

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2 Report

we select the heap sort algorithm which is introduced in lecture 18. The reason why we choose it is that the correctness of this algorithm has been proven.(Sides of lecture 18). In addition, Heapsort algorithm uses $O(n \log n)$ in the worst case. Also, the storage space required by this implementation of Heap Sort is in $O(\log n)$. (Sides of lecture 18) Hence, it satisfies the requirements for the sorting algorithm we need to implement for this assignment.