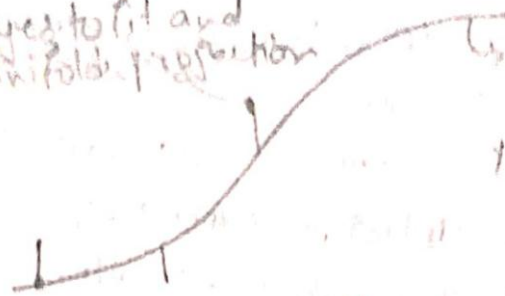


tries to fit and
manifold projection



low-dimensional manifold

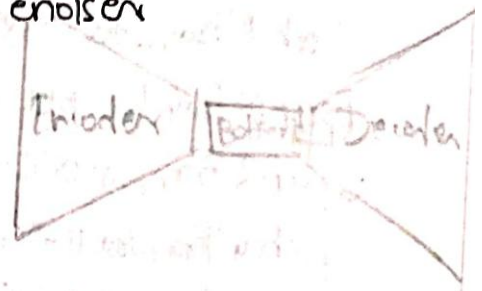
Noise \rightarrow additive in nature

upezp

$$\mathcal{L}(\lambda, \tilde{x}) = (\lambda - \tilde{x})^2 \text{ noiser}$$

$$\mathcal{L} = \mathbb{E}[(\lambda - \tilde{x})^2]$$

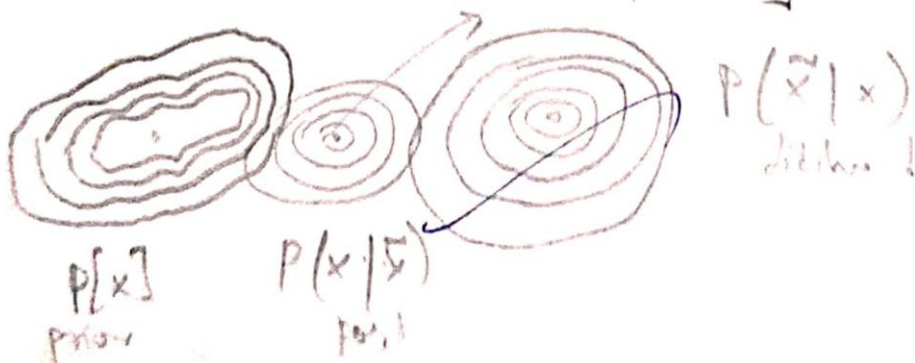
$$\arg\min_{\theta} \mathbb{E}[(\lambda - f_{\theta}(\tilde{x}))^2]$$



$$\hat{\lambda}_{\text{MMSE}} = \arg\min_{\lambda} \mathbb{E}[(\lambda - f(\tilde{x}))^2] \approx f_{\theta}$$

minimum mean sq. error

$$\mathbb{E}[x | \tilde{x} = \tilde{x}]$$



$$f_{\theta}(\tilde{x}) = \tilde{x} + \sigma \nabla \log p_{\sigma}(\tilde{x})$$

$$N/2 = 20 (0$$

EXP10

PERFORM COMPRESSION ON MNIST DATASET USING AUTOENCODER

AIM

To implement a Autoencoder (DAE) that performs image compression on the MNIST dataset, learns robust latent representations and evaluate the reconstruction quality using quantitative metrics (MSE, PSNR, SSIM)

OBJECTIVES

- * To load the MNIST dataset using the Kagle API and preprocess it.
- * To design a Denoising Autoencoder architecture for image compression and reconstruction.
- * To introduce Gaussian noise into the dataset for robustness (denoising concept).
- * To train and evaluate the model using MSE (Mean Squared Error), PSNR (Peak Signal to Noise Ratio), and SSIM (Structural Similarity Index)

PSEUDOCODE

- ↳ Import necessary libraries
- ↳ Download and load MNIST dataset
- ↳ Define Denoising Autoencoder architecture
 - ↳ Encoder: Input $\rightarrow 256 \rightarrow 128 \rightarrow$ latent (64)
 - ↳ Decoder: latent $\rightarrow 128 \rightarrow 256 \rightarrow$ output (28x28)
 - ↳ Activation: ReLU for hidden, Tanh for output.
- ↳ Define noise function.
 - ↳ Add Gaussian noise to images.
- ↳ Initialize model, optimize, and loss
- ↳ Train model for N epochs.
- ↳ Visualization
- ↳ Evaluation.

Loss/Evaluation

$$PSNR = 20 \log_{10} \left(\frac{MAX_i}{\sqrt{MSE}} \right)$$

MAX - Max possible pixel value

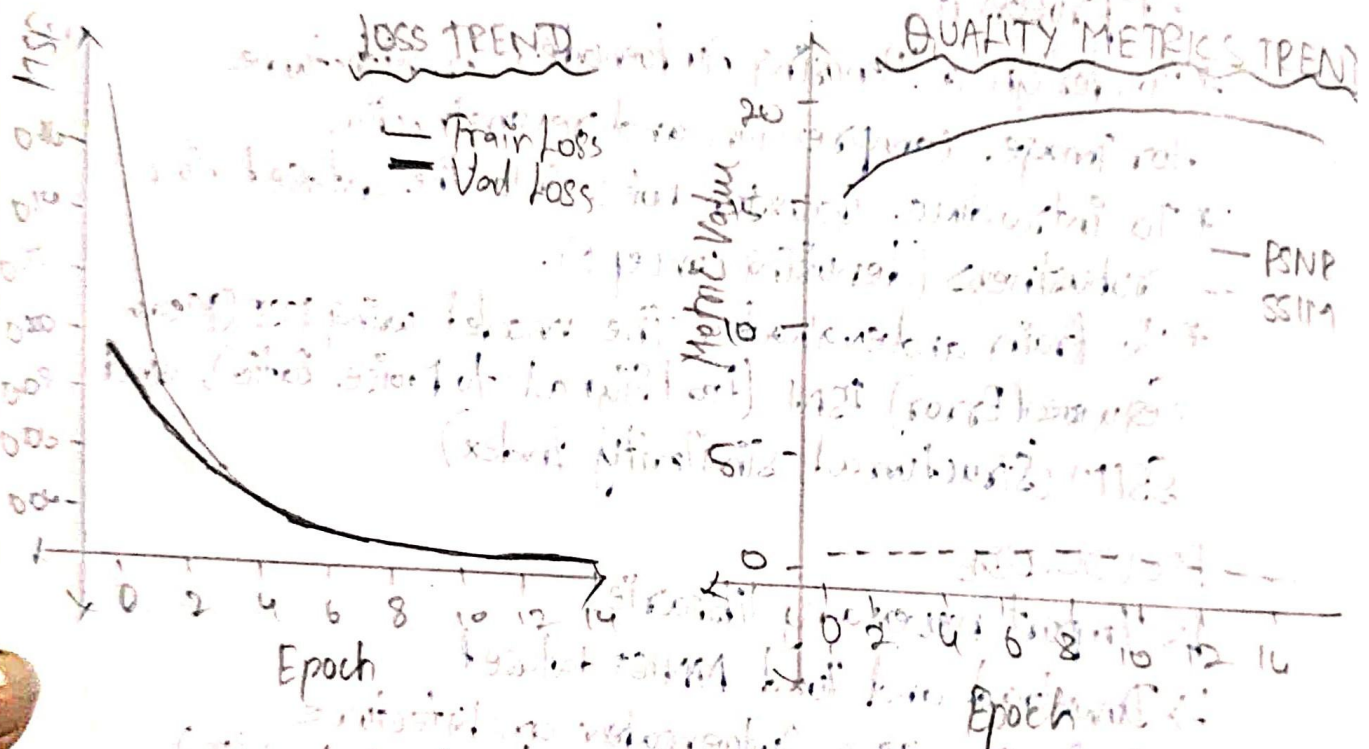
$$SSIM(x, y) = \frac{(2\mu_x\mu_y + C_1)(2\sigma_{xy} + C_2)}{(\mu_x^2 + \mu_y^2 + C_1)(\sigma_x^2 + \sigma_y^2 + C_2)}$$

$\mu_x, \mu_y \rightarrow$ Mean of original / Reconstructed Img

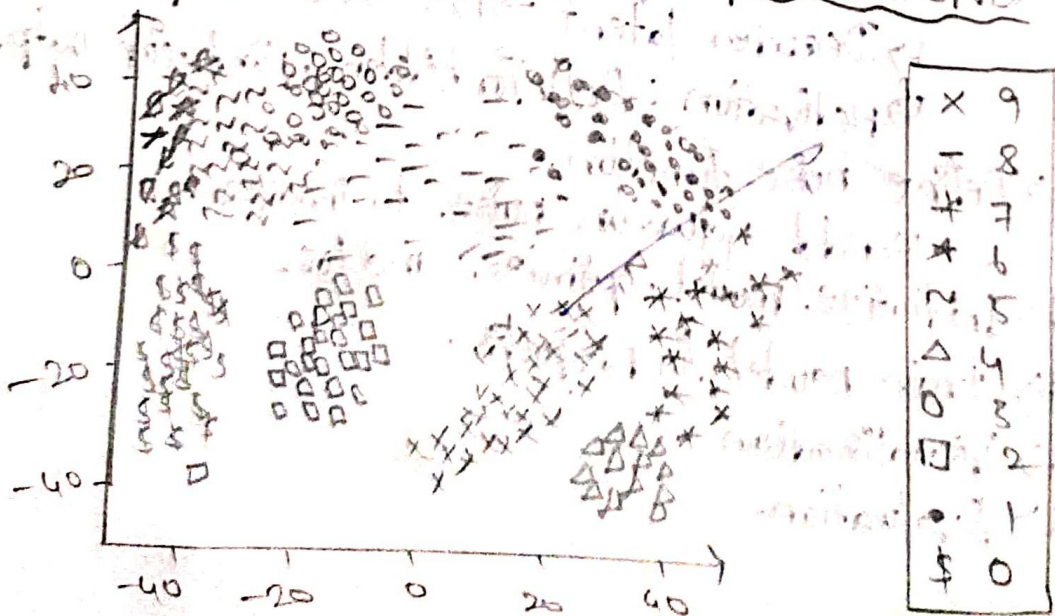
$\sigma_x, \sigma_y \rightarrow$ Var

$\sigma_{xy} \rightarrow$ Covariance

$C_1, C_2 \rightarrow$ Constant (stabilizing)



2D Visualization of Latent Space (t-SNE)



088

Epoch [1/15] | Train 0.1125 | Val: 0.0954 | PSNR: 16.98 | SSIM: 0.648
 Epoch [2/15] | Train 0.0789 | Val: 0.0871 | PSNR: 18.81 | SSIM: 0.706
 Epoch [3/15] | Train 0.0603 | Val: 0.0561 | PSNR: 19.25 | SSIM: 0.806
 Epoch [4/15] | Train 0.0517 | Val: 0.0497 | PSNR: 19.86 | SSIM: 0.828
 Epoch [5/15] | Train 0.0519 | Val: 0.0454 | PSNR: 20.21 | SSIM: 0.859
 Epoch [6/15] | Train 0.0420 | Val: 0.0424 | PSNR: 20.46 | SSIM: 0.850

Epoch [14/15] | Train 0.0202 | Val: 0.0204 | PSNR: 21.83 | SSIM: 0.886
 Epoch [15/15] | Train 0.0295 | Val: 0.0303 | PSNR: 21.87 | SSIM: 0.885



(re)initialize encoder & decoder

reinitialize encoder & decoder
 (x/3)g = (x/3)g

reinitialize encoder & decoder

$(x/3)g = (x/3)g$

reinitialize encoder & decoder

reinitialize encoder & decoder

(x/3)g = (x/3)g

$(x/3)g = (x/3)g$

RESULT:

The autoencoder (DAE) was implemented and evaluated and visualized successfully

```
Lab 10: MNIST Compression using Denoising Autoencoder Advanced Visualization + Metrics

import torch
import torch.nn as nn
import torch.optim as optim
from torch.utils.data import DataLoader, random_split
from torchvision import datasets, transforms
import matplotlib.pyplot as plt
import numpy as np
from sklearn.manifold import TSNE
from skimage.metrics import peak_signal_noise_ratio, structural_similarity as ssim
import seaborn as sns
import kagglehub

Download MNIST dataset using Kaggle API

path = kagglehub.dataset_download("arnavsharma45/mnist-dataset")
print("Path to dataset files:", path)

Downloading from https://www.kaggle.com/api/v1/datasets/download/arnavsharma45/mnist-dataset?dataset_version_number=1...
100% [9.14M/9.14M [00:01:00:00, 6.29MB/s]] extracting files...

Path to dataset files: /root/.cache/kagglehub/datasets/arnavsharma45/mnist-dataset/versions/1

Data preparation
```

```
print("Path to dataset files:", path)

Downloading from https://www.kaggle.com/api/v1/datasets/download/arnavsharma45/mnist-dataset?dataset_version_number=1...
100% [9.14M/9.14M [00:01:00:00, 6.29MB/s]] extracting files...

Path to dataset files: /root/.cache/kagglehub/datasets/arnavsharma45/mnist-dataset/versions/1

Data preparation

transform = transforms.Compose([
    transforms.ToTensor(),
    transforms.Normalize((0.5,), (0.5,))
])

dataset = datasets.MNIST(root=".", train=True, transform=transform, download=True)
train_size = int(0.8 * len(dataset))
val_size = len(dataset) - train_size
train_dataset, val_dataset = random_split(dataset, [train_size, val_size])
train_loader = DataLoader(train_dataset, batch_size=128, shuffle=True)
val_loader = DataLoader(val_dataset, batch_size=128, shuffle=False)

100% [9.14M/9.14M [00:01:00:00, 4.09MB/s]]
100% [28.9K/28.9K [00:00:00:00, 131KB/s]]
100% [1.65M/1.65M [00:01:00:00, 1.24MB/s]]
100% [4.54K/4.54K [00:00:00:00, 12.6MB/s]]

Define Denoising Autoencoder
```

```
Define Denoising Autoencoder

class DenoisingAutoencoder(nn.Module):
    def __init__(self, encoding_dim=64):
        super(DenoisingAutoencoder, self).__init__()
        self.encoder = nn.Sequential(
            nn.Linear(28*28, 256),
            nn.ReLU(True),
            nn.Linear(256, 128),
            nn.ReLU(True),
            nn.Linear(128, encoding_dim)
        )
        self.decoder = nn.Sequential(
            nn.Linear(encoding_dim, 128),
            nn.ReLU(True),
            nn.Linear(128, 256),
            nn.ReLU(True),
            nn.Linear(256, 28*28),
            nn.Tanh()
        )

    def forward(self, x):
        x = x.view(-1, 28*28)
        latent = self.encoder(x)
        recon = self.decoder(latent)
        return recon, latent

Noise Function
```



```
LAB_10
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Commands + Code + Text Run all
Connect 14

Noise Function

def add_noise(inputs, noise_factor=0.3):
    noisy = inputs + noise_factor * torch.randn_like(inputs)
    noisy = torch.clip(noisy, -1.0, 1.0)
    return noisy

Setup model, loss, optimizer

device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
model = DenoisingAutoencoder().to(device)
criterion = nn.MSELoss()
optimizer = optim.Adam(model.parameters(), lr=0.001)

Training with visualization checkpoints

num_epochs = 15
train_losses, val_losses, psnr_vals, ssim_vals = [], [], [], []

for epoch in range(num_epochs):
    model.train()
    total_loss = 0
    for imgs, _ in train_loader:
        imgs = imgs.to(device)
        noisy_imgs = add_noise(imgs)
        recon, _ = model(noisy_imgs)
        loss = criterion(recon, imgs.view(-1, 28*28))
        optimizer.zero_grad()
        loss.backward()
        optimizer.step()
        total_loss += loss.item()

    avg_train_loss = total_loss / len(train_loader)
    train_losses.append(avg_train_loss)

    # Validation
    model.eval()
    val_loss, psnr_epoch, ssim_epoch = 0, [], []
    with torch.no_grad():
        for imgs, _ in val_loader:
            imgs = imgs.to(device)
            noisy_imgs = add_noise(imgs)
            recon, _ = model(noisy_imgs)
            val_loss += criterion(recon, imgs.view(-1, 28*28)).item()
```

```
LAB_10
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num_epochs = 15
train_losses, val_losses, psnr_vals, ssim_vals = [], [], [], []

for epoch in range(num_epochs):
    model.train()
    total_loss = 0
    for imgs, _ in train_loader:
        imgs = imgs.to(device)
        noisy_imgs = add_noise(imgs)
        recon, _ = model(noisy_imgs)
        loss = criterion(recon, imgs.view(-1, 28*28))
        optimizer.zero_grad()
        loss.backward()
        optimizer.step()
        total_loss += loss.item()

    avg_train_loss = total_loss / len(train_loader)
    train_losses.append(avg_train_loss)

    # Validation
    model.eval()
    val_loss, psnr_epoch, ssim_epoch = 0, [], []
    with torch.no_grad():
        for imgs, _ in val_loader:
            imgs = imgs.to(device)
            noisy_imgs = add_noise(imgs)
            recon, _ = model(noisy_imgs)
            val_loss += criterion(recon, imgs.view(-1, 28*28)).item()
```

```
LAB_10
File Edit View Insert Runtime Tools Help
Commands + Code + Text Run all
Connect 14

recon_np = recon.view(-1, 1, 28, 28).cpu().numpy()
for i in range(10):
    orig, rec = imgs_np[i][0], recon_np[i][0]
    psnr_epoch.append(psnr_signal_noise_ratio(orig, rec, data_range=2))
    ssim_epoch.append(ssim(orig, rec, data_range=2))

avg_val_loss = val_loss / len(val_loader)
val_losses.append(avg_val_loss)
psnr_vals.append(np.mean(psnr_epoch))
ssim_vals.append(np.mean(ssim_epoch))

print(f"Epoch {(epoch+1)/(num_epochs)} | Train: {avg_train_loss:.4f} | Val: {avg_val_loss:.4f} | PSNR: {np.mean(psnr_epoch):.2f} | SSIM: {np.mean(ssim_epoch):.3f}")

# Show intermediate reconstruction
if (epoch+1) % 5 == 0:
    dataiter = iter(val_loader)
    imgs, _ = next(dataiter)
    noisy_imgs = add_noise(imgs).to(device)
    recon, _ = model(noisy_imgs)
    imgs = imgs.cpu().numpy()
    noisy_imgs = noisy_imgs.cpu().numpy()
    recon = recon.view(-1, 1, 28, 28).cpu().detach().numpy()

    fig, axes = plt.subplots(3, 8, figsize=(12, 5))
    for i in range(8):
        axes[0][i].imshow(imgs[i][0], cmap='gray'); axes[0][i].axis('off')
        axes[1][i].imshow(noisy_imgs[i][0], cmap='gray'); axes[1][i].axis('off')
        axes[2][i].imshow(recon[i][0], cmap='gray'); axes[2][i].axis('off')
    axes[0][0].set_title("Original")
    axes[1][0].set_title("Noisy")
    axes[2][0].set_title(f"Reconstructed (Epoch {epoch+1})")
```

