

## **CSE3442 (Fall 2020)**

### **Lab #1**

- 1.** Install the TI Code Composer Studio software on your laptop from [https://software-dl.ti.com/ccs/esd/documents/ccs\\_downloads.html](https://software-dl.ti.com/ccs/esd/documents/ccs_downloads.html).
- 2.** Download the Tivaware library SW-EK-TM4C123GXL-2.2.0.295.exe at <https://www.ti.com/tool/SW-TM4C> and extract the tm4c123gh6pm.h file from the /inc folder to your computer.
- 3.** Connect your controller board to your PC. If you do not have a board yet, there are a couple of boards you can borrow from the cabinet.
- 4.** Follow these steps in CCS:
  - a. Select File > New > Project
  - b. Select CCS Project and Select Next
  - c. Make sure the target is Tiva TM4C123GH6PM and the connection is Stellaris In-Circuit Debug Interface.
  - d. Give the project a name, use an Empty Project, and Select Finish
  - e. Copy the stop\_go.c code from class to the project directory.
  - f. If main.c exists in the project, delete it from the project.
  - g. Copy the tm4c123gh6pm.h file you downloaded earlier to the project directory.
  - h. Select the "Debug" button from the toolbar.
  - i. The program will compile and then stop at the opening brace ({} in main()).
  - j. Select View > Debug and press the green play arrow to continue.
  - k. Optional: To prevent the program from stopping in main() every time you run the program, go to Project > Properties and then Debug > Auto Run and Launch Options and remove "main" in the Run to symbol edit box.
- 5.** Verify that the stop go program runs as expected.
- 6.** Demonstrate this result to the GTA for credit.