

# Maxent Models and Discriminative Estimation





# Exponential Model Likelihood

- Maximum (Conditional) Likelihood Models :
  - Given a model form, choose values of parameters to maximize the (conditional) likelihood of the data.

$$\log P(C | D, \lambda) = \sum_{(c,d) \in (C,D)} \log P(c | d, \lambda) = \sum_{(c,d) \in (C,D)} \log \frac{\exp \sum_i \lambda_i f_i(c, d)}{\sum_{c'} \exp \sum_i \lambda_i f_i(c', d)}$$



## The Likelihood Value

- The (log) conditional likelihood of iid data  $(C, D)$  according to maxent model is a function of the data and the parameters  $\lambda$ :

$$\log P(C | D, \lambda) = \log \prod_{(c,d) \in (C,D)} P(c | d, \lambda) = \sum_{(c,d) \in (C,D)} \log P(c | d, \lambda)$$

- If there aren't many values of  $c$ , it's easy to calculate:

$$\log P(C | D, \lambda) = \sum_{(c,d) \in (C,D)} \log \frac{\exp \sum_i \lambda_i f_i(c, d)}{\sum_{c'} \exp \sum_i \lambda_i f_i(c', d)}$$



## The Likelihood Value

- We can separate this into two components:

$$\log P(C | D, \lambda) = \sum_{(c,d) \in (C,D)} \log \exp \sum_i \lambda_i f_i(c, d) - \sum_{(c,d) \in (C,D)} \log \sum_{c'} \exp \sum_i \lambda_i f_i(c', d)$$

$$\log P(C | D, \lambda) = N(\lambda) - M(\lambda)$$

- The derivative is the difference between the derivatives of each component



## The Derivative I: Numerator

$$\begin{aligned}\frac{\partial N(\lambda)}{\partial \lambda_i} &= \frac{\partial \sum_{(c,d) \in (C,D)} \log \exp \sum_i \lambda_{ci} f_i(c,d)}{\partial \lambda_i} = \frac{\partial \sum_{(c,d) \in (C,D)} \sum_i \lambda_i f_i(c,d)}{\partial \lambda_i} \\ &= \sum_{(c,d) \in (C,D)} \frac{\partial \sum_i \lambda_i f_i(c,d)}{\partial \lambda_i} \\ &= \sum_{(c,d) \in (C,D)} f_i(c,d)\end{aligned}$$

Derivative of the numerator is: the empirical count( $f_i, c$ )



## The Derivative II: Denominator

$$\begin{aligned}
 \frac{\partial M(\lambda)}{\partial \lambda_i} &= \frac{\partial \sum_{(c,d) \in (C,D)} \log \sum_{c'} \exp \sum_i \lambda_i f_i(c', d)}{\partial \lambda_i} \\
 &= \sum_{(c,d) \in (C,D)} \frac{1}{\sum_{c''} \exp \sum_i \lambda_i f_i(c'', d)} \frac{\partial \sum_{c'} \exp \sum_i \lambda_i f_i(c', d)}{\partial \lambda_i} \\
 &= \sum_{(c,d) \in (C,D)} \frac{1}{\sum_{c''} \exp \sum_i \lambda_i f_i(c'', d)} \sum_{c'} \frac{\exp \sum_i \lambda_i f_i(c', d)}{1} \frac{\partial \sum_i \lambda_i f_i(c', d)}{\partial \lambda_i} \\
 &= \sum_{(c,d) \in (C,D)} \sum_{c'} \frac{\exp \sum_i \lambda_i f_i(c', d)}{\sum_{c''} \exp \sum_i \lambda_i f_i(c'', d)} \frac{\partial \sum_i \lambda_i f_i(c', d)}{\partial \lambda_i} \\
 &= \sum_{(c,d) \in (C,D)} \sum_{c'} P(c' | d, \lambda) f_i(c', d) = \text{predicted count}(f_i, \lambda)
 \end{aligned}$$



## The Derivative III

$$\frac{\partial \log P(C | D, \lambda)}{\partial \lambda_i} = \text{actual count}(f_i, C) - \text{predicted count}(f_i, \lambda)$$

- The optimum parameters are the ones for which each feature's **predicted expectation** equals its **empirical expectation**. The optimum distribution is:
  - Always unique (but parameters may not be unique)
  - Always exists (if feature counts are from actual data).
- These models are also called maximum entropy models because we find the model having maximum entropy and satisfying the constraints:  $E_p(f_j) = E_{\tilde{p}}(f_j), \forall j$



## Finding the optimal parameters

- We want to choose parameters  $\lambda_1, \lambda_2, \lambda_3, \dots$  that maximize the conditional log-likelihood of the training data

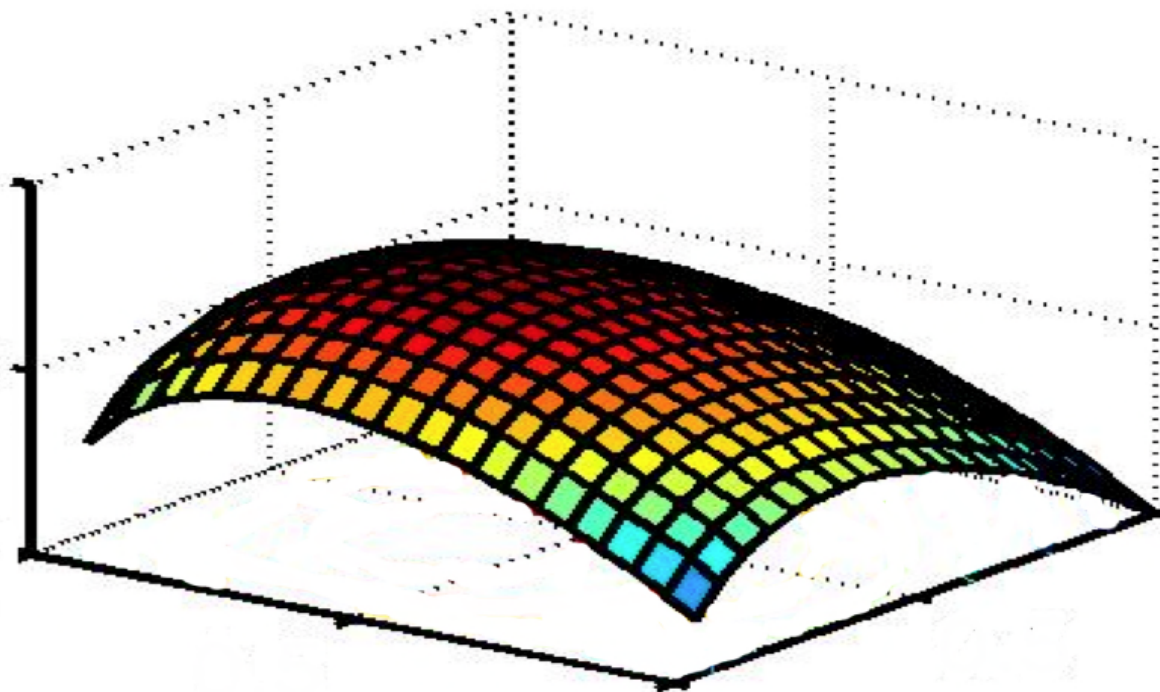
$$CLogLik(D) = \sum_{i=1}^n \log P(c_i | d_i)$$

- To be able to do that, we've worked out how to calculate the function value and its partial derivatives (its gradient)





# A likelihood surface





## Finding the optimal parameters

- Use your favorite numerical optimization package....
  - Commonly (and in our code), you **minimize** the negative of  $CLogLik$ 
    1. Gradient descent (GD); Stochastic gradient descent (SGD)
    2. Iterative proportional fitting methods: Generalized Iterative Scaling (GIS) and Improved Iterative Scaling (IIS)
    3. Conjugate gradient (CG), perhaps with preconditioning
    4. Quasi-Newton methods – limited memory variable metric (LMVM) methods, in particular, L-BFGS

