An Implementation of DVCM in Water Hammer Event

刘锦坤; 姜逸轩; 黑建聪

2024.5.21



Outline

- 1 Introduction of DVCM
- 2 Details of DVCM
- 3 Implementation of DVCM
- 4 Results of DVCM
- 5 Future Work



Introduction of DVCM

Introduction of DVCM

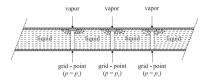


Fig. 9. Definition sketch for discrete vapor cavity model (adapted from Tijsseling, 1993, Fig. 4.9).

Sketch of DVCM Model

The sketch of DVCM is shown in the figure above. The DVCM model is a 1D model that can simulate the water hammer event in the pipeline. The model allows the discrete cavitation bubbles to be generated and collapsed at the grid points.



The basic equations of MOC(method of characteristics) are farmiliar to us. The equations are shown below:

$$\begin{cases} H_{j}^{t} - H_{j-1}^{t-\Delta t} + \frac{a}{gA}((Q_{u})_{j}^{t} - Q_{j-1}^{t-\Delta t}) + \frac{f\Delta x}{2gDA^{2}}(Q_{u})_{j}^{t}|Q_{j-1}^{t-\Delta t}| = 0\\ H_{j}^{t} - H_{j+1}^{t-\Delta t} - \frac{a}{gA}(Q_{j}^{t} - (Q_{u})_{j+1}^{t-\Delta t}) - \frac{f\Delta x}{2gDA^{2}}Q_{j}^{t}|(Q_{u})_{j+1}^{t-\Delta t}| = 0 \end{cases}$$

$$\tag{1}$$



$$\begin{cases}
H_{j}^{t} - H_{j-1}^{t-\Delta t} + \frac{a}{gA}((Q_{u})_{j}^{t} - Q_{j-1}^{t-\Delta t}) + \frac{f\Delta x}{2gDA^{2}}(Q_{u})_{j}^{t}|Q_{j-1}^{t-\Delta t}| = 0 \\
H_{j}^{t} - H_{j+1}^{t-\Delta t} - \frac{a}{gA}(Q_{j}^{t} - (Q_{u})_{j+1}^{t-\Delta t}) - \frac{f\Delta x}{2gDA^{2}}Q_{j}^{t}|(Q_{u})_{j+1}^{t-\Delta t}| = 0 \\
Q_{u} = Q
\end{cases}$$
(1)

H represents the head of the water, Q represents the downstream flow rate of the water, Q_u represents the upstream flow rate. The footnote represents the number of node, the headnode represents the time.

As we did in the previous assignment, we consider that $Q_u = Q$, and then solve the equations of the head $H_i^{t+\Delta t}$ and flow rate $Q_i^{t+\Delta t}$ these two unknowns.



But in the DVCM model, the cavitation bubbles are considered. Once if the head drops below the vapor pressure H^* , the cavitation happens and 2 equations are attached to the original equations:

$$\begin{cases} \dot{V} = -(Q_u) + Q \\ H = H^* \end{cases}$$

Since when $Q_u \neq Q$ and in which V represents the volumn of the cavitation bubble.



The discrete form of the equations would be more useful as shown in the following:

$$\begin{cases} V_j^{t+\Delta t} = V_j^t + \psi(-(Q_u)_j^{t+\Delta t} + Q_j^{t+\Delta t})\Delta t + (1-\psi)(-(Q_u)_j^t + Q_j^t)\Delta t \\ H_j^{t+\Delta t} = H^* \end{cases}$$
(2)

As we have learnt in mathmatical analysis, ψ is the weight factor generated by the mean value theorem of integrals.

Therefore, the unknowns are $(Q_u)_i^{t+\Delta t}$ and $Q_i^{t+\Delta t}$ in (1)

and (2) instead of $H_i^{t+\Delta t}$ and $Q_i^{t+\Delta t}$ (equals to $(Q_u)_i^{t+\Delta t}$).

After solving the Q and (Q_u) , we can get the ΔV and then update the V. Once updated V is less than 0, the cavitation bubble collapses and the equations go back to the original form.



Sumarry of Details of DVCM

In sumarry, when $H_i^t > H^*$ the normal equations are:

$$\begin{cases}
H_{j}^{t} - H_{j-1}^{t-\Delta t} + \frac{a}{gA}((Q_{u})_{j}^{t} - Q_{j-1}^{t-\Delta t}) + \frac{f\Delta x}{2gDA^{2}}(Q_{u})_{j}^{t}|Q_{j-1}^{t-\Delta t}| = 0 \\
H_{j}^{t} - H_{j+1}^{t-\Delta t} - \frac{a}{gA}(Q_{j}^{t} - (Q_{u})_{j+1}^{t-\Delta t}) - \frac{f\Delta x}{2gDA^{2}}Q_{j}^{t}|(Q_{u})_{j+1}^{t-\Delta t}| = 0 \\
Q_{u} = Q
\end{cases}$$
(1)

And once $H_j^t < H^*$ the equations are added:

$$\begin{cases}
V_j^{t+\Delta t} = V_j^t + \psi(-(Q_u)_j^{t+\Delta t} + Q_j^{t+\Delta t})\Delta t + (1-\psi)(-(Q_u)_j^t + Q_j^t)\Delta t \\
H_j^{t+\Delta t} = H^*
\end{cases}$$
(2)

And when $V_i^{t+\Delta t} < 0$, the equations go back to (1).



TALK IS CHEAP, SHOW ME THE CODE

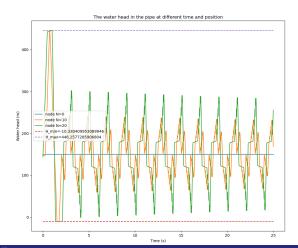
Some key parts of the code are shown below:

```
The iteration of the middle nodes
    C P = H[i-1,j-1]+Qu[i-1,j-1]*(B+S-R*abs(Qu[i-1,j-1]))
    H[i,i] = (C P+C M)/2
    Q[i,j] = Qu[i,j]
       E[i, j] = 0 (constant) H: NDArray[float64]
       Qu[i,j] = (-H[i,j]+H[i-1,j-1]+B*Q[i-1,j-1])/(B+R*abs(Q[i-1,j-1]))
       O[i,i] = (H[i,i]-H[i-1,i+1]+B*Ou[i-1,i+1])/(B+R*abs(Ou[i-1,i+1]))
H[i,j] = H \min
Q[i,j] = (H[i,j]-H[i-1,j+1]+B*Qu[i-1,j+1])/(B+R*abs(Qu[i-1,j+1]))
```

Key parts of the code to implement DVCM

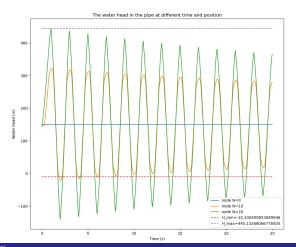


Results of DVCM





Compared to Normal MOC





Physics Features to Be Explained

- The cavitation bubbles are generated and collapsed in the DVCM model so in some periods of time, the pressure is a line with value H^* .
- The water head in the DVCM model is lower than the normal MOC model after the first oscillation. This could be explained that the generation and the diminishment of the cavitation bubbles consume the energy of the water. (Seems Good News? Less Pressure, Less Damage? Not Sure Yet!)
- The water head in the DVCM model is more fluctuated than the normal MOC model due to the turbulence of the cavitation bubbles.



Congratulation: We have set the primary step on the moon!

- What do the experimenters say?
- Considering whether the DVCM can be developed by the conservation of mass and energy.
- What about other improved 1D models (DGCM discrete gas cavity model)?
- What about high dimensional models? Seems to be hard, limited desire to try. (QAQ)

