

CS 311: Algorithm Design and Analysis

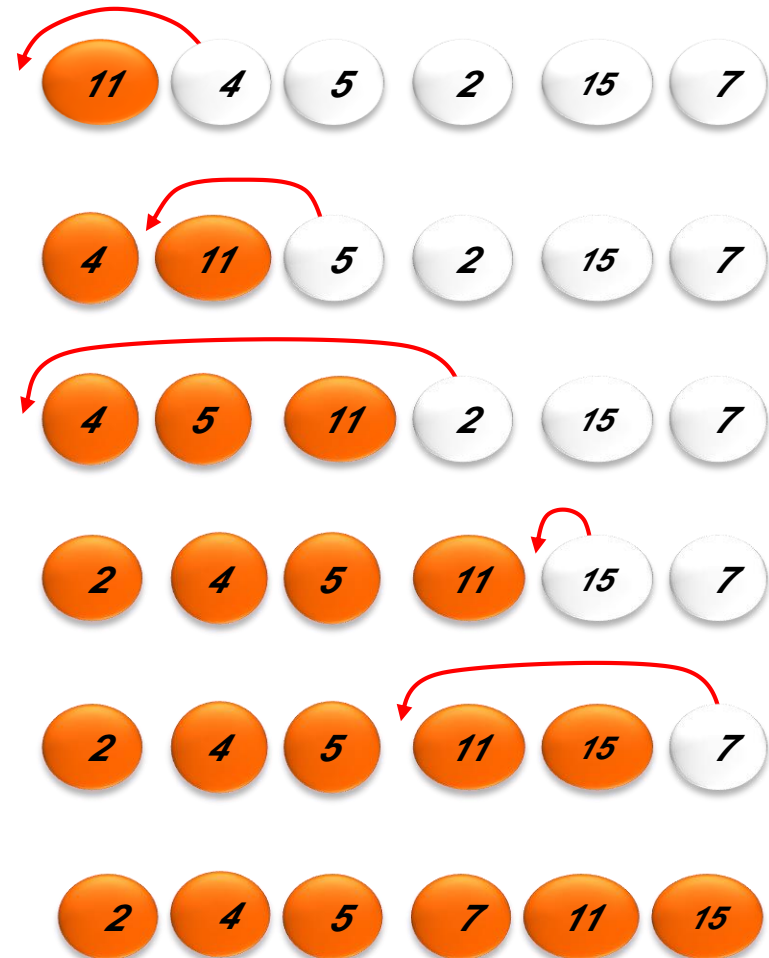
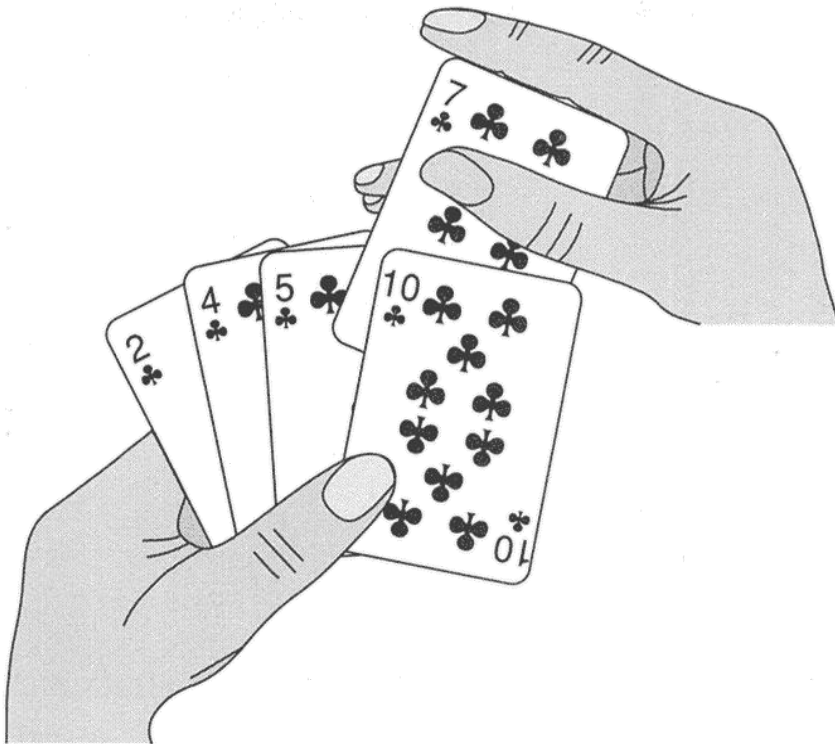
Lecture 3

Last Lecture we have

- Analysis of Algorithms
- Asymptotic notation
- Insertion sort

Insertion Sort

an incremental algorithm



An Example: Insertion Sort

```
InsertionSort(A, n) {  
    for i = 2 to n {  
        key = A[i]  
        j = i - 1;  
        while (j > 0) and (A[j] > key) {  
            A[j+1] = A[j]  
            j = j - 1  
        }  
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}
```

An Example: Insertion Sort

30	10	40	20
1	2	3	4

$i = \emptyset$	$j = \emptyset$	$key = \emptyset$
$A[j] = \emptyset$	$A[j+1] = \emptyset$	




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InsertionSort(A, n) {  
    for i = 2 to n {  
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An Example: Insertion Sort

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$i = 2$	$j = 1$	$\text{key} = 10$
$A[j] = 30$	$A[j+1] = 10$	

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1	2	3	4

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1	2	3	4

$i = 2$	$j = 0$	$\text{key} = 10$
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An Example: Insertion Sort

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1	2	3	4

$i = 3$	$j = 0$	$\text{key} = 10$
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$i = 4$	$j = 3$	$key = 20$
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An Example: Insertion Sort

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1	2	3	4

$i = 4$	$j = 1$	$\text{key} = 20$
$A[j] = 10$	$A[j+1] = 30$	

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```

Done!

Insertion Sort: Time Complexity

$T(n)$

$$= \Theta\left(\sum_{i=2}^n (1 + t_i + 1)\right)$$

$$= \Theta\left(n + \sum_{i=2}^n t_i\right)$$

$$= \Theta\left(n + \sum_{i=2}^n i\right)$$

$$= \Theta(n + n^2)$$

$$= \Theta(n^2).$$

Algorithm *InsertionSort*($A[1..n]$)

for $i \leftarrow 2 .. n$ **do**

LI: $A[1..i-1]$ is sorted, $A[i..n]$ is untouched.

§ insert $A[i]$ into sorted prefix $A[1..i-1]$ by right-cyclic-shift:

2. $key \leftarrow A[i]$

3. $j \leftarrow i-1$

4. **while** $j > 0$ and $A[j] > key$ **do**

5. $A[j+1] \leftarrow A[j]$

6. $j \leftarrow j-1$

7. **end-while**

8. $A[j+1] \leftarrow key$

9. **end-for**

end

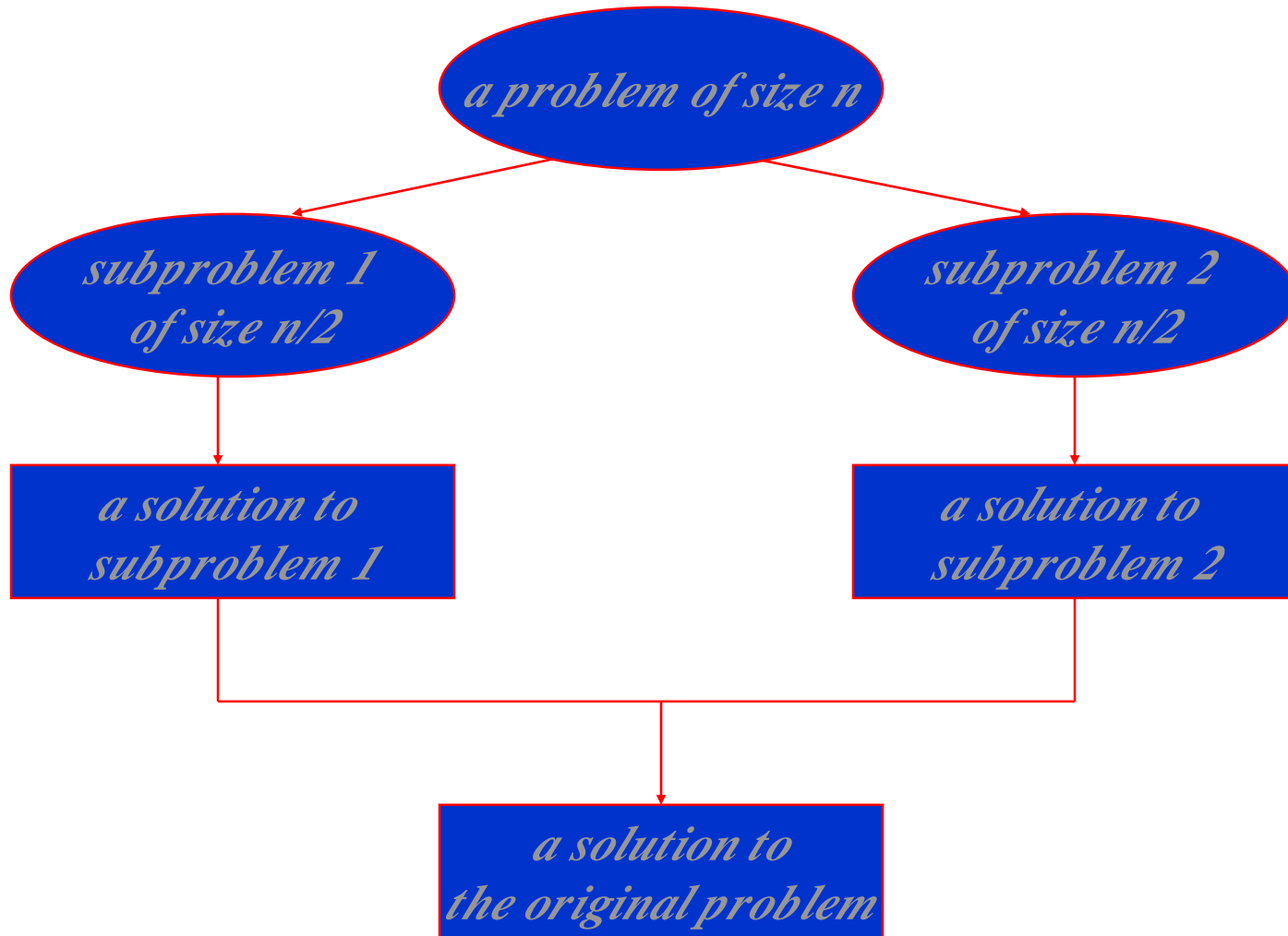
Worst-case: $t_i = i$ iterations (reverse sorted).

$$\sum_{i=2}^n i = \frac{n(n+1)}{2} - 1 = \Theta(n^2).$$

The divide-and-conquer Design Paradigm

- *Divide the problem into subproblems.*
- *Conquer the subproblems by solving them recursively.*
- *Combine subproblem solutions.*
- *Many algorithms use this paradigm.*

Divide-and-conquer Technique



Divide and Conquer

Examples

- *Sorting: mergesort and quicksort*
- *Matrix multiplication-Strassen's algorithm*
- *Binary search*
- *Powering a Number*
- *Closest pair problem*
- *....etc.*

Binary search

- Find an element in a sorted array:
 - **Divide**: Check middle element.
 - **Conquer**: Recursively search 1 sub array.
 - **Combine**: Trivial.
- Example: Find 9

3 5 7 8 9 12 15

Binary search

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- Find an element in a sorted array:
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- Example: Find 9

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5

7

8

9

12

15

Binary search

- Find an element in a sorted array:
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- Example: Find 9

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Binary search

- Find an element in a sorted array:
 - **Divide**: Check middle element.
 - **Conquer**: Recursively search 1 sub array.
 - **Combine**: Trivial.
- Example: Find 9

3 5 7 8  12 15

Binary Search

```
int binarySearch(int a[], int size, int x) {
    int low =0;
    int high = size -1;
    int mid;           // mid will be the index of
                       // target when it's found.
    while (low <= high) {
        mid = (low + high)/2;
        if (a[mid] < x)
            low = mid + 1;
        else if (a[mid] > x)
            high = mid - 1;
        else
            return mid;
    }
    return -1;
}
```

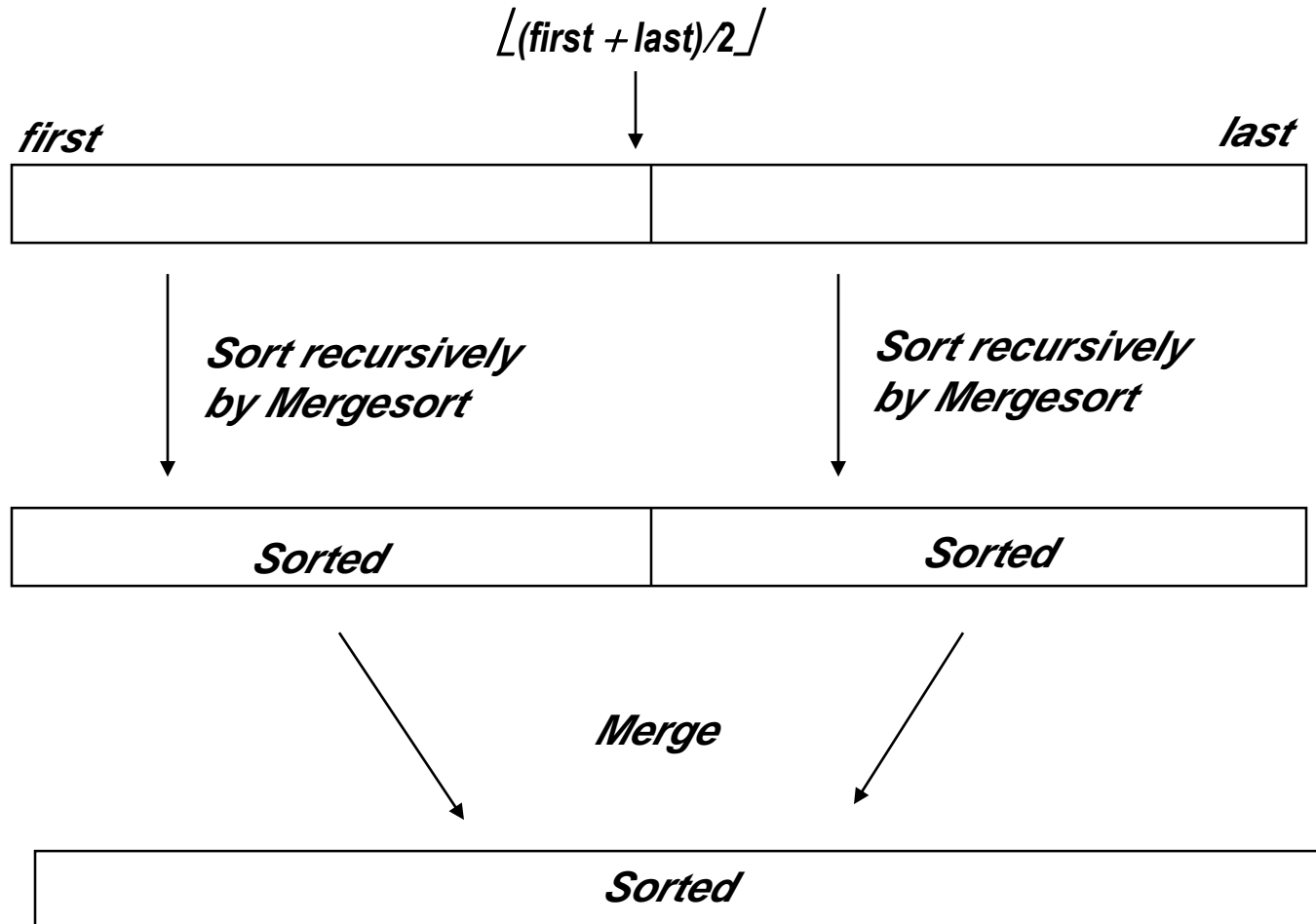
Mergesort

Algorithm:

- Split array $A[1..n]$ in two and make copies of each half in arrays $B[1 \dots \lfloor \frac{n}{2} \rfloor]$ and $C[1 \dots \lfloor \frac{n}{2} \rfloor]$
 - ⌚ *Sort arrays B and C*
 - ⌚ *Merge sorted arrays B and C into array A*

Using Divide and Conquer: Mergesort

- Mergesort Strategy



Mergesort

Algorithm:

- *Split array $A[1..n]$ in two and make copies of each half in arrays $B[1 \dots \lfloor \frac{n}{2} \rfloor]$ and $C[1 \dots \lfloor \frac{n}{2} \rfloor]$*
- *Sort arrays B and C*
- *Merge sorted arrays B and C into array A as follows:*
 - *Repeat the following until no elements remain in one of the arrays:*
 - *compare the first elements in the remaining unprocessed portions of the arrays*
 - *copy the smaller of the two into A , while incrementing the index indicating the unprocessed portion of that array*
 - *Once all elements in one of the arrays are processed, copy the remaining unprocessed elements from the other array into A .*

Algorithm: Mergesort

Input: Array E and indices first and last, such that the elements $E[i]$ are defined for $\text{first} \leq i \leq \text{last}$.

Output: $E[\text{first}], \dots, E[\text{last}]$ is a sorted rearrangement of the same elements

```
void mergeSort(Element[] E, int first, int last)
    if (first < last)
        int mid =  $\lfloor (\text{first} + \text{last}) / 2 \rfloor$ ;
        mergeSort(E, first, mid);
        mergeSort(E, mid+1, last);
        merge(E, first, mid, last);
    return;
```

Merge Sort

MERGE-SORT $A[1 \dots n]$

1. If $n = 1$, done.
2. Recursively sort $A[1 \dots \lceil n/2 \rceil]$ and $A[\lceil n/2 \rceil + 1 \dots n]$.
3. “*Merge*” the 2 sorted lists.

- How to express the cost of merge sort?

$$T(n) = 2T(n/2) + \Theta(n) \text{ for } n > 1, T(1) = 0 \Rightarrow \Theta(n \lg n)$$

Merge Sort

1. Divide: Trivial.

2. Conquer: Recursively sort subarrays.

3. Combine: Linear-time merge.

$$T(n) = 2T(n/2) + \Theta(n)$$

subproblems

*subproblem
size*

*cost of dividing
and combining*

Efficiency of Mergesort

⌚ *All cases have same efficiency: $\Theta(n \log n)$*

- Number of comparisons is close to theoretical minimum for comparison-based sorting:
 - $\lceil \lg n! \rceil \approx \lceil n \lg n - 1.44 n \rceil$

⌚ *Space requirement: $\Theta(n)$ (NOT in-place)*

⌚ *Can be implemented without recursion (bottom-up)*

Master theorem

- If $T(n) = aT\left(\left\lceil\frac{n}{b}\right\rceil\right) + O(n^d)$ for some constants $a > 0$, $b > 1$, and $d \geq 0$, then

$$T(n) = \begin{cases} O(n^d) & \text{if } d > \log_b a \\ O(n^d \log n) & \text{if } d = \log_b a \\ O(n^{\log_b a}) & \text{if } d < \log_b a. \end{cases}$$

- | | |
|--------------|---------------------------------|
| 1. $a < b^d$ | $T(n) \in \Theta(n^d)$ |
| 2. $a = b^d$ | $T(n) \in \Theta(n^d \lg n)$ |
| 3. $a > b^d$ | $T(n) \in \Theta(n^{\log_b a})$ |

The End

