

Expectation-Maximization Algorithm

Qinliang Su (苏勤亮)

Sun Yat-sen University

suqliang@mail.sysu.edu.cn

General Form of the Problem

Given the joint distribution

$$p(\boldsymbol{x},\boldsymbol{z};\boldsymbol{\theta}),$$

where x is the observed variable and z is the latent variable, we need to maximize the log likelihood w.r.t. x, that is,

$$\boldsymbol{\theta} = \arg \max_{\boldsymbol{\theta}} \log p(\boldsymbol{x}; \boldsymbol{\theta}),$$

where

$$p(\mathbf{x}; \boldsymbol{\theta}) = \sum_{\mathbf{z}} p(\mathbf{x}, \mathbf{z}; \boldsymbol{\theta})$$

What we have is the joint pdf $p(x, z; \theta)$, but what we need to optimize is the marginal pdf $p(x; \theta)$

Outline

- EM Algorithm
- Theoretical Guarantees
- Example: Training Gaussian Mixture Models
- EM Variants

EM Algorithm

Algorithm

E-step: Evaluating the expectation

$$Q(\boldsymbol{\theta}; \boldsymbol{\theta}^{(t)}) = \mathbb{E}_{p(\boldsymbol{z}|\boldsymbol{x}; \boldsymbol{\theta}^{(t)})}[\log p(\boldsymbol{x}, \boldsymbol{z}; \boldsymbol{\theta})]$$

M-step: Updating the parameter

$$\boldsymbol{\theta}^{(t+1)} = \arg \max_{\boldsymbol{\theta}} \mathcal{Q}(\boldsymbol{\theta}; \boldsymbol{\theta}^{(t)})$$

- Key integrant in EM
 - 1) The posteriori distribution $p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta}^{(t)})$
 - 2) The expectation of joint distribution $\log p(x, z; \theta)$ w.r.t. the posteriori
 - 3) Maximization

Outline

- EM Algorithm
- Theoretical Guarantees
- Example: Training Gaussian Mixture Models
- EM Variants

Re-representing the Log-likelihood

The log-likelihood can be reformulated as

$$\log p(\mathbf{x}; \boldsymbol{\theta}) = \sum_{\mathbf{z}} q(\mathbf{z}) \log p(\mathbf{x})$$

$$= \sum_{\mathbf{z}} q(\mathbf{z}) \log \frac{p(\mathbf{x}, \mathbf{z}; \boldsymbol{\theta}) q(\mathbf{z})}{p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta}) q(\mathbf{z})}$$

$$= \sum_{\mathbf{z}} q(\mathbf{z}) \log \frac{p(\mathbf{x}, \mathbf{z}; \boldsymbol{\theta})}{q(\mathbf{z})} + \sum_{\mathbf{z}} q(\mathbf{z}) \log \frac{q(\mathbf{z})}{p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta})}$$

$$= \sum_{\mathbf{z}} q(\mathbf{z}) \log \frac{p(\mathbf{x}, \mathbf{z}; \boldsymbol{\theta})}{q(\mathbf{z})} + \sum_{\mathbf{z}} q(\mathbf{z}) \log \frac{q(\mathbf{z})}{p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta})}$$

$$= \mathcal{L}(q, \boldsymbol{\theta}) + KL(q||p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta})), \quad \text{for } \forall \boldsymbol{\theta}, q(\mathbf{z})$$

Remark: The KL-divergence is used to *measure the distance* between two distributions q and p, which is defined as

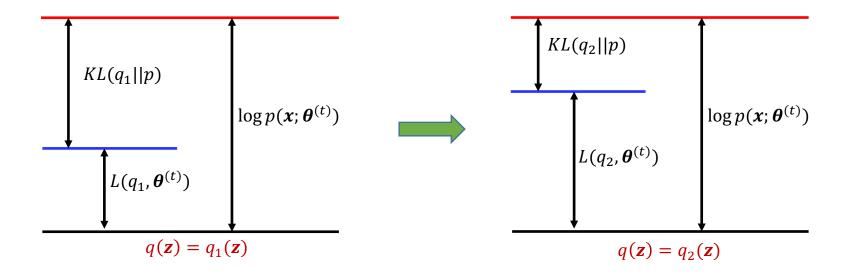
$$KL(q||p) \triangleq \int q(z) \log \frac{q(z)}{p(z)} dz \ge 0$$

• Thus, with the parameter at the t-th iteration denoted as $\boldsymbol{\theta}^{(t)}$, we have

$$\log p(\mathbf{x}; \boldsymbol{\theta}^{(t)}) = \mathcal{L}(q, \boldsymbol{\theta}^{(t)}) + KL(q||p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta}^{(t)}))$$

This equality holds for any distribution q(z)

Different q(z) will lead to different decomposition of $\log p(x; \theta^{(t)})$



Theoretical Justification for EM

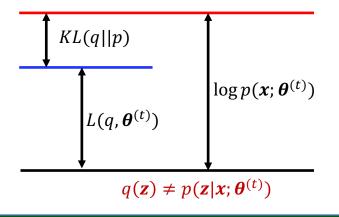
$$\log p(\mathbf{x}; \boldsymbol{\theta}^{(t)}) = \sum_{\mathbf{z}} q(\mathbf{z}) \log \frac{p(\mathbf{x}, \mathbf{z}; \boldsymbol{\theta}^{(t)})}{q(\mathbf{z})} + \sum_{\mathbf{z}} q(\mathbf{z}) \log \frac{q(\mathbf{z})}{p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta}^{(t)})}$$

• If we set $q(\mathbf{z}) = p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta}^{(t)})$, then we have

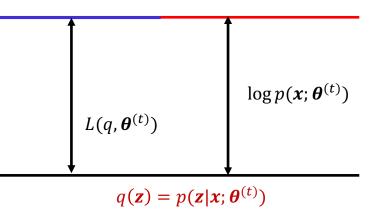
$$KL(q||p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)})) = 0$$

Thus, we have

$$\log p(\mathbf{x}; \boldsymbol{\theta}^{(t)}) = \mathcal{L}(p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta}^{(t)}), \boldsymbol{\theta}^{(t)})$$
$$= \sum_{\mathbf{z}} p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta}^{(t)}) \log \frac{p(\mathbf{x}, \mathbf{z}; \boldsymbol{\theta}^{(t)})}{p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta}^{(t)})}$$





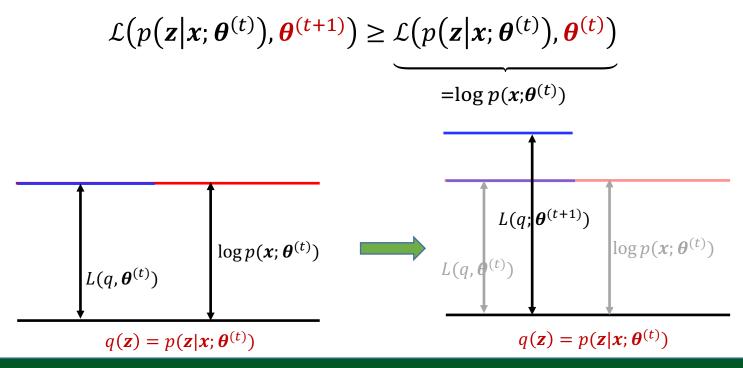


$$\log p(\mathbf{x}; \boldsymbol{\theta^{(t)}}) = \mathcal{L}(p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta^{(t)}}), \boldsymbol{\theta^{(t)}})$$
$$= \sum_{\mathbf{z}} p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta^{(t)}}) \log \frac{p(\mathbf{x}, \mathbf{z}; \boldsymbol{\theta^{(t)}})}{p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta^{(t)}})}$$

• If we update θ as

$$\boldsymbol{\theta}^{(t+1)} = \arg \max_{\boldsymbol{\theta}} \mathcal{L}(p(\boldsymbol{z}|\boldsymbol{x}; \boldsymbol{\theta}^{(t)}), \boldsymbol{\theta}),$$

then we must have the relation

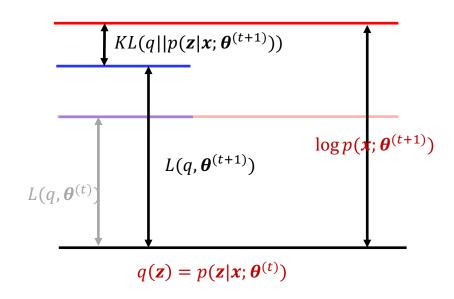


$$\log p(\mathbf{x}; \boldsymbol{\theta}^{(t+1)}) = \sum_{\mathbf{z}} q(\mathbf{z}) \log \frac{p(\mathbf{x}, \mathbf{z}; \boldsymbol{\theta}^{(t+1)})}{q(\mathbf{z})} + \sum_{\mathbf{z}} q(\mathbf{z}) \log \frac{q(\mathbf{z})}{p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta}^{(t+1)})}$$

• By setting $q(\mathbf{z}) = p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta}^{(t)})$, we obtain

$$\log p(\mathbf{x}; \boldsymbol{\theta}^{(t+1)}) = \underbrace{\mathcal{L}(p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta}^{(t)}), \boldsymbol{\theta}^{(t+1)})}_{\geq \log p(\mathbf{x}; \boldsymbol{\theta}^{(t)})} + \underbrace{KL(p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta}^{(t)})||p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta}^{(t+1)}))}_{\geq 0}$$

The KL-divergence is always non-negative



Thus, we can see that

$$\log p(\mathbf{x}; \boldsymbol{\theta}^{(t+1)}) \ge \log p(\mathbf{x}; \boldsymbol{\theta}^{(t)})$$

 $\max_{m{ heta}} \mathcal{L}ig(p(\mathbf{z}|\mathbf{x};m{ heta}^{(t)}),m{ heta}ig)$ can guarantee the increase of likelihood at each step

Equivalence between EM updating

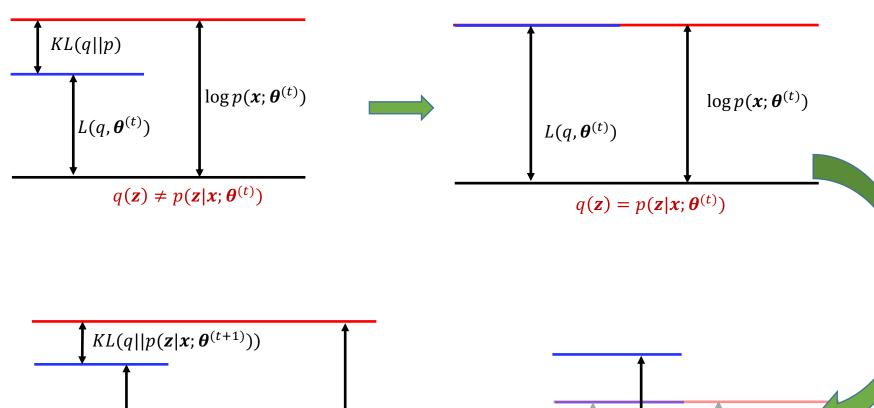
$$\arg \max_{\boldsymbol{\theta}} \mathcal{Q}(\boldsymbol{\theta}; \boldsymbol{\theta}^{(t)}) \text{ with } \mathcal{Q}(\boldsymbol{\theta}; \boldsymbol{\theta}^{(t)}) \triangleq \mathbb{E}_{p(\boldsymbol{z}|\boldsymbol{x}; \boldsymbol{\theta}^{(t)})}[\log p(\boldsymbol{x}, \boldsymbol{z}; \boldsymbol{\theta})]$$

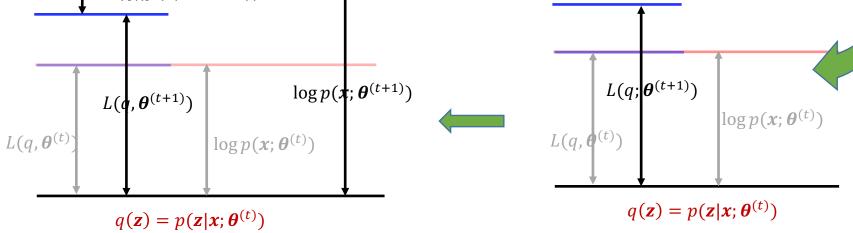
and the updating rule $\arg \max_{\boldsymbol{\theta}} \mathcal{L}(p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)}),\boldsymbol{\theta})$

$$\mathcal{L}(p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)}),\boldsymbol{\theta}) = \underbrace{\sum_{\mathbf{z}} p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)}) \log p(\mathbf{x},\mathbf{z};\boldsymbol{\theta})}_{\mathbb{E}_{p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)})}[\log p(\mathbf{x},\mathbf{z};\boldsymbol{\theta})]} - \underbrace{\sum_{\mathbf{z}} p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)}) \log p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)})}_{constant}$$

Therefore,
$$\arg \max_{\boldsymbol{\theta}} \mathcal{L}(p(\boldsymbol{z}|\boldsymbol{x};\boldsymbol{\theta}^{(t)}),\boldsymbol{\theta}) \iff \arg \max_{\boldsymbol{\theta}} \mathcal{Q}(\boldsymbol{\theta};\boldsymbol{\theta}^{(t)})$$

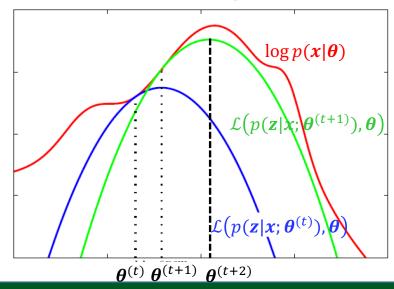
EM algorithm can guarantee the increase of likelihood at each step





A View in the Parameter Space

- 1) E-step (t): deriving the expression $\mathcal{L}(p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)}),\boldsymbol{\theta})$ given the model parameter $\boldsymbol{\theta}^{(t)}$
- 2) M-step (t): computing the optimal value $\theta^{(t+1)} = \arg \max_{\theta} \mathcal{L}(p(\mathbf{z}|\mathbf{x}; \theta^{(t)}), \theta)$
- 3) E-step (t+1): deriving the expression for $\mathcal{L}(p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t+1)}),\boldsymbol{\theta})$ given the model parameter $\boldsymbol{\theta}^{(t+1)}$
- 4) Repeating the above process until convergence



11/26/24

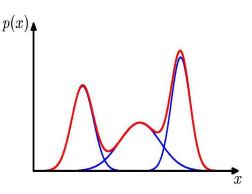
Outline

- EM Algorithm
- Theoretical Guarantees
- Example: Training Gaussian Mixture Models
- EM Variants

Gaussian Mixture Model Review

For a Gaussian mixture distribution, i.e.,

$$p(\mathbf{x}) = \sum_{k=1}^{K} \pi_k \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k),$$



it can be represented as the marginal distribution of the joint distribution

$$p(\mathbf{x}, \mathbf{z}) = p(\mathbf{x}|\mathbf{z})p(\mathbf{z})$$
$$= \prod_{k=1}^{K} [\pi_k \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)]^{z_k}$$

 $\mathbf{z} = [z_1, z_2, \cdots, z_K]$ follows the categorical distribution with parameter $\boldsymbol{\pi}$

EM Two Steps

It is a latent-variable model, thus we can use EM to optimize it

Remark: maximizing $\max_{\boldsymbol{\theta}} \mathcal{L}(p(\boldsymbol{z}|\boldsymbol{x};\boldsymbol{\theta}^{(t)}),\boldsymbol{\theta})$ is equivalent to $\max_{\boldsymbol{\theta}} \mathcal{Q}(\boldsymbol{\theta};\boldsymbol{\theta}^{(t)})$

- Reminder: Key integrant in EM
 - \triangleright E-step: Expectation w.r.t. the posteriori $p(z|x;\theta^{(t)})$

$$Q(\boldsymbol{\theta}; \boldsymbol{\theta}^{(t)}) = \frac{1}{N} \sum_{n=1}^{N} \mathbb{E}_{p(\boldsymbol{z}^{(n)}|\boldsymbol{x}^{(n)};\boldsymbol{\theta}^{(t)})} [\log p(\boldsymbol{x}^{(n)}, \boldsymbol{z}^{(n)}; \boldsymbol{\theta})]$$

M-step: Maximization

$$\boldsymbol{\theta}^{(t+1)} = \arg \max_{\boldsymbol{\theta}} \mathcal{Q}(\boldsymbol{\theta}; \boldsymbol{\theta}^{(t)})$$

EM: E-step

The posteriori distribution

$$p(\mathbf{z} = \mathbf{1}_k | \mathbf{x}; \boldsymbol{\theta}^{(t)}) = \frac{p(\mathbf{x}, \mathbf{z} = \mathbf{1}_k; \boldsymbol{\theta}^{(t)})}{\sum_{i=1}^K p(\mathbf{x}, \mathbf{z} = \mathbf{1}_i; \boldsymbol{\theta}^{(t)})}$$
$$= \frac{\mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_k^{(t)}, \boldsymbol{\Sigma}_k^{(t)}) \pi_k^{(t)}}{\sum_{i=1}^K \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_i^{(t)}, \boldsymbol{\Sigma}_i^{(t)}) \pi_i^{(t)}}$$

- 1_k denotes the one-hot vector with the k-th element being 1
- The log of the joint distribution $\log p(x, z; \theta)$

$$\log p(\mathbf{x}, \mathbf{z}; \boldsymbol{\theta}) = \sum_{k=1}^{K} z_k \cdot [\log \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k) + \log \pi_k]$$

Note that z can only be a one-hot vector

The expectation

$$\mathbb{E}_{p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)})}[\log p(\mathbf{x},\mathbf{z};\boldsymbol{\theta})]$$

$$= \sum_{k=1}^{K} \mathbb{E}_{p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)})}[z_k][\log \mathcal{N}(\mathbf{x}_n;\boldsymbol{\mu}_k,\boldsymbol{\Sigma}_k) + \log \pi_k]$$

> Due to $p(\mathbf{z} = \mathbf{1}_k | \mathbf{x}; \boldsymbol{\theta}^{(t)}) = \frac{\mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_k^{(t)}, \boldsymbol{\Sigma}_k^{(t)}) \pi_k^{(t)}}{\sum_{i=1}^K \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_i^{(t)}, \boldsymbol{\Sigma}_i^{(t)}) \pi_i^{(t)}}$, we have

$$\mathbb{E}_{p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)})}[z_k] = \frac{\mathcal{N}(\mathbf{x};\boldsymbol{\mu}_k^{(t)},\boldsymbol{\Sigma}_k^{(t)})\boldsymbol{\pi}_k^{(t)}}{\sum_{i=1}^K \mathcal{N}(\mathbf{x};\boldsymbol{\mu}_i^{(t)},\boldsymbol{\Sigma}_i^{(t)})\boldsymbol{\pi}_i^{(t)}} \triangleq \boldsymbol{\gamma}_k^{(t)}$$

Therefore, we have

$$Q(\boldsymbol{\theta}; \boldsymbol{\theta}^{(t)}) = \sum_{k=1}^{K} \gamma_k^{(t)} [\log \mathcal{N}(\boldsymbol{x}; \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k) + \log \pi_k]$$

• Substituting $\mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k) = \frac{1}{(2\mathrm{Pi})^{D/2} |\boldsymbol{\Sigma}_k|^{1/2}} \exp\left\{-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu}_k)^T \boldsymbol{\Sigma}_k^{-1} (\mathbf{x} - \boldsymbol{\mu}_k)\right\}$ into $Q(\cdot)$ gives

$$Q(\boldsymbol{\theta}; \boldsymbol{\theta}^{(t)}) = \sum_{k=1}^{K} \gamma_k^{(t)} \left[-\frac{1}{2} (\boldsymbol{x} - \boldsymbol{\mu}_k)^T \boldsymbol{\Sigma}_k^{-1} (\boldsymbol{x} - \boldsymbol{\mu}_k) - \frac{1}{2} \log |\boldsymbol{\Sigma}_k| + \log \pi_k \right] + C$$

- C is the constant
- So far, only one data example x is considered
- If data $x^{(n)}$ for $n = 1, 2, \dots N$ are considered, the $Q(\cdot)$ becomes

$$Q(\boldsymbol{\theta}; \boldsymbol{\theta}^{(t)}) = \frac{1}{N} \sum_{n=1}^{N} \sum_{k=1}^{K} \gamma_{nk}^{(t)} \left[-\frac{1}{2} (\boldsymbol{x}^{(n)} - \boldsymbol{\mu}_k)^T \boldsymbol{\Sigma}_k^{-1} (\boldsymbol{x}^{(n)} - \boldsymbol{\mu}_k) - \frac{1}{2} \log|\boldsymbol{\Sigma}_k| + \log \pi_k \right] + C$$

EM: M-step

$$Q(\boldsymbol{\theta}; \boldsymbol{\theta}^{(t)}) = \frac{1}{N} \sum_{n=1}^{N} \sum_{k=1}^{K} \gamma_{nk}^{(t)} \left[-\frac{1}{2} (\boldsymbol{x}^{(n)} - \boldsymbol{\mu}_k)^T \boldsymbol{\Sigma}_k^{-1} (\boldsymbol{x}^{(n)} - \boldsymbol{\mu}_k) - \frac{1}{2} \log |\boldsymbol{\Sigma}_k| + \log \pi_k \right] + C$$

• By taking derivatives w.r.t. μ_k , Σ_k and setting them to zero, we obtain the optimal θ as

$$\mu_k^{(t+1)} = \frac{1}{N_k} \sum_{n=1}^{N} \gamma_{nk}^{(t)} x^{(n)}$$

$$\Sigma_k^{(t+1)} = \frac{1}{N_k} \sum_{n=1}^{N} \gamma_{nk}^{(t)} \left(x^{(n)} - \mu_k^{(t+1)} \right) \left(x^{(n)} - \mu_k^{(t+1)} \right)^T$$

For π_k , we need to consider the optimization under constraint $\sum_{k=1}^{K} \pi_k = 1$, leading to the solution

$$\pi_k^{(t+1)} = \frac{N_k}{N}$$

where $N_k = \sum_{n=1}^N \gamma_{nk}^{(t)}$ is the effective number of examples assigned to the k-th class

Summary of EM Algorithm

• Given the current estimate $\{\mu_k, \Sigma_k, \pi_k\}_{k=1}^K$, update γ_{nk} as

$$\gamma_{nk} \leftarrow \frac{\mathcal{N}(\mathbf{x}^{(n)}; \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k) \pi_k}{\sum_{i=1}^K \mathcal{N}(\mathbf{x}^{(n)}; \boldsymbol{\mu}_i, \boldsymbol{\Sigma}_i) \pi_i}$$

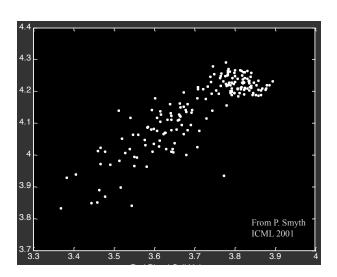
• Given the γ_{nk} , update μ_k , Σ_k and π_k as

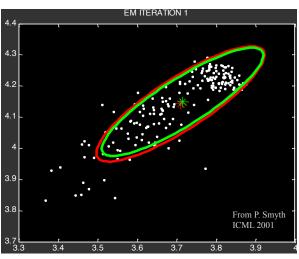
$$N_k \leftarrow \sum_{n=1}^N \gamma_{nk}$$

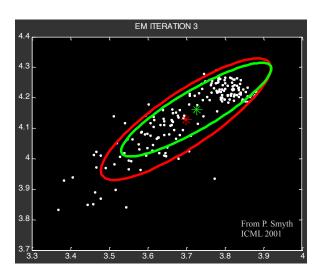
$$\boldsymbol{\mu}_k \leftarrow \frac{1}{N_k} \sum_{n=1}^N \gamma_{nk} \boldsymbol{x}^{(n)}$$

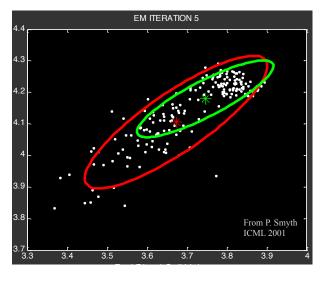
$$\boldsymbol{\Sigma}_k \leftarrow \frac{1}{N_k} \sum_{n=1}^N \gamma_{nk} (\boldsymbol{x}^{(n)} - \boldsymbol{\mu}_k) (\boldsymbol{x}^{(n)} - \boldsymbol{\mu}_k)^T$$

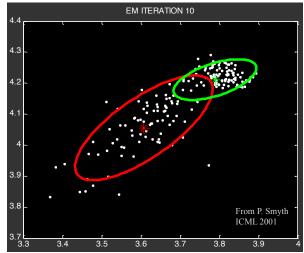
$$\pi_k \leftarrow \frac{N_k}{N}$$

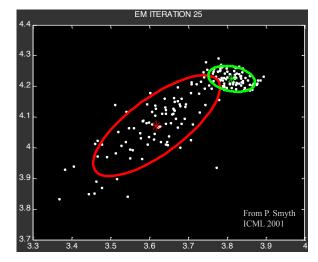












Relation to Soft K-Means

• When restricting Σ_k to the form $\Sigma_k = \sigma^2 I$, the EM updating rules for GMM are

$$\pi_k \leftarrow \frac{\sum_{n=1}^N \gamma_{nk}}{N}$$

$$\gamma_{nk} \leftarrow \frac{\pi_k e^{-\frac{1}{2\sigma^2} \|x^{(n)} - \mu_k\|^2}}{\sum_{i=1}^K \pi_i e^{-\frac{1}{2\sigma^2} \|x^{(n)} - \mu_i\|^2}}$$

$$\boldsymbol{\mu}_k \leftarrow \frac{\sum_{n=1}^N \gamma_{nk} \boldsymbol{x}^{(n)}}{\sum_{n=1}^N \gamma_{nk}} \quad = \quad = \quad$$

Updates in soft K-means

Setting
$$\pi_k$$
 and β as $\pi_k = \frac{1}{K}$, $\beta = \frac{1}{2\sigma^2}$

$$r_{nk} = \frac{e^{-\beta \|x^{(n)} - \mu_k\|^2}}{\sum_{i=1}^{K} e^{-\beta \|x^{(n)} - \mu_i\|^2}}$$

$$\boldsymbol{\mu}_k \leftarrow \frac{\sum_{n=1}^N r_{nk} \, \boldsymbol{x}^{(n)}}{\sum_{n=1}^N r_{nk}}$$

Outline

- EM Algorithm
- Theoretical Guarantees
- Example: Training Gaussian Mixture Models
- EM Variants

Review of the EM Algorithms

- To use EM algorithms, the key steps below are required
 - 1) Computing the posteriori distribution

$$p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)})$$

2) Evaluating the expectation of $\log p(x, z; \theta)$ w.r.t. the posteriori $p(z|x; \theta^{(t)})$, i.e.,

$$Q(\boldsymbol{\theta}; \boldsymbol{\theta}^{(t)}) = \mathbb{E}_{p(\boldsymbol{z}|\boldsymbol{x}; \boldsymbol{\theta}^{(t)})}[\log p(\boldsymbol{x}, \boldsymbol{z}; \boldsymbol{\theta})]$$

3) Maximizing

$$\boldsymbol{\theta}^{(t+1)} = \arg \max_{\boldsymbol{\theta}} \mathcal{Q}(\boldsymbol{\theta}; \boldsymbol{\theta}^{(t)})$$

However, not all of them are always achievable

Two Issues in EM Algorithm

Issue one

The maximization is not achievable

$$\boldsymbol{\theta}^{(t+1)} = \arg \max_{\boldsymbol{\theta}} \mathcal{Q}(\boldsymbol{\theta}; \boldsymbol{\theta}^{(t)})$$

- Issue two
 - 1) The posteriori $p(z|x; \theta^{(t)})$ cannot be derived analytically
 - 2) Even if $p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta}^{(t)})$ can be obtained, we still cannot derive the close-form expression for the expectation

$$\mathbb{E}_{p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)})}[\log p(\mathbf{x},\mathbf{z};\boldsymbol{\theta})]$$

Generalized EM

It is quite often in training LVMs that the optimization $\max_{m{\theta}} \mathcal{Q}(m{\theta}; m{\theta}^{(t)})$ cannot be solved

How to address this issue?

- Maximizing $Q(\theta; \theta^{(t)})$ is not necessary. Increasing $Q(\theta; \theta^{(t)})$ is sufficient to guarantee the EM algorithm to work
- That is, if we adopt SGD to update the parameter as

$$\boldsymbol{\theta}^{(t+1)} = \boldsymbol{\theta}^{(t)} + \gamma \cdot \frac{\partial \mathcal{Q}(\boldsymbol{\theta}; \boldsymbol{\theta}^{(t)})}{\partial \boldsymbol{\theta}} \bigg|_{\boldsymbol{\theta} = \boldsymbol{\theta}^{(t)}}$$

we can also guarantee the monotonic increase of log-likelihood

$$\log p(\mathbf{x}; \boldsymbol{\theta}^{(t+1)}) \ge \log p(\mathbf{x}; \boldsymbol{\theta}^{(t)})$$

Sketch of proof

First, after the SGD update, it can be easily seen that

$$Q(\boldsymbol{\theta}^{(t+1)}; \boldsymbol{\theta}^{(t)}) \ge Q(\boldsymbol{\theta}^{(t)}; \boldsymbol{\theta}^{(t)})$$

From $\mathcal{L}(p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)}),\boldsymbol{\theta}) = \int p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)}) \log \frac{p(\mathbf{x},\mathbf{z};\boldsymbol{\theta})}{p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)})} d\mathbf{z} = \mathcal{Q}(\boldsymbol{\theta};\boldsymbol{\theta}^{(t)}) - \int p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)}) \log p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)}) d\mathbf{z}$, we further have

$$\mathcal{L}(p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)});\boldsymbol{\theta}^{(t+1)}) \geq \mathcal{L}(p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)});\boldsymbol{\theta}^{(t)})$$

$$= \log p(\mathbf{x};\boldsymbol{\theta}^{(t)})$$

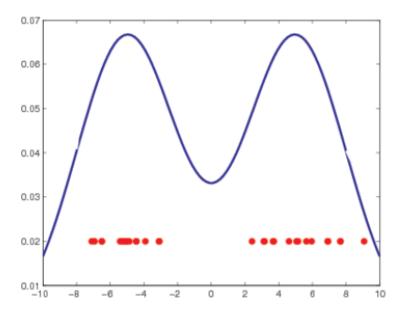
Due to

$$\log p(\mathbf{x}; \boldsymbol{\theta}^{(t+1)}) = \underbrace{\mathcal{L}(p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta}^{(t)}), \boldsymbol{\theta}^{(t+1)})}_{\geq \log p(\mathbf{x}|\boldsymbol{\theta}^{(t)})} + \underbrace{KL(p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta}^{(t)})||p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta}^{(t+1)}))}_{\geq 0}$$

$$\Longrightarrow \log p(\mathbf{x}; \boldsymbol{\theta}^{(t+1)}) \ge \log p(\mathbf{x}; \boldsymbol{\theta}^{(t)})$$

MCMC EM

 For any probability distributions, we can always draw samples from it, e.g., using Markov chain Monte Carlo (MCMC) methods



• Although the exact expression of the posteriori $p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta}^{(t)})$ is not known, we can use samples drawn from it to approximate it

• Thus, we can draw lots of samples z_s for $s = 1, \dots, S$ from the posteriori distribution $p(z|x; \theta^{(t)})$ such that

$$\mathbf{z}_{s} \sim p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)})$$

• Then, the expectation $\mathbb{E}_{p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)})}[\log p(\mathbf{x},\mathbf{z};\boldsymbol{\theta})]$ can be approximated as

$$Q(\boldsymbol{\theta}; \boldsymbol{\theta}^{(t)}) \approx \frac{1}{S} \cdot \sum_{s=1}^{S} \log p(\boldsymbol{x}, \boldsymbol{z}_{s}; \boldsymbol{\theta})$$

• We can optimize the approximate $\mathcal{Q}(oldsymbol{ heta};oldsymbol{ heta}^{(t)})$ with SGD algorithm

The two sub-problems in the Issue Two are both solved. Thus, latent-variable models can always be trained with MCMC EM

VB-EM

- Drawing samples from a distribution is computationally expensive
- An alternative approach is to use a simple distribution $q(z; \phi)$ to approximate the exact posterior distribution $p(z|x; \theta^{(t)})$

How to get the approximate simple distribution $q(\mathbf{z}; \boldsymbol{\phi})$?

- Idea
 - 1) Assuming a simple form for $q(z; \phi)$, e.g.,

$$q(\mathbf{z}; \boldsymbol{\phi}) = \prod \mathcal{N}(z_i; \mu_i, \sigma_i^2)$$

2) Finding the best ϕ that minimizes the KL-divergence

$$KL(q(\mathbf{z}; \boldsymbol{\phi}) || p(\mathbf{z}|\mathbf{x}; \boldsymbol{\theta}^{(t)}))$$

- Steps to update the model parameter θ
 - 1) Finding the best approximate $q(z; \phi)$ such that

$$\phi^{(t)} = \arg\min_{\phi} KL(q(\mathbf{z}; \phi) || p(\mathbf{z}|\mathbf{x}; \theta^{(t)}))$$

2) Using $q(\mathbf{z}; \boldsymbol{\phi}^{(t)})$ to compute expectation $\mathbb{E}_{p(\mathbf{z}|\mathbf{x};\boldsymbol{\theta}^{(t)})}[\log p(\mathbf{x},\mathbf{z};\boldsymbol{\theta})]$ approximately as

$$\tilde{Q}(\boldsymbol{\theta}; \boldsymbol{\phi}^{(t)}) = \mathbb{E}_{q(\mathbf{z}; \boldsymbol{\phi}^{(t)})}[\log p(\mathbf{x}, \mathbf{z}; \boldsymbol{\theta})]$$

3) Obtaining the new value $\theta^{(t+1)}$ as

$$\boldsymbol{\theta}^{(t+1)} = \arg \max_{\boldsymbol{\theta}} \tilde{\mathcal{Q}}(\boldsymbol{\theta}; \, \boldsymbol{\phi}^{(t)})$$

The two optimization problems can be equivalently written as

$$\min_{\boldsymbol{\phi}} KL(q(\boldsymbol{z}; \boldsymbol{\phi}) \| p(\boldsymbol{z} | \boldsymbol{x}; \boldsymbol{\theta}^{(t)})) \iff \max_{\boldsymbol{\phi}} \int q(\boldsymbol{z}; \boldsymbol{\phi}) \log \frac{p(\boldsymbol{z} | \boldsymbol{x}; \boldsymbol{\theta}^{(t)})}{q(\boldsymbol{z}; \boldsymbol{\phi})} d\boldsymbol{z}$$

$$\iff \max_{\boldsymbol{\phi}} \int q(\boldsymbol{z}; \boldsymbol{\phi}) \log \frac{p(\boldsymbol{x}, \boldsymbol{z}; \boldsymbol{\theta}^{(t)})}{q(\boldsymbol{z}; \boldsymbol{\phi})} d\boldsymbol{z}$$

$$\max_{\boldsymbol{\theta}} \mathbb{E}_{q(\boldsymbol{z}; \boldsymbol{\phi}^{(t)})} [\log p(\boldsymbol{x}, \boldsymbol{z}; \boldsymbol{\theta})] \iff \max_{\boldsymbol{\theta}} \int q(\boldsymbol{z}; \boldsymbol{\phi}^{(t)}) \log \frac{p(\boldsymbol{x}, \boldsymbol{z}; \boldsymbol{\theta})}{q(\boldsymbol{z}; \boldsymbol{\phi}^{(t)})} d\boldsymbol{z}$$

 The algorithm to optimize # and # can be understood as solving the following optimization problem in an alternative way

$$\max_{\boldsymbol{\phi},\boldsymbol{\theta}} \mathcal{L}(\boldsymbol{x};\boldsymbol{\theta},\boldsymbol{\phi})$$

with

$$\mathcal{L}(\boldsymbol{x};\boldsymbol{\theta},\boldsymbol{\phi}) \triangleq \int q(\boldsymbol{z};\boldsymbol{\phi}) \log \frac{p(\boldsymbol{x},\boldsymbol{z};\boldsymbol{\theta})}{q(\boldsymbol{z};\boldsymbol{\phi})} d\boldsymbol{z}$$

• Instead of updating θ , ϕ alternatively, we can also update them simultaneously with the SGD algorithm, that is,

$$\left. \boldsymbol{\theta}^{(t+1)} = \boldsymbol{\theta}^{(t)} + \gamma \cdot \frac{\partial \mathcal{L}(\boldsymbol{x}; \boldsymbol{\theta}, \boldsymbol{\phi})}{\partial \boldsymbol{\theta}} \right|_{\boldsymbol{\theta} = \boldsymbol{\theta}^{(t)}}$$

$$\phi^{(t+1)} = \phi^{(t)} + \gamma \cdot \frac{\partial \mathcal{L}(\mathbf{x}; \boldsymbol{\theta}, \boldsymbol{\phi})}{\partial \phi} \bigg|_{\boldsymbol{\phi} = \boldsymbol{\phi}^{(t)}}$$

The method is dubbed *variational Bayesian EM* (VB-EM)

• In general, we optimize $\mathcal{L}(x; \theta, \phi)$ w.r.t. the two parameters θ, ϕ simultaneously

• Actually, it can be proved that $\mathcal{L}(x; \theta, \phi)$ is a *lower bound* of the log-likelihood $\ln p(x; \theta)$ for any θ and ϕ , that is,

$$\ln p(\mathbf{x}; \boldsymbol{\theta}) \ge \mathcal{L}(\mathbf{x}; \boldsymbol{\theta}, \boldsymbol{\phi})$$

(Proof can be found in the next slide)

When the log-likelihood $\ln p(x; \theta)$ cannot be directly maximized, we can seek to optimize its lower bound

$$\mathcal{L}(\mathbf{x}; \boldsymbol{\theta}, \boldsymbol{\phi}) \triangleq \int q(\mathbf{z}; \boldsymbol{\phi}) \log \frac{p(\mathbf{x}, \mathbf{z}; \boldsymbol{\theta})}{q(\mathbf{z}; \boldsymbol{\phi})} d\mathbf{z}$$

where $q(\mathbf{z}; \boldsymbol{\phi})$ can be set to be any distribution form, e.g.,

$$q(\mathbf{z}; \boldsymbol{\phi}) = \prod \mathcal{N}(z_i; \mu_i, \sigma_i^2)$$

Proof of $\ln p(x; \theta) \ge \mathcal{L}(x; \theta, \phi)$

$$\ln p_{\theta}(\mathbf{x}) = \int_{\mathbf{z}} q_{\phi}(\mathbf{z}) \ln p_{\theta}(\mathbf{x}) d\mathbf{z} = \int_{\mathbf{z}} q_{\phi}(\mathbf{z}) \ln \frac{p_{\theta}(\mathbf{x}, \mathbf{z}) q_{\phi}(\mathbf{z})}{q_{\phi}(\mathbf{z}) p_{\theta}(\mathbf{z}|\mathbf{x})} d\mathbf{z}$$

$$= \int_{\mathbf{z}} q_{\phi}(\mathbf{z}) \ln \frac{p_{\theta}(\mathbf{x}, \mathbf{z})}{q_{\phi}(\mathbf{z})} d\mathbf{z} + \int_{\mathbf{z}} q_{\phi}(\mathbf{z}) \ln \frac{q_{\phi}(\mathbf{z})}{p_{\theta}(\mathbf{z}|\mathbf{x})} d\mathbf{z}$$

$$= \int_{\mathbf{z}} q_{\phi}(\mathbf{z}) \ln \frac{p_{\theta}(\mathbf{x}, \mathbf{z})}{q_{\phi}(\mathbf{z})} d\mathbf{z} + KL(q_{\phi}(\mathbf{z})||p_{\theta}(\mathbf{z}|\mathbf{x}))$$

$$\geq \int_{\mathbf{z}} q_{\phi}(\mathbf{z}) \ln \frac{p_{\theta}(\mathbf{x}, \mathbf{z})}{q_{\phi}(\mathbf{z})} d\mathbf{z}$$

$$\triangleq \mathcal{L}(\mathbf{x}; \boldsymbol{\theta}, \boldsymbol{\phi})$$