

# DeepLabCut AI Residency

## Day 2 Session 3:

### What could be done next after creating your videos?

July 30 & August 1, 2025  
McGill University, Montreal

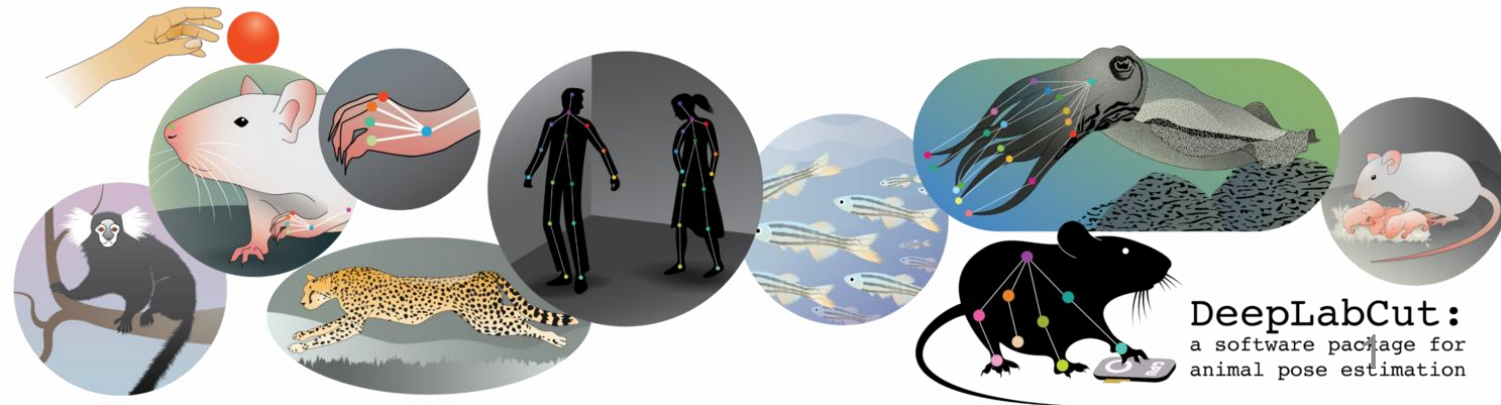
Jiayue Yang  
Vic Shao-Chinh Chiang



DeepLabCut  
AI Residency  
next-gen animal behavior



McGill



DeepLabCut:  
a software package for  
animal pose estimation

# Github troubleshooting

<https://github.com/DeepLabCut/DeepLabCut/issues>

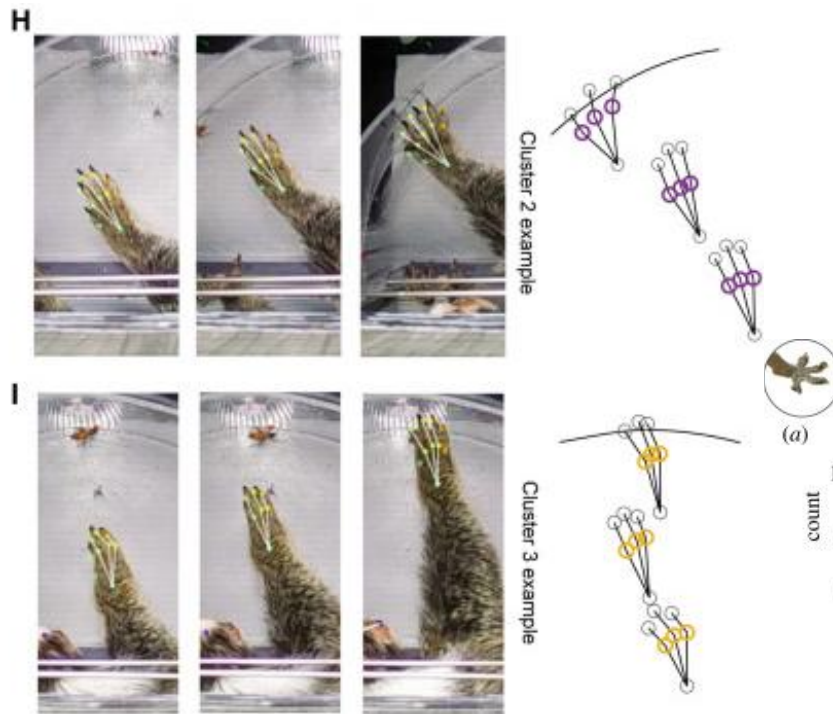
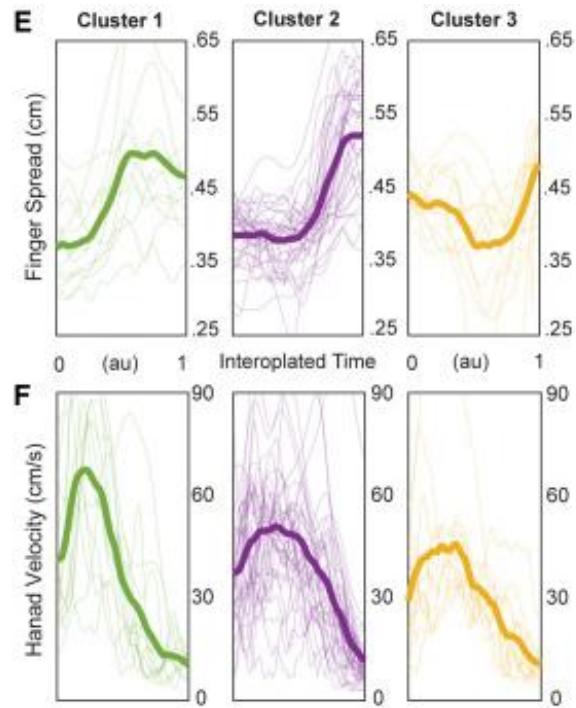
# Post-processing analysis

Predictions saved in the .csv file

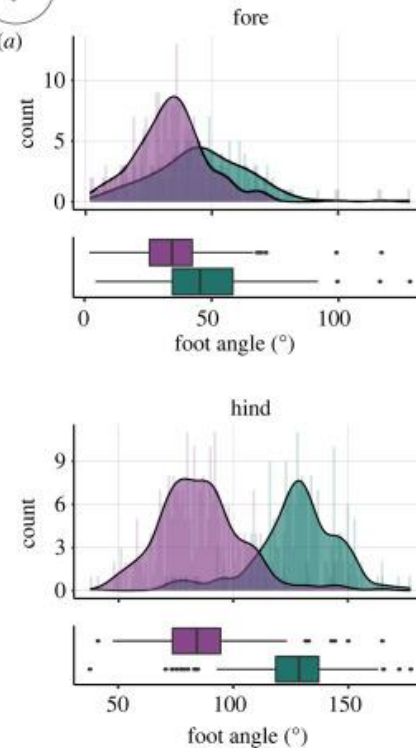
	A	B	C	D	E	F	G	H	I	J	K	L	M
1	scorer	DLC_Resn	DLC_Resn	DLC_Resn	DLC_Resn	DLC_Resn	DLC_Resn	DLC_Resn	DLC_Resn	DLC_Resn	DLC_Resn	DLC_Resn	DLC_Resn
2	bodyparts	snout	snout	snout	leftear	leftear	leftear	rightear	rightear	rightear	tailbase	tailbase	tailbase
3	coords	x	y	likelihood	x	y	likelihood	x	y	likelihood	x	y	likelihood
4	0	80.91712	92.05767	1	69.20795	108.6366	0.942331	92.07974	92.72308	1	136.106	180.6075	1
5	1	78.02665	88.78679	0.950241	70.09908	105.9495	0.91922	91.32231	90.80062	1	137.5963	177.1548	1
6	2	76.72874	87.0842	0.907064	70.9521	104.8231	0.925017	89.95668	88.45271	1	138.4398	174.4065	0.975117
7	3	75.42415	81.2308	0.906549	69.91133	100.4417	0.971143	90.21242	86.79662	1	140.3699	171.2766	0.941469
8	4	74.90831	79.4467	0.917339	70.00687	95.64727	0.982664	89.69899	81.51991	1	143.1502	168.5768	1
9	5	75.79663	76.99796	0.997803	65.7443	93.66921	1	88.60724	78.51907	1	145.0404	162.1291	1
10	6	75.07459	74.80866	1	65.55029	91.83193	1	88.082	76.3456	1	146.8154	157.6959	1
11	7	76.72284	73.38977	0.994815	66.74099	90.32472	0.963047	88.98244	77.13773	1	149.4682	157.2887	0.954272
12	8	78.424	73.10925	0.979836	72.33332	90.08562	0.949453	91.82968	74.81139	1	152.9919	147.7774	1
13	9	81.72089	67.74748	1	74.0369	85.96742	1	93.92986	74.25487	1	153.8246	145.0593	1
14	10	84.31126	64.64781	1	75.96573	82.4562	0.979163	96.87737	72.71422	1	155.452	142.5923	0.988791
15	11	86.33119	63.39129	0.905758	72.5575	81.35223	0.956696	97.62001	73.38286	1	157.3527	140.5434	0.908507
16	12	87.67729	63.92438	0.85362	74.5552	80.55028	0.962329	100.9537	73.13758	1	157.7419	138.1044	0.952924
17	13	100.1835	65.76128	0.821375	78.21173	79.31243	0.939936	105.9113	71.72961	1	160.0629	136.8153	0.983795
18	14	103.7123	62.18805	0.972323	82.93774	76.19315	1	108.4913	67.85687	1	163.8009	135.4301	0.973616
19	15	104.2369	61.19025	0.980276	85.79246	75.16173	1	110.6627	66.43133	1	168.4956	134.5776	0.925914

Predicted labels at each frame  
and animals (in pixel)

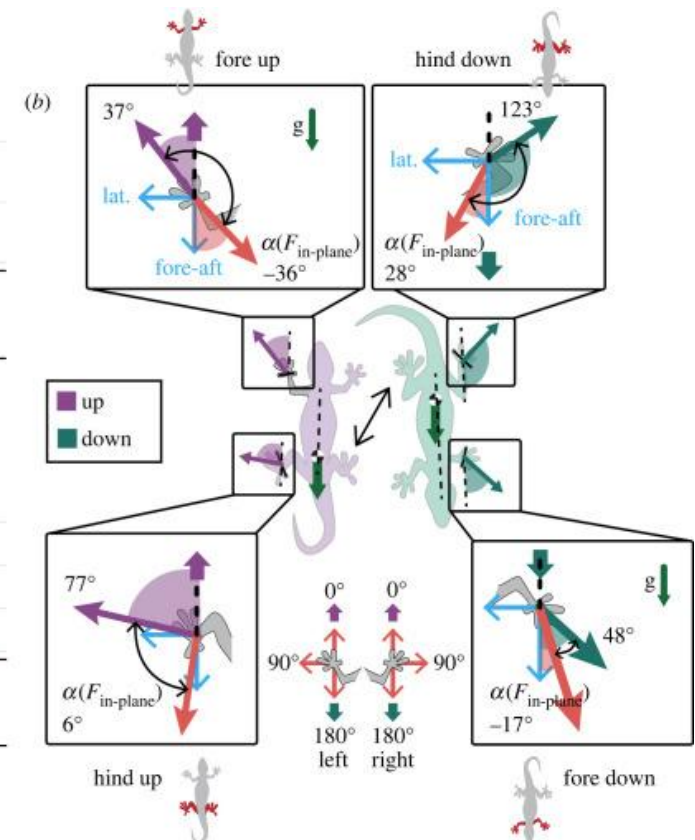
# Post-processing analysis



Shaw, et al. (2023). Current Biology.



Schultz, et al. (2023). J R Soc Interface.



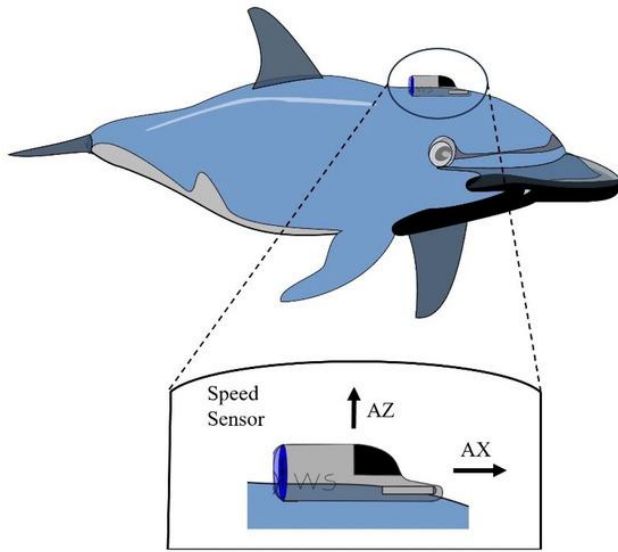
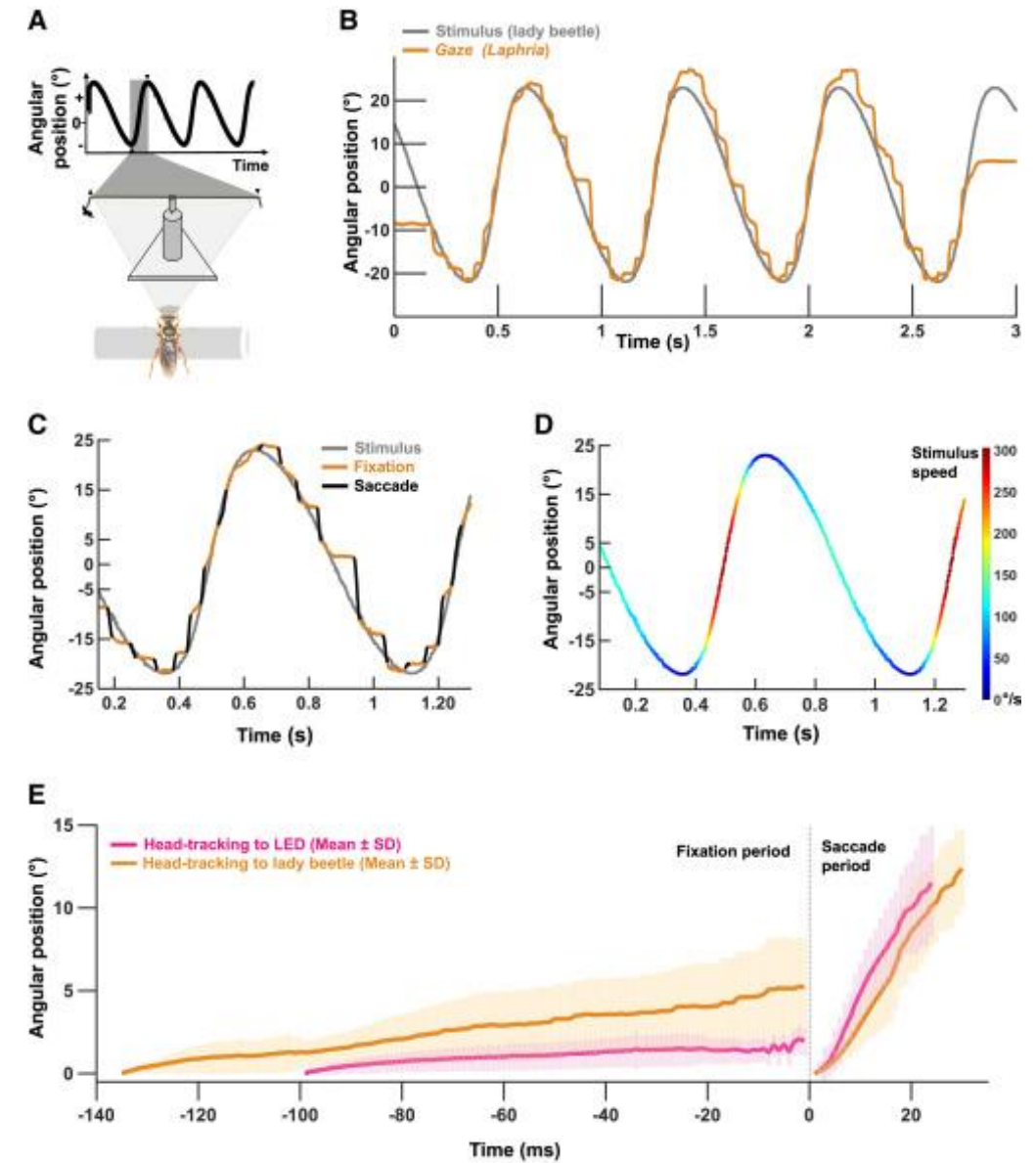


Table 5. Comparison of different approaches with our proposed system.

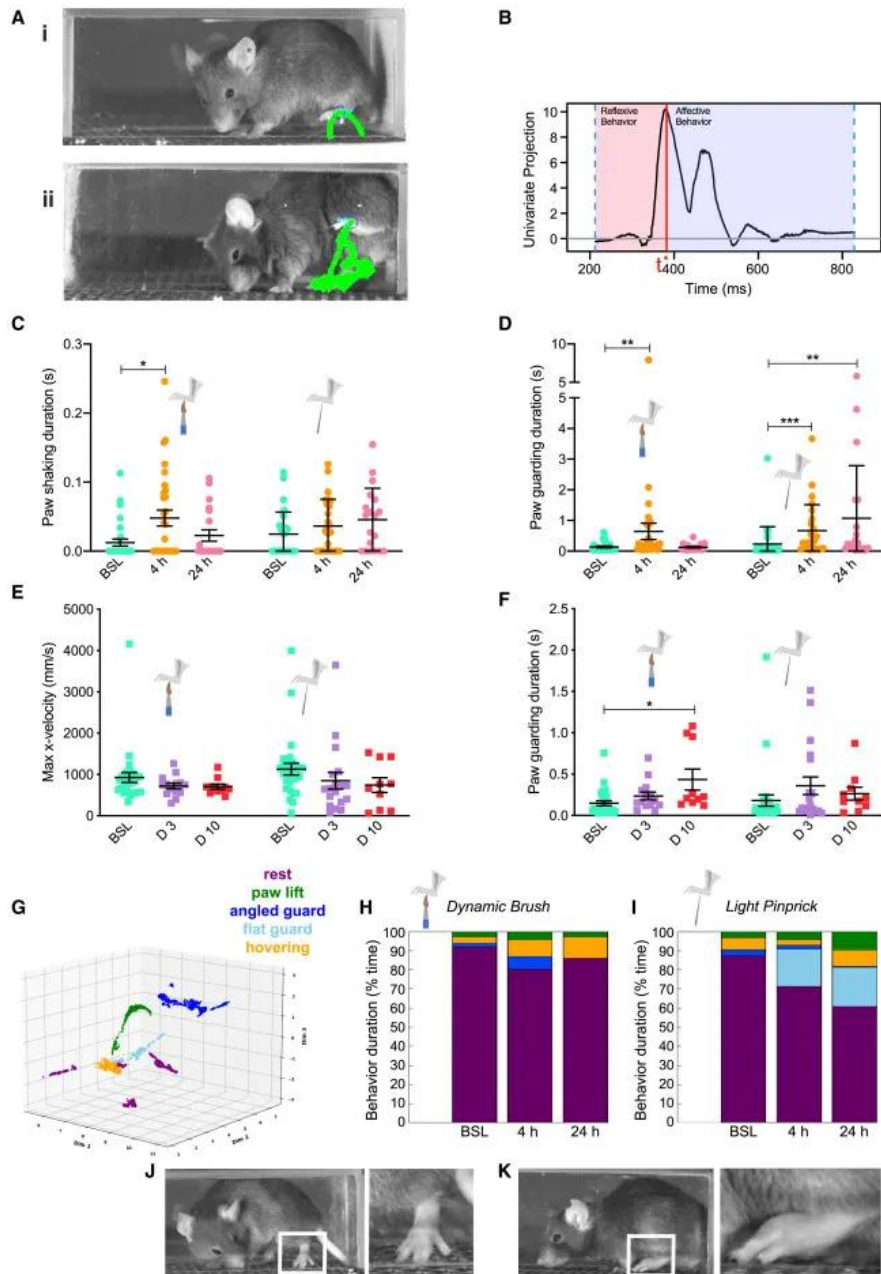
Methods	Purpose	Accuracy	Recall	Precision	F-Score
Compressive Tracking [23]	Detect and track dolphins	-	75.7%	78.8%	77.2%
OpenPose [30]	The angles of dolphin swimming	86%	85%	81%	82.9%
Faster R-CNN [24]	Track the trajectories of dolphins	81%	80.4%	82.3%	81.3%
Ours	Identify the daily behaviors of dolphins	94.3%	92.9%	93.6%	93.2%

Tseng, et al. (2024). J. Mar. Sci. Eng.

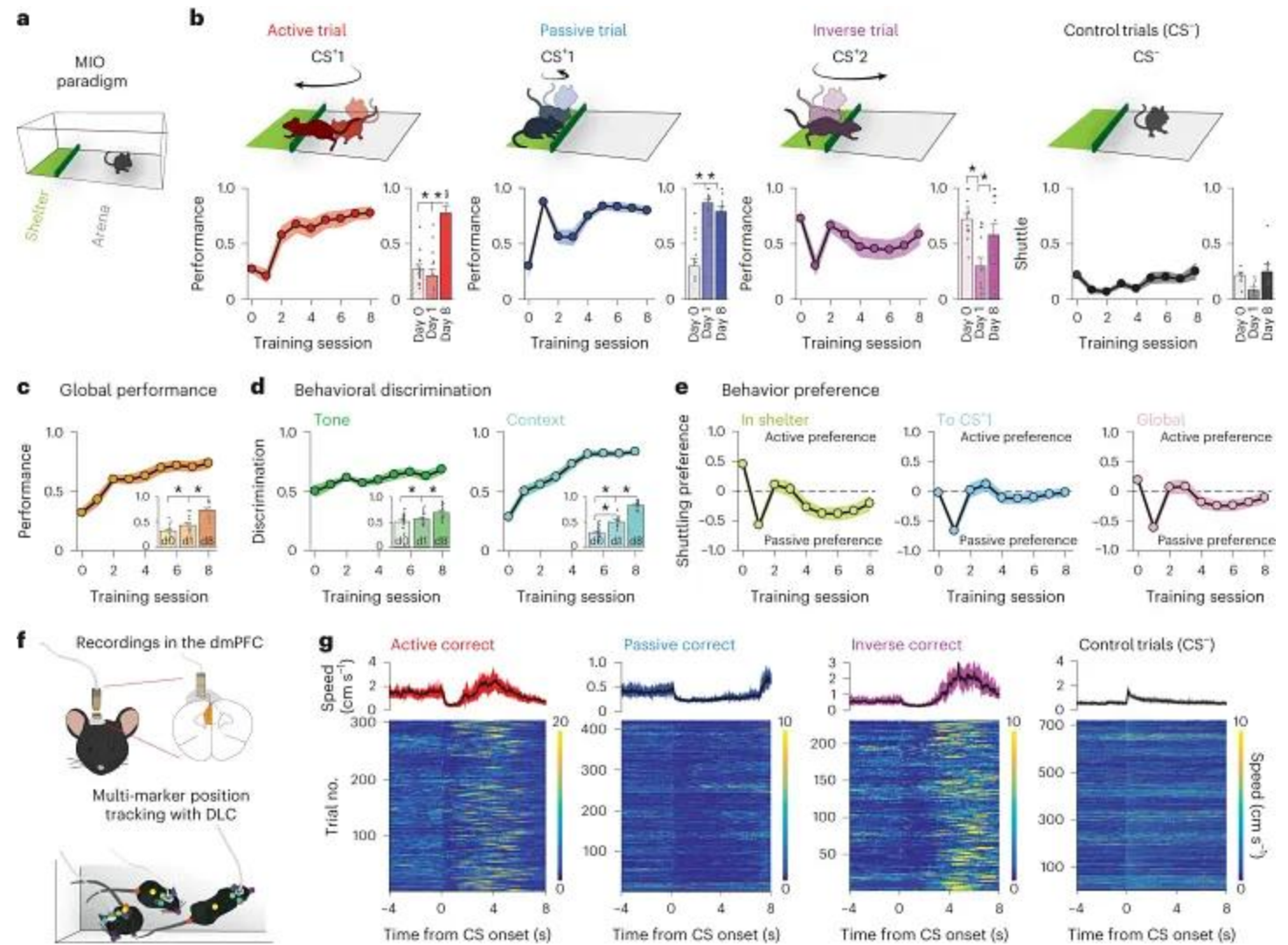


Talley, et al. (2023). Current Biology.





Bohic, et al. (2023). Neuron.



Martin-Fernandez, et al. (2023). Nature Neuroscience.

# DeepLabCut 3D

## DeepLabCut 3D

### 2D Project Folders



▶ training data,  
trained networks,  
config.yaml file

This is the master folder created when  
you create a project (Step 1)

### New (2D) videos for analysis



▶ batch process videos  
▶ analyzed data

you can place new videos here, and then run:  
`deeplabcut.analyze_videos(config_path,  
folderpath, videotype='.mp4')`

Your 2D or 3D project "entry point" is through the config.yaml file  
When you want to work on your project:

```
activate DLCenvName  
ipython  
import deeplabcut  
config_path = '/home/yourprojectfolder/config.yaml'
```

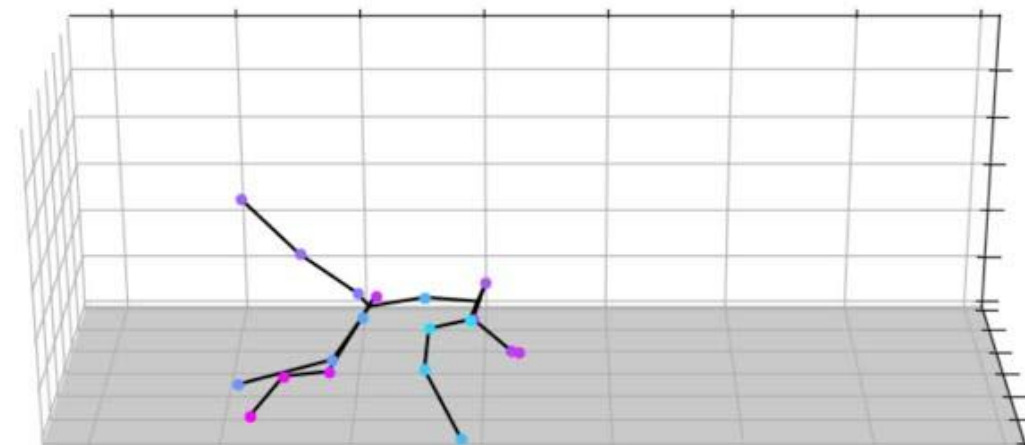
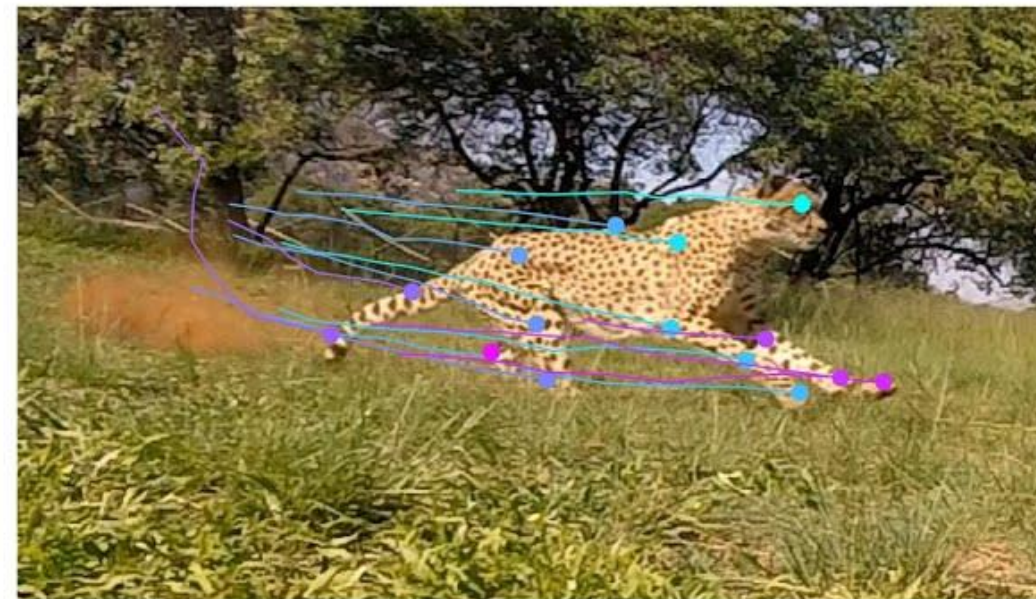
### 3D Project Folder



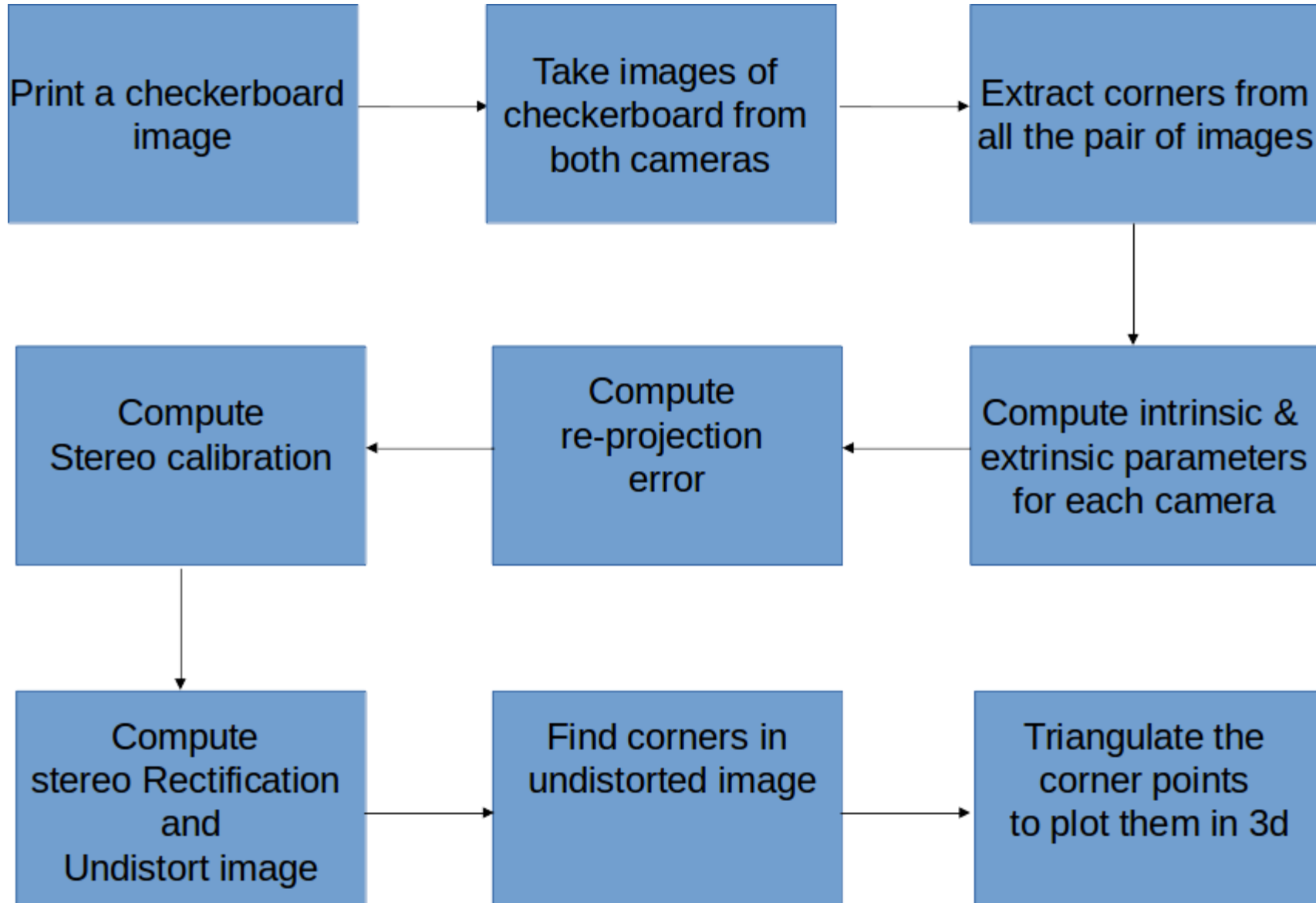
▶ 3D config.yaml  
tools for calibration,  
camera corrections

This is the 3D master folder created when  
you create a 3D project (Step 1)

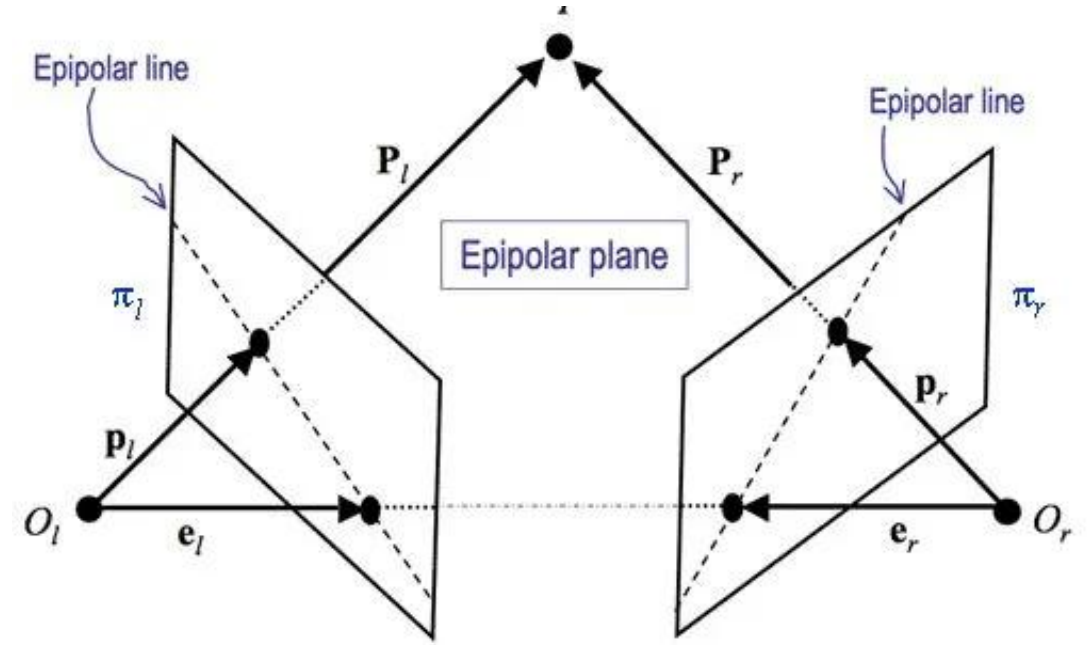
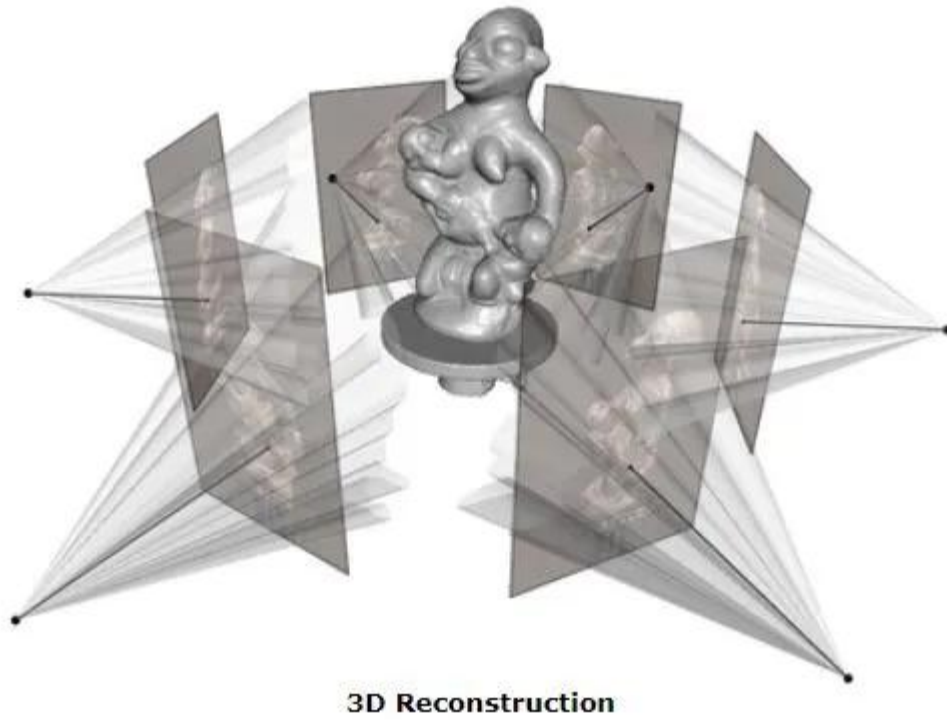
▶ batch process 3D video analysis:  
`deeplabcut.triangulate(  
config_path3d, video_folder)`



# DeepLabCut 3D workflow







**Stereo calibration** estimates the **intrinsic** and **extrinsic** parameters of two cameras used together to reconstruct 3D information from 2D images.

- How the 2D cameras' lenses distort the image?
- How far apart they are, and which way they're pointing?

# DeepLabCut 3D commands

1. Creating a 3D project config file, `deeplabcut.create_new_project_3d('3D_prog','scorer',num_cameras=2)`
2. Editing the config file skeleton & bodyparts based on 2D projects,
3. Extract calibration images (cameraName-##),  
- 30 - 50 pairs of images (1 per camera → pairs)
4. Calibrating cameras, - `deeplabcut.calibrate_cameras(config3d, cbrow=8, cbc=6, calibrate=True/False, alpha=0.9)`
5. Undistorting, `deeplabcut.check_undistortion(config_path3d, cbrow=8, cbc=6)`
6. Triangulating videos, `deeplabcut.triangulate(config_path3d, video_path, videotype='.mp4', filterpredictions=True, save_as_csv=True)`
7. Creating labeled video, `deeplabcut.create_labeled_video_3d(config_path3d, [video_path], videotype='.mp4', view=[120, 270], xlim=[-250, 250], ylim=[-250, 250], zlim=[-250, 250])`



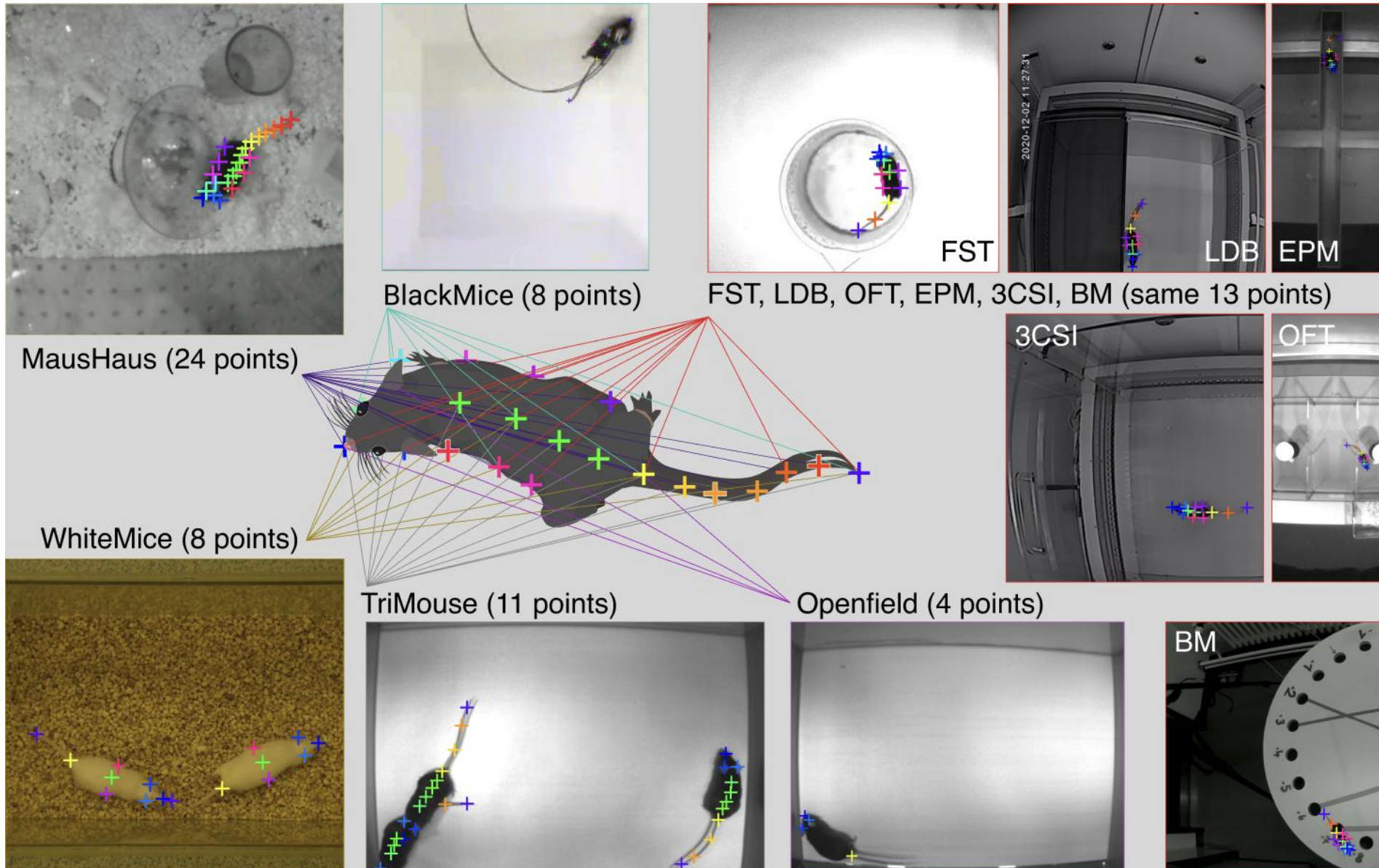
# Model Zoo

**a** 39 keypoint predictions with a single SA-Quadruped model across species



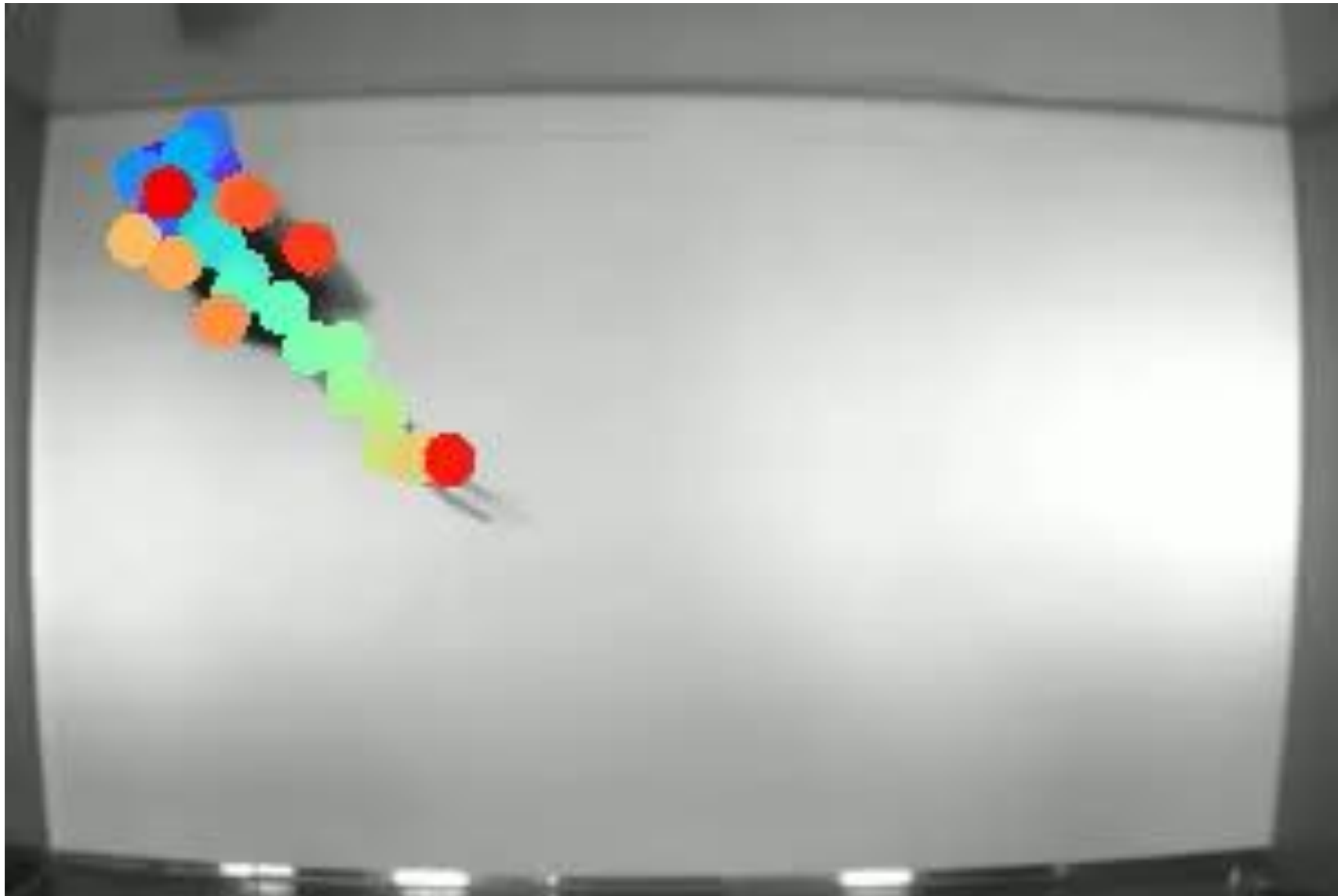


# Model Zoo

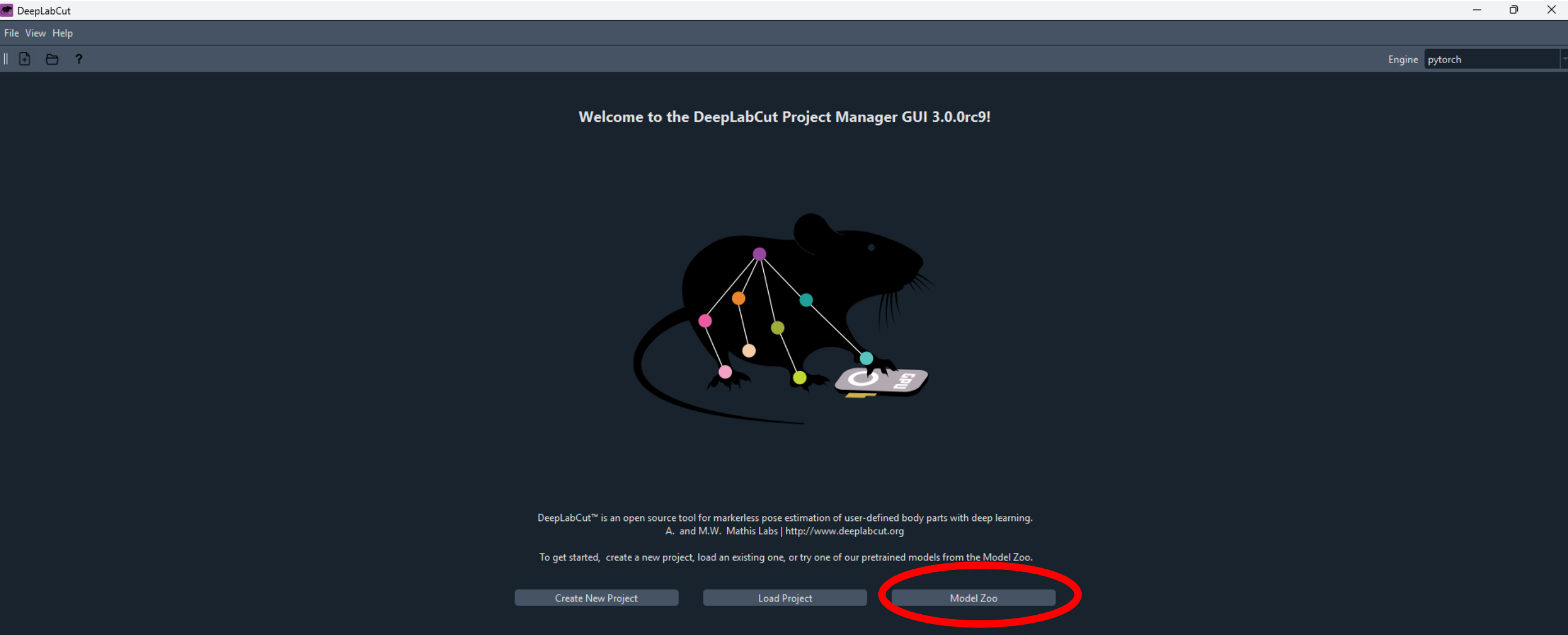


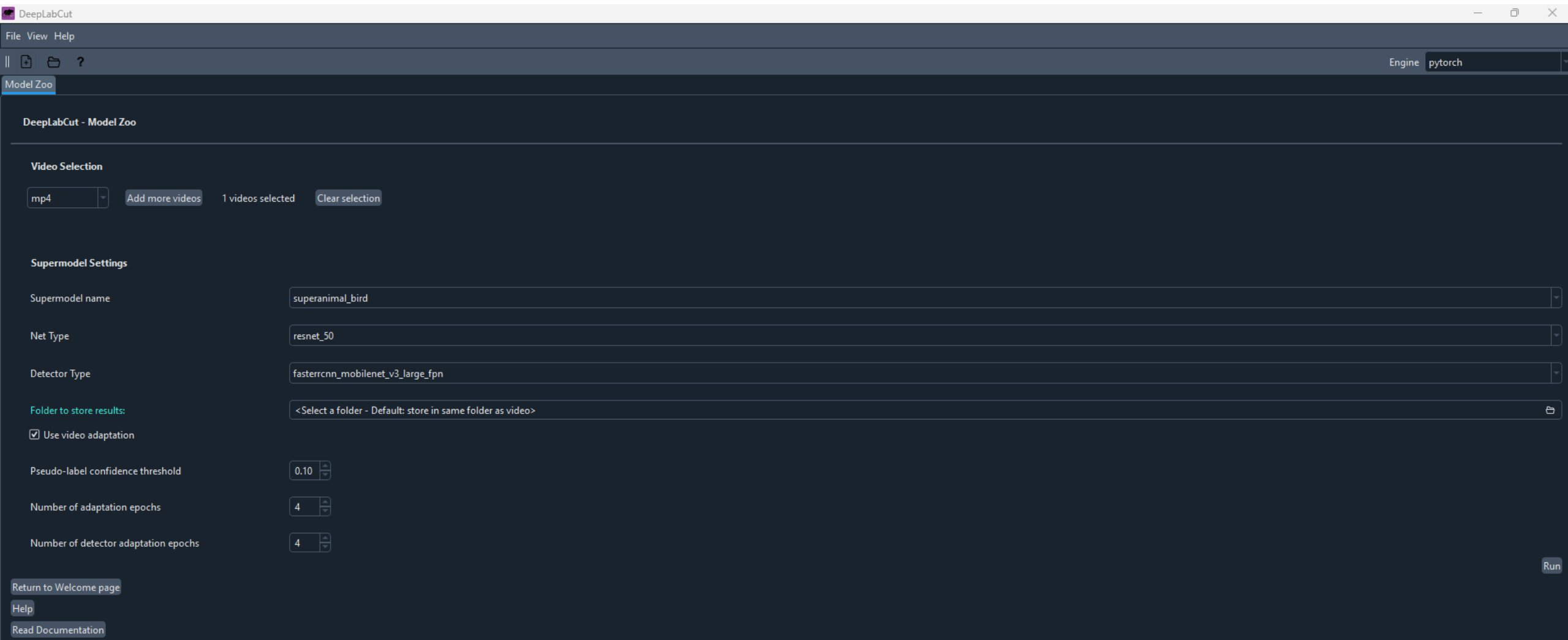


[https://github.com/DeepLabCut/DeepLabCut/blob/main/examples/COLAB/COLAB\\_DEMO\\_SuperAnimal.ipynb](https://github.com/DeepLabCut/DeepLabCut/blob/main/examples/COLAB/COLAB_DEMO_SuperAnimal.ipynb)



# Model Zoo GUI





# Try DLC model zoo!

On their website: <https://contrib.deeplabcut.org/>

HuggyFace app:

<https://huggingface.co/DeepLabCut/DeepLabCutModelZoo-SuperAnimal-Bird/tree/main>



<https://deeplabcut.github.io/DeepLabCut/docs/recipes/UsingModelZooPupil.html>



# You Only Look Once (YOLO)

## **You Only Look Once: Unified, Real-Time Object Detection**

Joseph Redmon\*, Santosh Divvala\*<sup>†</sup>, Ross Girshick<sup>¶</sup>, Ali Farhadi\*<sup>†</sup>

University of Washington\*, Allen Institute for AI<sup>†</sup>, Facebook AI Research<sup>¶</sup>

<http://pjreddie.com/yolo/>






*machine learning &  
knowledge extraction*



*Review*

## **A Comprehensive Review of YOLO Architectures in Computer Vision: From YOLOv1 to YOLOv8 and YOLO-NAS**

Juan Terven <sup>1,\*</sup> , Diana-Margarita Córdova-Esparza <sup>2</sup>  and Julio-Alejandro Romero-González <sup>2</sup> 

<sup>1</sup> Instituto Politecnico Nacional, CICATA-Qro, Queretaro 76090, Mexico

<sup>2</sup> Facultad de Informática, Universidad Autónoma de Querétaro, Queretaro 76230, Mexico; diana.cordova@uaq.mx (D.-M.C.-E.); julio.romero@uaq.mx (J.-A.R.-G.)

\* Correspondence: jrtervens@ipn.mx

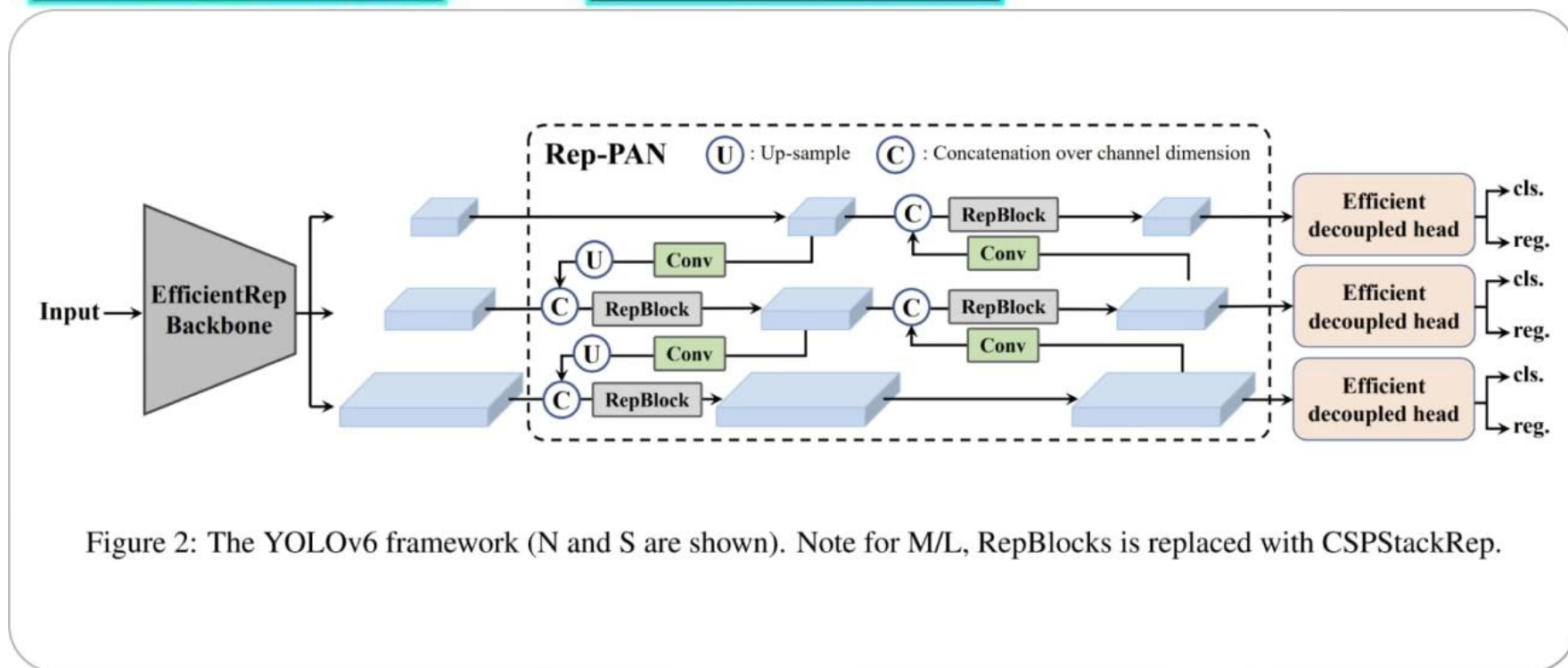
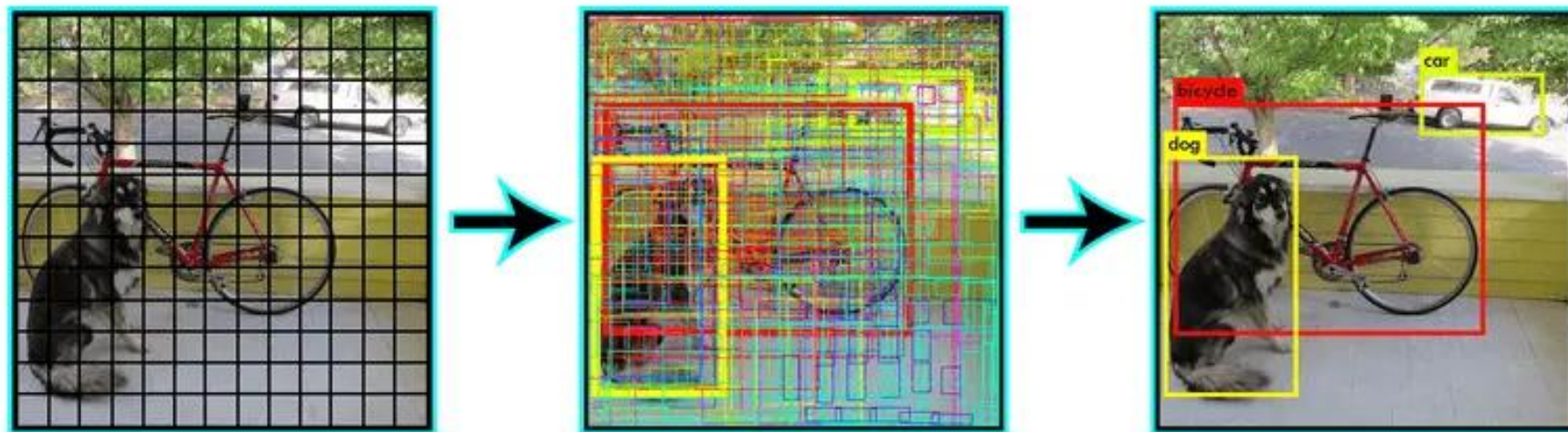


Figure 2: The YOLOv6 framework (N and S are shown). Note for M/L, RepBlocks is replaced with CSPStackRep.

# YOLOv8 commands

1. Creating a YOLO environment,
2. Install ultralytics, `pip install ultralytics`
3. Install pip dependency, including torch, etc.
4. Install pre-trained YOLOv8 model weights, <https://github.com/ultralytics/ultralytics>
5. Creating a .yaml file to define labels, locations of train & test sets,
6. Training the detection/recognition model, `yolo task=detect mode=train epochs=100 data=.yaml model=yolov8m.pt`
7. Running the prediction based on detection/recognition model, `yolo task=detect mode=predict model=best.pt show=True source=clip.mp4/image.jpg save_txt=True`