```
EN2550 Excercise 06
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Index No.: 190018V

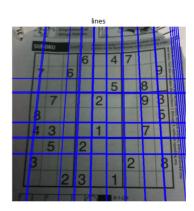
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Github : https://github.com/KCSAbeywickrama/EN2550-Excercises

```
In [ ]:
        # imports
        import numpy as np
        import matplotlib.pyplot as plt
        import cv2 as cv
        from mpl_toolkits.mplot3d import Axes3D
        from matplotlib import cm
In [ ]: # q1
        im=cv.imread('sudoku.png',cv.IMREAD_COLOR)
        assert im is not None
        gray=cv.cvtColor(im,cv.COLOR_BGR2GRAY)
        edges=cv.Canny(gray,50,150,apertureSize=3)
        lines=cv.HoughLines(edges,1,np.pi/180,200)
        for line in lines:
            rho,theta=line[0]
            a=np.cos(theta)
            b=np.sin(theta)
            x0,y0=a*rho,b*rho
            x1,y1=int(x0 + 1000*(-b)), int(y0 + 1000*(a))
            x2,y2=int(x0 - 1600*(-b)), int(y0 - 1000*(a))
            cv.line(im, (x1, y1), (x2, y2), (8,0,255), 2)
        fig, ax = plt.subplots(1,3, figsize = (20,8))
        ax[0].imshow(gray,cmap='gray')
        ax[0].set_title('gray')
        ax[0].axis("off")
        ax[1].imshow(edges,cmap='gray')
        ax[1].axis('off')
        ax[1].set_title("edges")
        ax[2].axis('off')
        ax[2].imshow(im)
        ax[2].set_title('lines')
        plt.show()
```





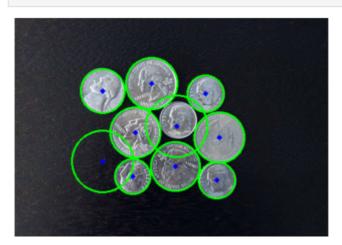


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In []: # q2

im = cv.imread(r'coins.jpg', cv.IMREAD_COLOR)
assert im is not None
gray = cv.cvtColor(im, cv.COLOR_BGR2GRAY)

circles = cv.HoughCircles(gray, cv.HOUGH_GRADIENT , 1, 50, param1=150, param2=20, rcircles = np.uint16(np.around(circles))
for i in circles[0,:]:
    # draw the outer circle
    cv.circle(im, (i[0], i[1]), i[2], (0,255,0), 2)
    # draw the center of Nge circle
    cv.circle(im, (i[0],i[1]),2, (0,0,255),3)

fig, ax = plt.subplots()
ax.imshow(im)
ax.axis('off')
plt.show()
```

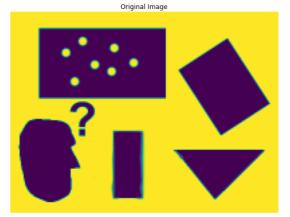


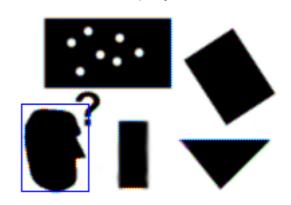
```
im=cv.imread(r'pic1.png',cv.IMREAD_REDUCED_GRAYSCALE_2)
assert im is not None
templ=cv.imread(r'templ.png',cv.IMREAD_REDUCED_GRAYSCALE_2)
assert templ is not None

im_edges = cv.Canny(im, 50, 250)
templ_edges = cv.Canny(templ, 50, 250)
alg = cv.createGeneralizedHoughGuil()
alg.setTemplate(templ_edges)
alg.setAngleThresh(100000)
alg.setScaleThresh(40000)
alg.setPosThresh(1000)
alg.setAngleStep(1)
alg.setScaleStep(0.1)
```

```
alg.setMinScale(0.9)
alg.setMaxScale(1.1)
positions, votes = alg.detect(im_edges)
out = cv.cvtColor(im, cv.COLOR BAYER BG2BGR)
for x, y, scale, orientation in positions[0]:
 halfHeight = templ.shape[0] / 2. * scale
 halfWidth = templ.shape[1]/ 2. * scale
 p1 = (int (x - halfWidth), int (y - halfHeight))
 p2 = (int (x + halfWidth), int (y + halfHeight))
 print("x = {}), y = {}), scale = {}), orientation = {}), p1 = {}), p2 = {}".format(x, y)
 cv.rectangle(out, p1, p2, (0,0,255))
fig, ax = plt.subplots(1,2, figsize = (20,8))
ax[0].imshow(im)
ax[0].set_title('Original Image')
ax[0].axis("off")
ax[1].imshow(out)
ax[1].axis('off')
ax[1].set_title("Output Image")
plt.show()
```

x = 29.0, y = 109.0, scale = 1.0, orientation = 0.0, p1 = (4, 76), p2 = (54, 141)





```
In [ ]: # q4
                                        a, b, c, d = [0, 0, 1], [0, 1, 1], [1, 1, 1], [1, 0, 1]
                                        X = np.array([a, b, c, d]).T
                                        theta = np.pi*30/180
                                        s = 2
                                        tx, ty = 0.5, 0.2
                                        \# H = np.array([[s*np.cos(theta), -s*np.sin(theta), tx], [s*np.sin(theta), s*np.cos(theta), s*np.cos(theta
                                        # Y = H @ X
                                        a11, a12, a21, a22 = 0.8, 1.2, 0.7, 1.5
                                        A = np.array([[a11, a12, tx], [a21, a22, ty], [0,0,1]])
                                        Y = A @ X
                                        x = np.append(X[0,:], X[0,0])
                                        y = np.append(X[1,:], X[1,0])
                                        fig, ax = plt.subplots(1,1)
                                        ax.plot(x, y, color='g')
                                        ax.set_aspect ('equal')
                                        x = np.append(Y[0,:], Y[0,0])
                                        y = np.append(Y[1,:], Y[1,0])
                                        ax.plot(x, y, color='r')
```

```
ax.set_aspect('equal')
plt.show()
```

```
2.5

2.0

1.5

1.0

0.5

0.0

0.0

0.5

1.0

1.5

2.0

2.5
```

```
In [ ]: # q5
        im1 = cv.imread(r'graf\img1.ppm', cv.IMREAD_ANYCOLOR)
        assert im1 is not None
        im4 = cv.imread(r'graf\img4.ppm', cv.IMREAD_ANYCOLOR)
        assert im4 is not None
        # H = np.array([[6.6378505e-01,6.8003334e-01-3.1230335e+01],
        # [-1.4495500e-01,9.7128304e-01,1.4877420e+02],
        # [4.2518504e-04,-1.3930359e-05,1.0000000e+00]])
        H = []
        with open(r'graf\H1to4p') as f:
          H = np.array([[float(h) for h in line.split()] for line in f])
        imlto4 =cv.warpPerspective(im4, np.linalg.inv(H), (2000,2000))
        fig, ax = plt.subplots(1,3, figsize = (20,8))
        ax[0].imshow(cv.cvtColor(im1,cv.COLOR_BGR2RGB))
        ax[0].axis('off')
        ax[0].set_title('Image 1')
        ax[1].imshow(cv.cvtColor(im4,cv.COLOR_BGR2RGB))
        ax[1].axis('off')
        ax[1].set_title('Image 2')
        ax[2].axis('off')
        ax[2].imshow(cv.cvtColor(imlto4,cv.COLOR_BGR2RGB))
        ax[2].set_title('Image 1 Warped')
        plt.show()
```





