

Computational methods and applications (AMS 147)

Homework 6 - Due Friday, March 17, 11:59 pm

Please submit to CANVAS a .zip file that includes the following Matlab functions:

tridiag_solver.m

AB3.m

solve_ODE_system.m

Exercise 1 Write a Matlab function that implements the Thomas algorithm to solve tridiagonal linear systems of equations in the form

$$\begin{bmatrix} a_1 & c_1 & 0 & \cdots & 0 \\ e_1 & a_2 & c_2 & \ddots & 0 \\ 0 & \ddots & \ddots & \ddots & 0 \\ \vdots & \ddots & & a_{n-1} & c_{n-1} \\ 0 & \cdots & 0 & e_{n-1} & a_n \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_{n-1} \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_{n-1} \\ b_n \end{bmatrix} \quad (1)$$

The function should be in the form

```
function x = tridiag_solver(e,a,c,b)
```

Input:

$\mathbf{e}=[e_1 \ e_2 \ \cdots \ e_{n-1}]$ $\mathbf{a}=[a_1 \ a_2 \ \cdots \ a_n]$ $\mathbf{c}=[c_1 \ c_2 \ \cdots \ c_{n-1}]$ $\mathbf{b}=[b_1 \ b_2 \ \cdots \ b_n]^T$

Output:

$\mathbf{x}=[x_1 \ x_2 \ \cdots \ x_n]^T$

Exercise 2 Consider the system of nonlinear ordinary differential equations

$$\begin{cases} \frac{dy(t)}{dt} = f(y(t), t) \\ y(0) = y_0 \end{cases} \quad (2)$$

where $f : \mathbb{R}^n \times [0, T] \rightarrow \mathbb{R}^n$, $y : [0, T] \rightarrow \mathbb{R}^n$. Write a Matlab function that solves the system (2) by using the third-order Adams-Bashforth scheme. To start-up the scheme (first two steps) you can

use the Euler-forward or the Heun method. The function should be in the form

```
function [y,t] = AB3(fun,y0,T,DT,IOSTEP)
```

Input:

fun: function handle representing $f(y,t)$

y0: column vector representing the initial condition

T: period of integration

DT: time step

IOSTEP: Input/output step. The solution is saved in the output matrix **y** every **IOSTEP** steps.

Output:

y: $n \times S$ matrix collecting the time snapshots of the solution to (2). Note that the total number of snapshots S (including the initial condition) is $\text{floor}(T/(IOSTEP*DT))+1$.

t: vector collecting the time instants at which the solution is saved in the output matrix **y**.

Exercise 3 Consider the following nonlinear dynamical system

$$\begin{cases} \frac{dy_1(t)}{dt} = -y_1(t) + y_2(t)y_3(t) \\ \frac{dy_2(t)}{dt} = -y_2(t) + (y_3(t) - 2)y_1(t) \\ \frac{dy_3(t)}{dt} = 1 - y_1(t)y_2(t) \end{cases} \quad (3)$$

It is known that the solution to (3) is chaotic in time and it settles on a strange attractor. By using the function **AB3.m** you coded in Exercise 2, compute the numerical solution to (3). To this end, set **NSTEPS**=1000000, **IOSTEP**=50, **DT**= 1e-3, **y0**=[1 2 3]^T, and write a function

```
function solve.ODE.system()
```

that returns the following items:

1. The plots of the trajectories $y_1(t)$, $y_2(t)$ and $y_3(t)$ versus time in **figure(1)**.
2. A three-dimensional plot of the curve $(y_1(t), y_2(t), y_3(t))$ in **figure(2)** (use the command **plot3()**). Such curve provides a visualization of the strange attractor.