

```
1: //
2: // Body.cpp
3: // ps3a
4: //
5: // Created by Jingxian Shi on 2/19/18.
6: // Copyright © 2018 Jingxian Shi. All rights reserved.
7: //
8:
9: #include "Body.hpp"
10:
11: Body::Body()
12: {
13:
14: }
15:
16: Body::Body(double xpos, double ypos, double xvel, double yvel, double mass, std::
string file_name)
17: {
18:     _xpos = xpos;
19:     _ypos = ypos;
20:     _xvel = xvel;
21:     _yvel = yvel;
22:     _mass = mass;
23:     _image_file = file_name;
24:
25:     _texture.loadFromFile(_image_file);
26:     _sprite.setTexture(_texture);
27:
28: }
29:
30: Body::~~Body()
31: {
32:
33: }
34:
35: std::ostream& operator<<(std::ostream& out, Body& body)
36: {
37:     out << body._xpos << " "
38:     << body._ypos << " "
39:     << body._xvel << " "
40:     << body._yvel << " "
41:     << body._mass << " "
42:     << body._image_file;
43:
44:     return out;
45: }
46:
47: std::istream& operator>>(std::istream& in, Body& body)
48: {
49:     in >> body._xpos >> body._ypos >> body._xvel >> body._yvel >> body._mass >> b
ody._image_file;
50:     body._texture.loadFromFile(body._image_file);
51:     body._sprite.setTexture(body._texture);
52:
53:     return in;
54: }
55:
56: void Body::draw(sf::RenderTarget& target, sf::RenderStates states) const
57: {
58:     sf::Sprite image = _sprite;
59:
60:     image.setPosition(_window_size/2.0 + _xpos * _window_size * 0.5 / _univ_size,
_window_size/2.0 - _ypos * _window_size * 0.5 / _univ_size);
61:
62:     target.draw(image, states);
```

```
63: }
64:
65: void Body::step(double seconds, double force_x, double force_y)
66: {
67:     double accel_x = force_x / _mass;
68:     double accel_y = force_y / _mass;
69:
70:     _xvel += accel_x * seconds;
71:     _yvel += accel_y * seconds;
72:
73:     _xpos += _xvel * seconds;
74:     _ypos += _yvel * seconds;
75: }
```

```
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7: //
8:
9: #ifndef Body_hpp
10: #define Body_hpp
11:
12: #include <stdio.h>
13: #include <iostream>
14: #include <string>
15: #include <SFML/Graphics.hpp>
16:
17: class Body : public sf::Drawable
18: {
19: public:
20:     Body();
21:     Body(double xpos, double ypos, double xvel, double yvel, double mass, std::string file_name);
22:     ~Body();
23:     void setWindowSize(int window_size) {_window_size = window_size;}
24:     void setUnivSize(double univ_size) {_univ_size = univ_size;}
25:     double getUnivSize() {return _univ_size;}
26:     void step(double seconds, double force_x, double force_y);
27:
28:     double getPosX() {return _xpos;}
29:     double getPosY() {return _ypos;}
30:     double getVelX() {return _xvel;}
31:     double getVelY() {return _yvel;}
32:     double getMass() {return _mass;}
33:
34:     friend std::ostream& operator<<(std::ostream& out, Body& body);
35:     friend std::istream& operator>>(std::istream& in, Body& body);
36:
37: private:
38:     virtual void draw(sf::RenderTarget& target, sf::RenderStates states) const;
39:
40:     double _univ_size;
41:     int _window_size;
42:     double _xpos, _ypos, _xvel, _yvel, _mass;
43:     std::string _image_file;
44:     sf::Texture _texture;
45:     sf::Sprite _sprite;
46: };
47:
48:
49: #endif /* Body_hpp */
50:
```