



جامعة الملك عبد الله  
للعلوم والتقنية  
King Abdullah University of  
Science and Technology

أكاديمية كاوست  
KAUST ACADEMY



# The Art of Training Deep Neural Networks

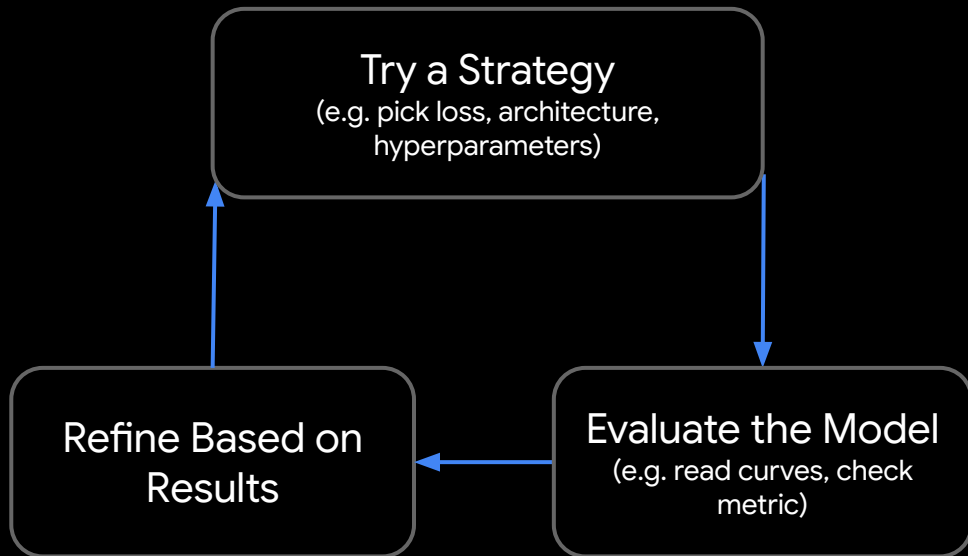
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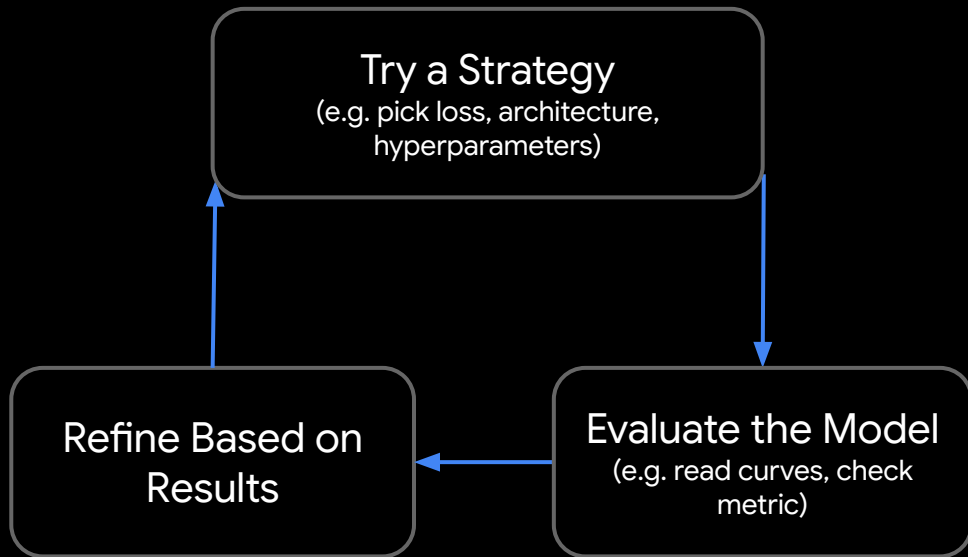
# Introduction

- Training AI models is an **iterative process** of trying, failing, and refining.
- Success depends on **empirical experimentation**, not just theory.
- Practically, we can offer guidelines on what is likely to work, but there are **no guarantees**.



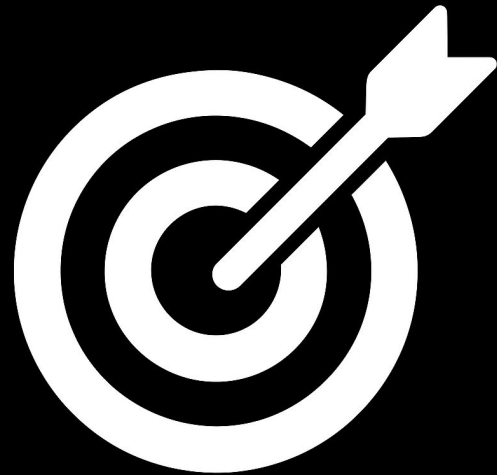
# Introduction

- In this session, we'll explore the **key components** that influence deep learning training.
- What they are, why they matter, and how to optimize them.



# Losses & Metrics

*What You Optimize Is What You Get.*



# Loss vs Metric: spot the difference

Role	Used during	Differentiable?	Typical examples
Loss	?	?	Cross-Entropy, MSE, L1, Huber, Focal, Dice-Loss
Metric	?	?	Accuracy, F1, mAP, IoU, AUC-ROC, MAE

# Loss vs Metric: spot the difference

Role	Used during	Differentiable?	Typical examples
<b>Loss</b>	Back-prop optimisation	Yes	Cross-Entropy, MSE, L1, Huber, Focal, Dice-Loss
<b>Metric</b>	Validation / reporting	No	Accuracy, F1, mAP, IoU, AUC-ROC, MAE

***“Loss is for machines, metrics are for humans.”***

# Some Popular Losses

Loss	Minimises ...	Used for ...
Mean Squared Error (MSE)	$L^2$ distance between points/pixels	Regression / autoencoders
Mean Absolute Error (MAE)	?	Regression / autoencoders
Huber (Smooth L1) Loss	?	Regression / autoencoders
Dice / IoU Loss	?	Segmentation / Detection
Cross-Entropy (CE) / KL divergence	?	Classification / language models (LLMs)





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*Is MAE differentiable?*



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*Is MAE differentiable? No, but we can use a special type of gradient (subgradient) to minimize it.*



# Some Popular Losses

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Dice / IoU Loss	Overlap ratio between masks/boxes	Segmentation / Detection
Cross-Entropy (CE) / KL divergence	Information (entropy) difference between probability distributions	Classification / language models (LLMs)

# Some Popular Losses

***Q: Can we optimize for multiple losses at the same time?👀***

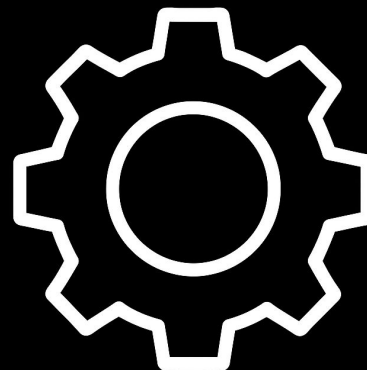


# Some Popular Composite Losses

Scenario	Composite Loss	Purpose
Detection (Yolo)	$BCE_{obj} + BCE_{cls} + \lambda \cdot IoU_{reg}$	Objectness + class + boxes
Segmentation (UNet)	$CE + \lambda \cdot Dice$	Pixels + mask overlap
Generative (VAE)	$Reconstruction_{obj} + \beta \cdot KL$	Rebuild + Gaussian latent
Generative (GAN)	$CE_{adv} + \lambda \cdot Perceptual$	Realism + texture & color details

# Hyperparameters Tuning

*Loss tells us where to climb  
Hyper-params decide how fast and which path.*





# Hyperparameters

## What are Hyper-parameters?

⇒ values you set before training (not learned).

## Role?

⇒ steer optimisation speed, capacity & generalisation.

## How to set them?

⇒ pick sensible starters → train → inspect → iterate.



# Hyperparameters Tuning

Hyperparameter	Quick rule-of-thumb
Optimiser	Usually <b>Adam/AdamW</b> works the best.
LR	<b>CNNs-based</b> : (1e-3–1e-4)-ish ↔ <b>Transformers-based</b> : (1e-5–1e-6)-ish. Usually used with a <b>scheduler</b> (learning rate decay).
Batch size	<b>Vision</b> : (4–32)-ish ↔ <b>Text</b> : (1–16)-ish keep fixed; scale only if needed.
Epochs	<b>Vision</b> ≈ 5–300; <b>NLP</b> ≈ 1-10; <b>LLMs</b> ≈ 1 (up to 3).
Img size / sequence length	prototype small (e.g. <b>img_size</b> ≈ 224*224, <b>seq_len</b> ≈ 256) → upscale when everything else is stable.
Backbone family & size	start tiny → scale up once pipeline is stable (e.g. <b>EfficientNetV2-Small</b> → <b>EfficientNetV2-Large</b> , <b>BERT-base</b> → <b>BERT-large</b> , etc.).



# Hyperparameters Tuning

**Tip:** Scale batch size when adjusting learning rate.

But by how much?



# Hyperparameters Tuning

**Tip:** Scale batch size when adjusting learning rate.

1. SGD: Use linear scaling rule\*

$$\text{LR}_{new} = \text{LR}_{old} \times \frac{\text{Batch Size}_{new}}{\text{Batch Size}_{old}}$$

2. Adam/AdamW: Square-root scaling rule\*

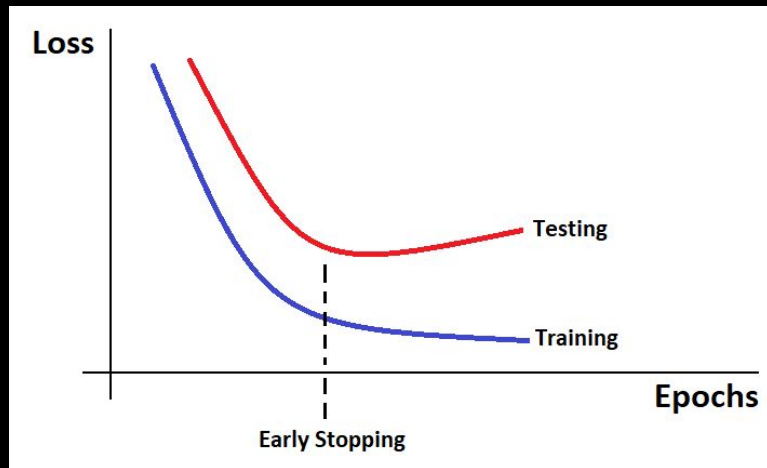
$$\text{LR}_{new} = \text{LR}_{old} \times \sqrt{\frac{\text{Batch Size}_{new}}{\text{Batch Size}_{old}}}$$

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\*Granzio D., Zohren S., Roberts S., "Learning Rates as a Function of Batch Size: A Random Matrix Theory Approach to Neural Network Training," arXiv:2006.09092, 2020.

# Early Stopping

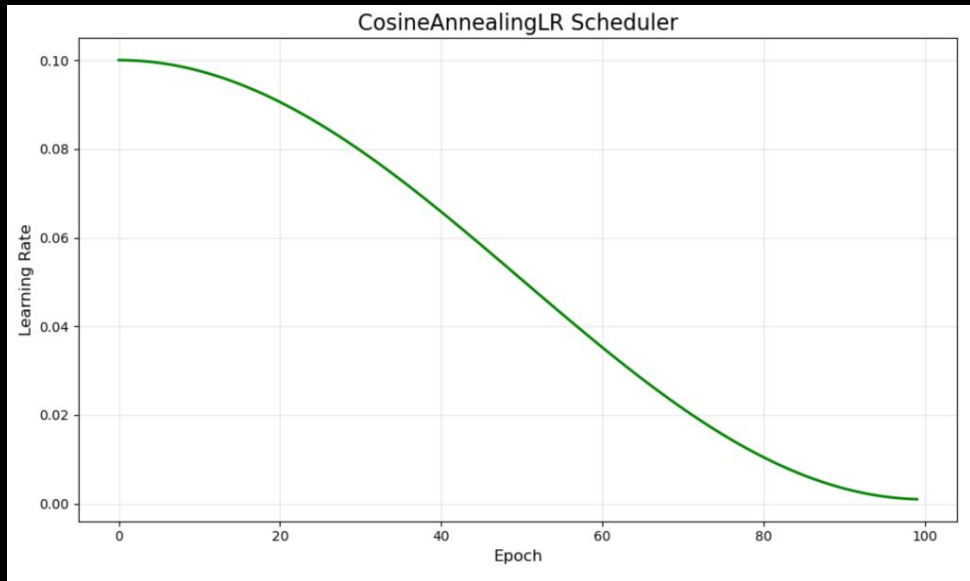
- **Goal:** stop training just after validation metric flattens or degrades.
- **How:** monitor `val-loss` / `val-metric`  $\rightarrow$  `patience=N epochs`.
- Helps auto-select **optimal epochs value**.





# Schedulers

- A **scheduler** is the rule that automatically **adjusts the learning rate** during training.
- They help speed convergence, escape plateaus, and reach a better optimum.
- Most teams now default to **cosine decay**.



# Schedulers Types

Scheduler Type	How It Triggers	Typical Use-case
Step-based	After every optimiser <b>step</b>	When <b>low</b> number of epochs used (e.g. NLP)
Epoch-based	After every <b>epoch</b>	When a <b>high</b> number of epochs used (e.g. Vision, Audio,...etc)

# Warm-up

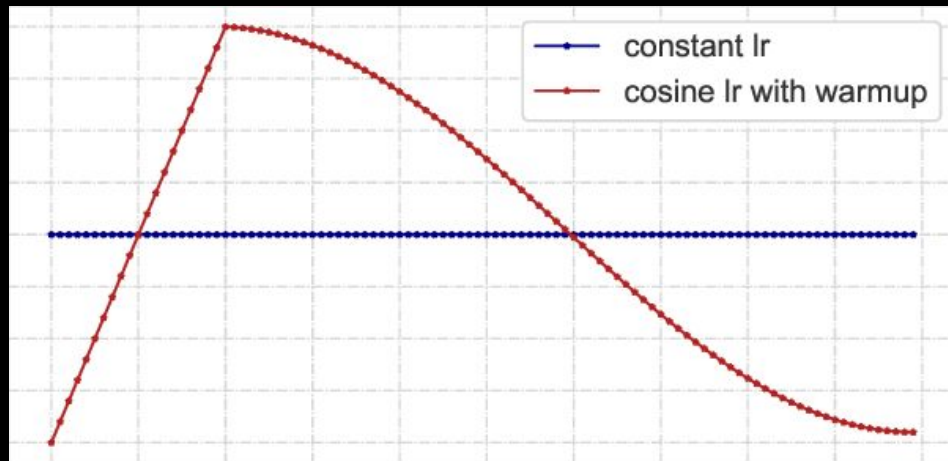
- **Problem:**
  - large initial LR + random weights  
⇒ gradients explode.
  - large initial LR + Pretrained weights  
⇒ Forget previous knowledge.





# Warm-up

- **Solution:** gradually **increase** LR from 0  $\rightarrow$  base LR over some steps/epochs (or 3-5 % of total steps/epochs).
- Usually used with **Transformers**.



# Early-Stopping vs Fixed Epochs

- **Which one is better:**
  - Many epochs + Early stopping.
  - Fixed epochs + Learning rate scheduler.

# Early-Stopping vs Fixed Epochs

- **Which one is better:**

- Many epochs + Early stopping.
- Fixed epochs + Learning rate scheduler.

⇒ **Recommended:**

1. Use **early stopping initially** to discover optimal epoch range.
2. Then, set a **fixed number of epochs** and **apply a scheduler** to smoothly decay the learning rate within that range.

# Augmentations

- **Data augmentation** is generating new training examples from existing ones through various transformations.
- **Types:**

## *Random Augmentations:*

Flip, Crop, Noise,...

## *Mix Augmentations:*

MixUp, CutMix,...

- **How to choose?** do error analysis  
→ add augs that mimics real mistakes.
- **Note:** heavy augs  $\Rightarrow$  add more epochs.

# Tuning Order (practical)

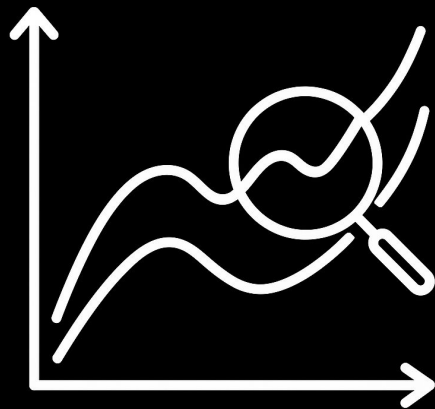
1. **LR & Epochs:** lock batch size unless GPU forces change.
2. **Scheduler:** cosine is usually the best.
3. **Augmentations:** add gradually, re-train.
4. **Model / Input complexity:** scale backbone, image size, sequence length.

# Tuning Order (practical)

- **Tips:**
  - Make one change at a time.
  - Start with small experiments, then scale up.
  - Always ensure the loss behaves normally and check for common bugs (e.g., exploding loss, NaNs, unstable curves).

# Reading & Debugging Loss Curves

*See the Signal, Catch the Bug*





# Debugging Loss Curves

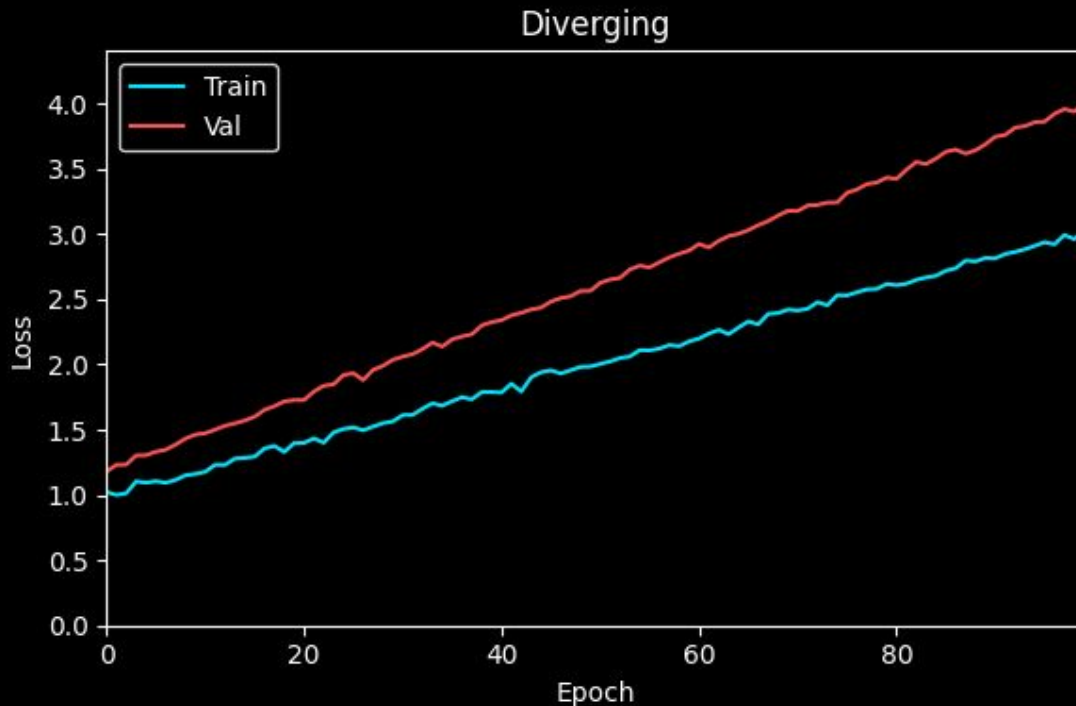
- Let's have a look at some plots...





# Case 1: Diverging

Why did this happen?

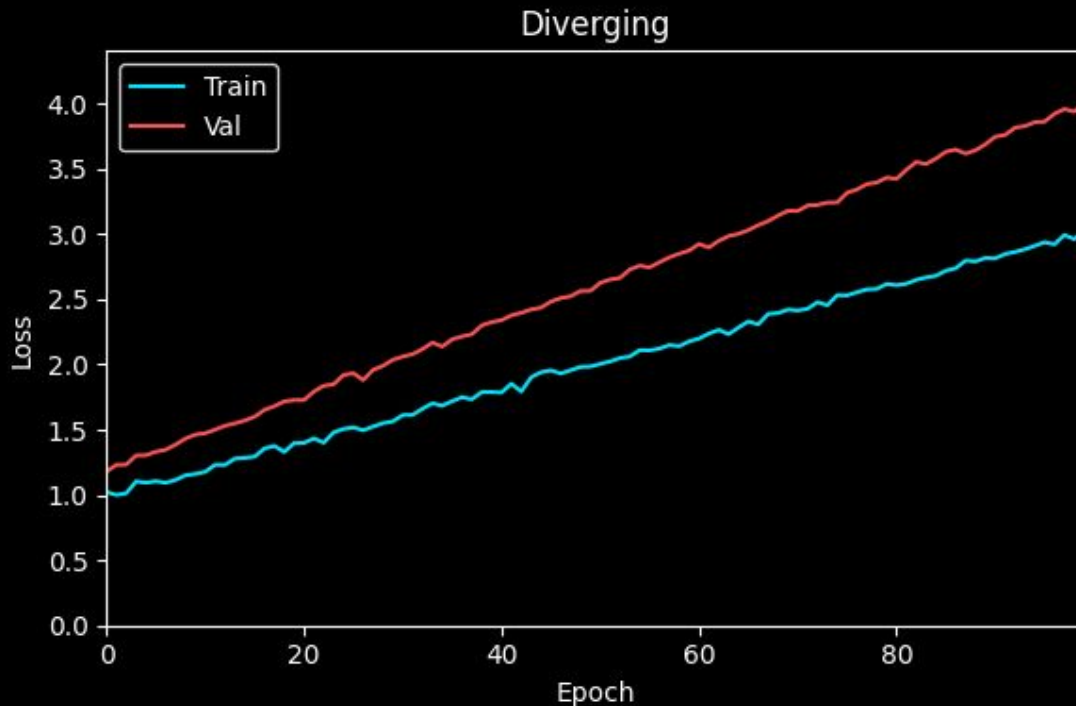




# Case 1: Diverging

Why did this happen?

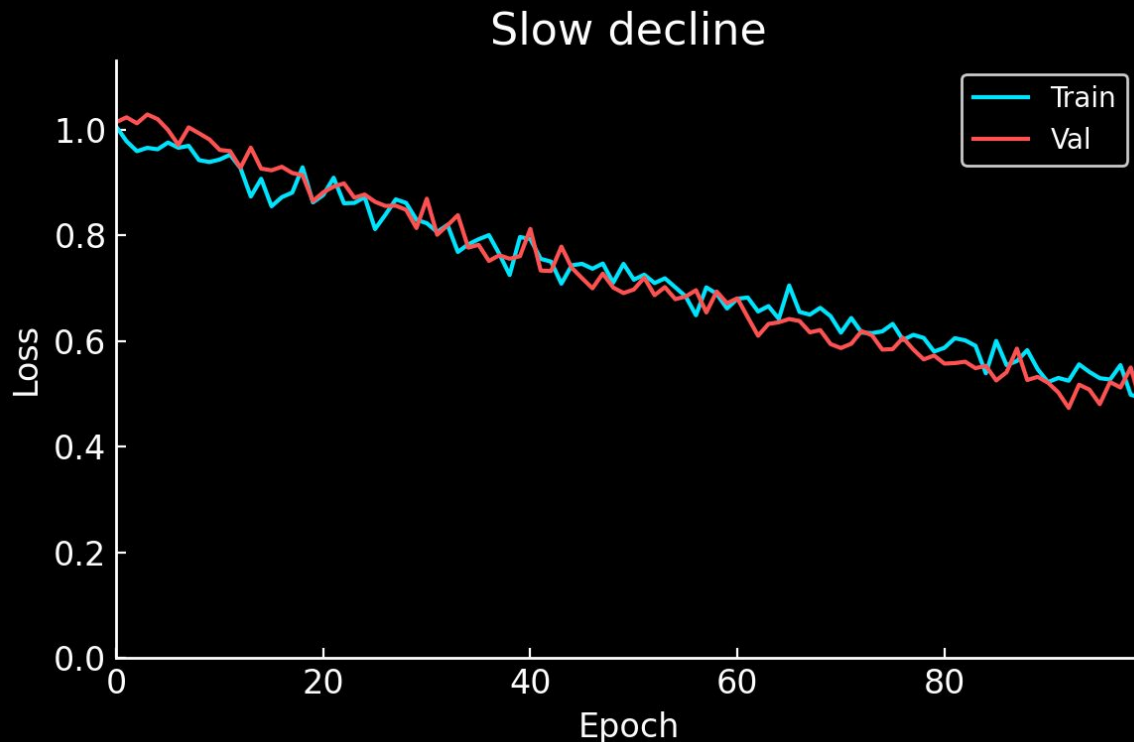
- High LR
- Exploding gradient
- Bad data
- No normalization





## Case 2: Slow Decline

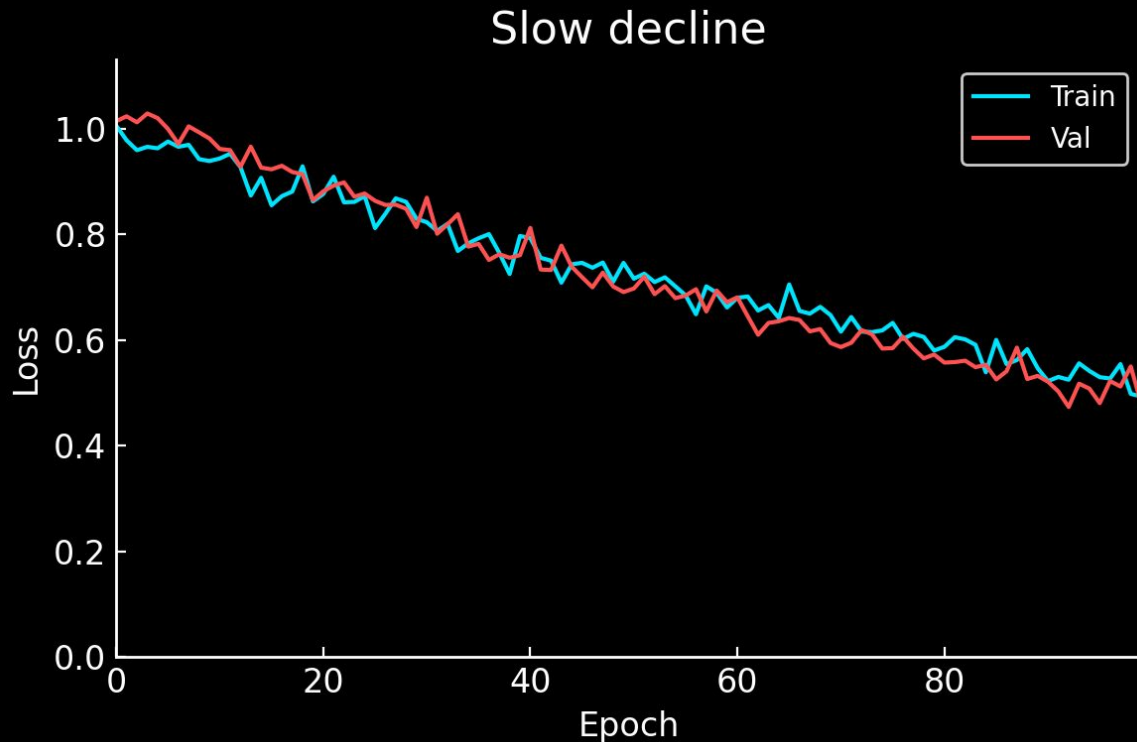
Why did this happen?



## Case 2: Slow Decline

Why did this happen?

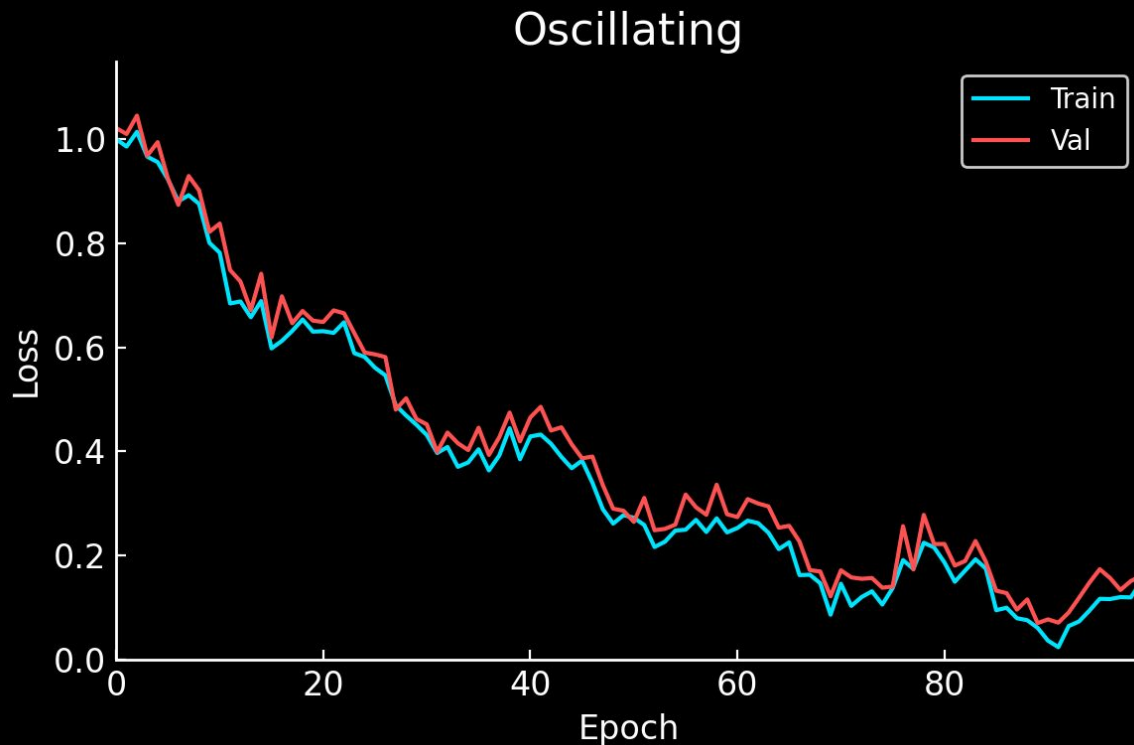
- Very small LR
- Vanishing gradients





# Case 3: Oscillating

Why did this happen?

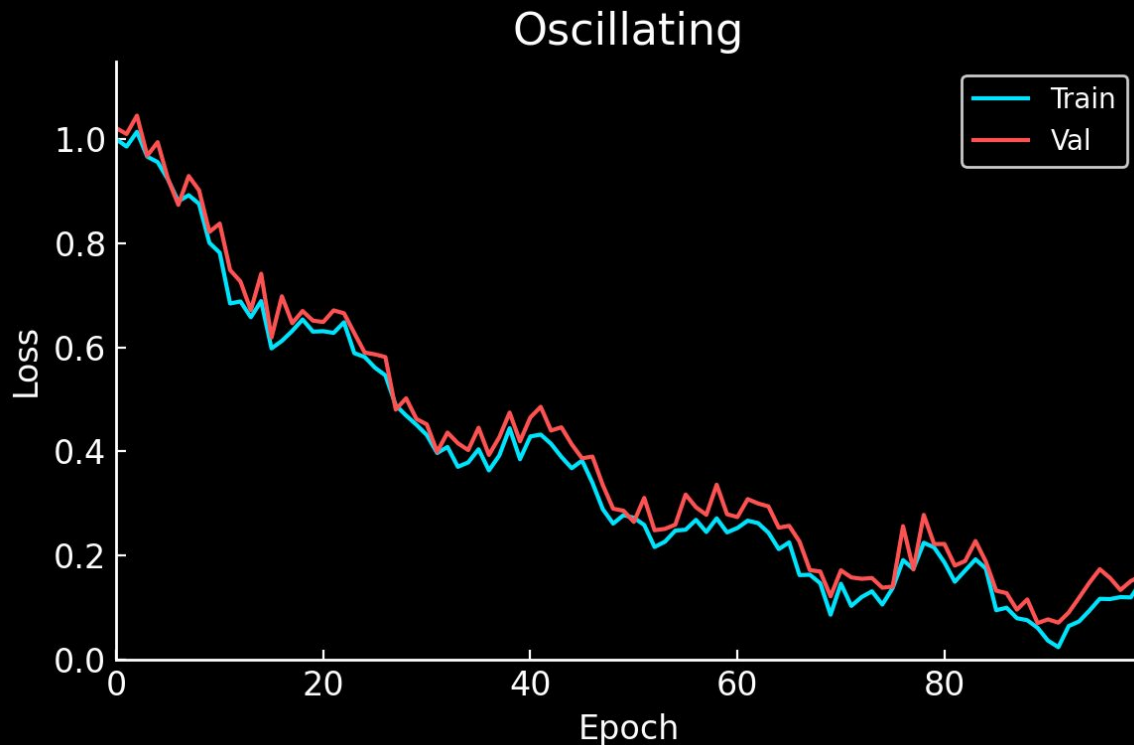




# Case 3: Oscillating

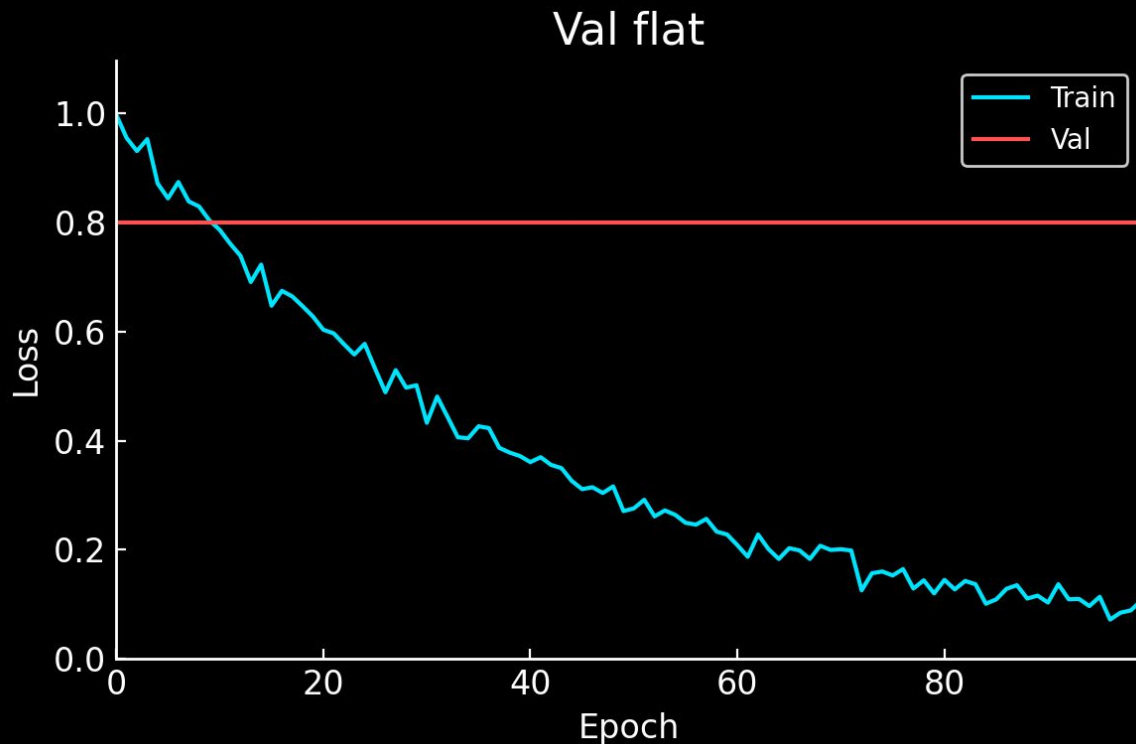
Why did this happen?

- High LR
- Small batch size
- Poor shuffle
- A lot of bad samples



## Case 4: Val flat

Why did this happen?

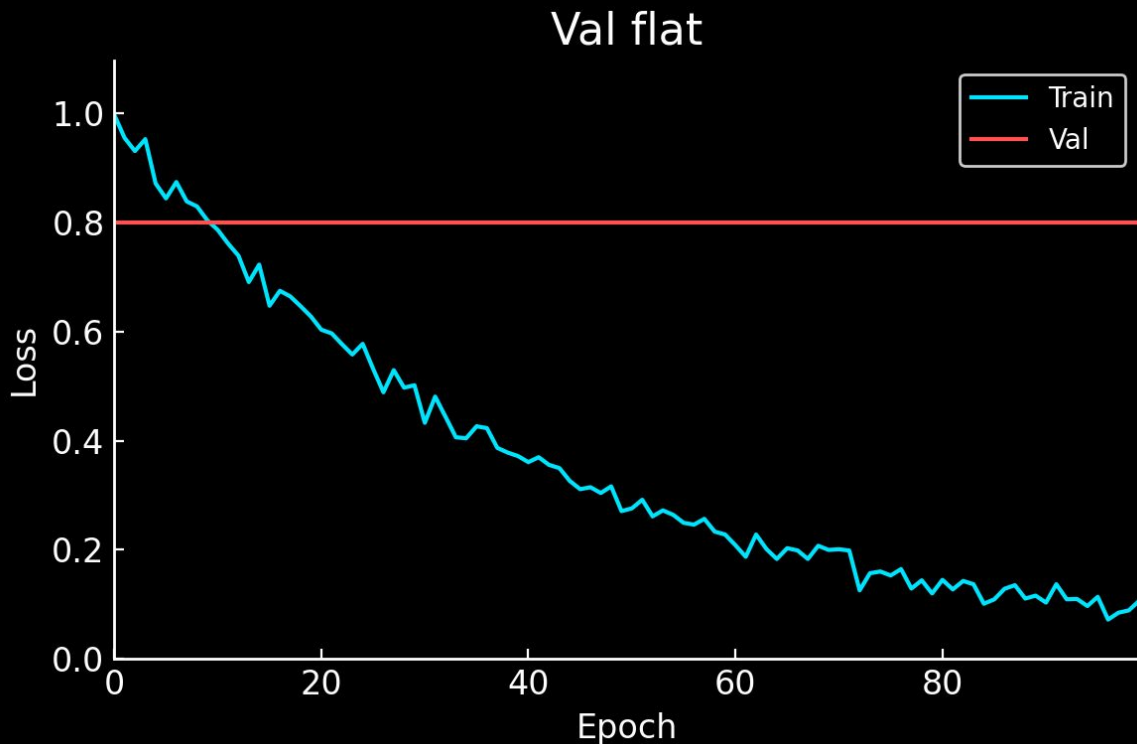




## Case 4: Val flat

Why did this happen?

- Coding bug in data preparation (e.g. wrong labels)
- Very hard val (distribution shift)
- Significant imbalance

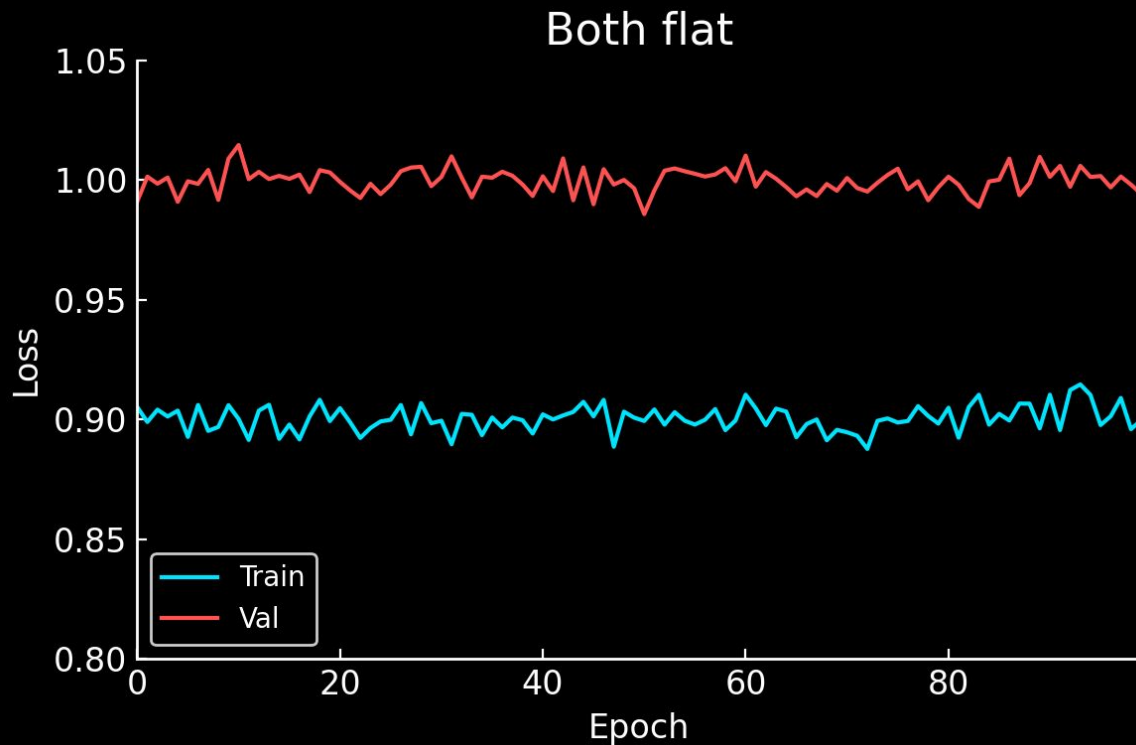






# Case 5: Both flat

Why did this happen?

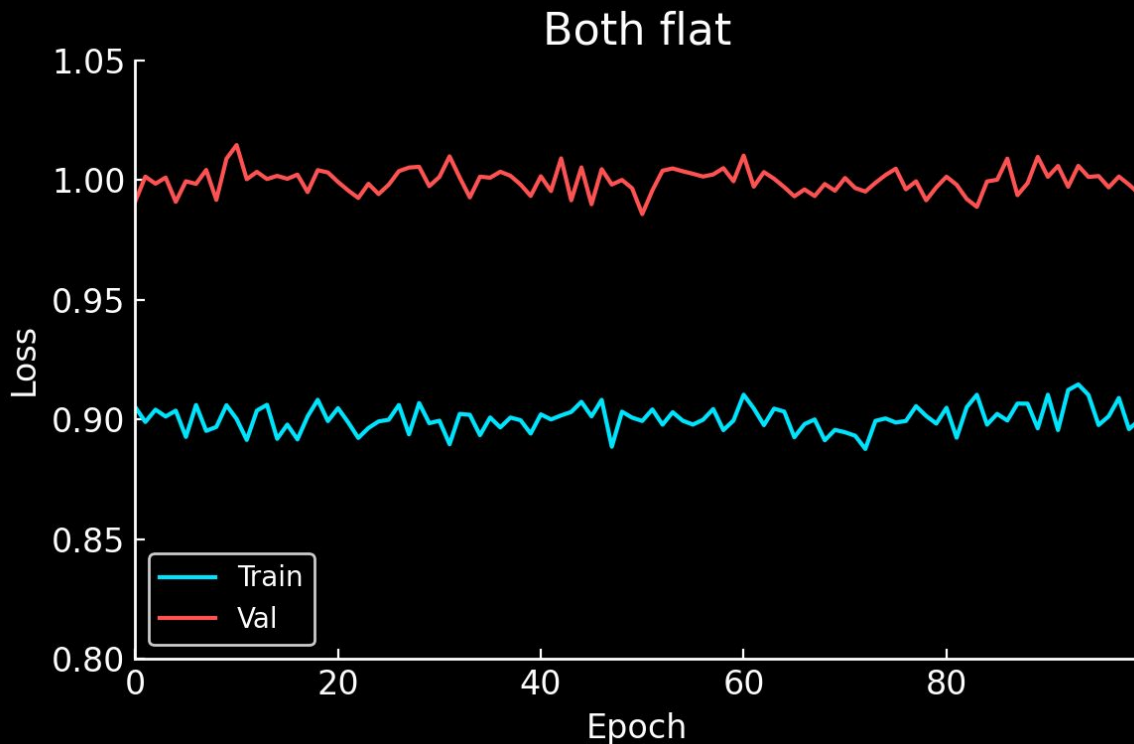




# Case 5: Both flat

Why did this happen?

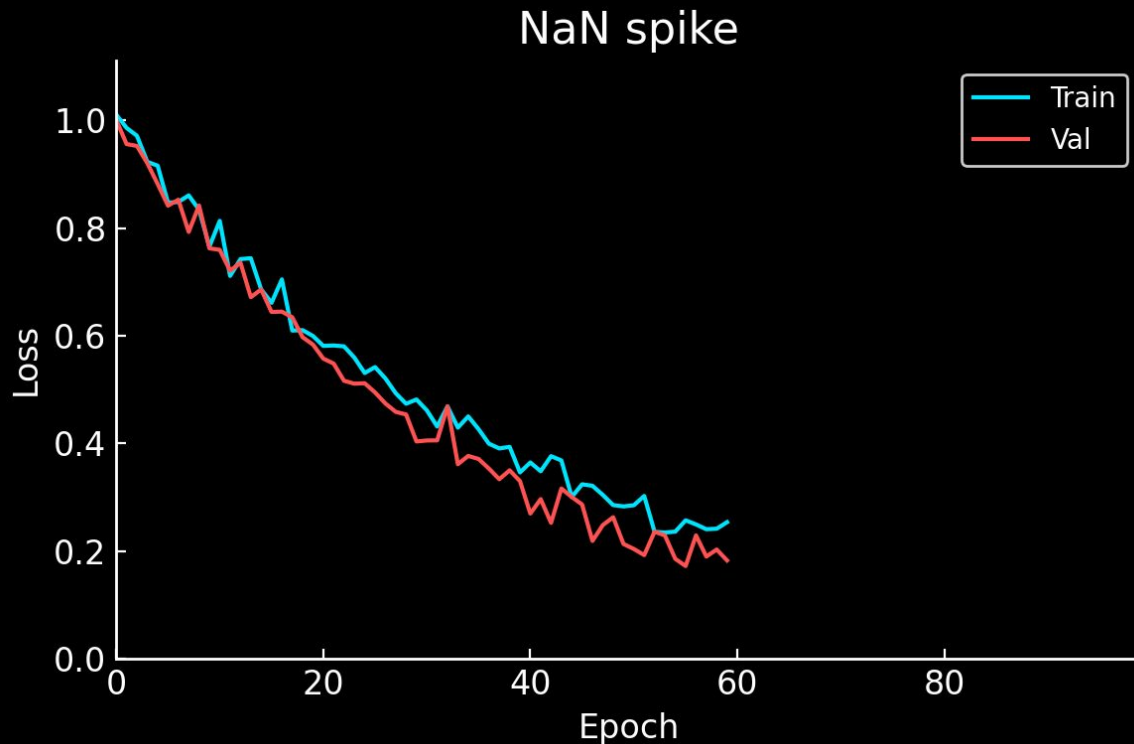
- Wrong loss
- Arch mismatch
- Bad labels
- Frozen grads
- Very small LR
- No normalization





# Case 6: NaN Loss

Why did this happen?

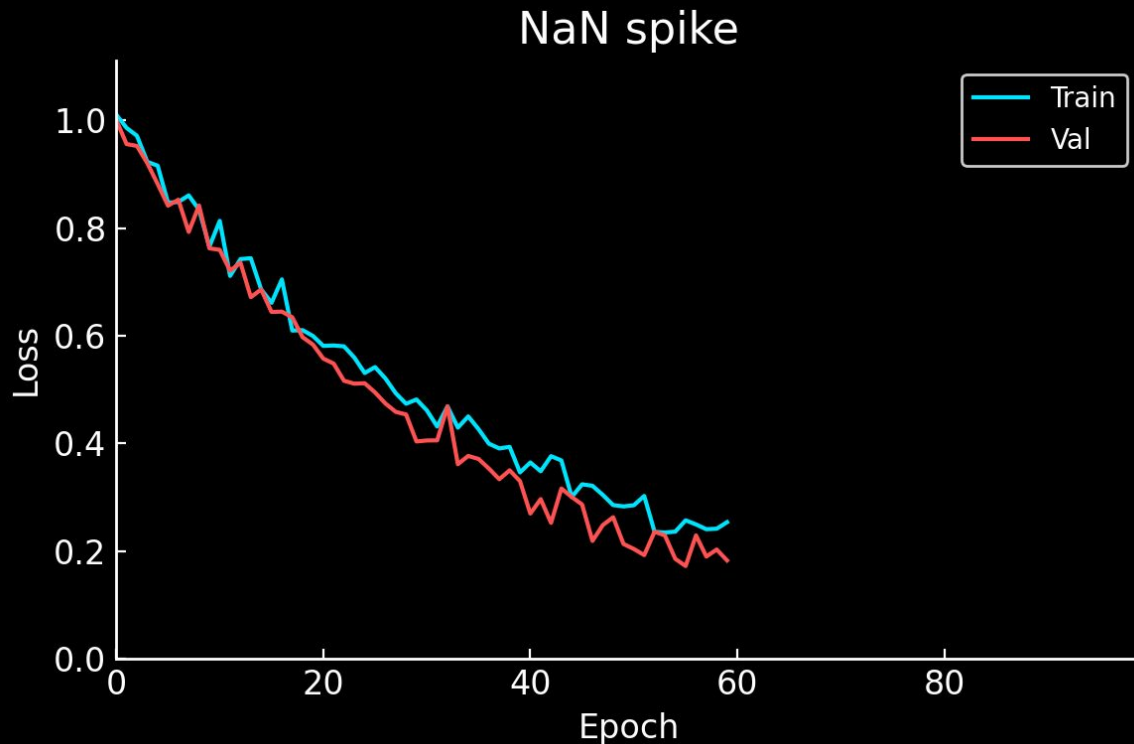




# Case 6: NaN Loss

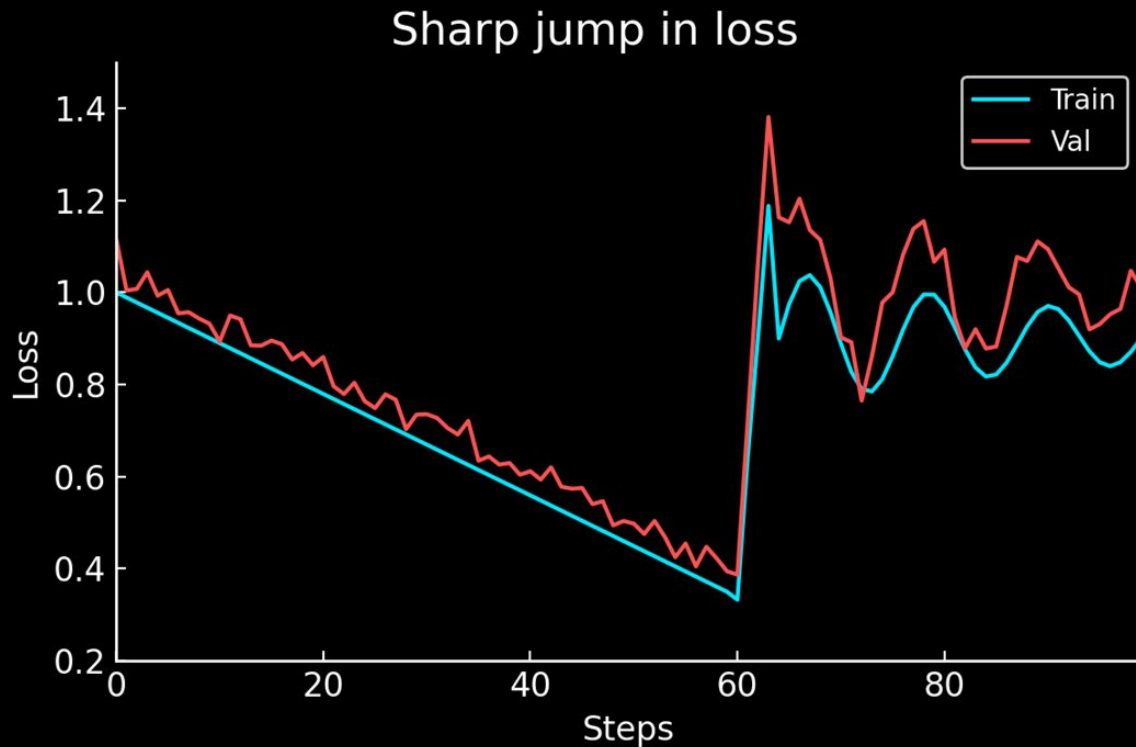
Why did this happen?

- Grad explode
- Log/Div 0



# Case 7: Sharp jump

Why did this happen?

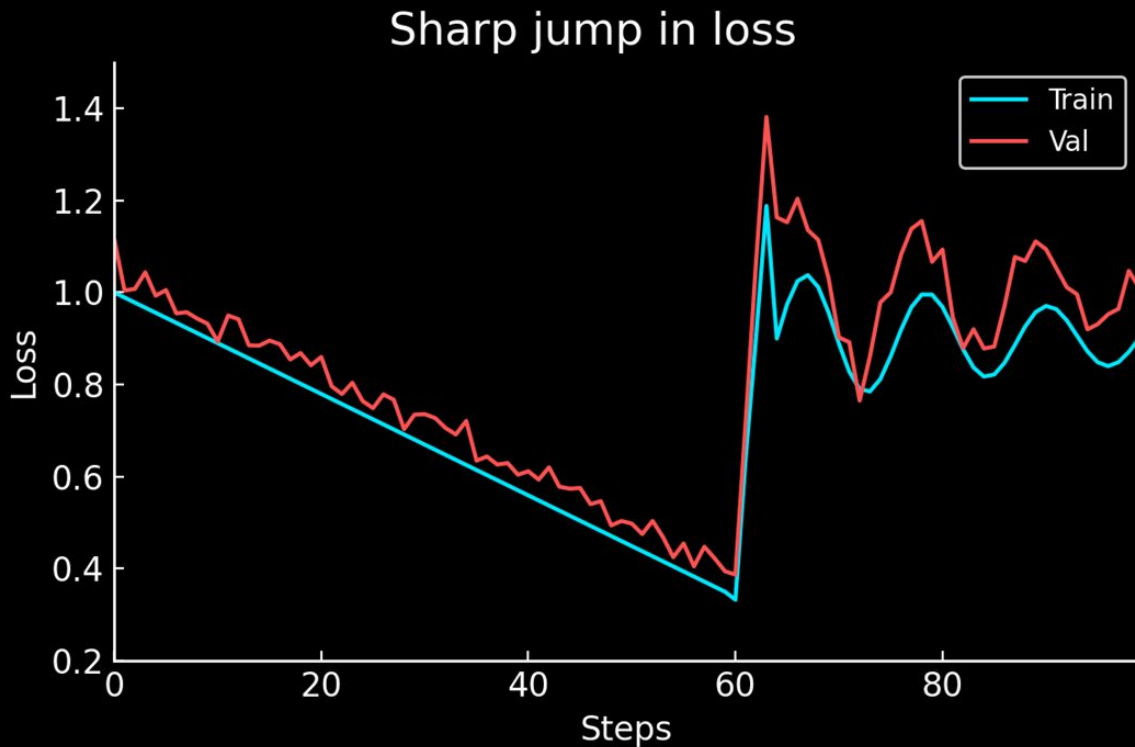




# Case 7: Sharp jump

Why did this happen?

- NaNs/Inf
- Outliers
- Poor shuffling



## Case 8: Val rises, train falls

Why did this happen?





## Case 8: Val rises, train falls

Why did this happen?

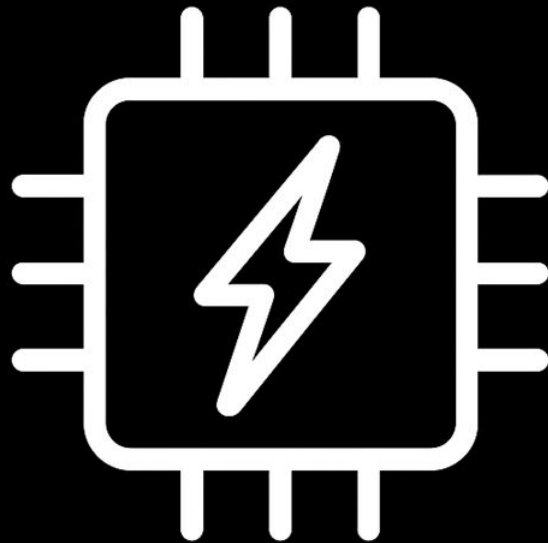
- Overfitting (Big Model, many epochs, few data, weak aug,...)





# Memory & Speed Optimisation

*Train Faster, Fit Bigger.*



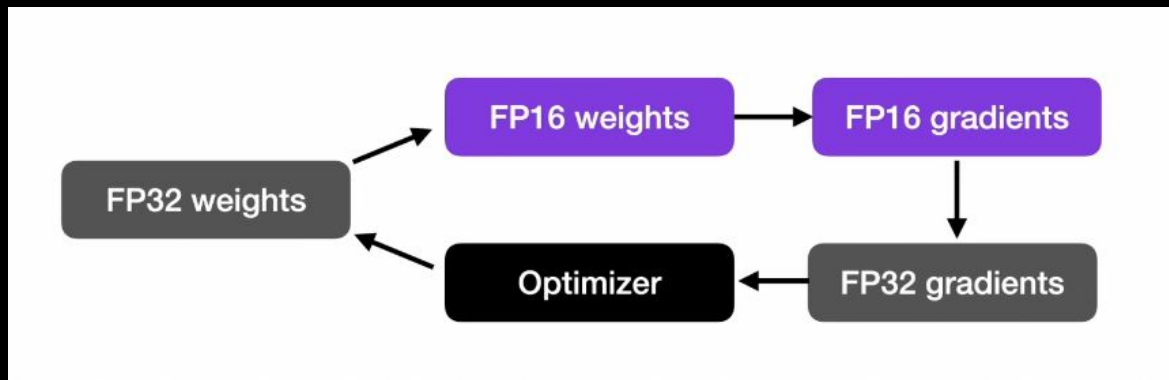
# Mixed Precision

- **Mixed precision** combines the use of both FP32 and lower bit floating points (FP16) to reduce memory footprint during model training.
- It halves GPU memory use and often boosts training throughput by 1.5–2×.
- [Implementation.](#)

# Mixed Precision

- How it works?

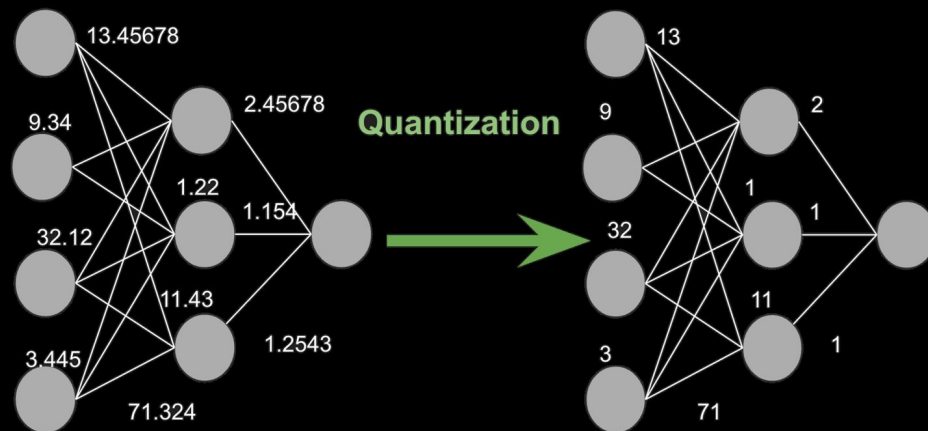
1. FP32 original weights are kept for full-precision updates.
2. Cast to FP16 for forward/backward.
3. Compute FP16 gradients, then cast back to FP32.
4. Optimizer updates the FP32 “original” copy.





# Quantization

- Convert the weights of a trained model from FP32  $\rightarrow$  INT8/4.
- **Why?**
  - Model size  $\downarrow$  4–8 $\times$
  - Inference speed  $\uparrow$  2–4 $\times$
  - Minimal accuracy drop  $\downarrow$



# Mixed Precision vs Quantization

	Mixed Precision	Quantization
Data type	FP32 ↔ FP16 (floats)	FP32 → INT8/4 (integers)
When to use	Training	Inference
Benefit	½ memory & 1.5–2× training speed	4–8× smaller model & 2–4× faster inference
Drawback	Needs GPU support (AMP)	Possible small accuracy drop

*Why not training on INT8/4 to make training even faster/lighter?🐼*



# Mixed Precision vs Quantization

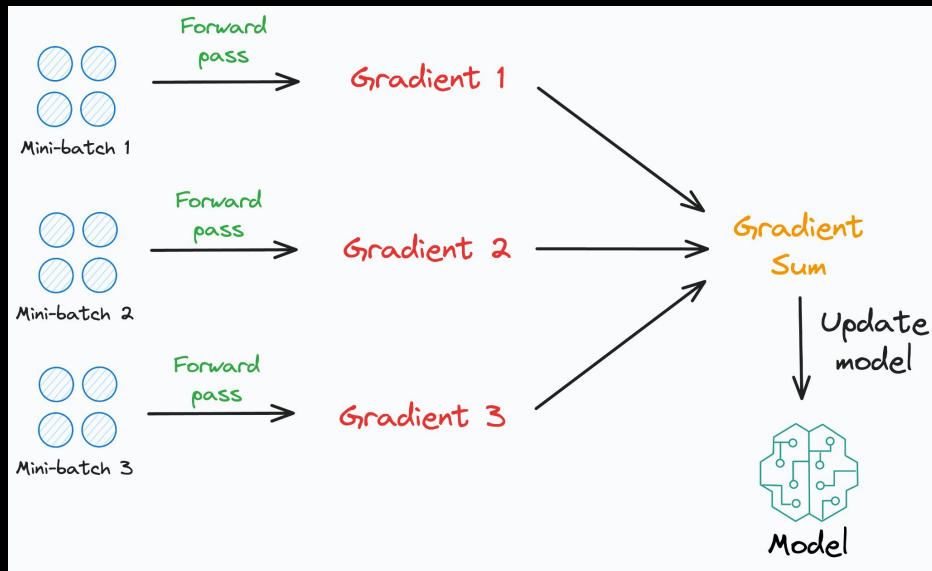
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*Why not training on INT8/4 to make training even faster/lighter? unstable or no learning.*



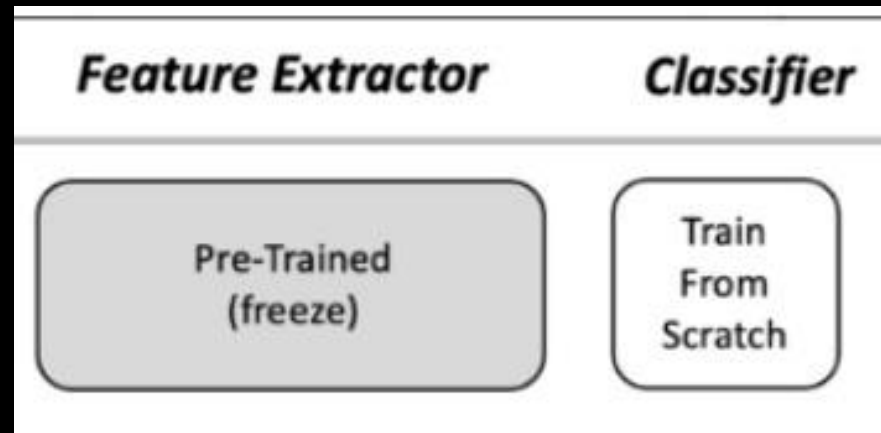
# Gradient Accumulation

- Simulate large-batch training on limited GPU memory.
- **How:** accumulate gradients over  $k$  mini-batches before optimizer step.
- **Result:**
  - Stable updates
  - Bigger effective batch size without OOM.



# Freezing Backbone

- Freeze pretrained backbone and train only head or adapter layers.
- **Benefits:**
  - Faster training
  - Lower memory
  - Less overfitting on small data





# Knowledge Distillation (Teacher-Student Models)

- Knowledge distillation is a machine learning technique that aims to transfer the learnings of a large pre-trained model (teacher) to a smaller model (student).
- Why?
  - $\approx 95\%$  accuracy with  $< \frac{1}{2}$  parameters.
  - Memory & latency  $\downarrow \rightarrow$  deploy on edge/phone.
  - Decrease inference cost significantly.



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- Why?
  - $\approx 95\%$  accuracy with  $< \frac{1}{2}$  parameters.
  - Memory & latency  $\downarrow \rightarrow$  deploy on edge/phone.
  - Decrease inference cost significantly.

Example: **GPT-o3**  $\rightarrow$  **GPT-o3-mini**

# Knowledge Distillation (Teacher-Student Models)

There are many ways of doing distillation, but simplest way is:

1. Inference teacher on large unlabeled pool  $\rightarrow$  soft logits.
2. Consider these logits as labels.
3. Train student on these labels with loss:

$$\text{KLDiv}(\text{Student logits} \parallel \text{Teacher logits})$$

# Thanks for Attending!

Prepared By: Mohamed Eltayeb