```
import numpy as np
import tensorflow as tf
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Dense, Conv2D, Flatten
height, width, channels = 100, 100, 3
num samples = 1000
X train = np.random.random((num samples, height, width, channels))
y train = np.random.random((num samples, 1))
                                 + Code
                                            + Text
model = Sequential([
   Conv2D(24, (5, 5), strides=(2, 2), activation='relu', input_shape=(height, width, channel
   Conv2D(36, (5, 5), strides=(2, 2), activation='relu'),
   Conv2D(48, (5, 5), strides=(2, 2), activation='relu'),
   Flatten(),
   Dense(100, activation='relu'),
   Dense(50, activation='relu'),
   Dense(10, activation='relu'),
   Dense(1)
])
model.compile(optimizer='adam', loss='mse')
model.fit(X_train, y_train, epochs=10, validation_split=0.2)
model.save('self_driving_model.h5')
    Epoch 1/10
    Epoch 2/10
```

```
25/25 [==================== ] - 3s 122ms/step - loss: 0.0860 - val loss: 0.0849
Epoch 3/10
Epoch 4/10
25/25 [============== ] - 4s 166ms/step - loss: 0.0850 - val loss: 0.0919
Epoch 5/10
25/25 [============= ] - 3s 120ms/step - loss: 0.0893 - val_loss: 0.1095
Epoch 6/10
Epoch 7/10
Epoch 8/10
25/25 [============= ] - 4s 173ms/step - loss: 0.0780 - val loss: 0.0881
Epoch 9/10
25/25 [============= ] - 3s 120ms/step - loss: 0.0745 - val loss: 0.0860
Epoch 10/10
25/25 [================== ] - 3s 121ms/step - loss: 0.0701 - val loss: 0.0889
```

Double-click (or enter) to edit