

DA_exercises

October 11, 2017

Linear Model

$$z_n = 0.5z_{n-1} + \xi_{n-1} \quad (1)$$

with $\xi_{n-1} \sim N(0, B)$ and $z_0 \sim N(0, 0.4)$

Observations

$$y_n = z_n + \eta_n \quad (2)$$

$\eta_{n-1} \sim N(0, R)$

Kalman filter

Forecast formulas:

$$\hat{m}_{n+1} = A\hat{m}_n \quad (3)$$

$$\hat{C}_{n+1} = A\hat{C}_nA^\top + B \quad (4)$$

Analysis formulas

$$m_{n+1} = \hat{m}_{n+1} - K_{n+1}(H\hat{m}_{n+1} - y_{n+1}) \quad (5)$$

$$C_{n+1} = \hat{C}_{n+1} - K_{n+1}H\hat{C}_{n+1} \quad (6)$$

with Kalman gain

$$K_{n+1} = \hat{C}_{n+1}H^\top (R + H\hat{C}_{n+1}H^\top)^{-1} \quad (7)$$

Exercise: Please implement the Kalman filter for the example above
Lorenz equations

$$\dot{x} = \sigma(y - x) \quad (8)$$

$$\dot{y} = x(\rho - z) - y \quad (9)$$

$$\dot{z} = xy - \beta z \quad (10)$$

Ensemble Kalman Filter

$$z_{n+1}^i = \hat{z}_{n+1}^i - K_{n+1}(H\hat{z}_{n+1}^i - \tilde{y}_{n+1}^i) \quad (11)$$

$$m_n \approx \frac{1}{M} \sum_{i=1}^M z_n^i \quad (12)$$

$$C_n \approx \frac{1}{M} \sum_{i=1}^M (z_n^i - m_n)(z_n^i - m_n)^\top \quad (13)$$

Exercise: Please implement the Ensemble Kalman filter for the Lorenz equation

Particle filter

Exercise: Please implement the Particle filter with resampling for the Lorenz equation