pdf_draft

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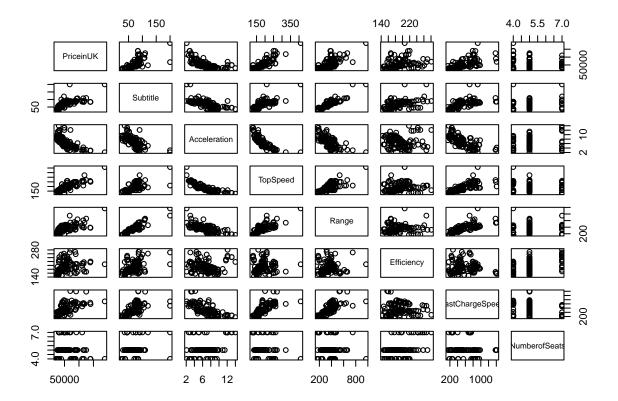
4/20/2022

Model Selection

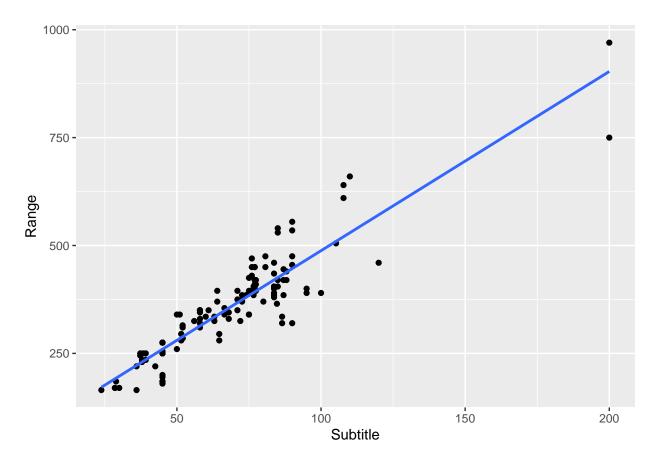
Variable Selection

The first thing was to check the correlations between some of the variables and visualize the data.

##		Subtitle Acceleration TopSpeed Range Efficience	су
##	Subtitle	1.00000000 -0.65205890 0.68551542 0.91104205 0.4226688	35
##	Acceleration	-0.65205890 1.00000000 -0.83536291 -0.70220767 -0.0300938	36
##	TopSpeed	0.68551542 -0.83536291 1.00000000 0.74349641 0.0781084	1 5
##	Range	0.91104205 -0.70220767 0.74349641 1.00000000 0.0449622	25
##	Efficiency	0.42266885 -0.03009386 0.07810845 0.04496225 1.0000000	00
##	${\tt FastChargeSpeed}$	0.60230194 -0.71134894 0.73572843 0.72271112 -0.0264225	50
##	NumberofSeats	0.08103089	23
##	PriceinUK	0.70390802 -0.70863967 0.86502374 0.68439993 0.3053172	28
##		FastChargeSpeed NumberofSeats PriceinUK	
##	Subtitle	0.6023019	
##	Acceleration	-0.7113489 0.30861901 -0.7086397	
##	TopSpeed	0.7357284 -0.21958021 0.8650237	
##	Range	0.7227111 -0.06531154 0.6843999	
##	Efficiency	-0.0264225	
##	${\tt FastChargeSpeed}$	1.0000000 -0.16516351 0.6495690	
##	NumberofSeats	-0.1651635 1.00000000 -0.1491998	
##	PriceinUK	0.6495690 -0.14919979 1.0000000	



The most highly correlated variables are Subtitle and Range. These have a correlation of 0.91104205 and seem to have similar plots in the scatter plot matrix. A zoomed in scatter plot is included below.



When zoomed in, the two variables seem to have a linear relationship with each other. This indicates that one of these may be dropped. Subtitle and Range have respective correlations 0.7039080 and 0.6843999 with the response. Since Subtitle has a stronger correlation with the response, that will be the predictor that is kept.

Transformations

In the first row of the scatter plot matrix, TopSpeed and Acceleration appear to form a parabola when next to each other. As such, a quadratic transformation will be applied to those two variables.

Number of Seats also appears to behave as a factor in the scatter plot matrix. As such, it will be transformed into one.

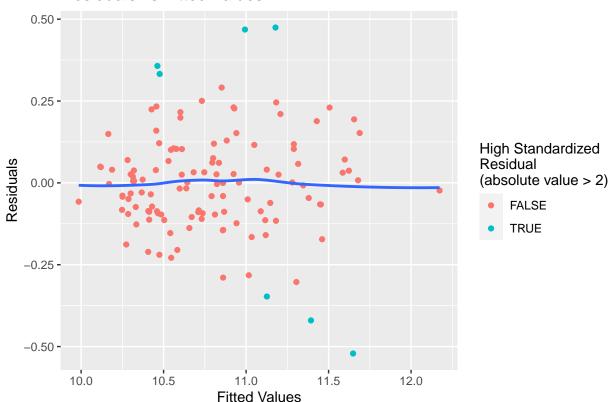
In order to handle non-constant variance, logarithmic transformations will be applied to the other predictors and response variables.

Full Model

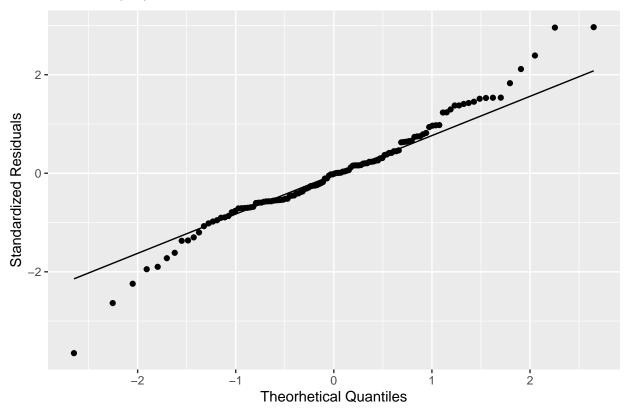
```
##
## Call:
## lm(formula = ., data = data)
##
## Residuals:
## Min 1Q Median 3Q Max
## -0.52123 -0.09026 -0.00196 0.08179 0.47444
##
## Coefficients:
```

```
Estimate Std. Error t value Pr(>|t|)
##
## (Intercept)
                                   5.237e+00 9.592e-01
                                                          5.460 2.90e-07 ***
## log(Subtitle)
                                              9.933e-02
                                                          4.039 9.86e-05 ***
                                   4.012e-01
## poly(Acceleration, 2, raw = T)1 -2.076e-01 5.572e-02
                                                         -3.726 0.000307 ***
## poly(Acceleration, 2, raw = T)2 1.387e-02
                                              3.076e-03
                                                          4.510 1.61e-05 ***
## poly(TopSpeed, 2, raw = T)1
                                   1.321e-02
                                              3.176e-03
                                                          4.159 6.30e-05 ***
## poly(TopSpeed, 2, raw = T)2
                                  -1.910e-05
                                              5.803e-06
                                                         -3.291 0.001334 **
## log(Efficiency)
                                              1.738e-01
                                   5.679e-01
                                                          3.267 0.001443 **
## log(FastChargeSpeed)
                                  -6.657e-03
                                              6.781e-02
                                                         -0.098 0.921973
## DriveFront Wheel Drive
                                  -2.338e-02
                                              6.980e-02
                                                         -0.335 0.738269
## DriveRear Wheel Drive
                                  -3.726e-02 5.891e-02
                                                         -0.632 0.528352
## factor(NumberofSeats)5
                                              4.791e-02
                                                         -2.646 0.009308 **
                                  -1.268e-01
## factor(NumberofSeats)7
                                  -2.770e-01 7.294e-02
                                                         -3.798 0.000238 ***
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.1665 on 112 degrees of freedom
## Multiple R-squared: 0.8815, Adjusted R-squared: 0.8698
## F-statistic: 75.71 on 11 and 112 DF, p-value: < 2.2e-16
## `geom_smooth()` using method = 'loess' and formula 'y ~ x'
```

Residuals vs Fitted Values



Normal Q-Q



Reduced Model

This full model seems to have met the assumptions for linear regression. However, it still contains predictors that are not significant. In order to reduce the model, a step-wise process will be used with BIC as the metric.

```
##
## Call:
  lm(formula = log(PriceinUK) ~ log(Subtitle) + poly(Acceleration,
##
       2, raw = T) + poly(TopSpeed, 2, raw = T) + log(Efficiency) +
##
       factor(NumberofSeats), data = data)
##
## Residuals:
##
       Min
                  1Q
                       Median
                                    3Q
                                            Max
## -0.53164 -0.09592 -0.00326 0.08894
                                       0.48461
##
## Coefficients:
##
                                     Estimate Std. Error t value Pr(>|t|)
## (Intercept)
                                    5.139e+00 8.158e-01
                                                           6.299 5.67e-09 ***
## log(Subtitle)
                                    3.836e-01 8.049e-02
                                                           4.766 5.55e-06 ***
## poly(Acceleration, 2, raw = T)1 -2.248e-01
                                               4.879e-02
                                                          -4.608 1.06e-05 ***
## poly(Acceleration, 2, raw = T)2 1.456e-02
                                               2.845e-03
                                                           5.117 1.26e-06 ***
## poly(TopSpeed, 2, raw = T)1
                                    1.280e-02
                                               2.711e-03
                                                           4.722 6.66e-06 ***
## poly(TopSpeed, 2, raw = T)2
                                   -1.852e-05 5.013e-06
                                                          -3.695 0.000338 ***
## log(Efficiency)
                                    6.144e-01 1.454e-01
                                                           4.225 4.81e-05 ***
## factor(NumberofSeats)5
                                                          -2.615 0.010118 *
                                   -1.197e-01
                                               4.577e-02
## factor(NumberofSeats)7
                                   -2.726e-01 7.175e-02 -3.799 0.000234 ***
```

```
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.1646 on 115 degrees of freedom
## Multiple R-squared: 0.881, Adjusted R-squared: 0.8727
## F-statistic: 106.4 on 8 and 115 DF, p-value: < 2.2e-16</pre>
```

This process removed log(FastChargeSpeed) and Drive from the model. The assumptions still appear to be met. In order to ensure no significant predictors were removed, a partial F-Test will be conducted between the two models.

```
## Analysis of Variance Table
## Model 1: log(PriceinUK) ~ log(Subtitle) + poly(Acceleration, 2, raw = T) +
       poly(TopSpeed, 2, raw = T) + log(Efficiency) + factor(NumberofSeats)
## Model 2: log(PriceinUK) ~ log(Subtitle) + poly(Acceleration, 2, raw = T) +
       poly(TopSpeed, 2, raw = T) + log(Efficiency) + log(FastChargeSpeed) +
       Drive + factor(NumberofSeats)
##
##
     Res.Df
              RSS Df Sum of Sq
                                    F Pr(>F)
## 1
        115 3.1166
                   3 0.012972 0.156 0.9256
## 2
        112 3.1036
```

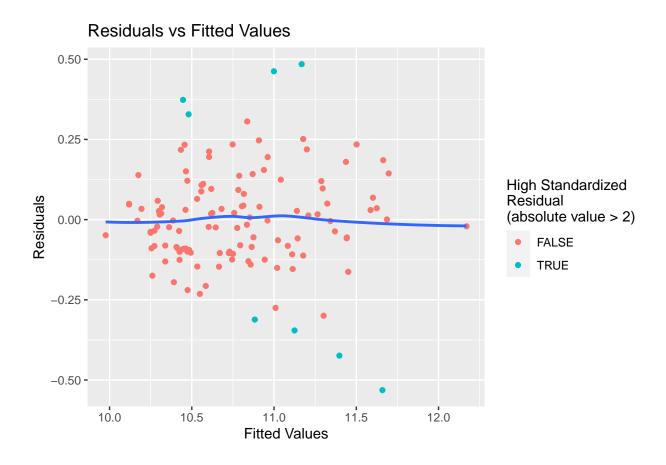
Since the p-value is high, we lack statistically significant evidence that any significant predictors were dropped.

This leaves us with the formula:

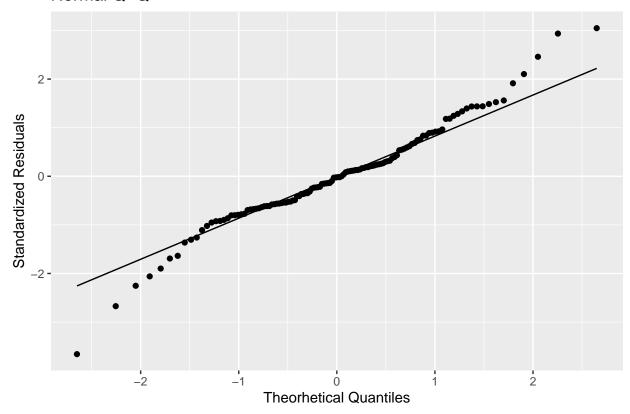
```
\begin{split} \ln \text{PriceinUK} &= \beta_0 \\ &+ \beta_1 \ln \text{Subtitle} \\ &+ \beta_2 \text{Acceleration} + \beta_3 \text{Acceleration}^2 \\ &+ \beta_4 \text{TopSpeed} + \beta_5 \text{TopSpeed}^2 \\ &+ \beta_6 \ln \text{Efficiency} \\ &+ \beta_7 \left( \text{NumberofSeats} == 5 \right) + \beta_8 \left( \text{NumberofSeats} == 7 \right) \\ &+ \epsilon \end{split}
```

It may also help to check some diagnostic plots.

```
## `geom_smooth()` using method = 'loess' and formula 'y ~ x'
```



Normal Q-Q



From the visual tests, the normality and constant variance conditions appear to be met. However it may help to perform some tests.

First, a Shapiro-Wilkes test will be used to test for normality.

```
##
## Shapiro-Wilk normality test
##
## data: .
## W = 0.97173, p-value = 0.0105
```

Here, the p-value is significant to reject normality. However, the W-statistic is larger than 0.95, which indicates that the standardized residuals are highly correlated with the theoretical quantiles. As such, there is not enough evidence to refute normality. Since normality is not rejected, we now test for constant variance.

```
##
## studentized Breusch-Pagan test
##
## data: .
## BP = 31.577, df = 8, p-value = 0.0001109
```

Since the p-value is low, we reject constant variance.

Using the data, we can determine some of the high leverage points:

	Name	PriceinUK
3	Nissan e-NV200 Evalia	30255
14	Tesla Roadster	189000
19	Tesla Model Y Long Range Dual Motor	54000

	Name	PriceinUK
20	Tesla Model Y Performance	60000
35	Mercedes EQV 300 Long	70665
42	Tesla Cybertruck Single Motor	39000
44	Tesla Cybertruck Tri Motor	68000
84	Tesla Model S Plaid	118980
115	${\it Mercedes EQB~350~4MATIC}$	50000

and the high residual points

	Name	PriceinUK
42	Tesla Cybertruck Single Motor	39000
43	Tesla Cybertruck Dual Motor	48000
44	Tesla Cybertruck Tri Motor	68000
77	Opel Zafira-e Life L 50 kWh	49465
96	Kia EV6 GT	58295
105	Mercedes EQS 450+	95000
106	Mercedes EQS 580 4MATIC	115000
115	${\it Mercedes EQB~350~4MATIC}$	50000