Convolutional Neural Network (Recap)

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CNN - Definition



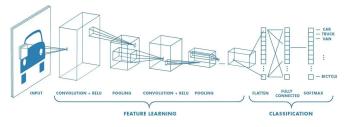
- Convolutional Neural Networks (CNNs) are a class of deep learning models specifically designed for processing structured grid data, such as images.
- ► They are particularly effective for tasks like image classification, object detection, and segmentation.
- ► CNNs leverage the spatial structure of images by using convolutional layers to automatically learn hierarchical features.
- ► The architecture typically consists of convolutional layers, activation functions, pooling layers, and fully connected layers.
- ► CNNs are known for their ability to capture local patterns and translate them into higher-level representations.

CNN Architecture



What is a CNN?

A CNN is a deep network of neurons with learnable filters that perform convolution operations on inputs, usually images, to extract hierarchical features.



Why use CNNs?

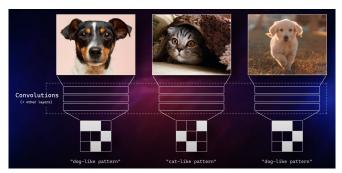
Parameter sharing and sparse connectivity reduce number of parameters and improve spatial feature extraction.

CNN Architecture



What makes a Convolutional Neural Network?

Characterised by "Convolutional Layer" – they are able to detect "abstract features" and "almost ideas within the image"



Components of a CNN



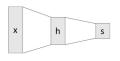
Convolution Layers



Pooling Layers



Fully-Connected Layers



Activation Function



Normalization

$$\hat{x}_{i,j} = \frac{x_{i,j} - \mu_j}{\sqrt{\sigma_j^2 + \varepsilon}}$$

CNN - Convolutional Layer



Operation:

ightharpoonup Element-wise multiply filter with image patch and sum ightarrow feature map.

Hyperparameters:

- kernel size
- number of filters
- stride
- padding

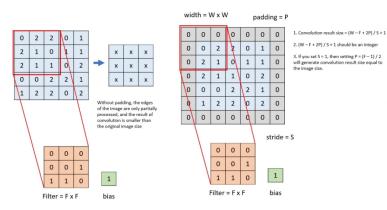
```
Listing 1: Code snippet (PyTorch)
import torch.nn as nn

conv = nn.Conv2d(in_channels=3, out_channels=16,
    kernel_size=3, stride=1, padding=1)

output = conv(input_tensor) # input_tensor: [
    batch_size, 3, H, W]
```

CNN - Convolutional Layer



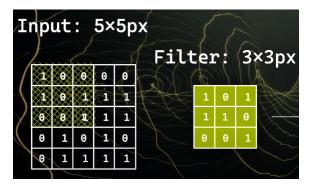


Quick Exercise (5 mins)



Let's find out what this can give us:

- ► Padding = 0
- ► Stride = 1



Note: Once you traverse entire image/matrix it will give you a matrix calls Feature Map or Activation Map.

CNN - Activation Functions



Role:

► Introduce non-linearity so multiple conv layers can learn complex mappings.

Common:

- ► ReLU (Rectified Linear Unit)
- Leaky ReLU
- Sigmoid
- ▶ Tanh

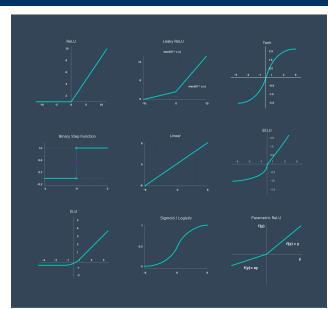
Listing 2: Code snippet (PyTorch)

```
import torch.nn.functional as F

x = conv(input_tensor)
x = F.relu(x)  # ReLU
x = F.leaky_relu(x, 0.1)  # Leaky ReLU
```

CNN - Activation Functions





CNN - Pooling Layers



Purpose:

▶ Downsample feature maps, reduce spatial dims and parameters, add invariance.

Types:

- Max Pooling
- Average Pooling
- Global Average Pooling
- ► Global Max Pooling

```
Listing 3: Code snippet (PyTorch)
```

```
import torch.nn as nn
pool = nn.MaxPool2d(kernel_size=2, stride=2)
pooled = pool(x)  # halves H and W
```

CNN - Pooling Layers



