

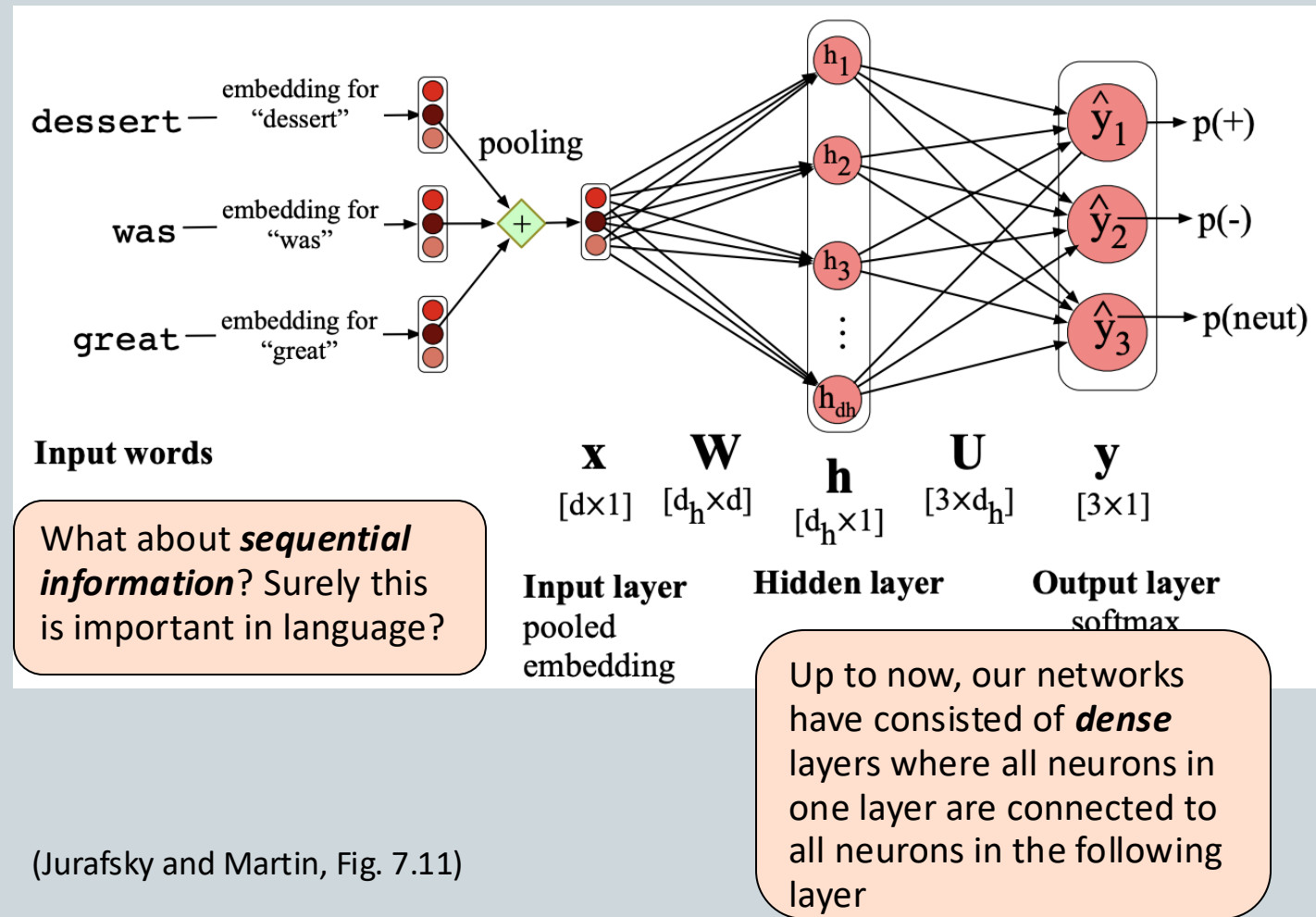
# Further neural network architectures

*NLP in one day*

**KING'S**  
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# Other architectures



(Jurafsky and Martin, Fig. 7.11)

We can design network topologies different neural processing units to increase the efficiency and representational power of our layers:

- Connect regions of input or hidden layers to single nodes in the next layer (**locally connected**)
- Learn features from one region that can be applied to others (**convoluting**)
- Carry over information from one step to the next (**memory**)

Updating our weights becomes more complicated!

# Convolution - sharpening

0	0	0	0	0
0	0	-1	0	0
0	-1	5	-1	0
0	0	-1	0	0
0	0	0	0	0



From the GIMP manual, V2.8, <https://docs.gimp.org/en/index.html>



# Convolution - blurring

0	0	0	0	0
0	1	1	1	0
0	1	1	1	0
0	1	1	1	0
0	0	0	0	0



From the GIMP manual, V2.8, <https://docs.gimp.org/en/index.html>

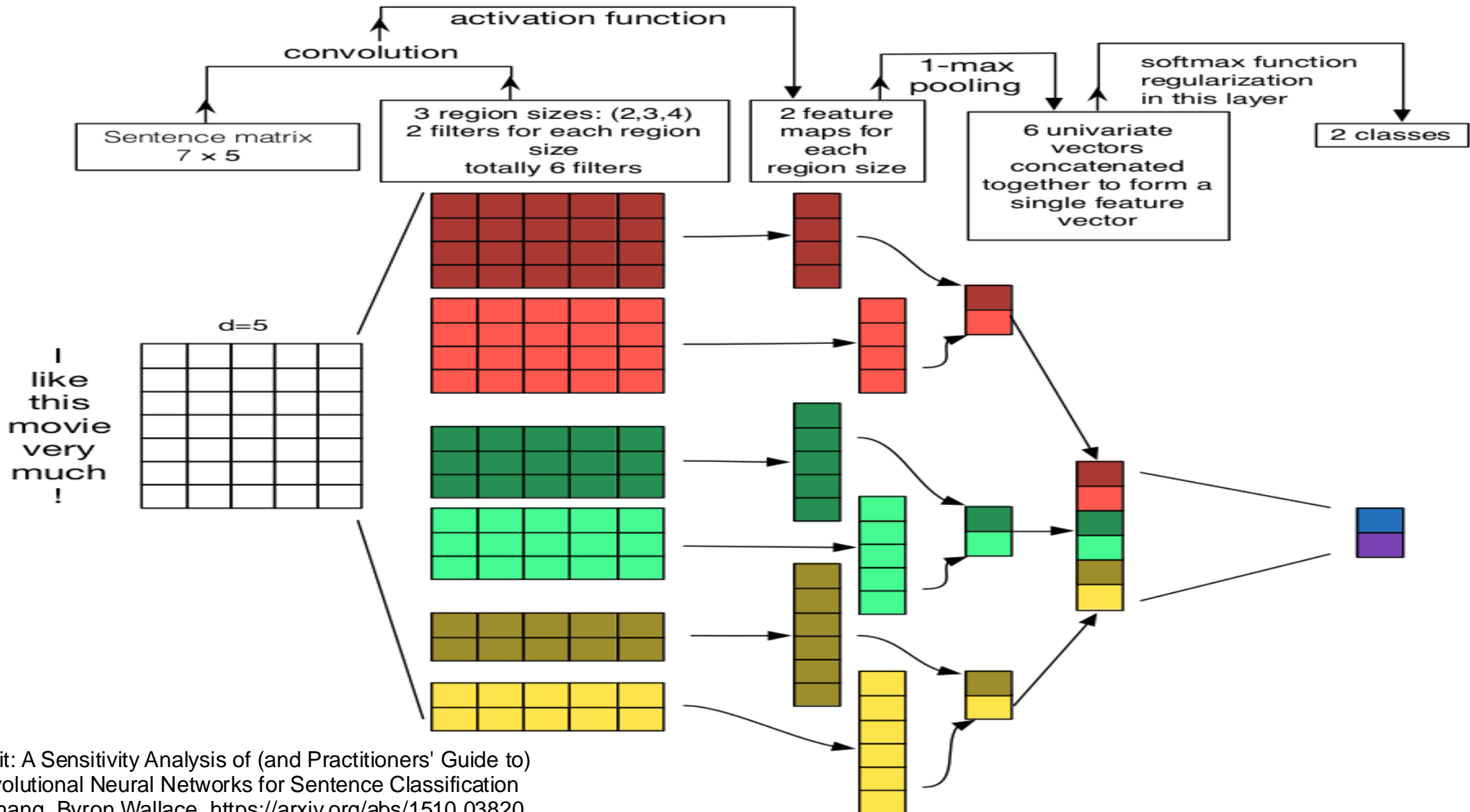
# Convolution - edge detection

	0	1	0	
	1	-4	1	
	0	1	0	



From the GIMP manual, V2.8, <https://docs.gimp.org/en/index.html>

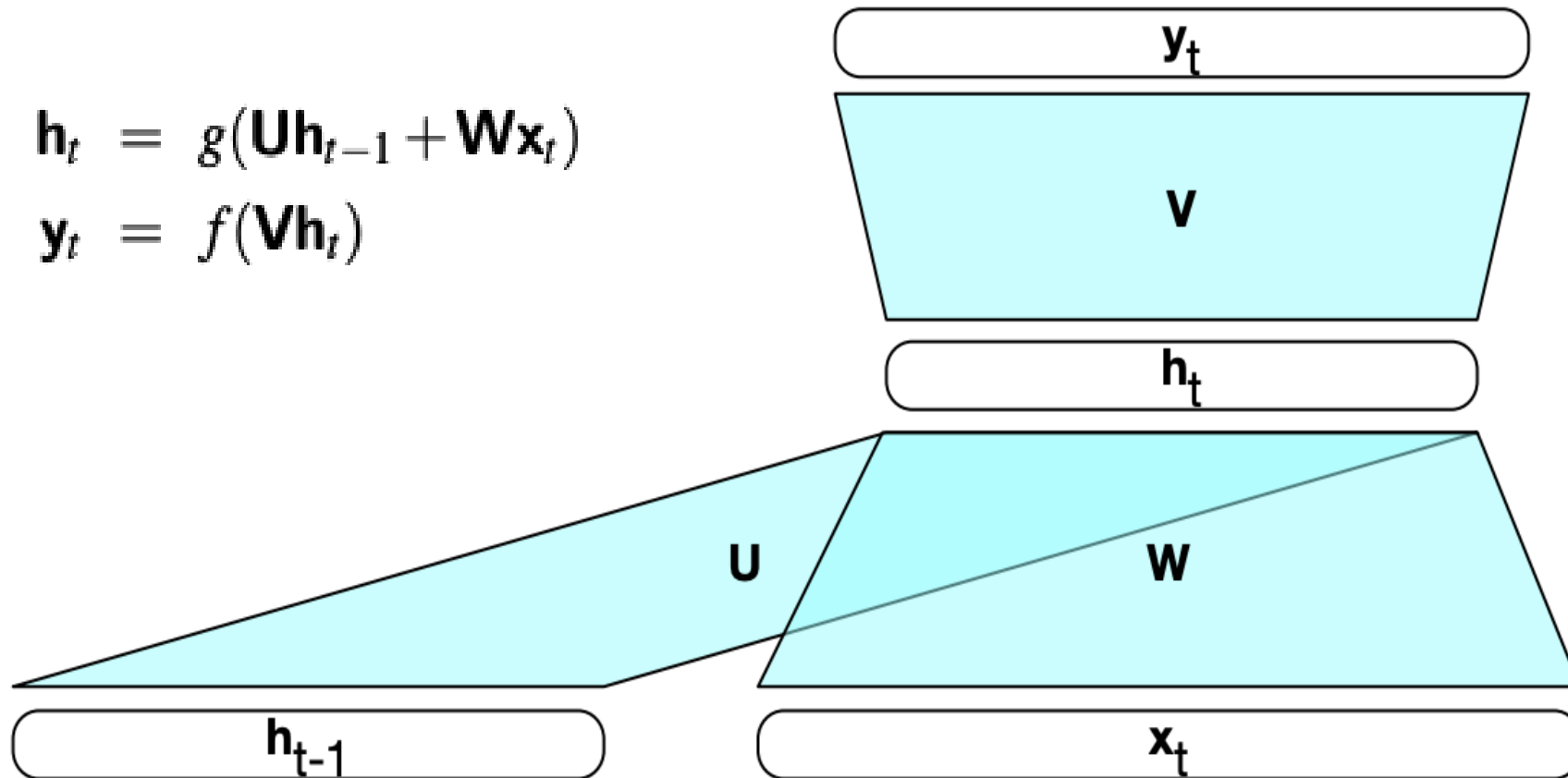
# Applying convolution to text with CNNs



# Recurrent neural network (RNN)

$$\mathbf{h}_t = g(\mathbf{U}\mathbf{h}_{t-1} + \mathbf{W}\mathbf{x}_t)$$

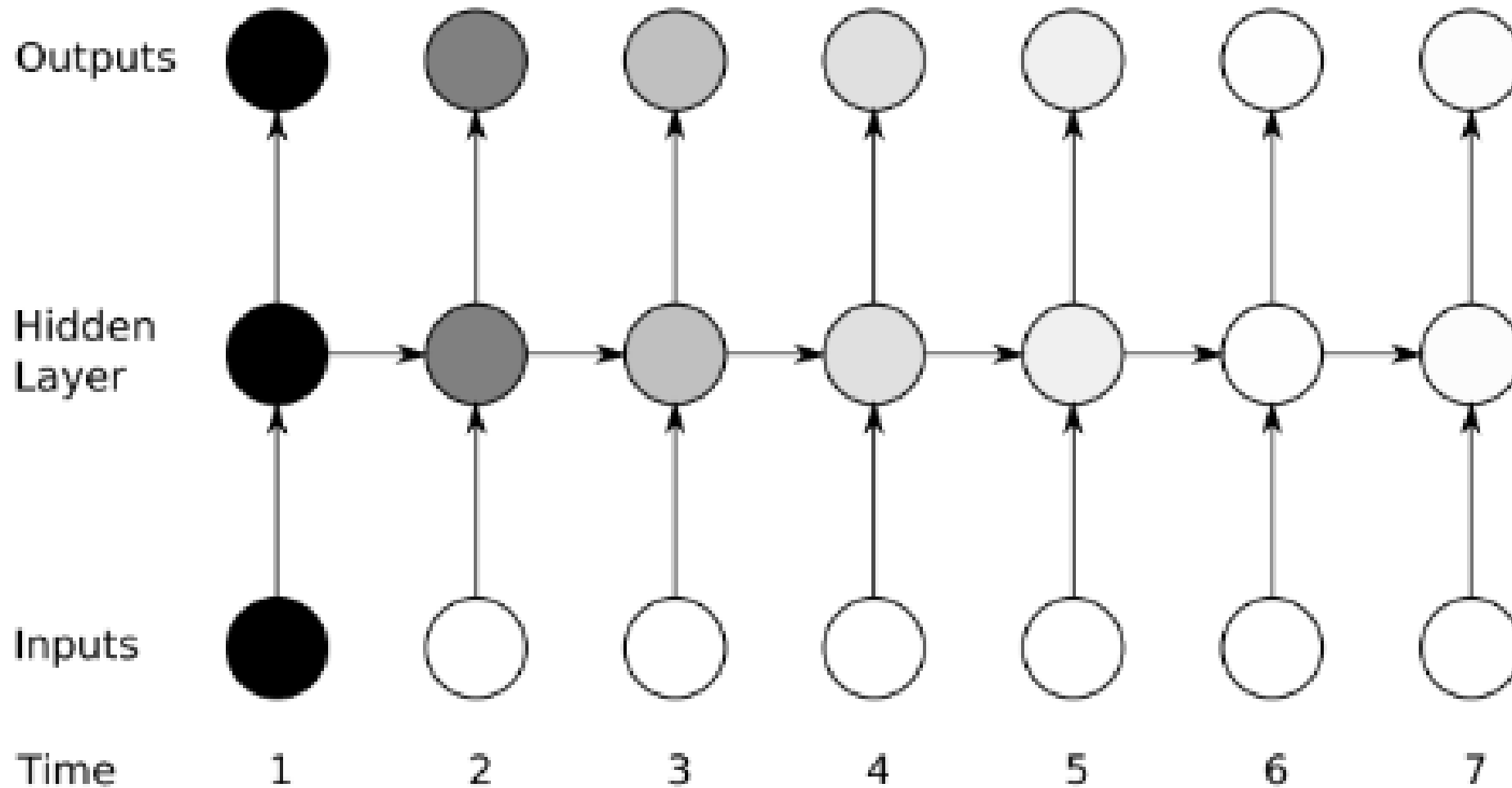
$$\mathbf{y}_t = f(\mathbf{V}\mathbf{h}_t)$$



To take account of sequential information, we could feed in the output from the previous step to each new step

(Jurafsky and Martin, Fig. 9.3)

## RNN: the signals degrade over time





# Long Short Term Memory (LSTM)

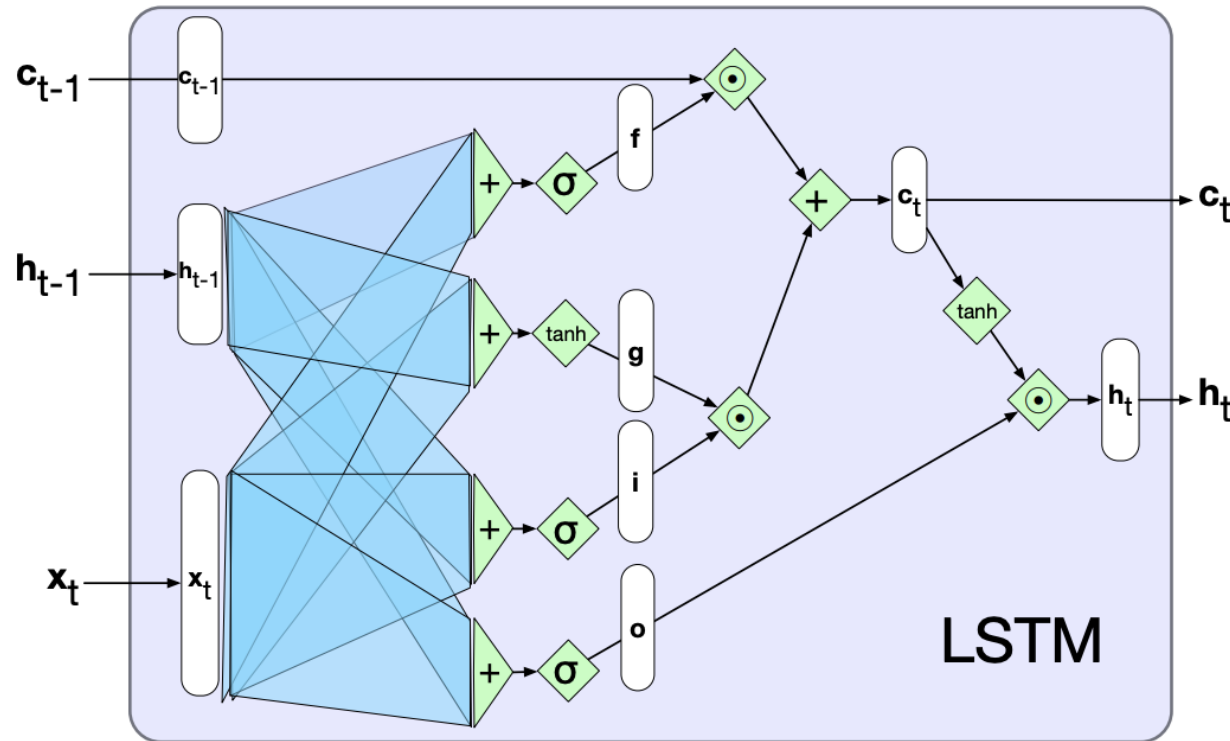
We can overcome the decay of RNNs by learning what we should forget and what we should remember at each step

Context  $\mathbf{c}$  and hidden state  $\mathbf{h}$  vectors are passed through from previous step

**Forget** gate  $\mathbf{f}$  deletes information from the context no longer needed

**Add** gate  $\mathbf{g}$  selects information to add to the current context

**Output** gate  $\mathbf{o}$  selects what information is required for the current hidden state (not future ones, which were dealt with above)



# LSTM selectively forgets and remembers information at each step

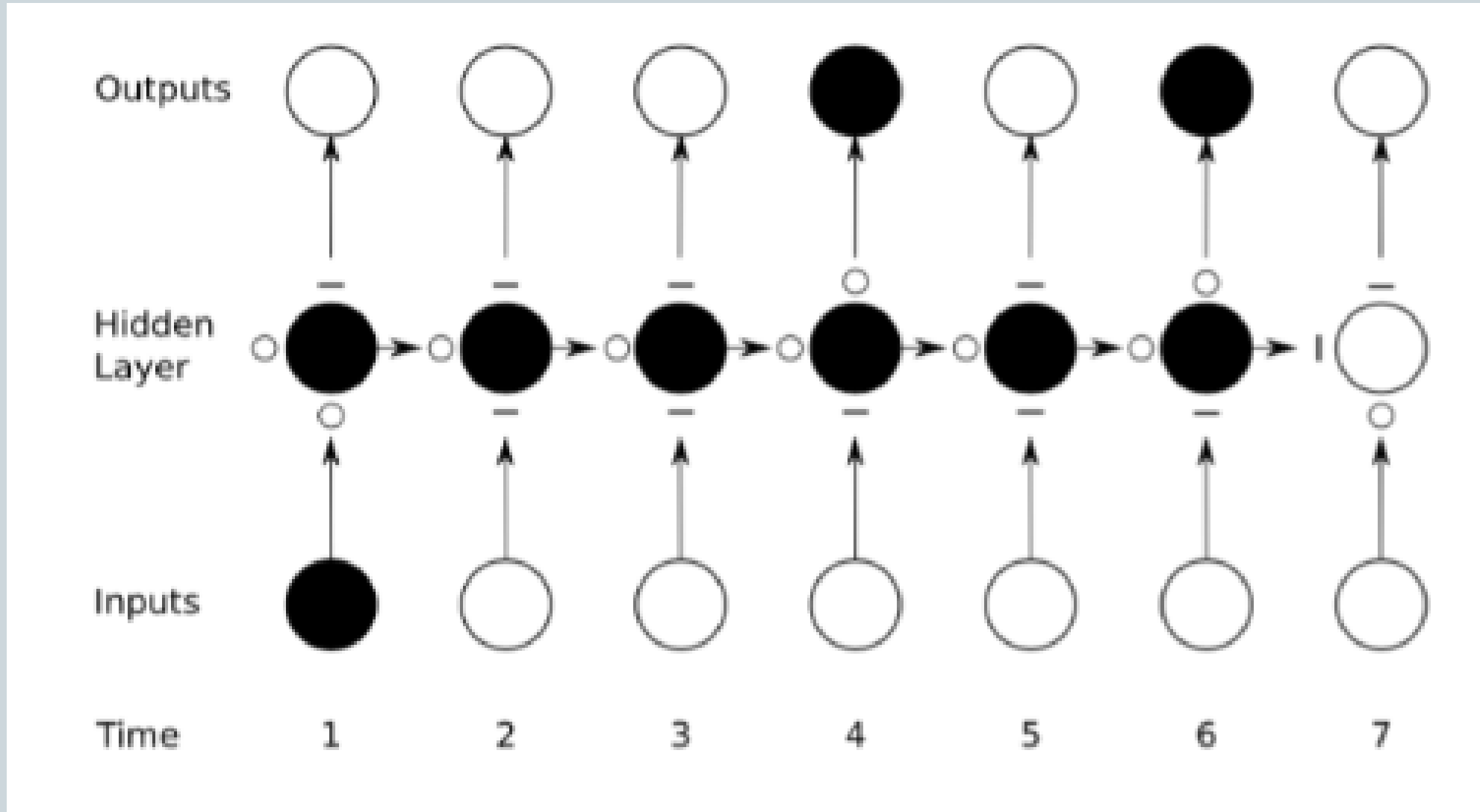
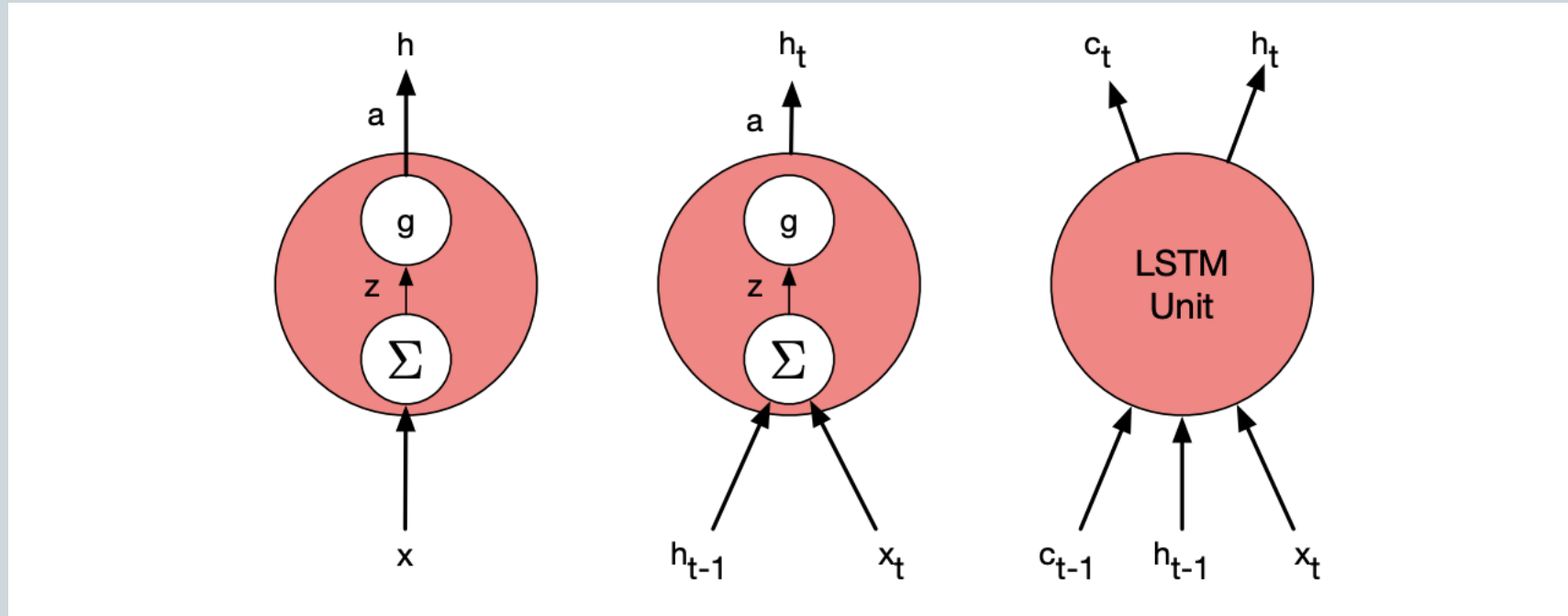


Image: Alex Graves, Supervised sequence labelling. Springer. 2012.

# We can see these as different processing units



Simple  
feedforward  
unit

Recurrent unit

LSTM unit – as with  
the others, it is self-  
contained - modular

(Jurafsky and Martin, Fig. 9.14)

# Thank you

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