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Learning for Safety-Critical Control with Control Barrier Functions

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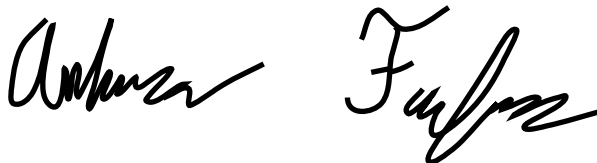
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