Setup guide to getting YOLO object detection working with Intel RealSense cameras

1. **Install Realsense for ROS**:
- https://github.com/IntelRealSense/realsense-ros **(Go with Method 1)**
2. **Clone this repository to catkin_ws/src and then *catkin build***
3. **Install PyTorch**

   If you want to use the GPU version of PyTorch, follow the Cuda 11.0 installation tutorial below **(Skip the CUDNN installation)**
   Cuda 11.0 Installation

   Or just use the CPU variant of Pytorch **(the GPU variant is much faster)**
   https://pytorch.org/get-started/locally/ **(Link to PyTorch)**

NB! The first one is for GPU while the latter corresponds to the CPU variant of PyTorch.

To get the object detection working with RealSense you need to:
- cd ~/catkin_ws
- roslaunch realsense2_camera rs_camera.launch
- Open up a new terminal

- roslaunch ros_yolo yolo.launch