

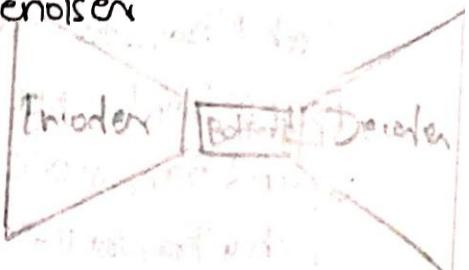
Ingest to fit and
 manifold projection
 $\tilde{x} = f(x)$
 f : $\mathbb{R}^n \rightarrow \mathbb{R}^m$
 \mathcal{M} : \mathbb{R}^m manifold
 \mathcal{M} : \mathbb{R}^n manifold
 \mathcal{M} : \mathbb{R}^m manifold
 Noise \rightarrow additive in nature

upezp

$$\mathcal{L}(x, \tilde{x}) = (x - \tilde{x})^2 \text{ enoisen}$$

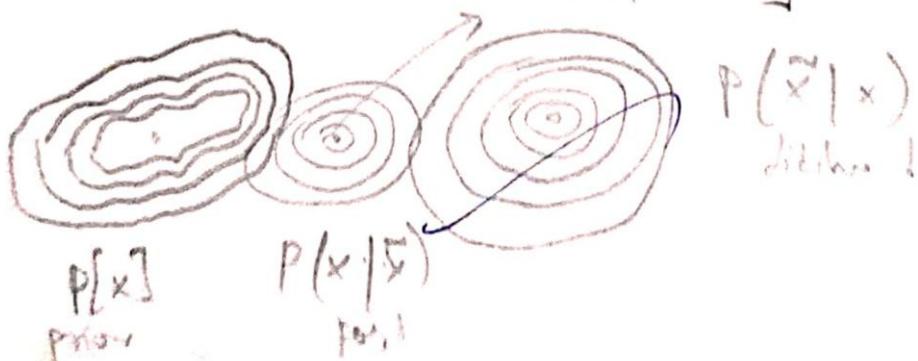
$$\mathcal{L} = E[(x - \tilde{x})^2]$$

$$\underset{\tilde{x}}{\operatorname{argmin}} E[(x - f(\tilde{x}))^2]$$



$$\hat{x}_{\text{MMSE}} = \underset{\text{minimum mean sq. error}}{\operatorname{argmin}} E[(x - f(\tilde{x}))^2] \approx f_0.$$

$$E[x | \tilde{x} = \tilde{x}]$$



$$f_0(\tilde{x}) = \tilde{x} + \sigma \nabla \log P_0(\tilde{x})$$

$$N/2 = 20(0)$$

Exp 10

PERFORM COMPRESSION ON MNIST DATASET USING AUTOENCODER

AIM

To implement a Autoencoder (DAE) that performs image compression on the MNIST dataset, learns, robust latent representations and evaluate the reconstruction quality using quantitative metrics (MSE, PSNR, SSIM)

OBJECTIVES

- * To load the MNIST dataset using the Kaggel API and preprocess it.
- * To design a Denoising Autoencoder architecture for image compression and reconstruction.
- * To introduce Gaussian noise into the dataset for robustness (denoising concept).
- * To train and evaluate the model using MSE (Mean Squared Error), PSNR (Peak Signal to Noise Ratio), and SSIM (Structural Similarity Index)

PSEUDOCODE

- ↳ Import necessary libraries
- ↳ Download and load MNIST dataset
- ↳ Define Denoising Autoencoder architecture
 - ↳ Encoder: Input $\rightarrow 256 \rightarrow 128 \rightarrow$ latent(64)
 - ↳ Decoder: latent $\rightarrow 128 \rightarrow 256 \rightarrow$ output(28×28)
 - ↳ Activation: ReLU for hidden, Tanh for output.
- ↳ Define noise function.
 - ↳ Add Gaussian noise to images.
- ↳ Initialize model, optimize, and loss
- ↳ Train model for N epochs.
- ↳ Visualization
- ↳ Evaluation.

Loss / Evaluation

$$PSNR = 20 \log_{10} \left(\frac{MAX}{\sqrt{MSE}} \right)$$

MAX - Max possible pixel value

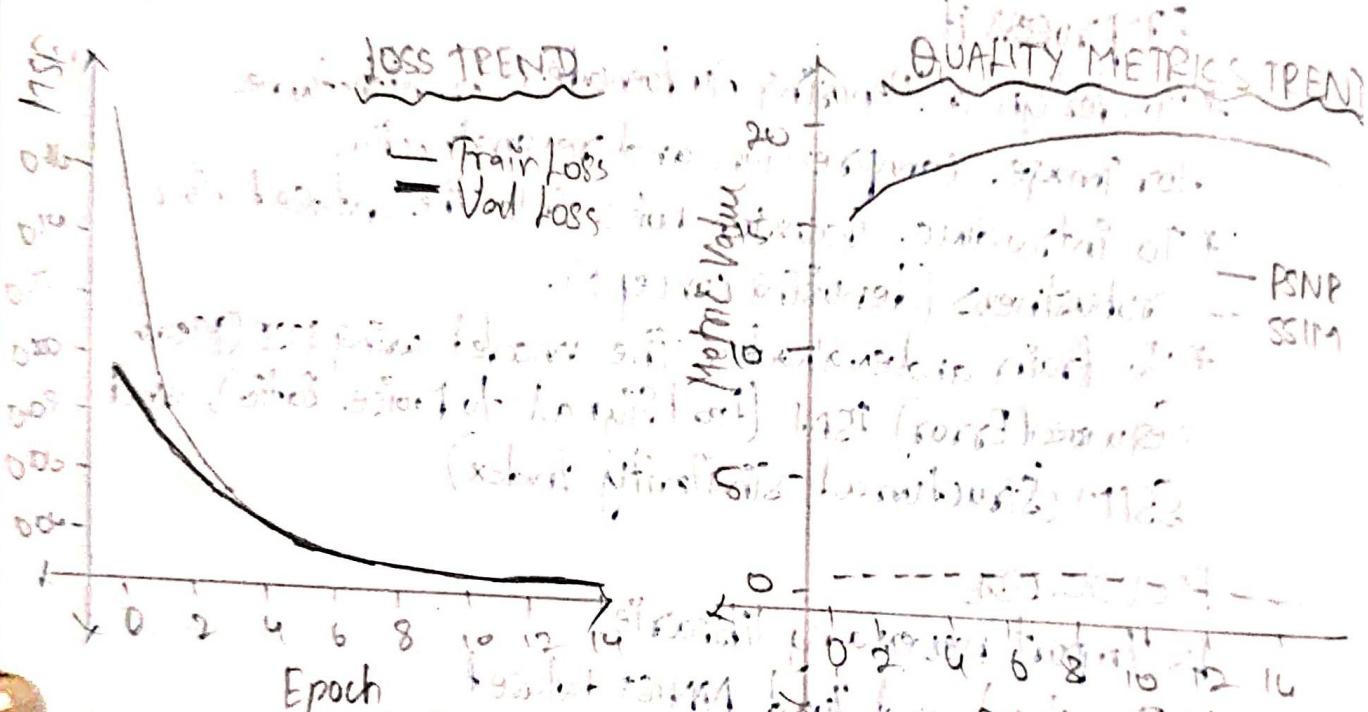
$$SSIM(x, y) = \frac{(2M_a M_y + C_1)(2\sigma_{xy} + C_2)}{(M_a^2 + M_y^2 + C_1)(\sigma_x^2 + \sigma_y^2 + C_2)}$$

$$\text{where } M_a, M_y \rightarrow \text{Mean of original / Reconstructed Img}$$

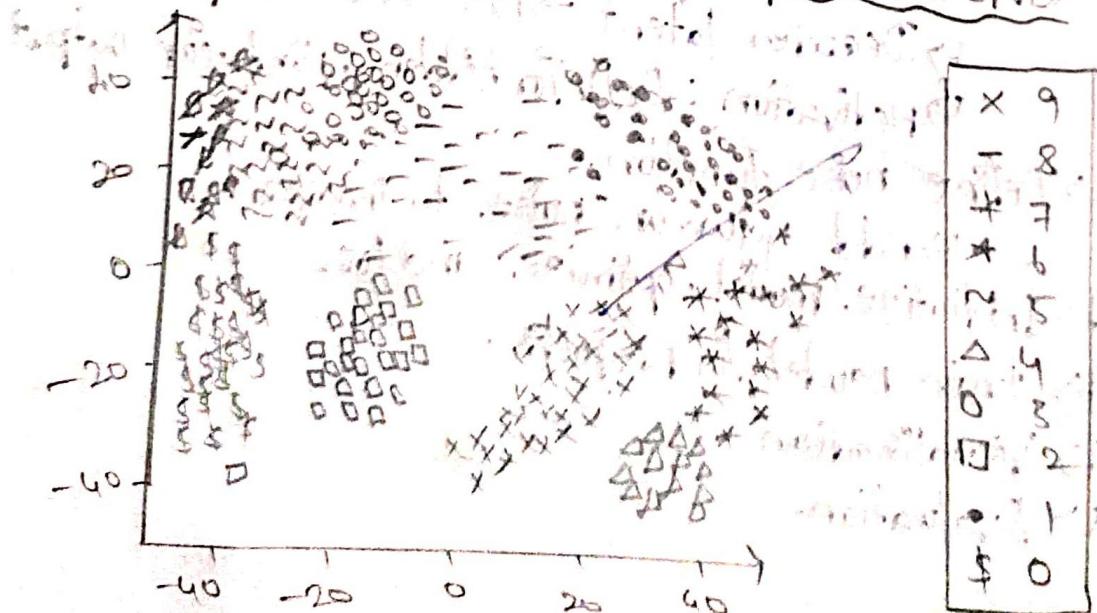
$\sigma_{xy} \rightarrow$ Correlation between pixels

$\sigma_x, \sigma_y \rightarrow$ Covariance

$C_1, C_2 \rightarrow$ Constants (stabilizing)



2D Visualizations of Latent Space (t-SNE)



OSS

Epoch [1/15] | Train 0.4135 | Val: 0.0756 | PSNR: 16.98 | SSIM: 0.688
Epoch [2/15] | Train 0.0789 | Val: 0.0191 | PSNR: 18.81 | SSIM: 0.966
Epoch [3/15] | Train 0.0603 | Val: 0.0261 | PSNR: 19.25 | SSIM: 0.806
Epoch [4/15] | Train 0.0517 | Val: 0.0192 | PSNR: 19.86 | SSIM: 0.828
Epoch [5/15] | Train 0.0517 | Val: 0.0184 | PSNR: 20.21 | SSIM: 0.859
Epoch [6/15] | Train 0.0439 | Val: 0.0174 | PSNR: 20.46 | SSIM: 0.850
⋮
⋮
Epoch [14/15] | Train 0.0202 | Val: 0.0204 | PSNR: 21.88 | SSIM: 0.886
Epoch [15/15] | Train 0.0295 | Val: 0.0303 | PSNR: 21.87 | SSIM: 0.885

(initially - no loss to the
model of loss)

(at 3rd epoch loss)
evaluated at each step

$$(E, H)_{\text{gt}} = (x, z)_p$$

repeat the loop

→ get noisy and the training batch

→ (E, H) trained model generated

$$E \sim \mathcal{N}((E, H)_{\text{gt}}), H = f(E), E \sim \mathcal{N}(0, I), B = E + N$$

→ repeat the loop

RESULT:

The autoencoder (DAE) was implemented and evaluated and visualized successfully.

Academia - Academic Web Servi x LAB_10 - Colab x KAVINRAJ06/DLT_LAB x +

<https://colab.research.google.com/drive/1Ifq-b4l6ZqXlpK0wHoM06jNboINRnj?authuser=2>

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Lab 10: MNIST Compression using Denoising Autoencoder Advanced Visualization + Metrics

```

import torch
import torch.nn as nn
import torch.optim as optim
from torch.utils.data import DataLoader, random_split
from torchvision import datasets, transforms
import matplotlib.pyplot as plt
import numpy as np
from sklearn.manifold import TSNE
from skimage.metrics import peak_signal_noise_ratio, structural_similarity as ssim
import seaborn as sns
import kagglehub

```

Download MNIST dataset using Kaggle API

```

path = kagglehub.dataset_download("arnavsharma45/mnist-dataset")
print("Path to dataset files:", path)

Downloading from https://www.kaggle.com/api/v1/datasets/download/arnavsharma45/mnist-dataset?dataset_version_number=1...
100%|██████████| 9.14M/9.14M [00:01<00:00, 6.29MB/s]Extracting files...

```

Path to dataset files: /root/.cache/kagglehub/datasets/arnavsharma45/mnist-dataset/versions/1

Data preparation

Variables Terminal

```

print("Path to dataset files:", path)

Downloading from https://www.kaggle.com/api/v1/datasets/download/arnavsharma45/mnist-dataset?dataset_version_number=1...
100%|██████████| 9.14M/9.14M [00:01<00:00, 6.29MB/s]Extracting files...

```

Path to dataset files: /root/.cache/kagglehub/datasets/arnavsharma45/mnist-dataset/versions/1

Data preparation

```

transform = transforms.Compose([
    transforms.ToTensor(),
    transforms.Normalize((0.5,), (0.5,))
])

dataset = datasets.MNIST(root="./data", train=True, transform=transform, download=True)
train_size = int(0.8 * len(dataset))
val_size = len(dataset) - train_size
train_dataset, val_dataset = random_split(dataset, [train_size, val_size])
train_loader = DataLoader(train_dataset, batch_size=128, shuffle=True)
val_loader = DataLoader(val_dataset, batch_size=128, shuffle=False)

```

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100%	28.9k/28.9k [00:00<00:00, 13.1kB/s]
100%	1.65M/1.65M [00:01<00:00, 1.24MB/s]
100%	4.54k/4.54k [00:00<00:00, 12.6MB/s]

Define Denoising Autoencoder

Variables Terminal

```

class DenoisingAutoencoder(nn.Module):
    def __init__(self, encoding_dim=64):
        super(DenoisingAutoencoder, self).__init__()
        self.encoder = nn.Sequential(
            nn.Linear(28*28, 256),
            nn.ReLU(True),
            nn.Linear(256, 128),
            nn.ReLU(True),
            nn.Linear(128, encoding_dim)
        )
        self.decoder = nn.Sequential(
            nn.Linear(encoding_dim, 128),
            nn.ReLU(True),
            nn.Linear(128, 256),
            nn.ReLU(True),
            nn.Linear(256, 28*28),
            nn.Tanh()
        )

    def forward(self, x):
        x = x.view(-1, 28*28)
        latent = self.encoder(x)
        recon = self.decoder(latent)
        return recon, latent

```

Noise Function

Variables Terminal

Noise Function

```
def add_noise(inputs, noise_factor=0.3):
    noisy = inputs + noise_factor * torch.randn_like(inputs)
    noisy = torch.clip(noisy, -1.0, 1.0)
    return noisy
```

Setup model, loss, optimizer

```
device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
model = DenoisingAutoencoder().to(device)
criterion = nn.MSELoss()
optimizer = optim.Adam(model.parameters(), lr=0.001)
```

Training with visualization checkpoints

```
num_epochs = 15
train_losses, val_losses, psnr_vals, ssim_vals = [], [], [], []

for epoch in range(num_epochs):
    model.train()
    total_loss = 0
    for imgs, _ in train_loader:
        noisy_imgs = add_noise(imgs)
        recon, _ = model(noisy_imgs)
        loss = criterion(recon, imgs.view(-1, 28*28))
        optimizer.zero_grad()
        loss.backward()
        optimizer.step()
        total_loss += loss.item()

    avg_train_loss = total_loss / len(train_loader)
    train_losses.append(avg_train_loss)

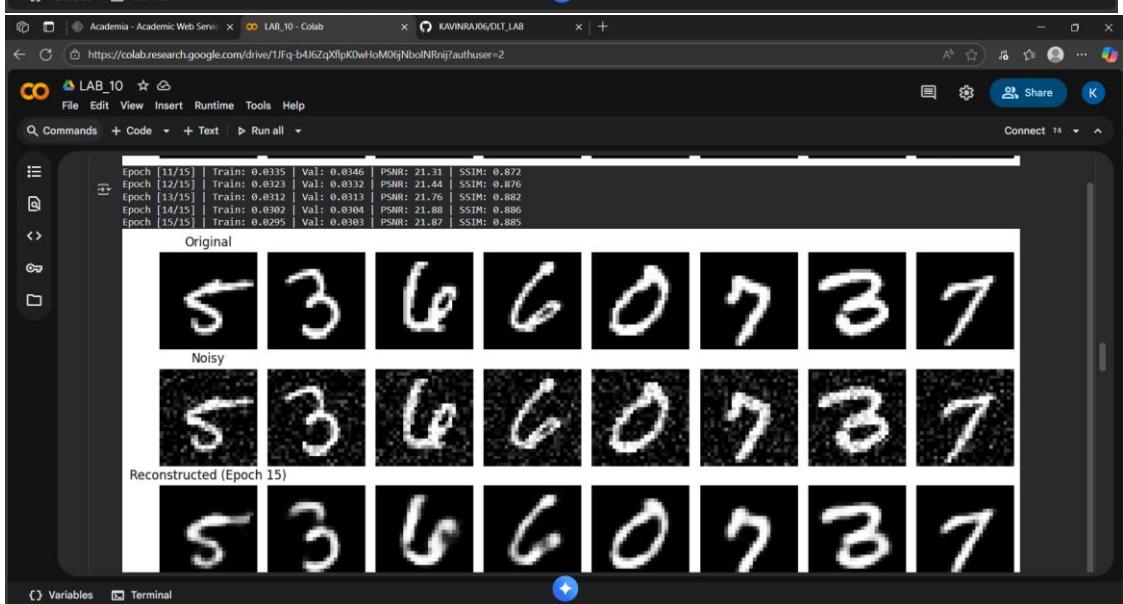
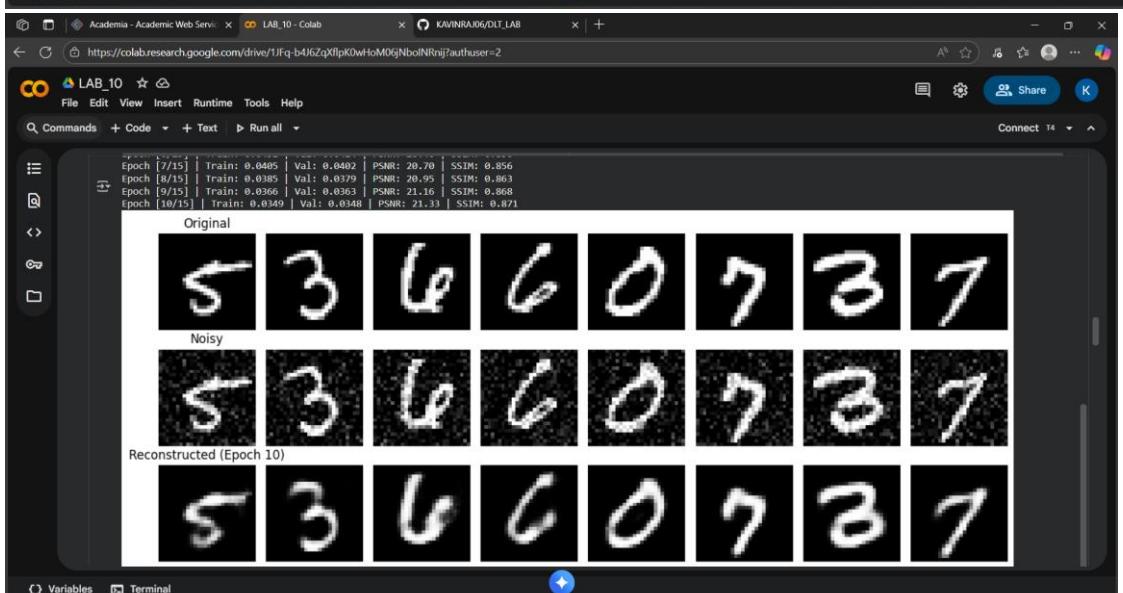
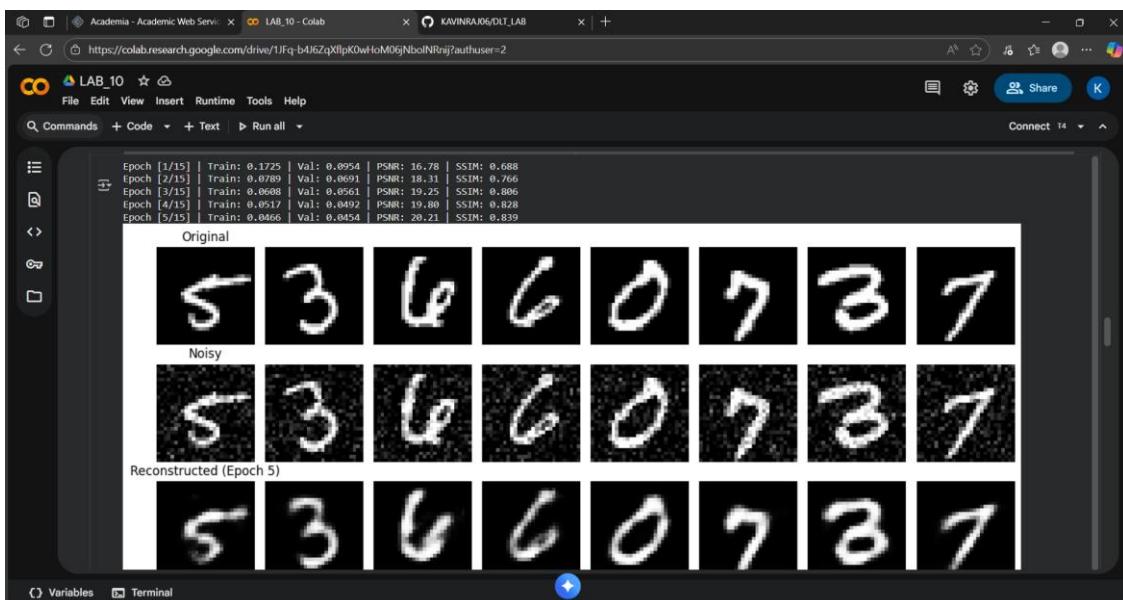
    # Validation
    model.eval()
    val_loss, psnr_epoch, ssim_epoch = 0, [], []
    with torch.no_grad():
        for imgs, _ in val_loader:
            imgs = imgs.to(device)
            noisy_imgs = add_noise(imgs)
            recon, _ = model(noisy_imgs)
            val_loss += criterion(recon, imgs.view(-1, 28*28)).item()

    avg_val_loss = val_loss / len(val_loader)
    val_losses.append(avg_val_loss)
    psnr_vals.append(np.mean(psnr_epoch))
    ssim_vals.append(np.mean(ssim_epoch))

    print(f"Epoch [{(epoch+1)}/{num_epochs}] | Train: {avg_train_loss:.4f} | Val: {avg_val_loss:.4f} | PSNR: {np.mean(psnr_epoch):.2f} | SSIM: {np.mean(ssim_epoch):.3f}")

    # Show intermediate reconstruction
    if (epoch+1) % 5 == 0:
        dataiter = iter(val_loader)
        imgs, _ = next(dataiter)
        noisy_imgs = add_noise(imgs).to(device)
        recon, _ = model(noisy_imgs)
        imgs = imgs.cpu().numpy()
        noisy_imgs = noisy_imgs.cpu().numpy()
        recon = recon.view(-1, 1, 28, 28).cpu().detach().numpy()

        fig, axes = plt.subplots(3, 8, figsize=(12, 5))
        for i in range(8):
            axes[0][i].imshow(imgs[i][0], cmap='gray'); axes[0][i].axis('off')
            axes[1][i].imshow(noisy_imgs[i][0], cmap='gray'); axes[1][i].axis('off')
            axes[2][i].imshow(recon[i][0], cmap='gray'); axes[2][i].axis('off')
            axes[0][i].set_title("Original")
            axes[1][i].set_title("Noisy")
            axes[2][i].set_title(f"Reconstructed (Epoch {epoch+1})")
```



Training Curves: MSE, PSNR, SSIM

```

plt.figure(figsize=(10,4))
plt.subplot(1,2,1)
plt.plot(train_losses, label="Train Loss")
plt.plot(val_losses, label="Validation Loss")
plt.xlabel("Epoch"); plt.ylabel("MSE"); plt.legend(); plt.title("Loss Trend")
plt.subplot(1,2,2)
plt.plot(psnr_vals, label="PSNR")
plt.plot(ssim_vals, label="SSIM")
plt.xlabel("Epoch"); plt.ylabel("Metric Value"); plt.legend(); plt.title("Quality Metrics Trend")
plt.tight_layout(); plt.show()

```

Variables Terminal

Loss Trend

Epoch	Train Loss	Validation Loss
0	0.17	0.09
1	0.10	0.06
2	0.08	0.04
3	0.07	0.03
4	0.06	0.02
5	0.05	0.01
6	0.045	0.005
7	0.04	0.002
8	0.038	0.001
9	0.035	0.001
10	0.032	0.001
11	0.03	0.001
12	0.028	0.001
13	0.026	0.001
14	0.024	0.001

Quality Metrics Trend

Epoch	PSNR	SSIM
0	15	0
1	16	0
2	17	0
3	18	0
4	19	0
5	20	0
6	20.5	0
7	20.8	0
8	21	0
9	21.2	0
10	21.5	0
11	21.8	0
12	22	0
13	22.2	0
14	22.5	0

Latent Feature Heatmap

```

model.eval()
latent_vectors = []
labels = []
with torch.no_grad():
    for imgs, lbls in val_loader:
        imgs = imgs.to(device)
        _, latent = model(imgs)
        latent_vectors.append(latent.cpu().numpy())
        labels.extend(lbls.numpy())
latent_vectors = np.concatenate(latent_vectors)
labels = np.array(labels)

sns.heatmap(np.corrcoef(latent_vectors.T), cmap="coolwarm")
plt.title("Heatmap of Latent Feature Correlations")
plt.show()

```

Variables Terminal

