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1: #include <iostream>
2: #include "Body.hpp"
3: #include <SFML/Graphics/CircleShape.hpp>
4: #include <SFML/Graphics/RectangleShape.hpp>
5: #include <sstream>
6: #include <vector>
7: #include <cmath>
8:
9: using namespace std;
10:
11: int main(int argc, const char * argv[])
12: {
13:     if(argc != 3)
14:     {
15:         cout << "Wrong number of arguments" << endl;
16:         return -1;
17:     }
18:
19:     double total_t = atof(argv[1]);
20:     double delta_t = atof(argv[2]);
21:     double t = 0;
22:
23:     int num_body;
24:     double universe_radius;
25:
26:     cin >> num_body >> universe_radius;
27:
28:     int window_size = 500;
29:     sf::RenderWindow window(sf::VideoMode(window_size, window_size), "Universe");
30:     window.setFramerateLimit(1);
31:
32:     vector<Body*> body;
33:
34:     for(int i = 0; i < num_body; i++)
35:     {
36:         body.push_back(new Body);
37:         cin >> (*body[i]);
38:         (*body[i]).setWindowSize(window_size);
39:         (*body[i]).setUnivSize(universe_radius);
40:     }
41:
42:     double gravity = 6.67e-11;
43:
44:     while (window.isOpen())
45:     {
46:         sf::Event event;
47:         while (window.pollEvent(event))
48:         {
49:             if (event.type == sf::Event::Closed){
50:                 window.close();
51:             }
52:         }
53:
54:         if (t < total_t)
55:         {
56:             for(int i = 0; i < num_body; i++)
57:             {
58:                 double force_x = 0;
59:                 double force_y = 0;
60:
61:                 for(int j = 0; j < num_body; j++)
62:                 {
63:                     if(i != j)
64:                     {
65:                         double delta_x = body[j]->getPosX() - body[i]->getPosX();
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66:             double delta_y = body[j]->getPosY() - body[i]->getPosY();
67:             double r = sqrt(pow(delta_x, 2) + pow(delta_y, 2));
68:             double force = ((gravity * body[i]->getMass() * body[j]->
getMass())
69:                 / pow(r, 2));
70:
71:             force_x = force_x + force * delta_x / r;
72:             force_y = force_y + force * delta_y / r;
73:         }
74:     }
75:     body[i]->step(delta_t, force_x, force_y);
76: }
77: t += delta_t;
78: }
79:
80: window.clear(sf::Color::Black);
81: for(int i = 0; i < num_body; i++)
82: {
83:     window.draw(*body[i]);
84: }
85: window.display();
86: }
87:
88: for (int i = 0; i < num_body; i++)
89: {
90:     cout << (*body[i]) << endl;
91: }
92:
93: return 0;
94: }
95:
```