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Research Interest

- Guaranteeing safety and verification in fields of robotics and machine learning
- Integrating theoretical and practical approaches for real-world application in robotics
- General and fundamental research applicable to various fields such as robotics, control theory, machine learning, and optimization

Education

Korea Advanced Institute of Science and Technology (KAIST)

Daejeon, S.Korea

MASTER'S STUDENT IN AEROSPACE ENGINEERING

Mar. 2021 - Present

• GPA: 3.92/4.0

Seoul National University (SNU)

Seoul, S.Korea

Mar. 2015 - Feb. 2021

B.S. IN MECHANICAL ENGINEERING

- GPA: 3.83/4.0. Summa Cum Laude
- Leave of Absence for Mandatory Military Service (2017 2019)

Publications

- [C3] <u>J. Han</u>*, Y.Min*, B.Jeong, H.Chae and H.Choi. "DS-K3DOM: 3-D Dynamic Occupancy Grid Mapping with Kernel Inference and Dempster-Shafer Evidential Theory" (*equal contribution) International Conference on Robotics and Automation (ICRA), 2023 (Accepted). [preprint] [code]
- [C2] <u>J. Han</u>, and H.Choi. "Computation of Tight Forward Reachable Set for a Multirotor based on the Nonlinear Adaptive Controller" American Control Conference (ACC), 2023 (Submitted). [preprint]
- [C1] <u>J. Han</u>, M. Tahk, and H. Choi, "Pseudospectral method-based safe motion planning for quadrotors in a cluttered environment" AIAA Science and Technology Forum (Scitech), 2022. [paper]

Research Experience _____

Autonomous Decision and Control Lab, CU Boulder

Boulder, CO

VISITING SCHOLAR | ADVISOR: PROF. ZACHARY SUNBERG

OCT. 2022 - Present

· developing decision making algorithm of control system with temporal logic and reachability

Lab for information and Control Systems, KAIST

Daejeon, S.Korea

RESEARCH ASSISTANT | ADVISOR: PROF. HAN-LIM CHOI

Jan. 2021 – Present

- Proposed algorithm for kernel-based 3-dimensional dynamic occupancy grid map (DS-K3DOM) [C3]
- Proposed method for real-time computation of tighter forward reachable set (FRS) of multirotor [C2]
- Planned optimal trajectory in cluttered environment for quadrotors [C1]
- installed sensors to hardware equipment for research projects funded by KI-Robotics and ADD
- maintained motion capture system in KARPE

Innovative Design and Integrated Manufacturing Lab, SNU

Seoul, S.Korea

RESEARCH INTERN | ADVISOR: PROF. SUNG-HOON AHN

Jun. 2020 - Aug. 2020

• Conducted thesis research on planning path and object recognition of 6 DOF robot actuator for surface cleaning

Review Activities

• IEEE Control System Letters (L-CSS), 2022



Programming C/C++, Python, MATLAB

Libraries & Tools ROS, CUDA, Pytorch, LaTeX, SolidWorks

Languages Korean (Native), English (Fluent, 2 years in U.S. military, GRE 157/168/3.5, TOEFL MyBest 100)

Honors & Awards

SCHOLARSHIPS

2023 - 2025 Korean Government Scholarship for Ph.D Program, USD 40,000 per year, Government of S. Korea	the U.S.
2021 - 2023 Government-Funded Scholarship, 90% Tuition, KAIST	Daejeon, S.Korea
Sp. 2020 SNU Alumni-Funded Scholarship, Full Tuition, SNU Alumni Foundation	Seoul, S.Korea
2015 - 2017 Merit-Based Scholarship, $\{50\%, Full \times 2, 33\%\}$ Tuition, SNU and SNU Foundation	Seoul, S.Korea

AWARDS

Dec. 2019 Outstanding Award, SNU ME Materials and Manufacturing Process Course	Seoul, S.Korea
Jun. 2016 Participation Award, Seoul Hackathon, Administration of Seoul	Seoul, S.Korea
Dec. 2015 Creative Award, SNU ME Creative Engineering Design Course	Seoul, S.Korea

Extracurricular Activity _____

2nd Infantry Divison, US Army

Unit Supply Specialist, Sergeant

• Served in military as Korean augmentation to the United States army(KATUSA) agent.

- Managed unit supply in air ambulance company.
- Partly was in charge of COC (Change of Command) inspection and ARMS inspection

DALISHA (SNU Running Crew)

LEADERSHIP MEMBER

• Led running during COVID-19.

• Managed accounting in the crew.

Pyeongtaek, S.Korea

Nov. 2017 - Aug. 2019

Seoul, S.Korea

Sep. 2018 - Feb. 2021