

# CURVES IN $\mathbb{R}^n$

LET  $I = [a, b] \subset \mathbb{R}$ . A VECTOR FIELD

$$r: I \rightarrow \mathbb{R}^n \quad (n=2,3)$$

IS CALLED A CURVE IN  $\mathbb{R}^n$ .

$r(a) \equiv$  INITIAL POINT OF THE CURVE

$r(b) \equiv$  FINAL POINT.

$C = \{r(t) \mid t \in I\}$  IS THE PATH TRAVERSED  
BY  $r$ .

IF WE WRITE  $r(t) = (x(t), y(t), z(t))$  ( $n=3$ )

THEN  $x(t), y(t), z(t)$  ARE THE COMPONENTS OF  
 $r$ .

## EXAMPLE

🚩  $r(t) = (a \cos t, a \sin t, bt) \quad (t \in \mathbb{R})$

THIS CURVE IS A **HELIX**.

🚩 SAY  $r$  IS SIMPLE IF  $r$  IS ONE-ONE.

🚩  $r$  IS SAID TO BE SMOOTH IF IT IS  
CONTINUOUSLY DIFFERENTIABLE.

🚩 A SMOOTH CURVE  $\gamma$  IS REGULAR IF  $\gamma'(t) \neq 0 \quad \forall t$

🚩 SUPPOSE  $\gamma_1, \gamma_2$  ARE CURVES, i.e.

$$\gamma_1: [a, b] \rightarrow \mathbb{R}^n, \quad \gamma_2: [c, d] \rightarrow \mathbb{R}^n.$$

WE SAY  $\gamma_1$  AND  $\gamma_2$  ARE EQUIVALENT

IF THERE EXISTS  $\phi: [a, b] \rightarrow [c, d]$  WHICH IS

- ONE-ONE, ONTO AND SUCH THAT BOTH

$\phi, \psi$  ARE CONTINUOUSLY DIFFERENTIABLE,

WHERE  $\psi: [c, d] \rightarrow [a, b], \quad \psi(x) = \phi^{-1}(x).$

- $\gamma_1 = \gamma_2 \circ \phi$

## EXAMPLE

$$\gamma_1: [0, 2] \rightarrow \mathbb{R}^3, \quad \gamma_2: [0, 1] \rightarrow \mathbb{R}^3.$$

$$\gamma_1(t) = (t, 0, 0), \quad \gamma_2(t) = (t + t^3, 0, 0).$$

$$\text{CONSIDER } \phi(t) = t + t^3, \quad \phi: [0, 1] \rightarrow [0, 2]$$

CHECK THAT  $\gamma_1, \gamma_2$  ARE EQUIVALENT.

# TANGENT VECTOR

SUPPOSE  $r: I \rightarrow \mathbb{R}^3$  IS A SMOOTH CURVE.

$$r'(t) := \lim_{\Delta t \rightarrow 0} \frac{r(t+\Delta t) - r(t)}{\Delta t}$$

IF  $r$  IS A REGULAR CURVE,  $r'(t)$  IS

CALLED THE TANGENT VECTOR (OR VELOCITY VECTOR) AT (TIME)  $t$ .

$$T_r(t_0) = \frac{1}{\|r'(t_0)\|} \cdot r'(t_0)$$

IS CALLED THE UNIT TANGENT VECTOR TO  $r(t)$  AT  $t_0$ .

🚩 LET  $r_1: [a, b] \rightarrow \mathbb{R}^3$ ,  $r_2: [c, d] \rightarrow \mathbb{R}^3$  BE EQUIVALENT REGULAR CURVES. THEN

$$T_{r_2}(t) = \pm T_{r_1}(\phi(t)) \quad \text{WHERE}$$

$\phi: (c, d) \rightarrow (a, b)$  IS THE

PARAMETRIZATION.



THE LENGTH OF THE CURVE  $\mathbf{r}$  IS GIVEN

BY

$$L := \int_a^b \left\| \frac{d\mathbf{r}}{dt} \right\| dt$$



IF  $C$  IS THE REGULAR CURVE DESCRIBED BY

$\mathbf{r}$ , THE LENGTH OF THE CURVE BETWEEN

TWO POINTS DESCRIBED BY  $\mathbf{r}(t_0)$  AND  $\mathbf{r}(t)$

IS GIVEN BY

$$s = s(t) = \int_{t_0}^t \left\| \mathbf{r}'(u) \right\| du$$

THIS DEFINITION IS INDEPENDENT OF THE

PARAMETRIZATION.



IF FOR A SMOOTH CURVE  $C$  WITH PARAMETRIZATION

$$\mathbf{r}(t), \text{ WE HAVE } \left\| \frac{d\mathbf{r}}{dt}(t) \right\| = 1 \quad \forall t$$

THEN FOR EVERY  $t_0 \in \text{Dom}(\mathbf{r})$  THE

PARAMETER  $s = t - t_0$  GIVES AN ARC LENGTH

PARAMETRIZATION OF  $\mathbf{r}(s)$  FOR  $C$  W.R.T THE

REFERENCE POINT  $t_0$ .



IF  $\mathbf{r}(t) = x(t)\vec{i} + y(t)\vec{j}$ , THE **UNIT** ( $\mathbf{r}(t) \neq \vec{0}$ )

**NORMAL VECTOR**  $\mathbf{n}$  IS DEFINED AS

$$\mathbf{n} = \pm \frac{y'(t)\vec{i} - x'(t)\vec{j}}{\sqrt{(x'(t))^2 + (y'(t))^2}}$$

# EXAMPLE

$$\mathbf{r}(t) = a \cos t \vec{i} + a \sin t \vec{j} + bt \vec{k}.$$

$$t_0 = 0.$$

LENGTH OF THE HELIX TILL THE POINT

$\mathbf{r}(t)$  FROM  $\mathbf{r}(0)$  IS GIVEN BY

$$s = \int_0^t \|\mathbf{r}'(u)\| du = \int_0^t \sqrt{a^2 + b^2} du = t\sqrt{a^2 + b^2}$$

$$\left( \begin{array}{l} \text{SINCE } \mathbf{r}'(u) = (-a \sin t, a \cos t, b) \\ \Rightarrow \|\mathbf{r}'(u)\| = \sqrt{a^2 + b^2}. \end{array} \right)$$