

Master Thesis

Process Enhancement by Incorporating Negative Instances in Model Repair

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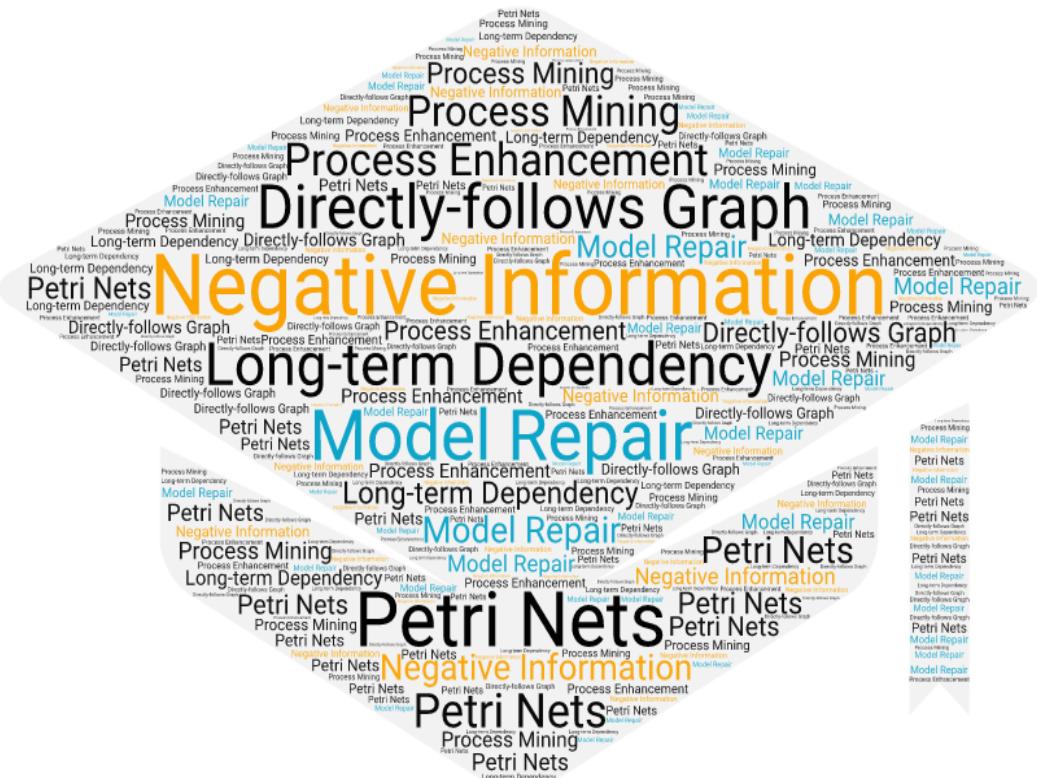
Supervisor: Dr. Sebastiaan J. van Zelst

Examiners: Prof. Wil M.P. van der Aalst
Prof. Thomas Rose

Institute: Lehrstuhl für Process and Data Science

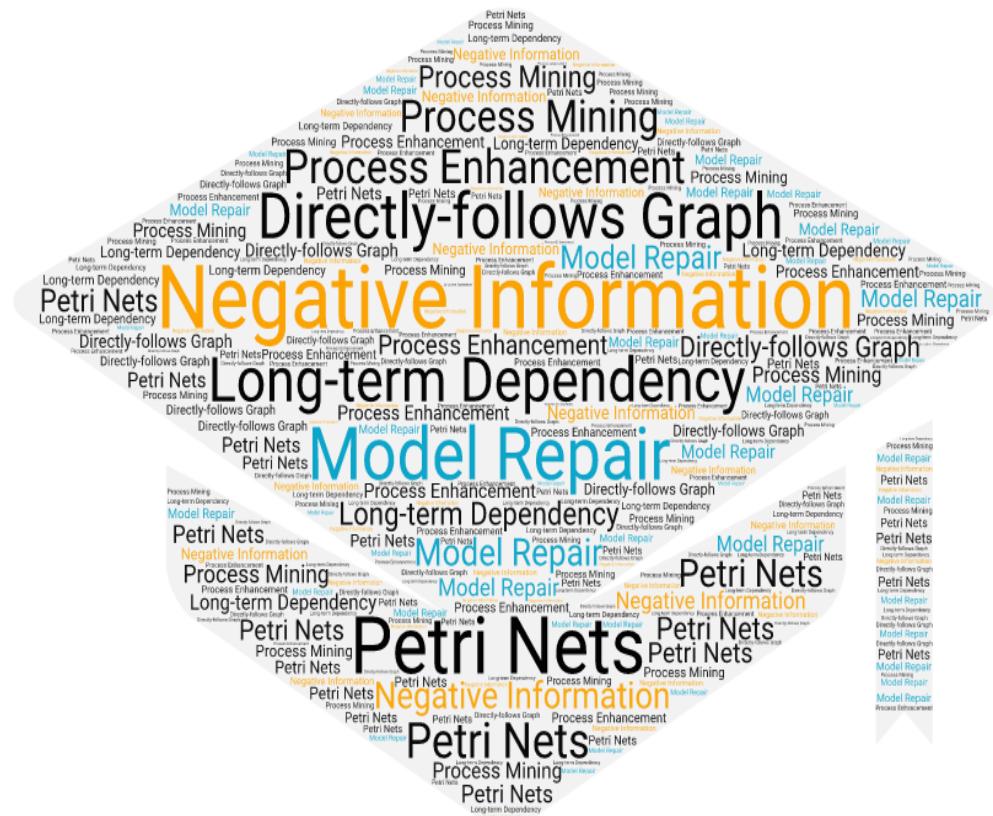
Outline

- Motivation
- Problem Definition
- Approach
- Demo
- Evaluation
- Conclusion

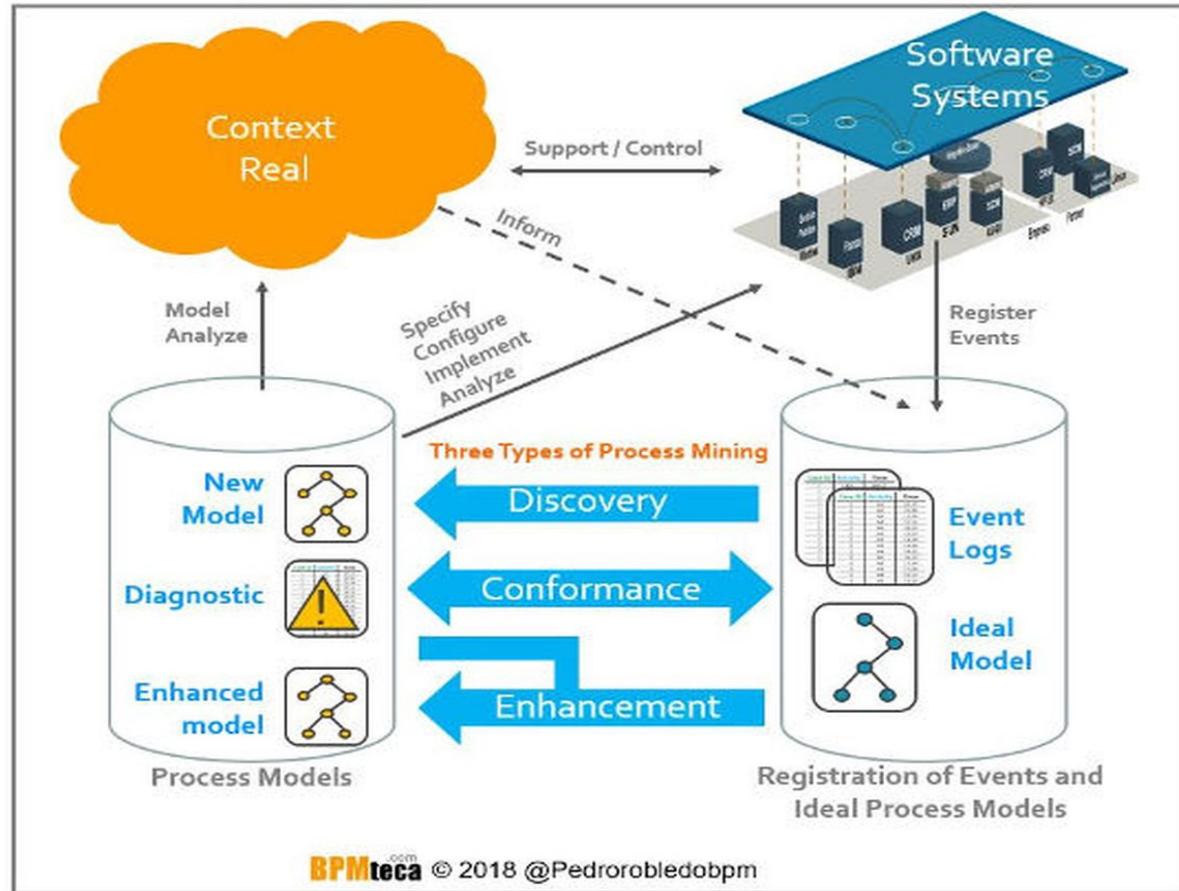


Outline

- **Motivation**
 - Scope
 - Related work
 - Motivating examples
- **Problem Definition**
- **Approach**
- **Demo**
- **Evaluation**
- **Conclusion**

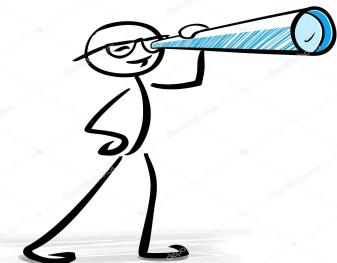


Scope



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Process Mining

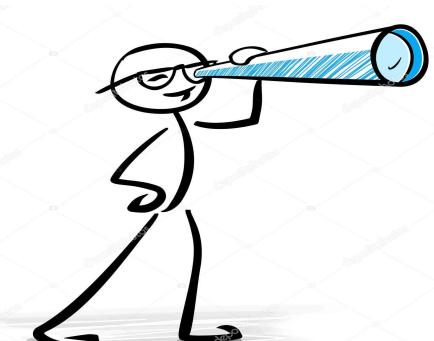
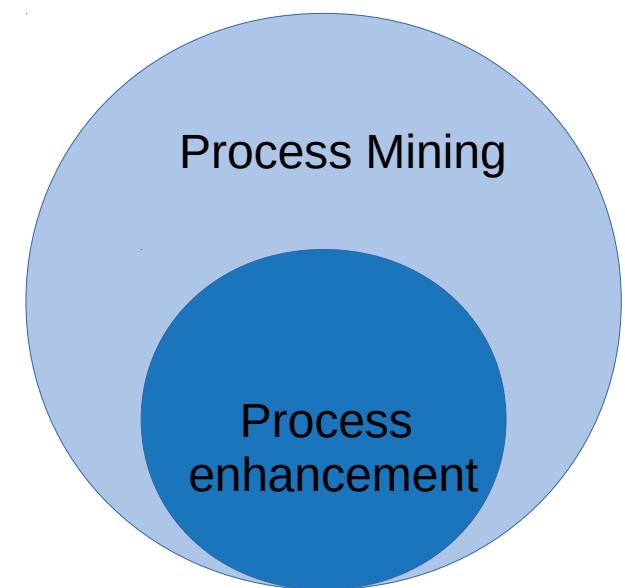
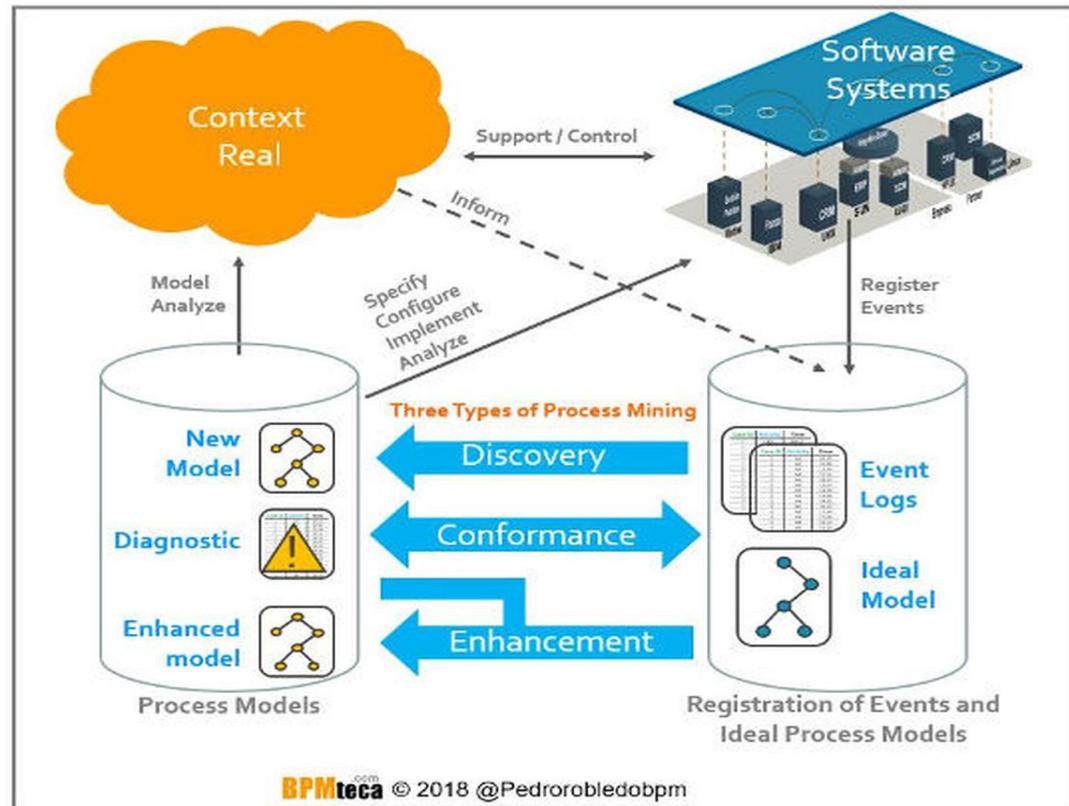


<https://medium.com/@pedrorobledobpm/process-mining-plays-an-essential-role-in-digital-transformation-384839236bbe>

May 26, 2019

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Scope

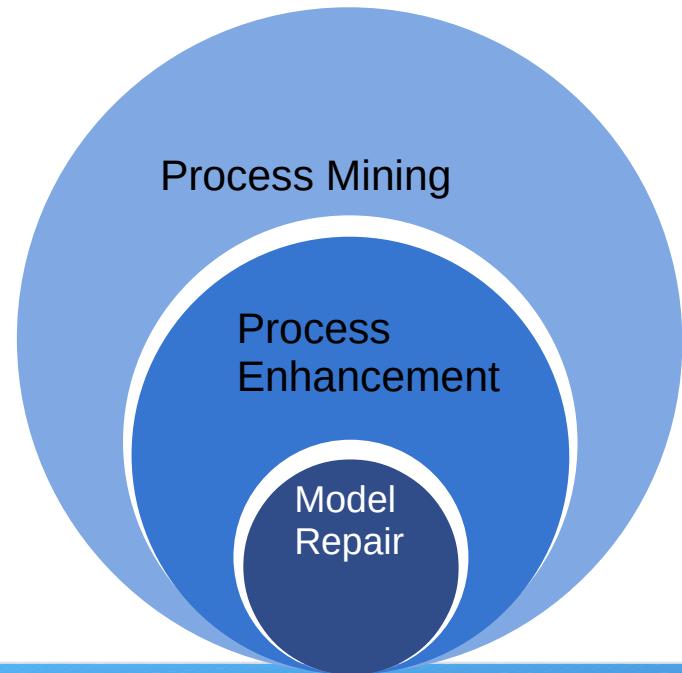
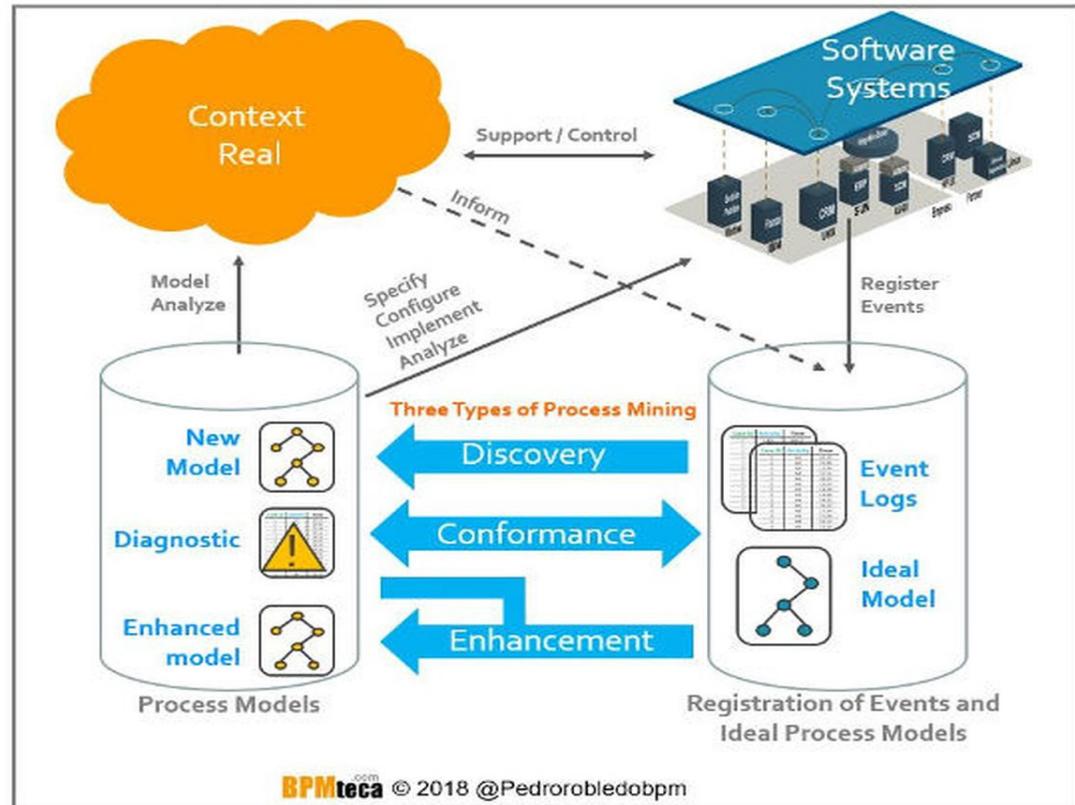


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Scope

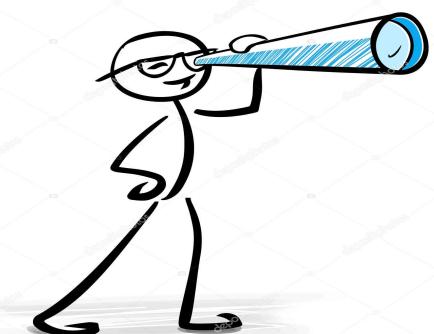
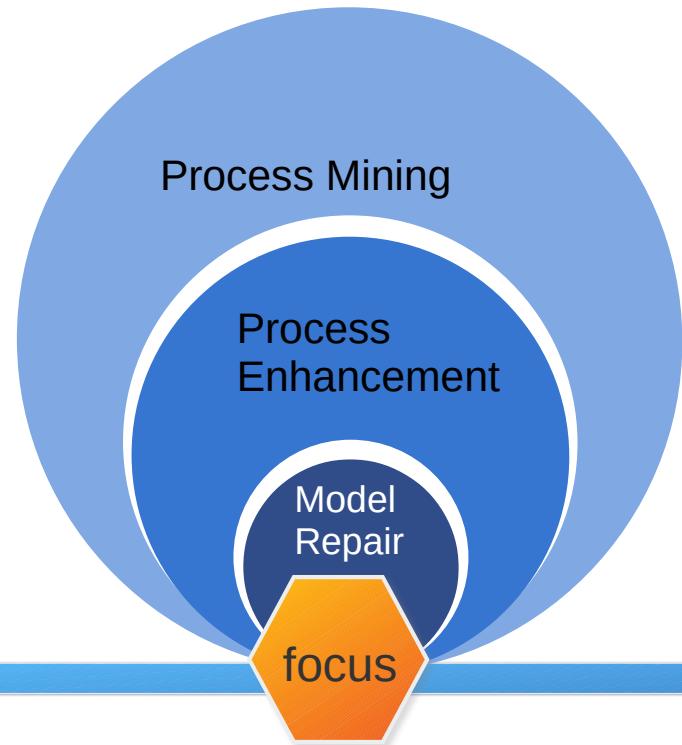
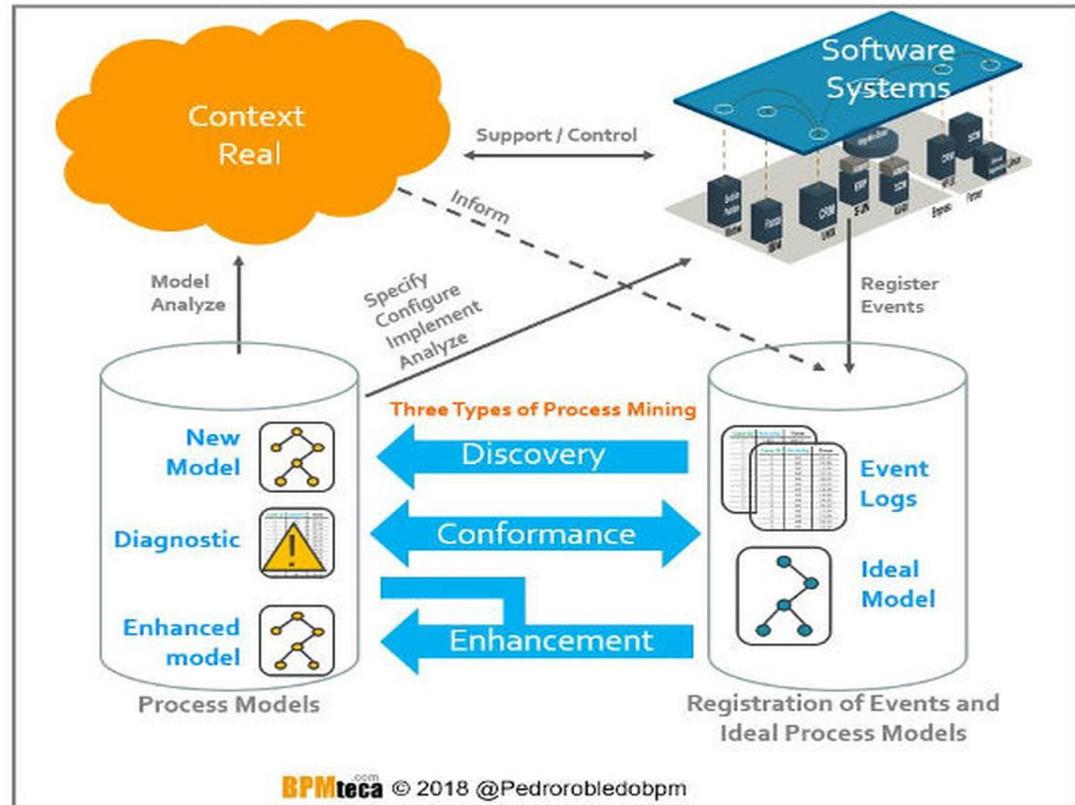


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Scope

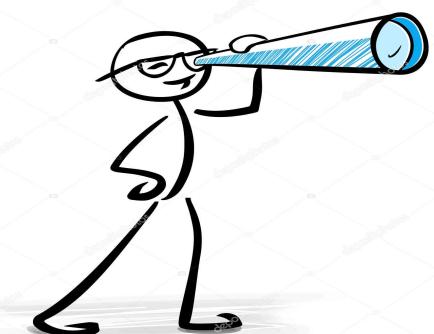
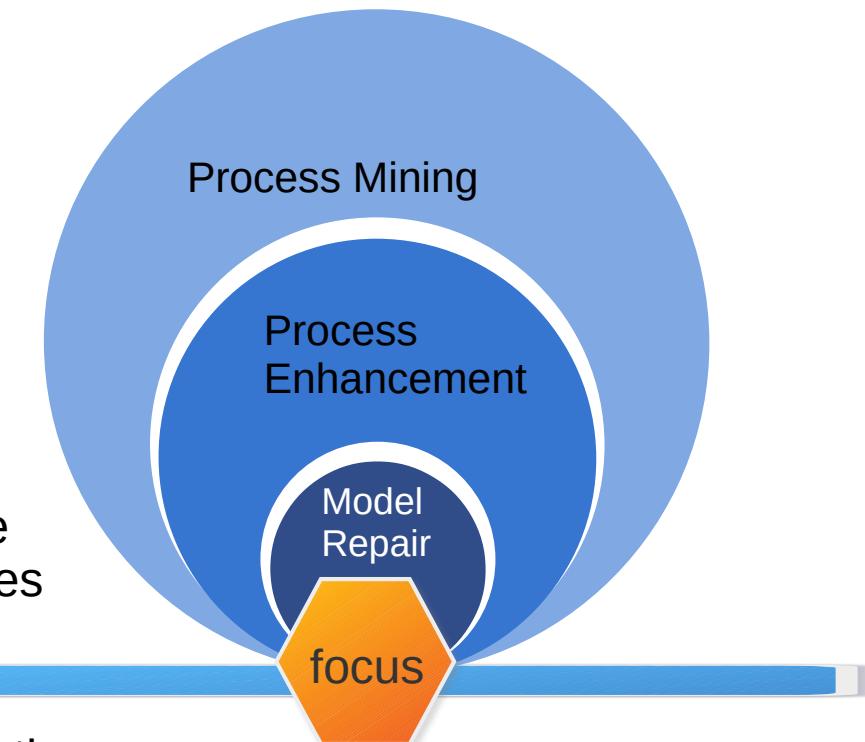
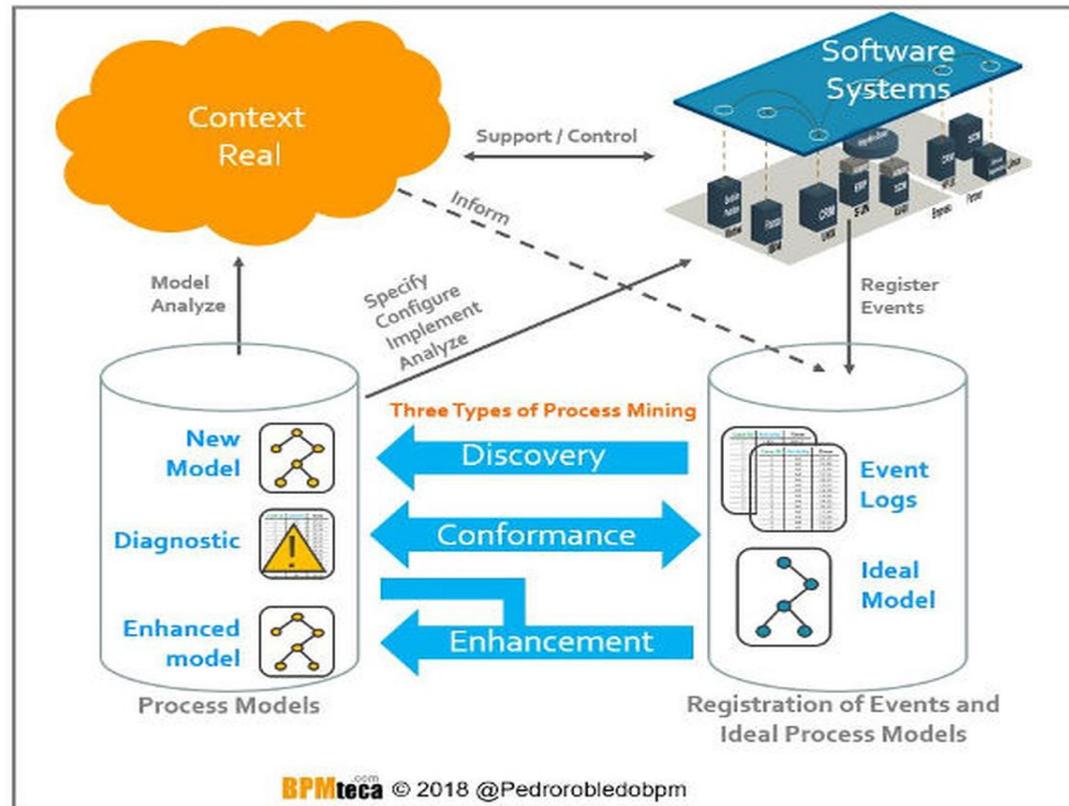


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Scope



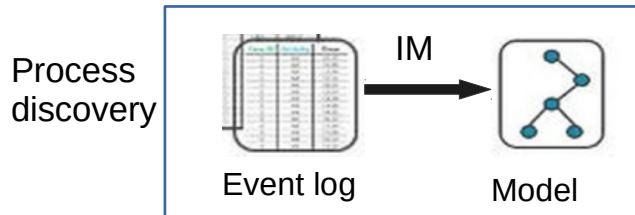
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Related Work

- **Rediscovery**



- **Model Repair by Fahland**

- Deviations
- Subprocesses

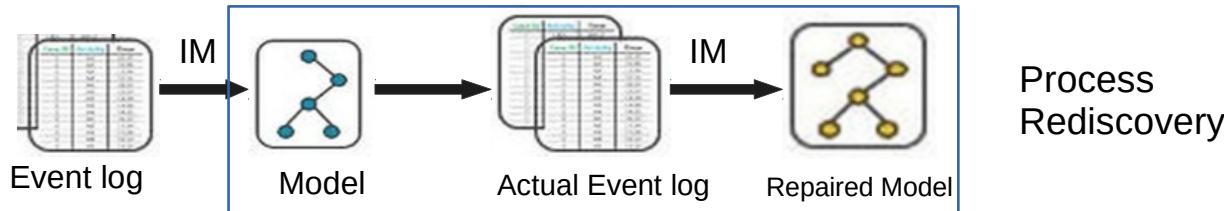
- **Model Repair by Dees**

- Event log with performance labels
- Classify deviations
- Fahland's repair only on positive deviations



Related Work

- **Rediscovery**

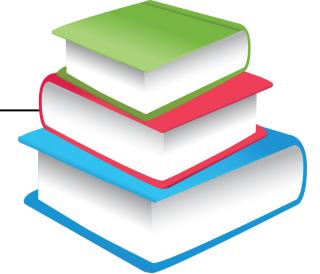


- **Model Repair by Fahland**

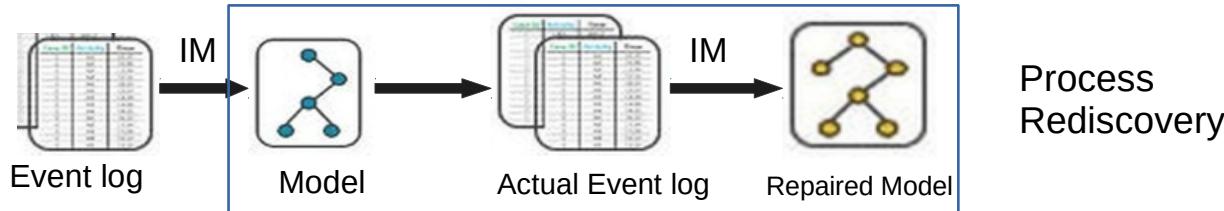
- **Model Repair by Dees**



Related Work

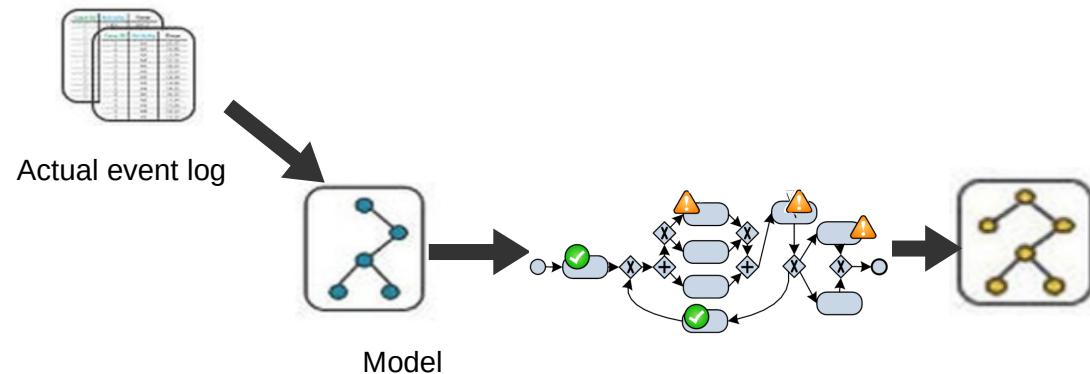


- **Rediscovery**



- **Model Repair by Fahland**

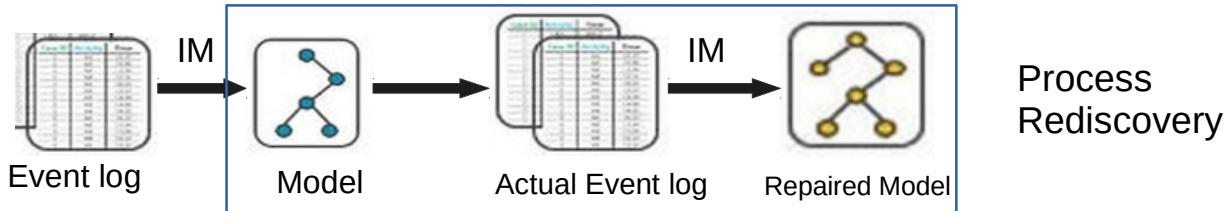
- Deviations
- Subprocesses



- **Model Repair by Dees**

Related Work

- **Rediscovery**

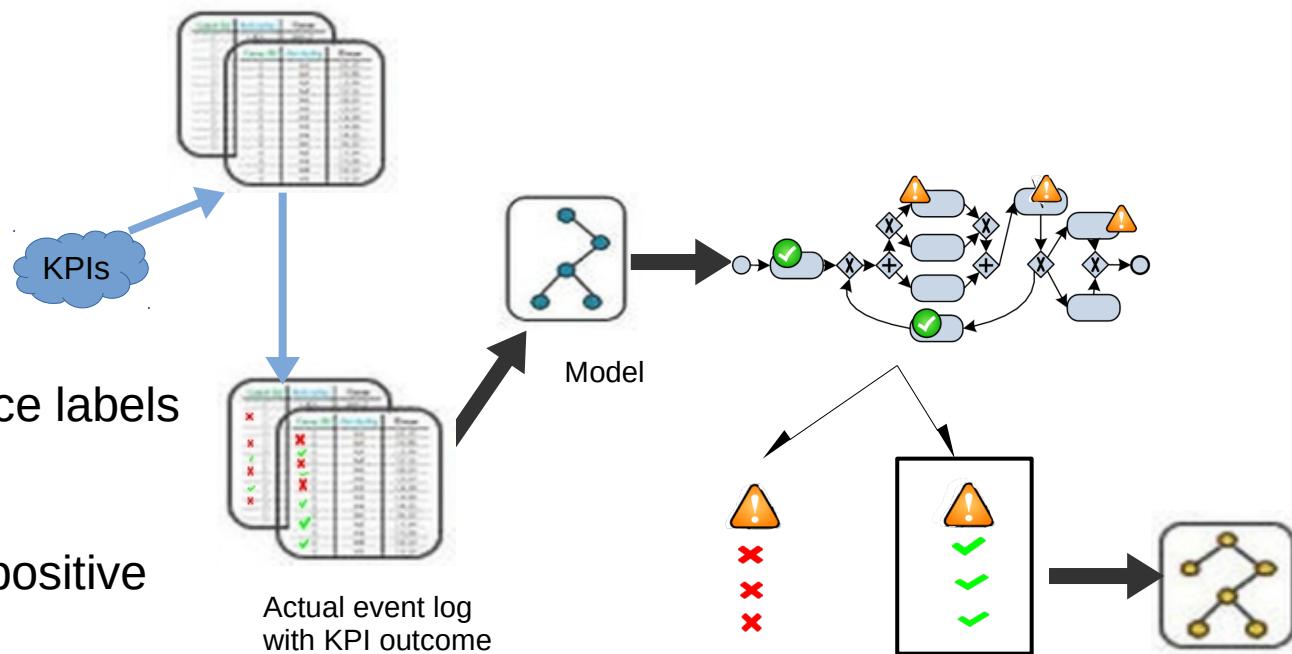


- **Model Repair by Fahland**

- Deviations
- Subprocesses

- **Model Repair by Dees**

- Event log with performance labels
- Classify deviations
- Fahland's repair only on positive deviations



Motivation – shortcomings

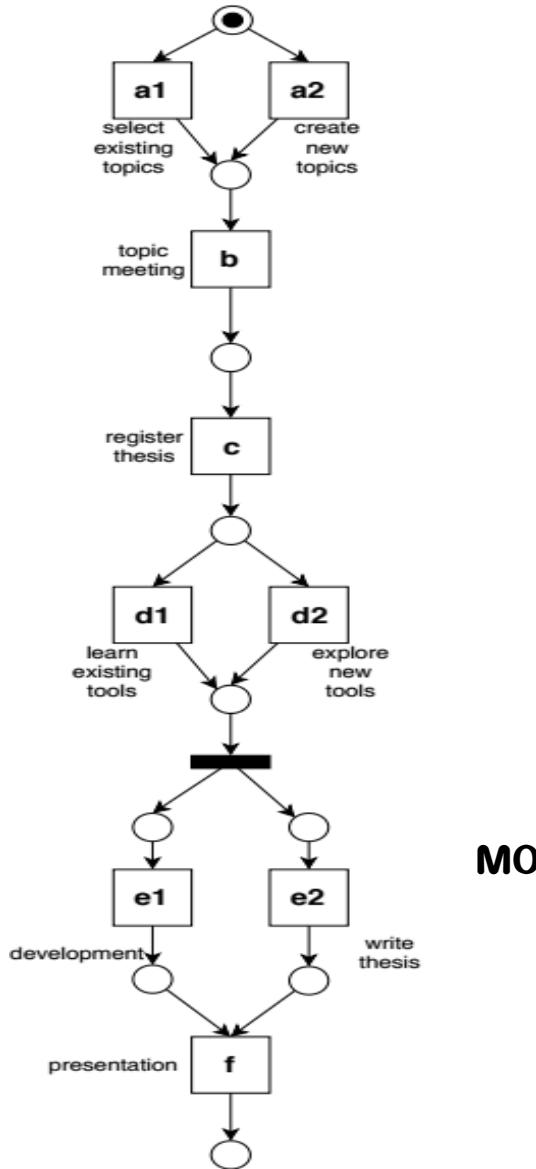
Master thesis process

M0: reference model

x1: write propose

x2: check course requirement

$$L_1 := \{ < a1, b, \mathbf{x1}, c, d1, e1, e2, f >^{50, pos}, \\ < a1, b, \mathbf{x2}, c, d2, e1, e2, f >^{50, pos}, \}$$



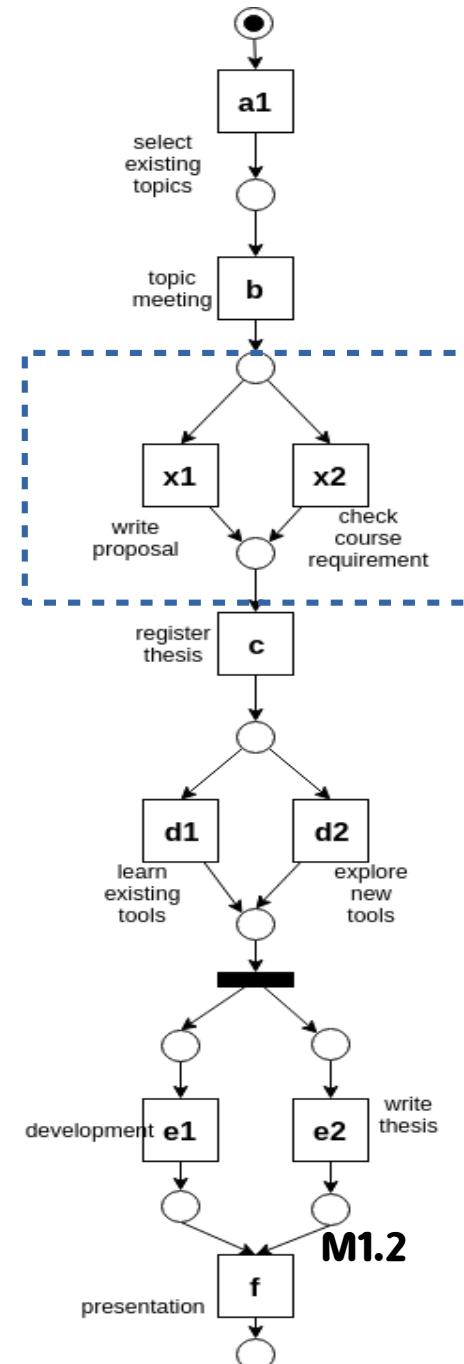
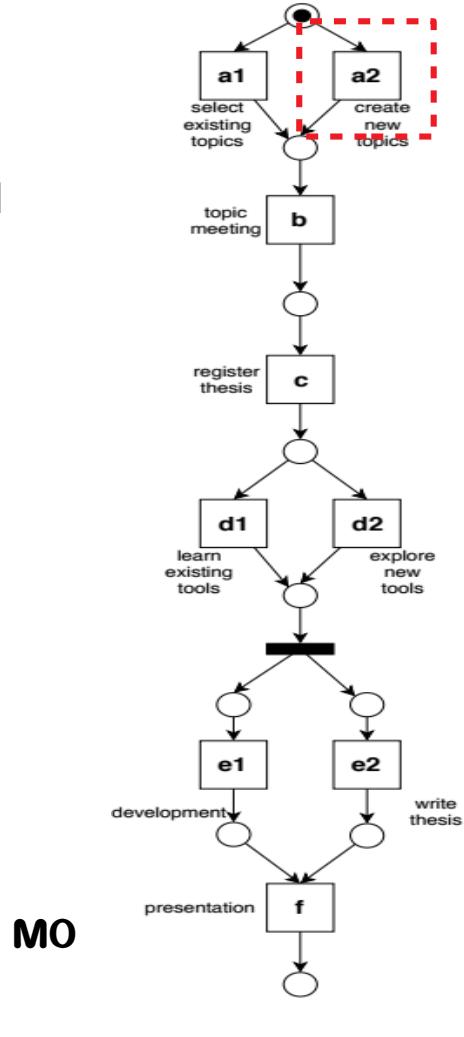
Motivation – shortcomings

$$L_1 := \{< a1, b, \mathbf{x1}, c, d1, e1, e2, f >^{50, pos}, \\ < a1, b, \mathbf{x2}, c, d2, e1, e2, f >^{50, pos}, \}$$

- IM not consider reference model



Similarity decreases!



Motivation – shortcomings

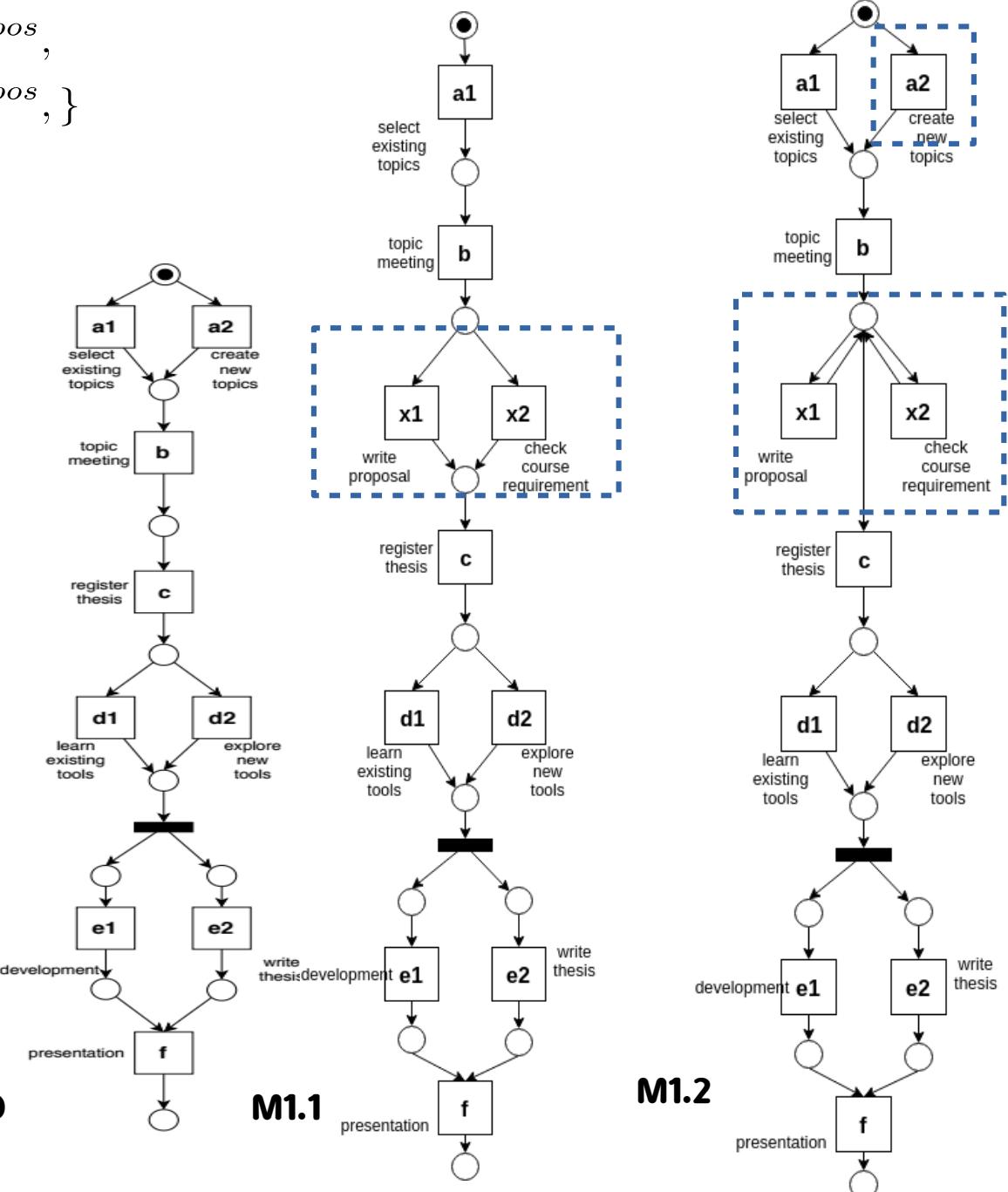
$$L_1 := \{ < a1, b, \mathbf{x1}, c, d1, e1, e2, f >^{50, pos}, \\ < a1, b, \mathbf{x2}, c, d2, e1, e2, f >^{50, pos}, \}$$

- IM not consider reference model
- Fahland's: add subprocesses as loops
- Dee's: same as Fahland's method



Similarity decreases!

Precision decrease by adding subprocess in loops



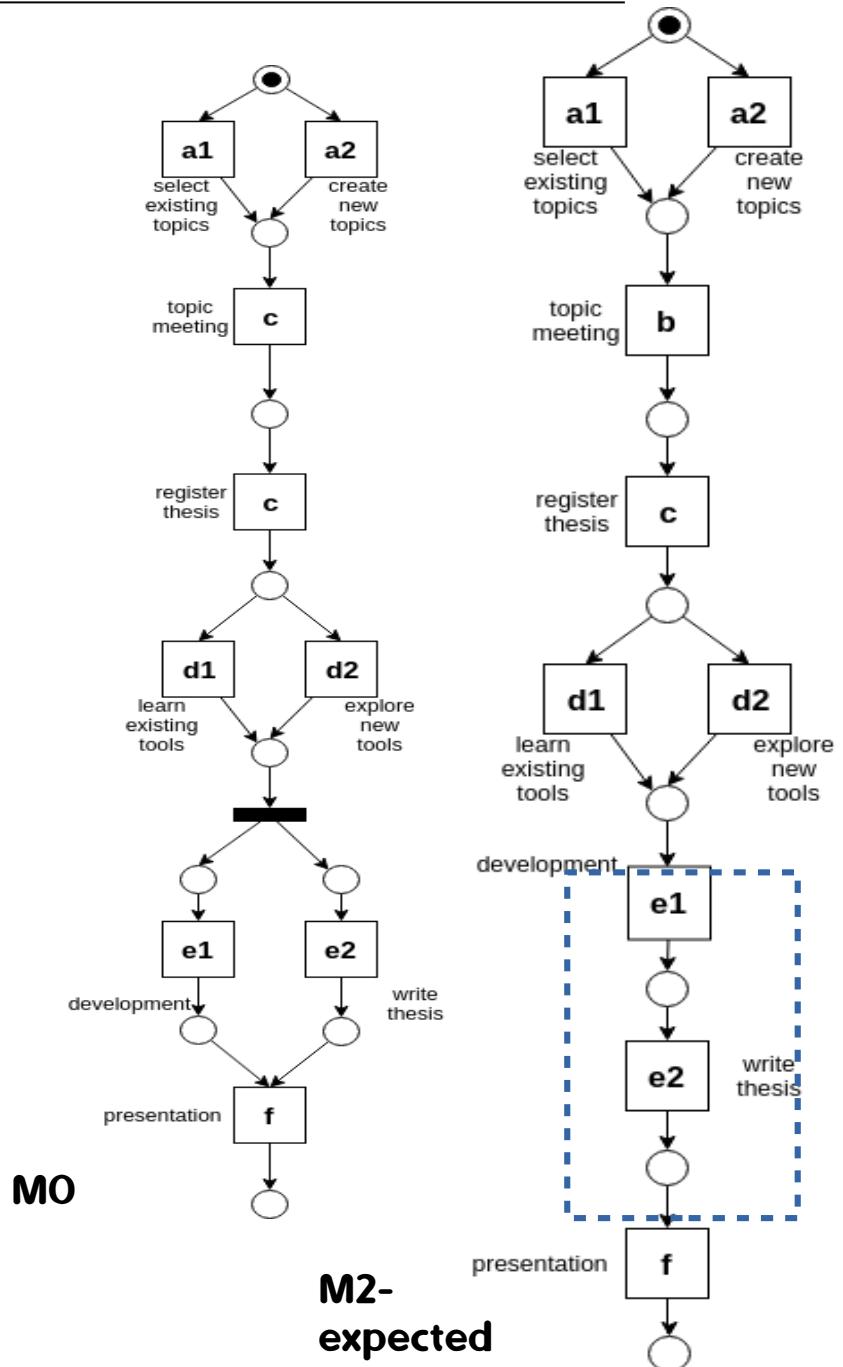
Motivation – shortcomings

$$L_2 := \{ < a1, b, c, d2, \mathbf{e1}, \mathbf{e2}, f >^{30, pos}, \\ < a2, b, c, d1, \mathbf{e1}, \mathbf{e2}, f >^{20, pos}; \\ < a2, b, c, d2, \mathbf{e2}, \mathbf{e1}, f >^{10, pos}; \\ < a1, b, c, d2, \mathbf{e2}, \mathbf{e1}, f >^{20, neg}, \\ < a1, b, c, d1, \mathbf{e2}, \mathbf{e1}, f >^{20, neg}; \\ < a2, b, c, d1, \mathbf{e1}, \mathbf{e2}, f >^{5, neg} \}$$

- IM keeps the model same
- Fahland's keep model same
- Dee's keep model same



Unable to adapt model with negative information



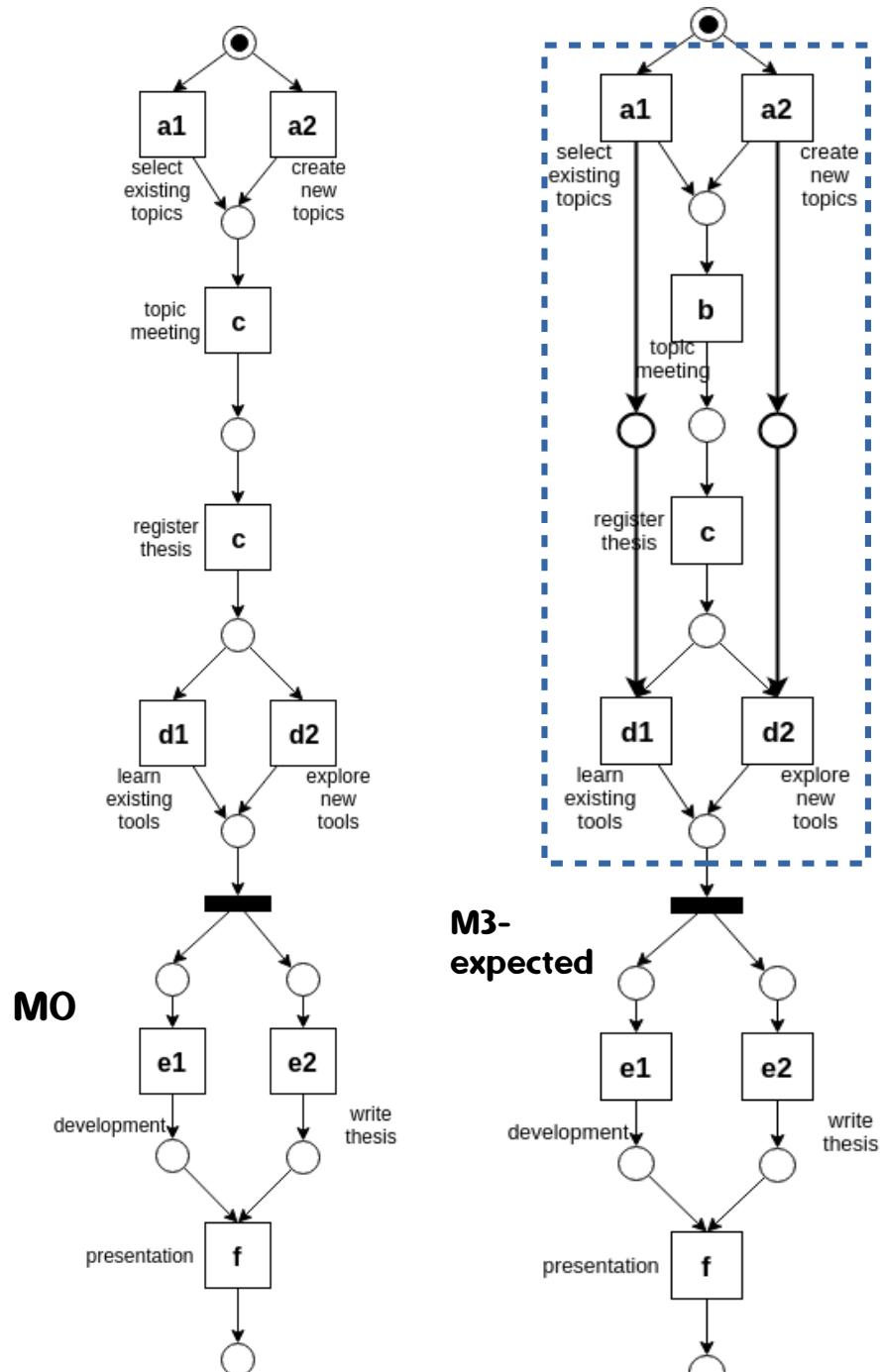
Motivation – shortcomings

$$L_3 := \{< a1, b, c, d1, e1, e2, f >^{50, pos}, \\ < a2, b, c, d2, e1, e2, f >^{50, pos}, \\ < a1, b, c, d2, e1, e2, f >^{50, neg}, \\ < a2, b, c, d1, e1, e2, f >^{50, neg} \}$$

- **Long-term dependency**
 - Choices decides choices
 - Additional places to limit behavior



Unable to detect long-term dependency



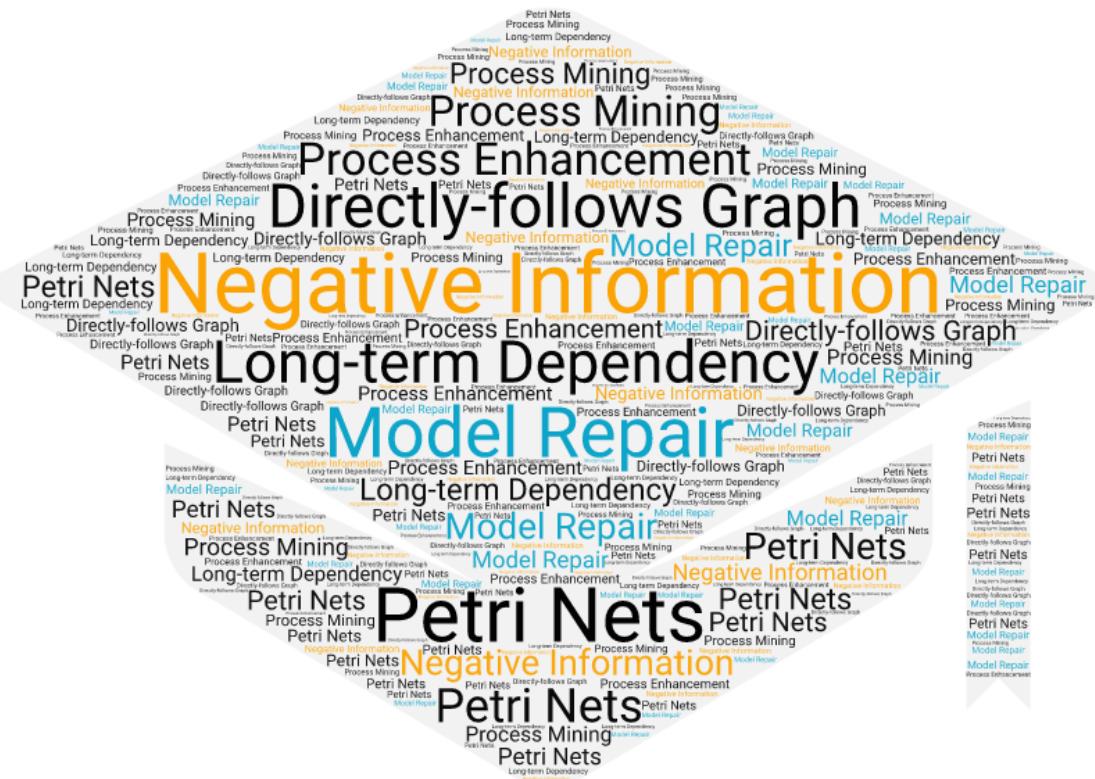
Motivation – Shortcomings

- Similarity decreases with rediscovery
- Precision decrease by adding subprocess in loops
- Unable to adapt model with negative information
- Unable to detect long-term dependency



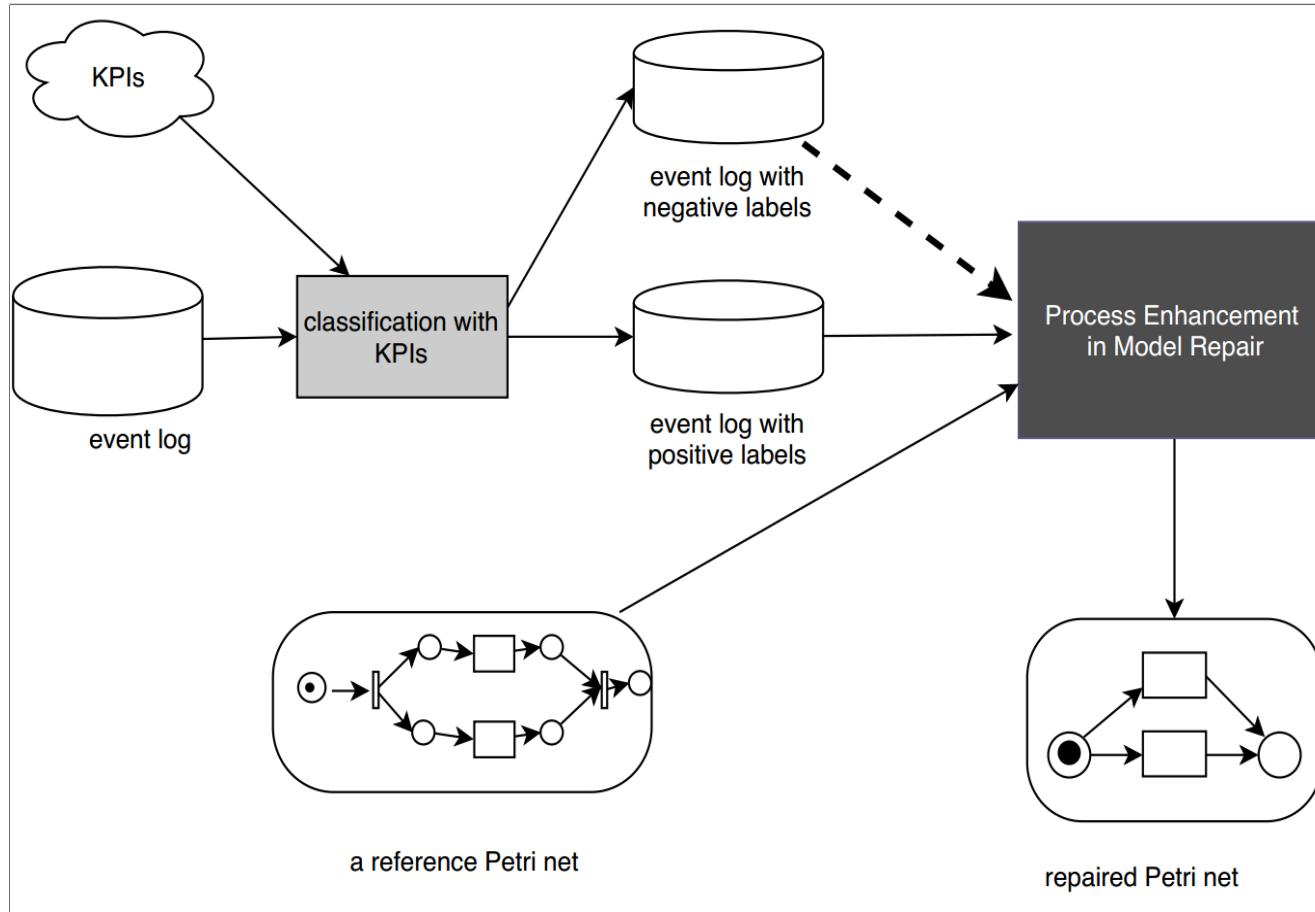
Outline

- Motivation for Research
- Problem Definition
- Approach
- Demo
- Evaluation
- Conclusion



Research Problem

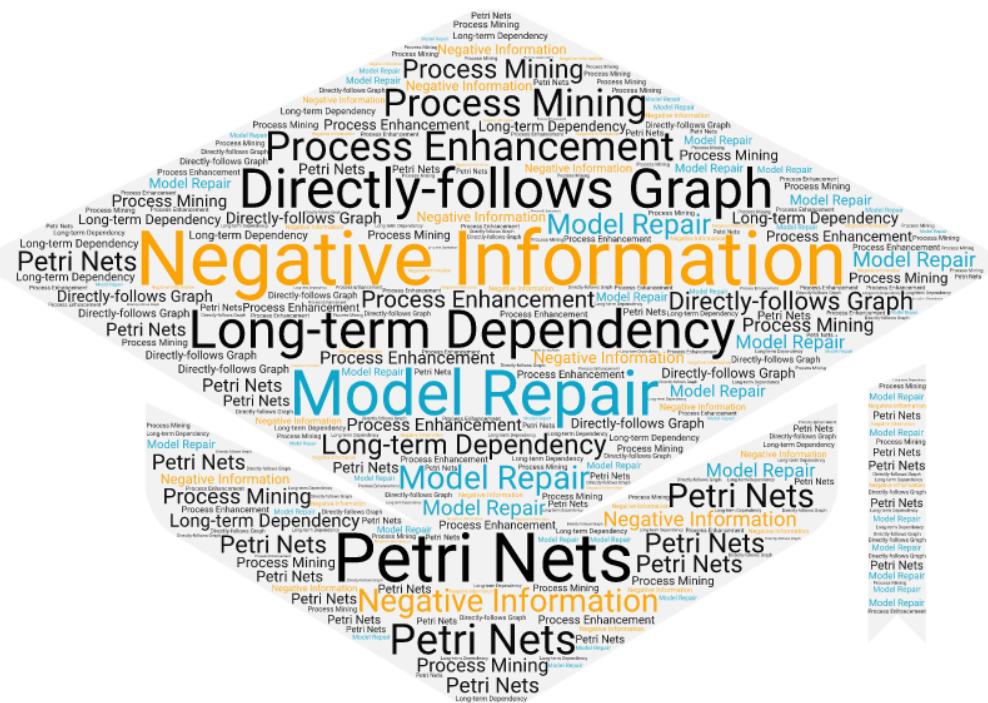
Given an **event log with labels**, a **reference Petri net**, how to incorporate **negative instances** to generate the **repaired Petri net** which supports better performance?



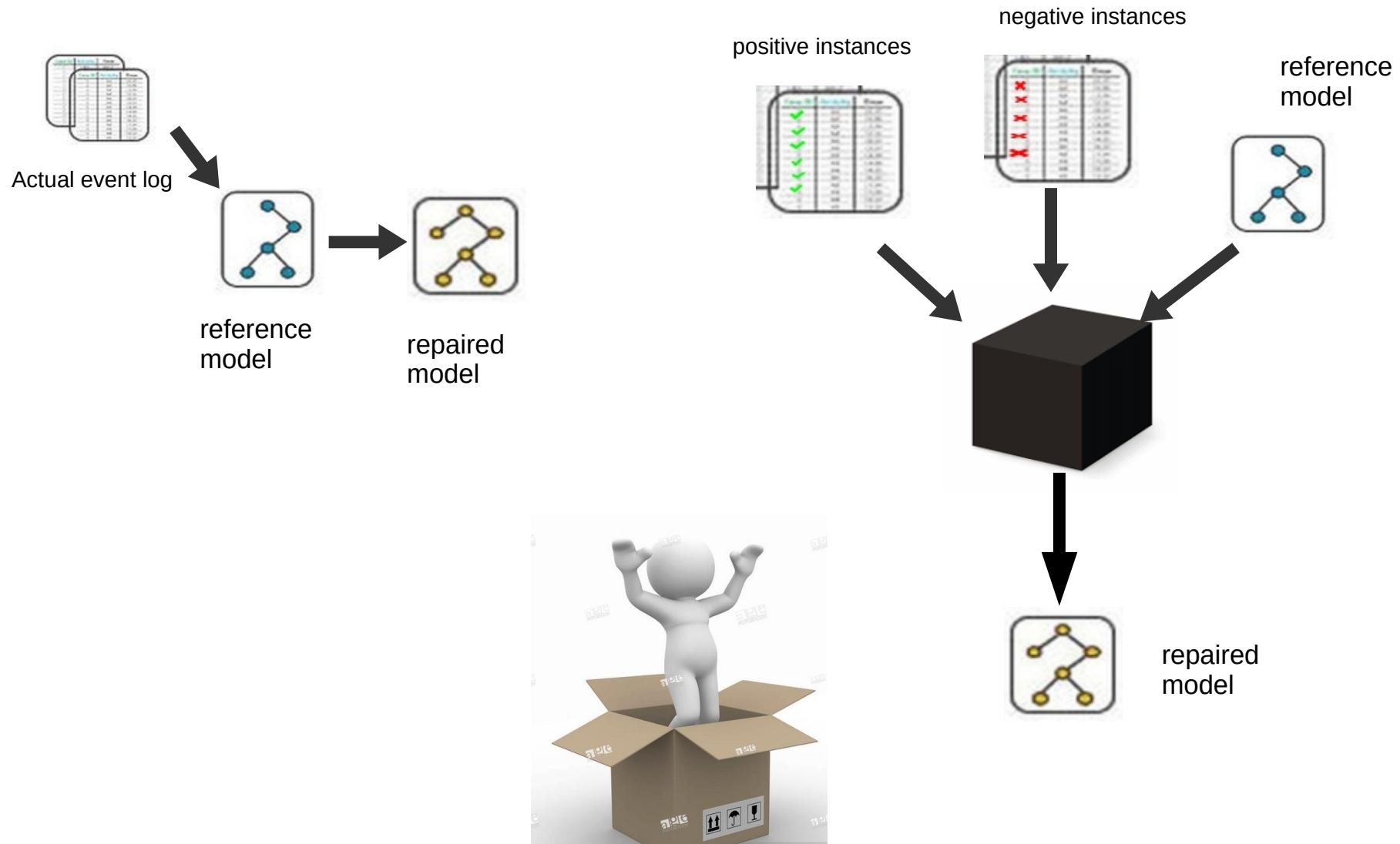
- enforce positive instances
- block negative instances
- similar
- simple
-

Outline

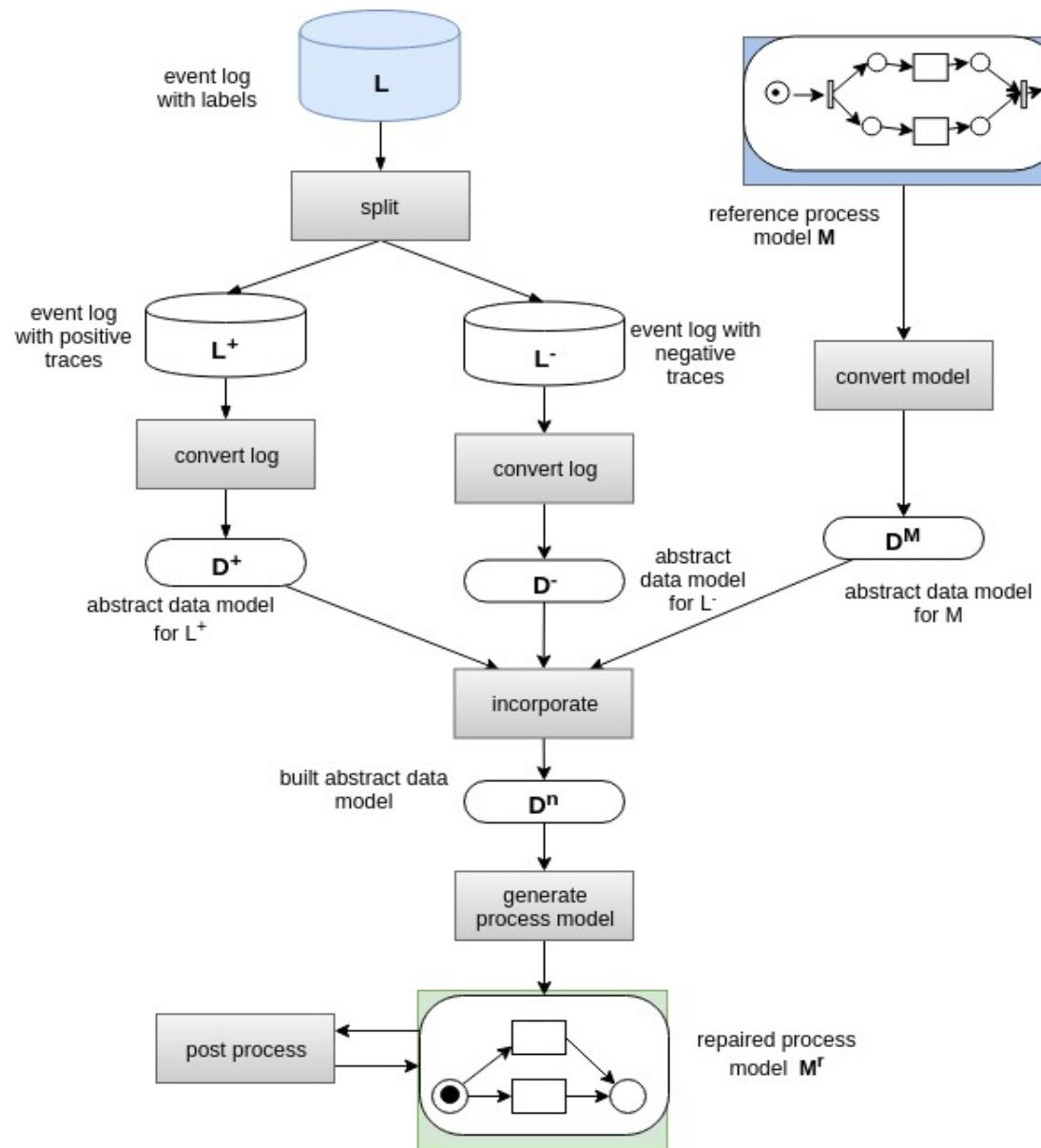
- Motivation for Research
 - Problem Definition
 - Approach
 - Framework
 - Data models
 - Modules
 - Demo
 - Evaluation
 - Conclusion



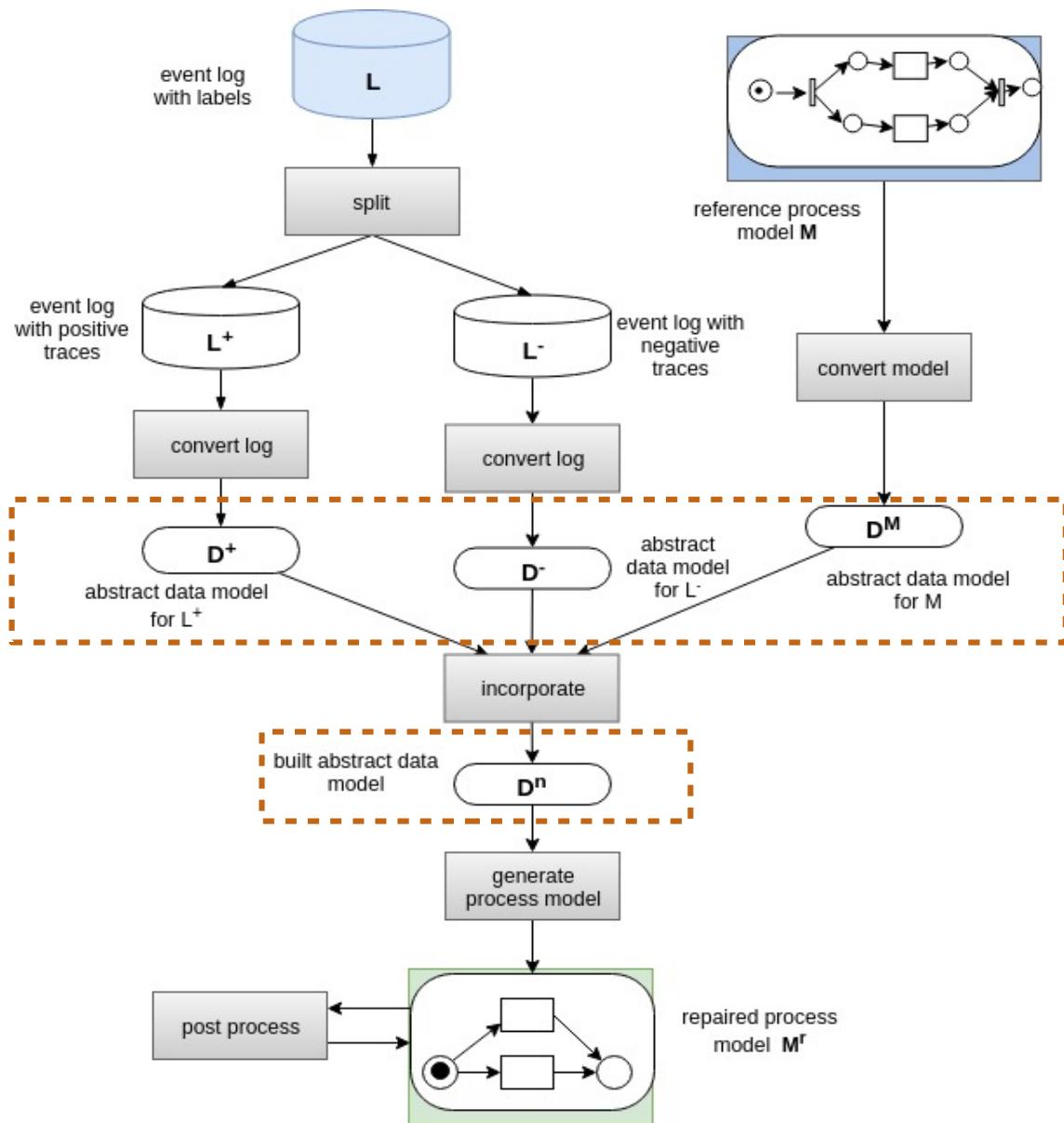
Algorithm – framework



Algorithm – framework



Algorithm – data model



Data Model – directly-follows graph

A directly-follows graph of an event log L is $G(L) = (A, F, A_{start}, A_{end})$ where A is the set of activities in L , $F = \{(a, b) \in A \times A | a >_L b\}$ is the directly-follows relation set, A_{start}, A_{end} are the set of start and end activities respectively,
 $A_{start} = \{a | \exists \sigma \in L, a = \sigma(1)\}$, $A_{end} = \{a | \exists \sigma \in L, a = \sigma(|\sigma|)\}$

The cardinality of $G(L)$ is defined

$$\begin{aligned}\forall (a, b) \in F, c(a, b) &= \sum_{\sigma \in L} |\{i \in \{1, 2, \dots, |\sigma|\} | \sigma(i) = a \text{ and } \sigma(i+1) = b\}| \\ \forall a \in A_{start}, c(a) &= \sum_{\sigma \in L} |\{\sigma | \sigma(1) = a\}| \\ \forall a \in A_{end}, c(a) &= \sum_{\sigma \in L} |\{\sigma | \sigma(|\sigma|) = a\}|\end{aligned}$$

$$L = \{\langle a, c, d \rangle^{20}, \langle b, c, e \rangle^{10}, \\ \langle a, c, e \rangle^{20}, \langle b, c, d \rangle^{10}\}$$

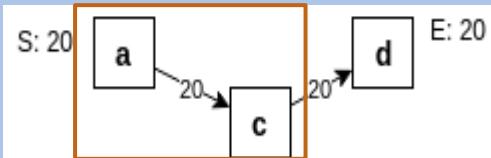
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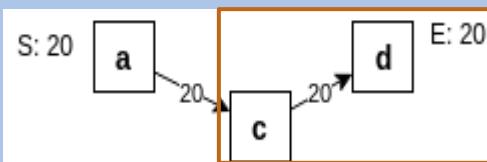
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$$L = \{\langle a, [c, d] \rangle^{20}, \langle b, c, e \rangle^{10}, \\ \langle a, c, e \rangle^{20}, \langle b, c, d \rangle^{10}\}$$



Data Model – directly-follows graph

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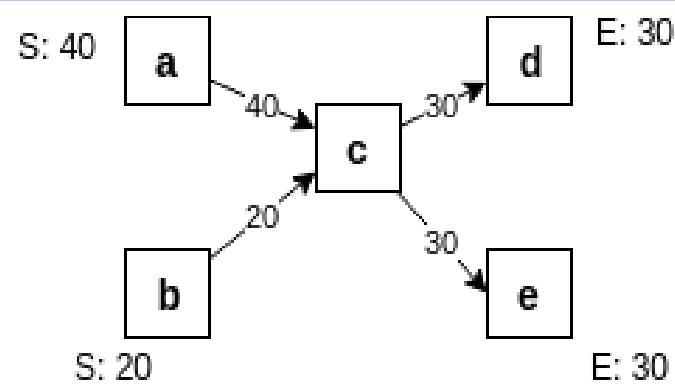
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$$L = \{\langle a, c, d \rangle^{20}, \langle b, c, e \rangle^{10}, \\ \langle a, c, e \rangle^{20}, \langle b, c, d \rangle^{10}\}$$

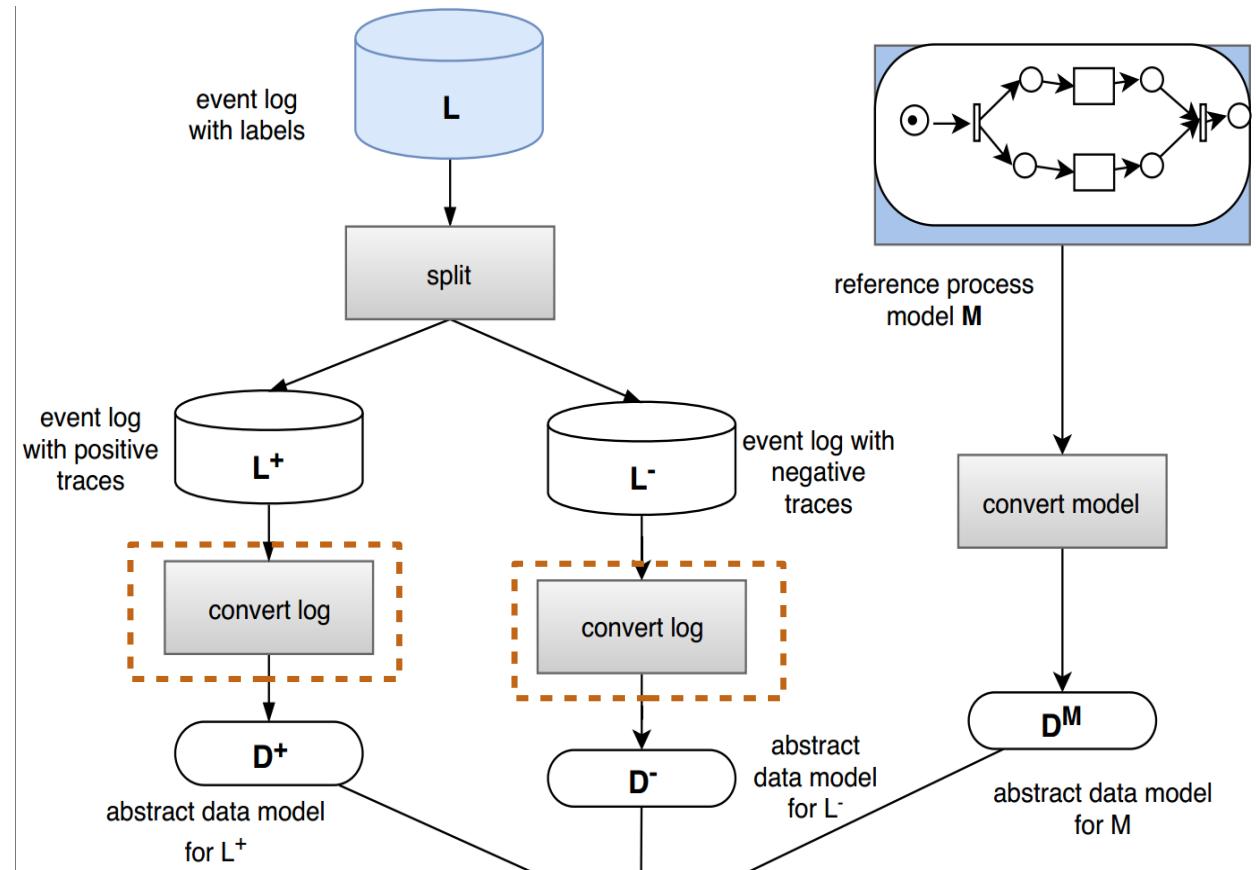
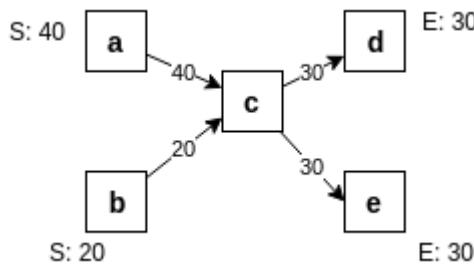


Convert to directly-follows graph

From Event log

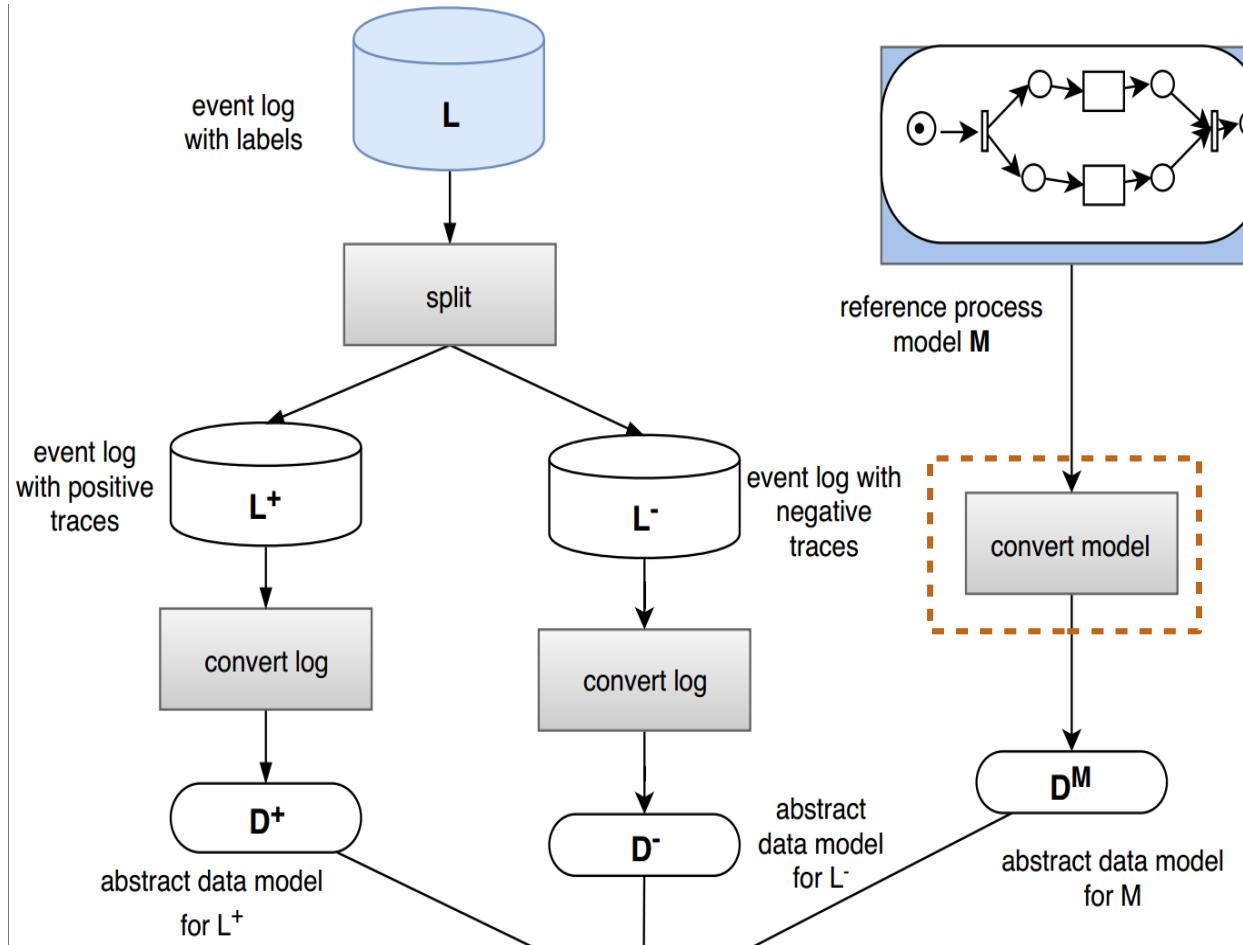
- Directly-follows relation
- Existing plugin

$$L = \{\langle a, c, d \rangle^{20}, \langle b, c, e \rangle^{10}, \\ \langle a, c, e \rangle^{20}, \langle b, c, d \rangle^{10}\}$$



Convert to directly-follows graph

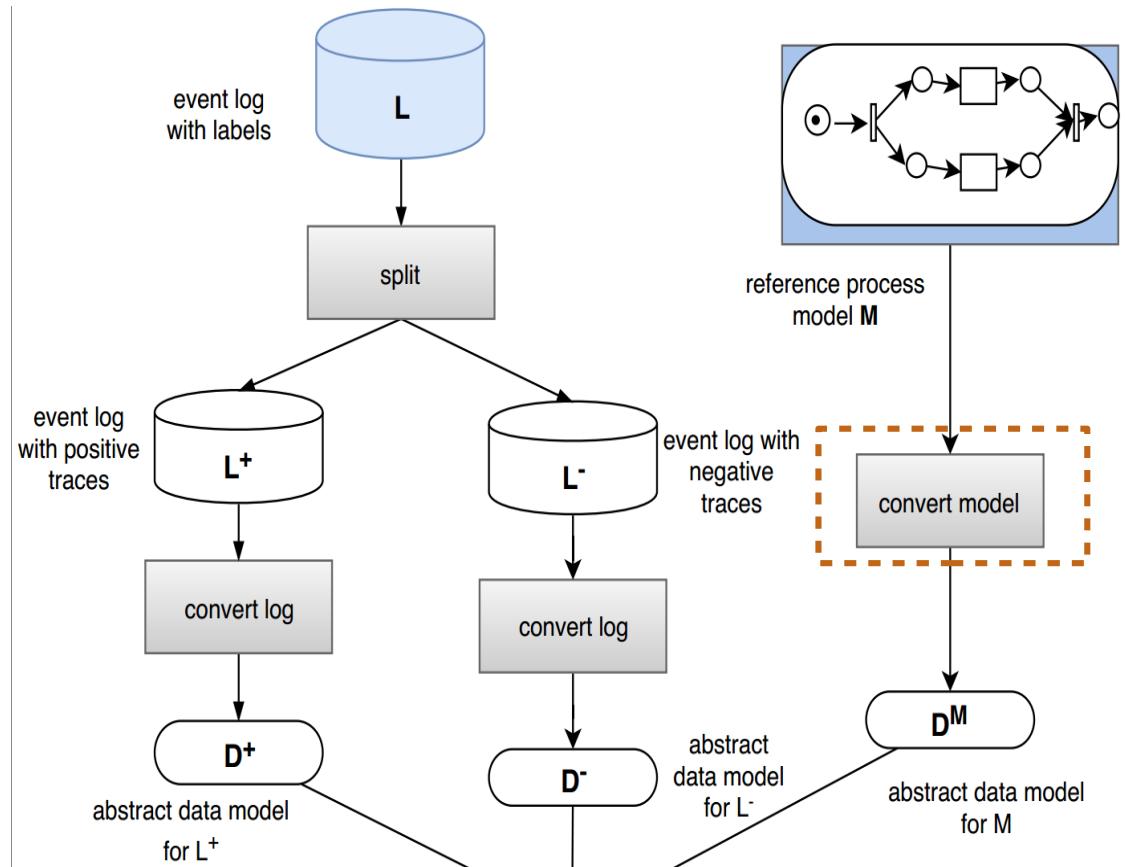
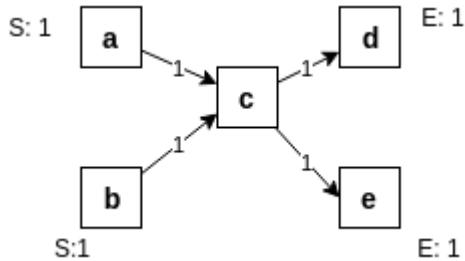
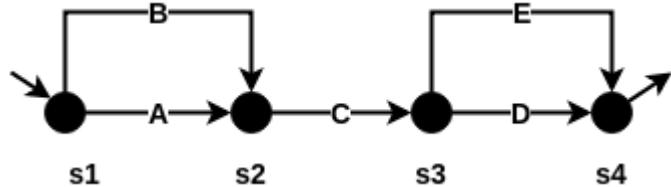
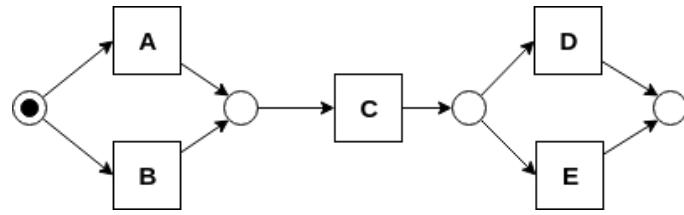
From Petri net



Convert to directly-follows graph

From Petri net

- Transition System
- Transitions before and after states



Data Model

- **Unification of cardinality**

- Models from existing model, positive and negative event log

- For any directly-follows relation

$$u(a, b) = \frac{c(a, b)}{\sum_{(a, b') \in F} c(a, b')}$$

- For any start activity

$$u(a) = \frac{c(a)}{\sum_{a' \in A_{start}} c(a')}$$

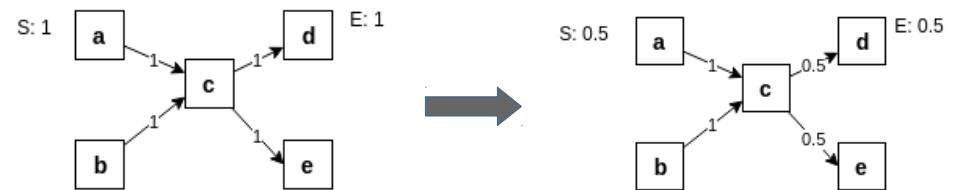
- For any end activity

$$u(a) = \frac{c(a)}{\sum_{a' \in A_{end}} c(a')}$$



dfg from event log

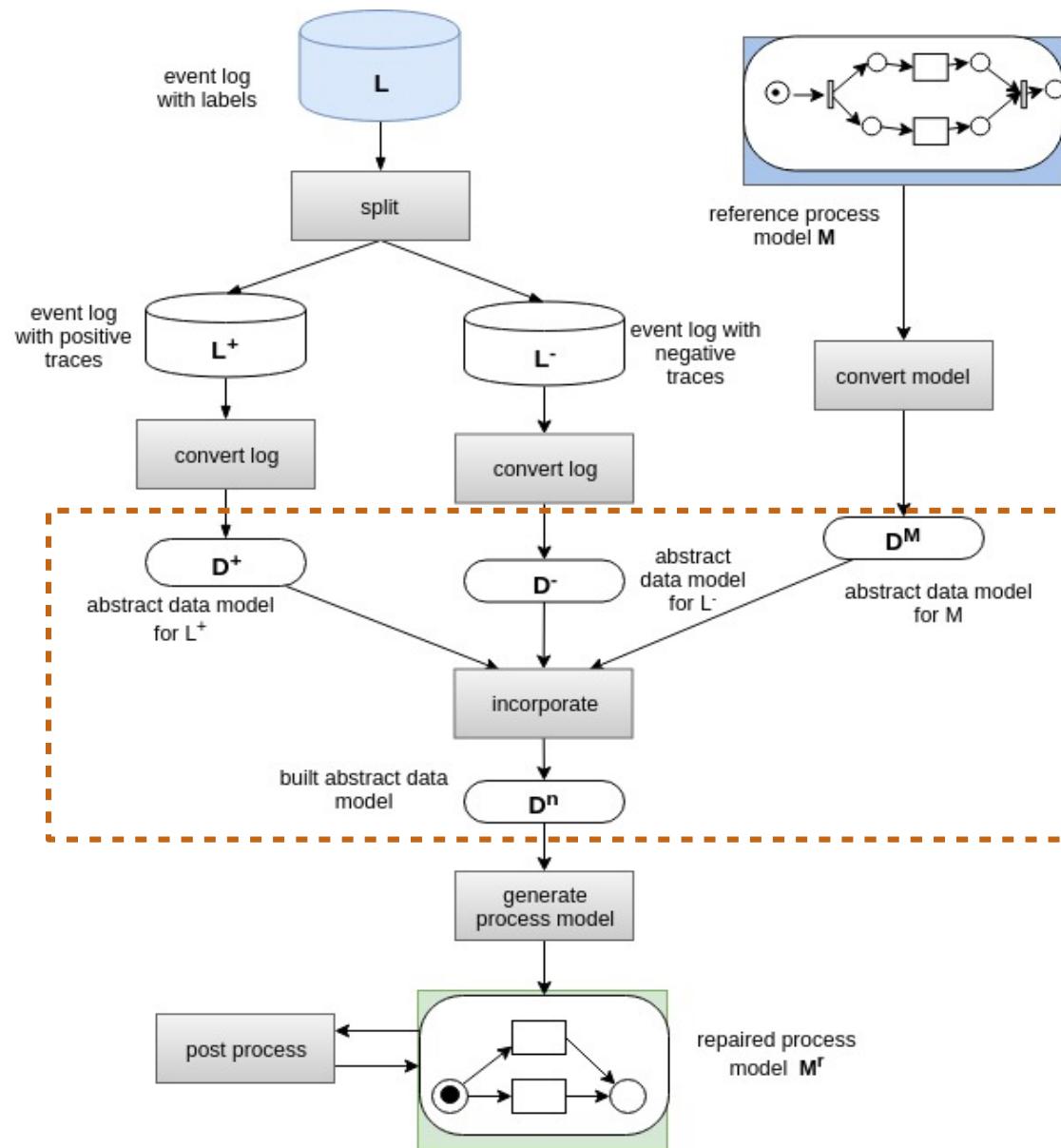
Unified dfg from event log



dfg from model

Unified dfg from model

Algorithm – data model



Incorporate Data Models

- Incorporate method**

- For any directly-follows relation

$$u^n(a, b) = u^M(a, b) + u^+(a, b) - u^-(a, b)$$

- For any start activity,

$$a \in A_{start}^M \cup A_{start}^+ \cup A_{start}^-, u^n(a) = u^M(a) + u^+(a) - u^-(a)$$

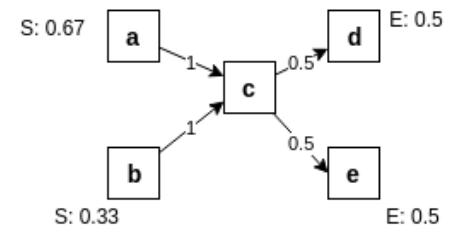
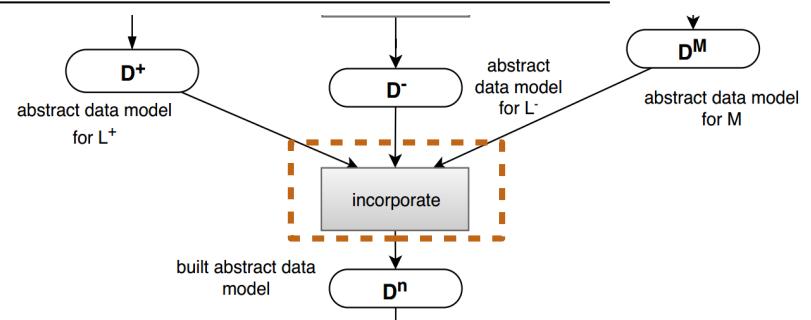
- For any end activity,

$$a \in A_{end}^M \cup A_{end}^+ \cup A_{end}^-, u^n(a) = u^M(a) + u^+(a) - u^-(a)$$

- Weighted value**

- Three control weights w^+, w^-, w^M

$$u_w^n(a, b) = w^M \cdot u^M(a, b) + w^+ \cdot u^+(a, b) - w^- \cdot u^-(a, b)$$

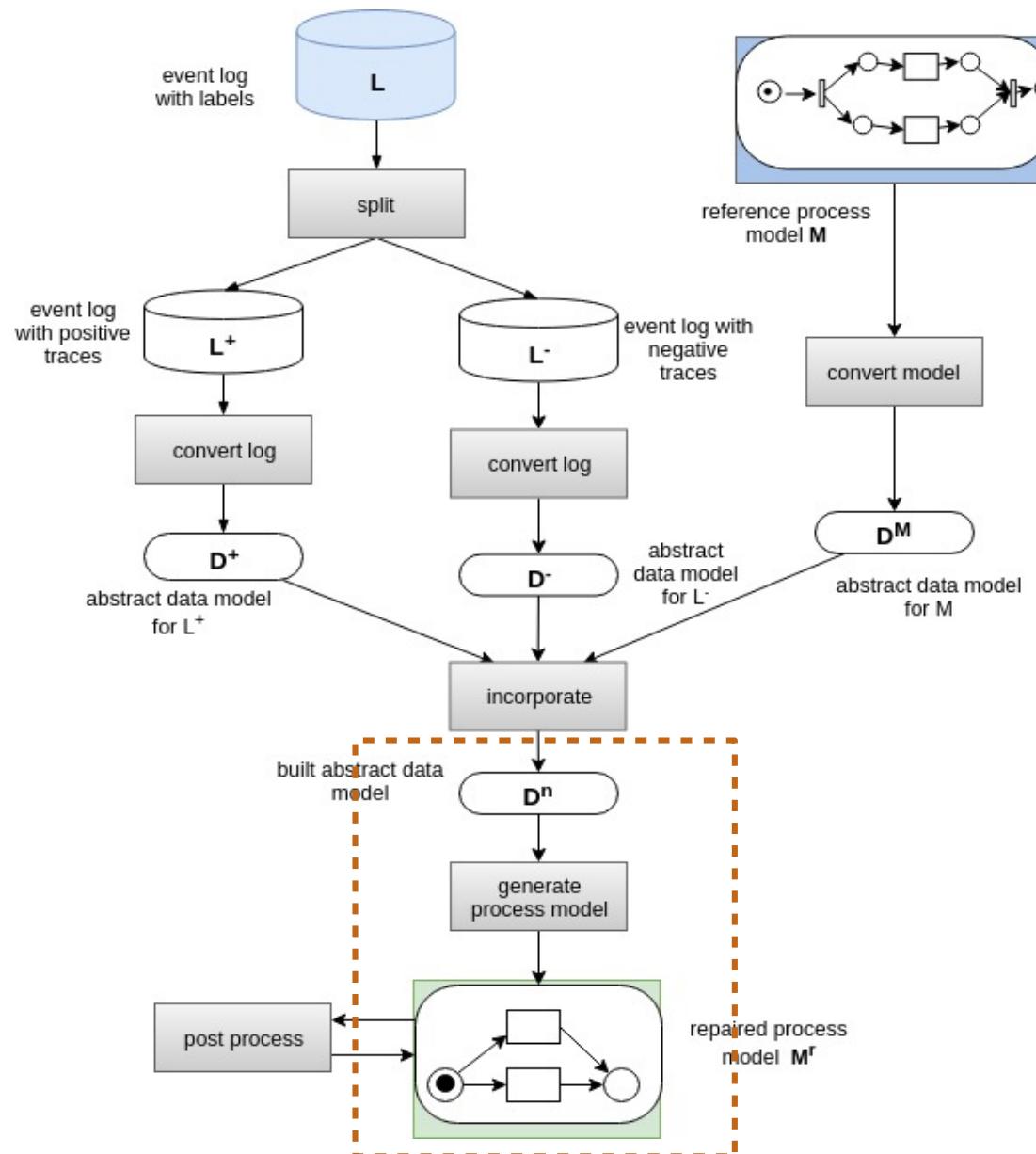


new unified dfg: D^n

$w^M = 1, w^+ = w^- = 0 \rightarrow$ Keep the reference model

$w^+ = 1, w^M = w^- = 0 \rightarrow$ Mine a new model from positive instances

Algorithm – data model

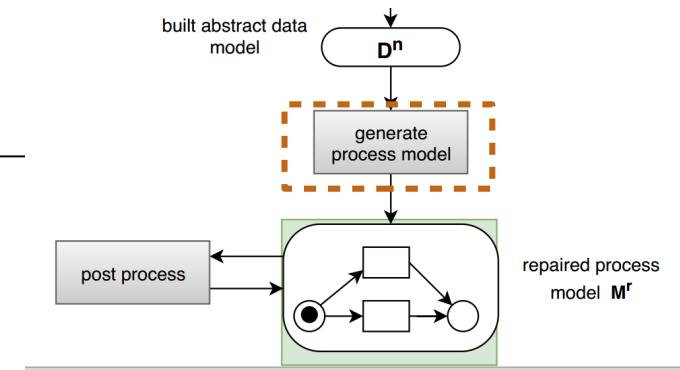
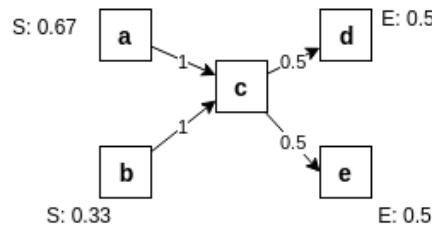


Generate Petri net

- Choose directly-follows relation

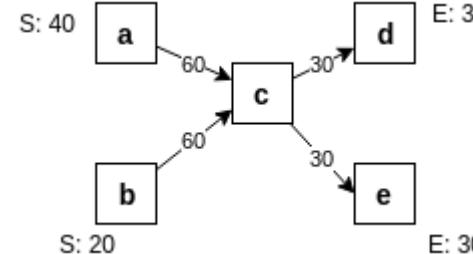
$$u_w^n(a, b) > t$$

- T=0



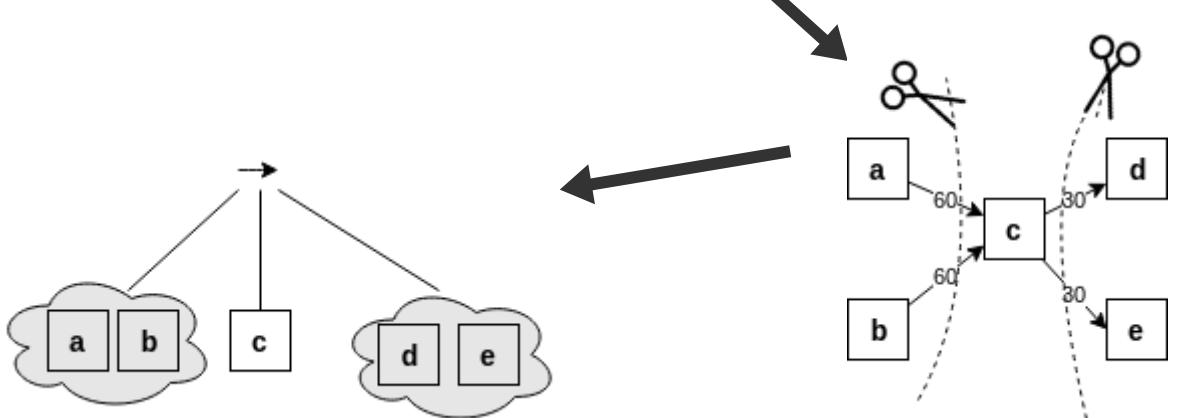
- Assign normal cardinality back

$$c^n(a, b) = u_w^n(a, b) \cdot (|L^+| + |L^-|)$$



- IM algorithm

- Directly-follows graph
- Process tree
- Petri net

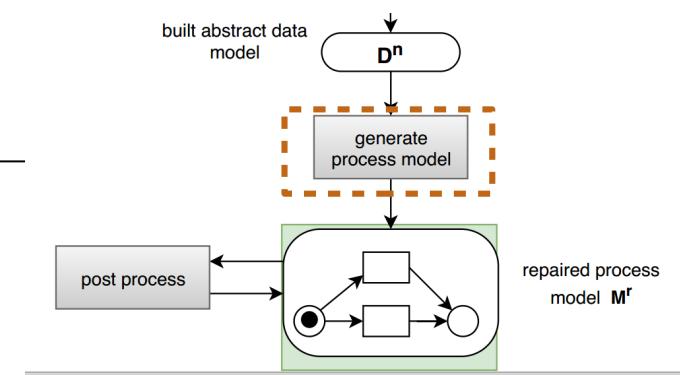
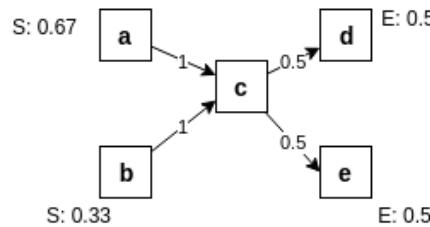


Generate Petri net

- Choose directly-follows relation

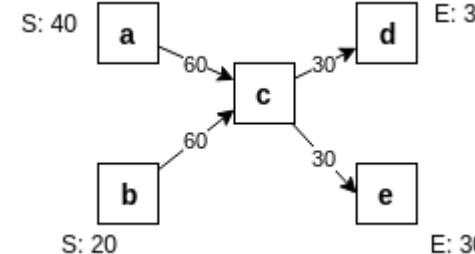
$$u_w^n(a, b) > t$$

- $T=0$



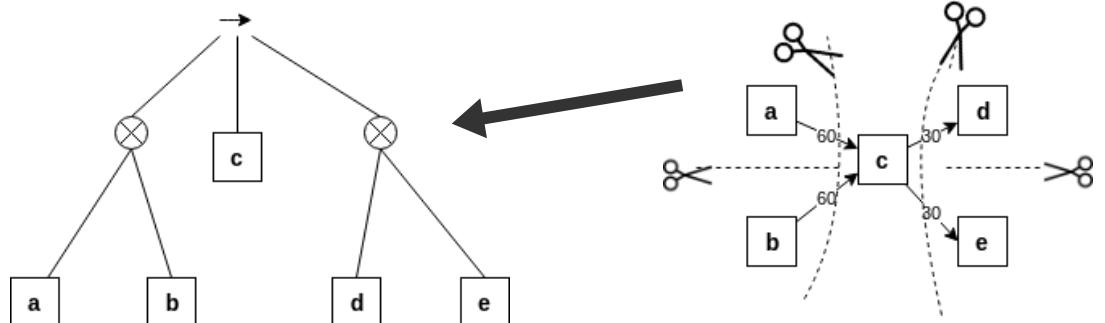
- Assign normal cardinality back

$$c^n(a, b) = u_w^n(a, b) \cdot (|L^+| + |L^-|)$$



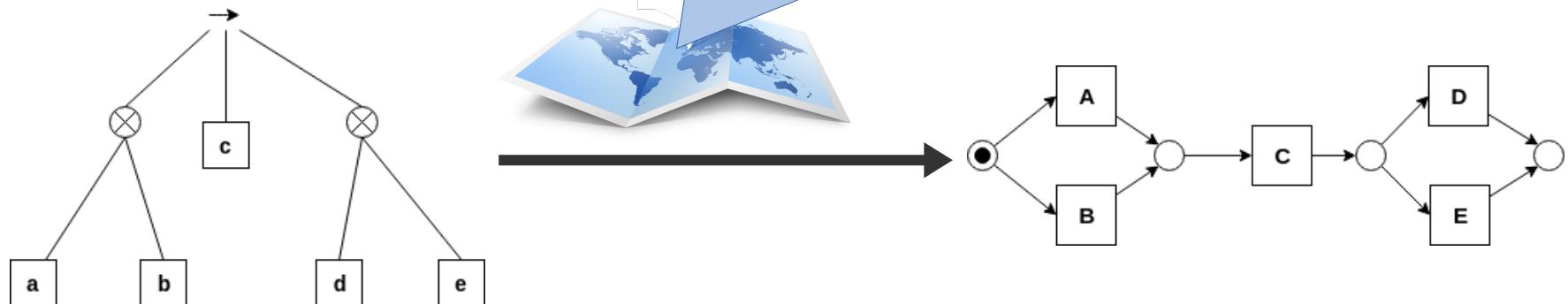
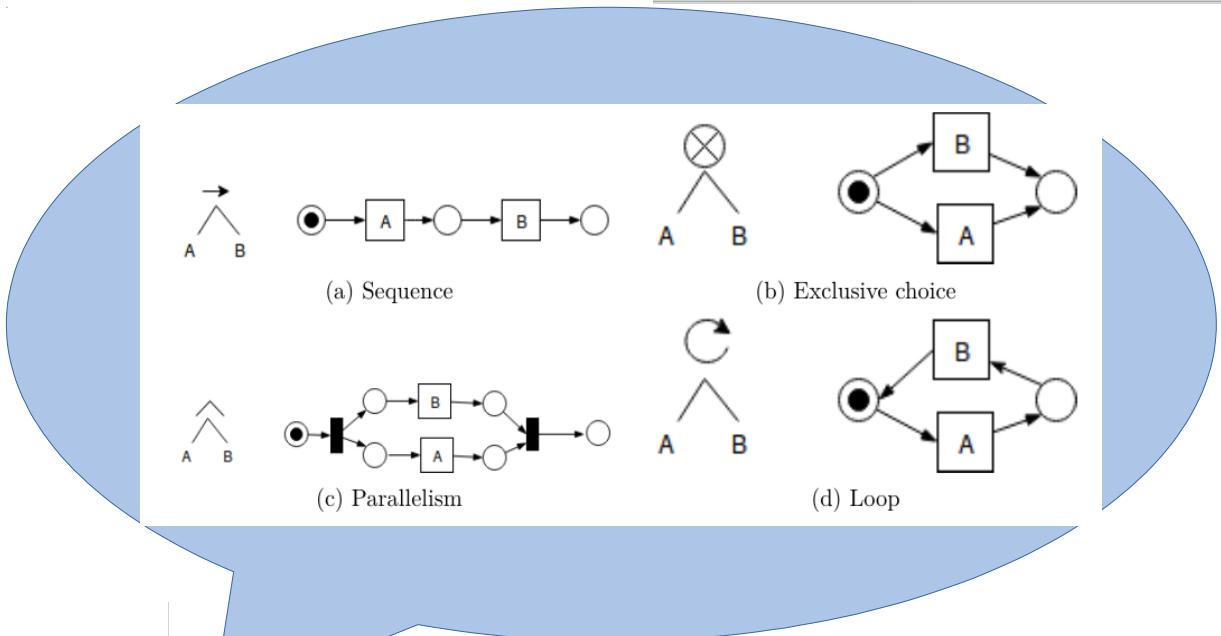
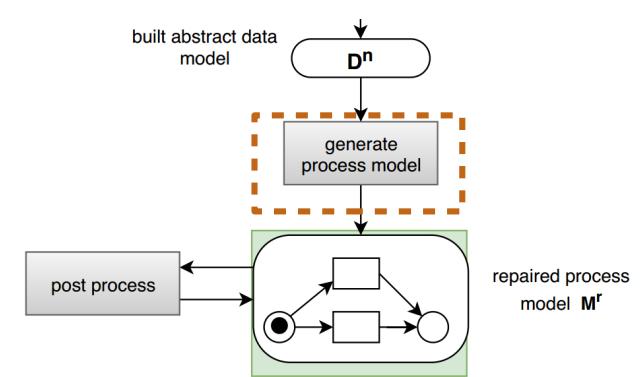
- IM algorithm

- Directly-follows graph
- Process tree
- Petri net



Generate Petri net

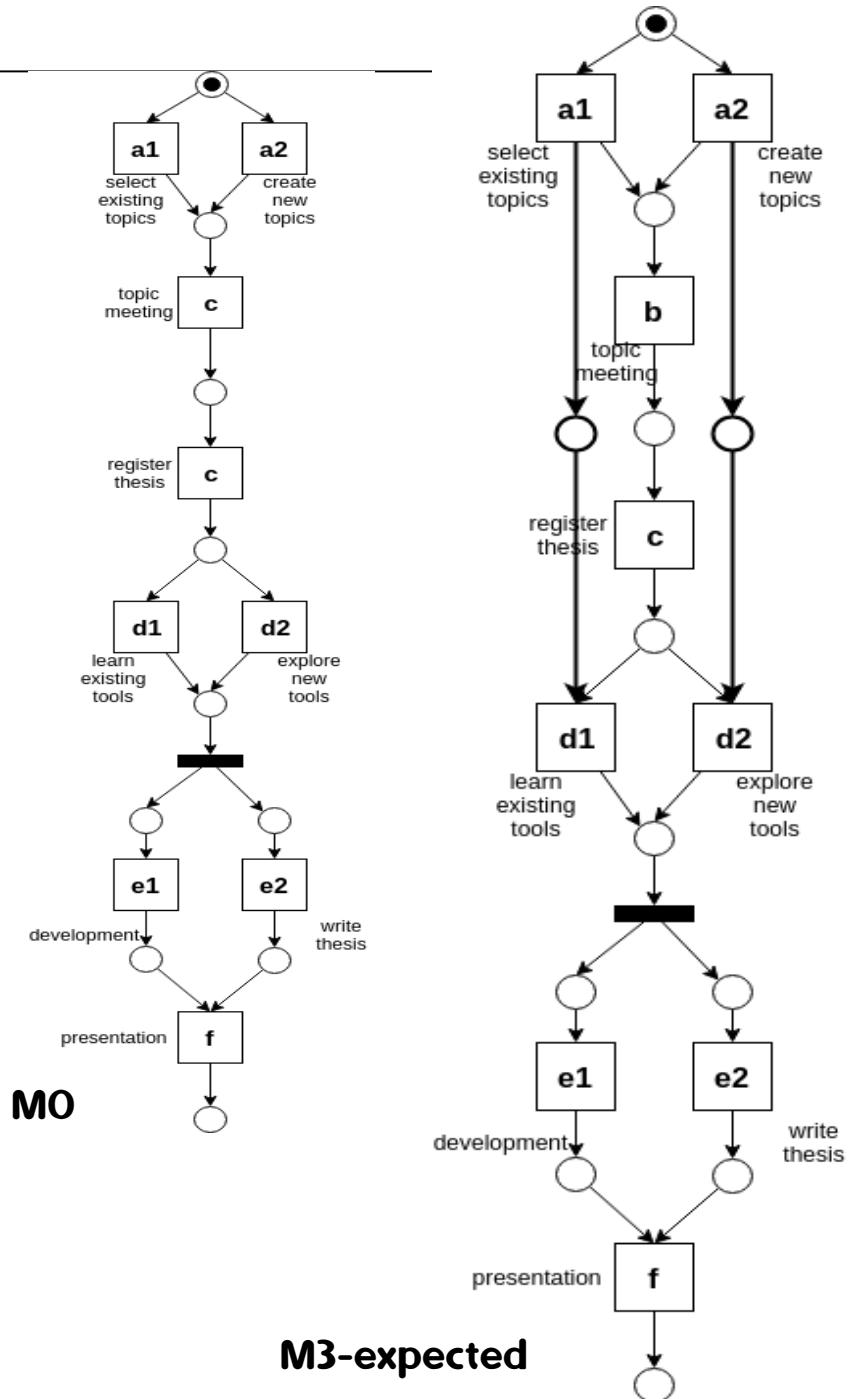
- Filter unified directly-follows relation
- Transform into normal dfg
- IM algorithm
 - Directly-follows graph
 - Process tree
 - Petri net



Post Process Petri net

- Long-term dependency
 - Choices dependency
 - Exclusive choices
 - Strong correlation

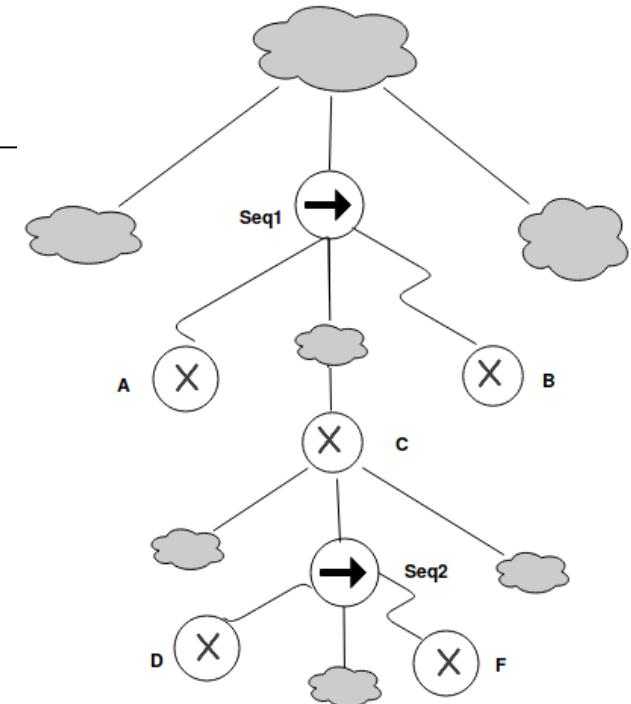
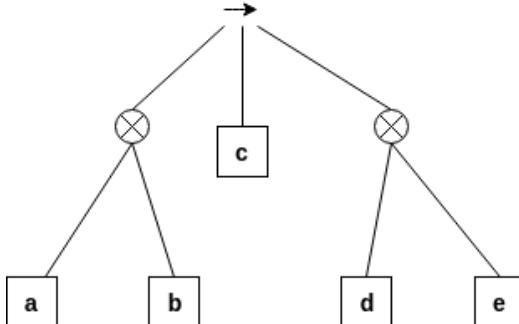
$$L_3 := \{< \mathbf{a1}, b, c, \mathbf{d1}, e1, e2, f >^{50, pos}, \\ < \mathbf{a2}, b, c, \mathbf{d2}, e1, e2, f >^{50, pos}; \\ < \mathbf{a1}, b, c, \mathbf{d2}, e1, e2, f >^{50, neg}, \\ < \mathbf{a2}, b, c, \mathbf{d1}, e1, e2, f >^{50, neg}\}$$



Post Process Petri net

- Long-term dependency

- Process tree as intermediate result
- Exclusive choices
 - ✓ xor blocks/branches
- In order
 - ✓ Least common ancestor is Seq
 - A < C < B, D < F
 - ✓ In same level
 - A,B,C pair
 - D,F pair
- Strong correlation



Post Process Petri net

- Long-term dependency
 - Strong correlation: frequently coexist

$$d(X_i, Y_j) = w^+ \cdot d^+(X_i, Y_j) - w^- \cdot d^-(X_i, Y_j) > t$$

$$d^+(X_i, Y_j) = \begin{cases} 0, & \text{if } \sum_{Y_k \in T} f_{L^+}(X_i, Y_k) = 0; \\ \frac{f_{L^+}(X_i, Y_j)}{\sum_{Y_k \in T} f_{L^+}(X_i, Y_k)}, & \text{otherwise} \end{cases}$$

$$d^-(X_i, Y_j) = \begin{cases} 0, & \text{if } \sum_{Y_k \in T} f_{L^-}(X_i, Y_k) = 0; \\ \frac{f_{L^-}(X_i, Y_j)}{\sum_{Y_k \in T} f_{L^-}(X_i, Y_k)}, & \text{otherwise} \end{cases}$$

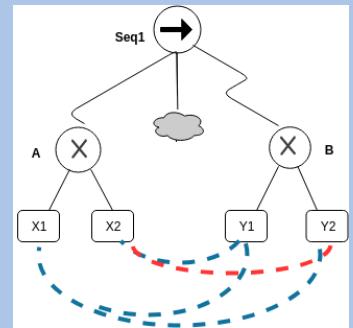
Frequency of multiple xor branches is
 $f_L(X_i, Y_j) = \sum_{\sigma \in L} |\{\sigma | \sigma \models X_i \wedge \sigma \models Y_j\}|$

Frequency of an xor branch X_i in an event log L is the count of traces which replay this xor branch,
 $f : X \rightarrow N, f_L(X) = \sum_{\sigma \in L} |\{\sigma | \sigma \models X\}|$

$$\begin{aligned} L_3 := & \{<\mathbf{a1}, b, c, \mathbf{d1}, e1, e2, f>^{50, pos}, \\ & <\mathbf{a2}, b, c, \mathbf{d2}, e1, e2, f>^{50, pos}; \\ & <\mathbf{a1}, b, c, \mathbf{d2}, e1, e2, f>^{50, neg}, \\ & <\mathbf{a2}, b, c, \mathbf{d1}, e1, e2, f>^{50, neg}\} \end{aligned}$$

$$\begin{aligned} w^+ &= 1, w^- = 1, t = 0 \\ d(a1, d1) &= d^+(a1, d1) - d^-(a1, d1) \\ &= 50/50 - 0 = 1; \\ d(a1, d2) &= d^+(a1, d2) - d^-(a1, d2) \\ &= 0 - 50/50 = -1; \\ d(a2, d1) &= -1; \\ d(a2, d2) &= 1. \end{aligned}$$

$$LT = \{a1 \rightsquigarrow d1, a2 \rightsquigarrow d2\}.$$

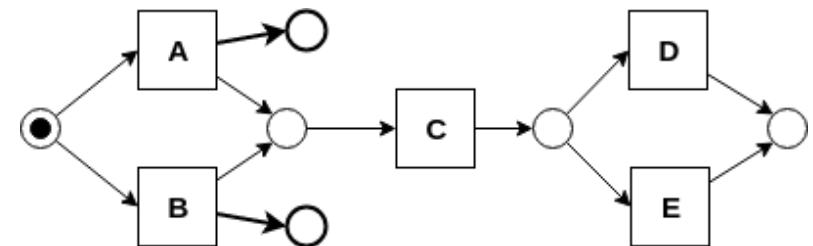
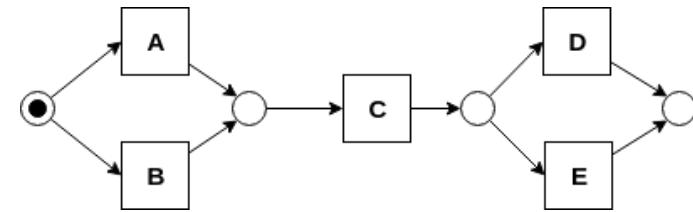


Algorithm – add long-term dependency

- express on Petri net
 - ✓ Add silent transition

– Add control place as post-place post after $S=\{A,B\}$

$$S = \{A, B\}, T = \{D, E\}, LT = \{A \rightsquigarrow D, A \rightsquigarrow E, B \rightsquigarrow E\}.$$

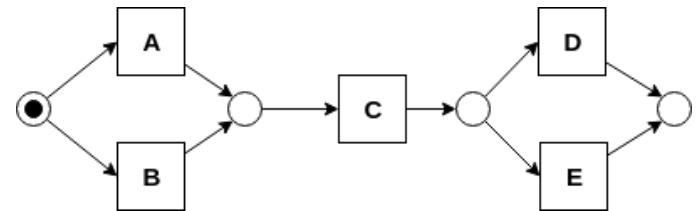


Algorithm – add long-term dependency

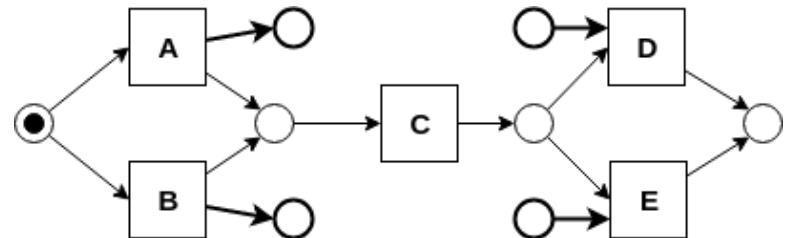
- How to express on Petri net

- ✓ Add silent transition
 - Add control place as post-place post after $S=\{A,B\}$

- Add control place as pre-place before $T=\{D,E\}$



$$LT = \{A \rightsquigarrow D, A \rightsquigarrow E, B \rightsquigarrow E\}.$$



Algorithm – add long-term dependency

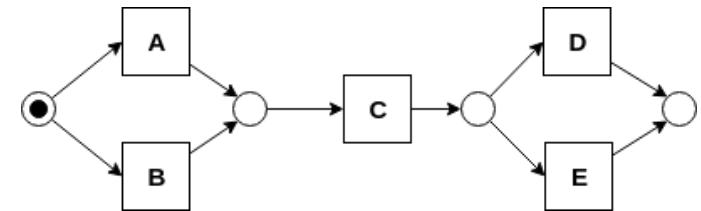
- How to express on Petri net

- ✓ Add silent transition

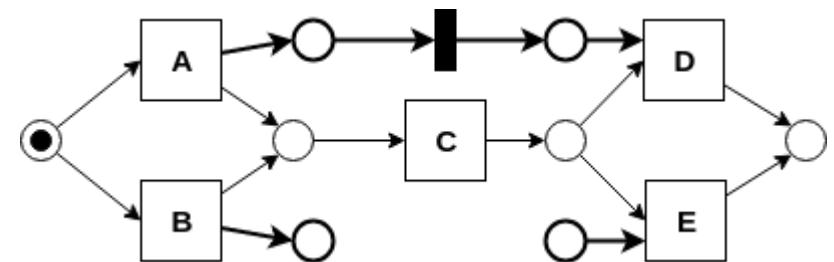
- Add control place as post-place post after $S=\{A,B\}$

- Add control place as pre-place before $T=\{D,E\}$

- Add silent transitions for each long-term dependency



$$LT = \{A \rightsquigarrow D, A \rightsquigarrow E, B \rightsquigarrow E\}.$$



Algorithm – add long-term dependency

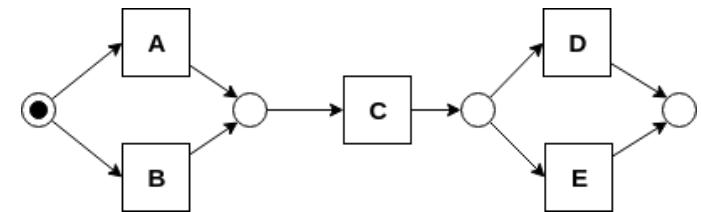
- How to express on Petri net

- ✓ Add silent transition

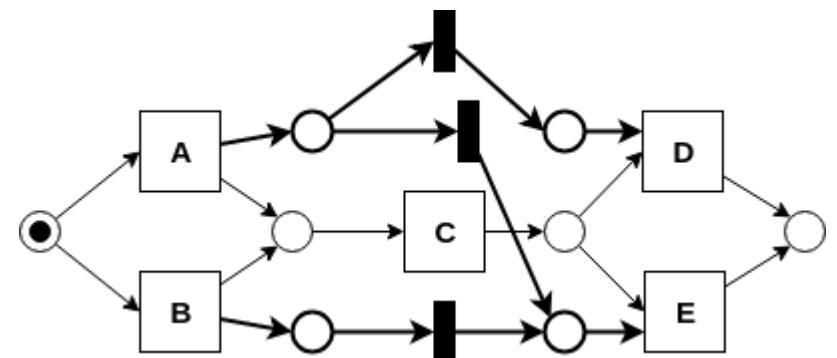
- Add control place as post-place post after S

- Add control place as pre-place before T

- Add silent transitions for each long-term dependency



$$LT = \{A \rightsquigarrow D, A \rightsquigarrow E, B \rightsquigarrow E\}.$$



Algorithm – add long-term dependency

- Long-term dependency Situations

1. $LT = \{A \rightsquigarrow D, A \rightsquigarrow E, B \rightsquigarrow D, B \rightsquigarrow E\}$.

$LT_S = \{A, B\}, LT_T = \{D, E\}, |LT| = |S| \cdot |T|$.

$$LT_S := \{X_i \mid \exists Y_j, X_i \rightsquigarrow Y_j \in LT\}$$

$$LT_T := \{Y_j \mid \exists X_i, X_i \rightsquigarrow Y_j \in LT\}$$

2. $LT = \{A \rightsquigarrow D, A \rightsquigarrow E, B \rightsquigarrow E\}$.

$LT_S = \{A, B\}, LT_T = \{D, E\} LT_S = S$ and $LT_T = T, |LT| < |S| \cdot |T|$.

3. $LT = \{A \rightsquigarrow D, B \rightsquigarrow E\}$.

$LT_S = \{A, B\}, LT_T = \{D, E\} LT_S = S$ and $LT_T = T, |LT| < |S| \cdot |T|$.

4. $LT = \{A \rightsquigarrow D, B \rightsquigarrow D\}$.

$LT_S = S, LT_T \subsetneq T$.

5. $LT = \{A \rightsquigarrow D, A \rightsquigarrow E\}$.

$LT_S \subsetneq S, LT_T = T$.

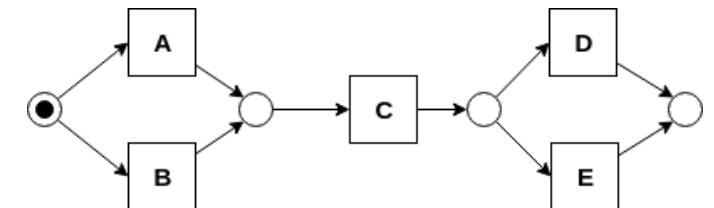
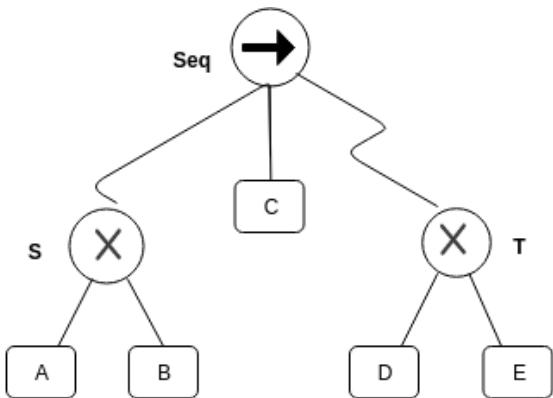
6. $LT = \{A \rightsquigarrow E\}$.

$LT_S \subsetneq S, LT_T \subsetneq T$.

7. $LT = \emptyset$

- Situation 1 is full dependency ==> no consideration

- Situation 7 is empty. ==> no consideration



Algorithm – add long-term dependency

- Long-term dependency Situations

1. $LT = \{A \rightsquigarrow D, A \rightsquigarrow E, B \rightsquigarrow D, B \rightsquigarrow E\}$.

$LT_S = \{A, B\}, LT_T = \{D, E\}, |LT| = |S| \cdot |T|$.

2. $LT = \{A \rightsquigarrow D, A \rightsquigarrow E, B \rightsquigarrow E\}$.

$LT_S = \{A, B\}, LT_T = \{D, E\} LT_S = S$ and $LT_T = T, |LT| < |S| \cdot |T|$.

3. $LT = \{A \rightsquigarrow D, B \rightsquigarrow E\}$.

$LT_S = \{A, B\}, LT_T = \{D, E\} LT_S = S$ and $LT_T = T, |LT| < |S| \cdot |T|$.

4. $LT = \{A \rightsquigarrow D, B \rightsquigarrow D\}$.

$LT_S = S, LT_T \subsetneq T$.

5. $LT = \{A \rightsquigarrow D, A \rightsquigarrow E\}$.

$LT_S \subsetneq S, LT_T = T$.

6. $LT = \{A \rightsquigarrow E\}$.

$LT_S \subsetneq S, LT_T \subsetneq T$.

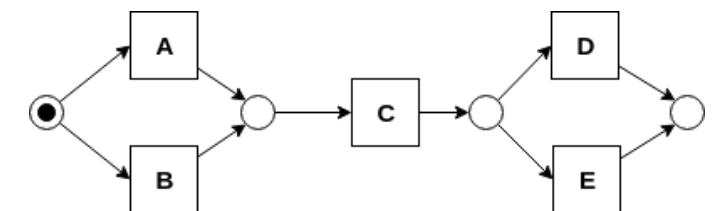
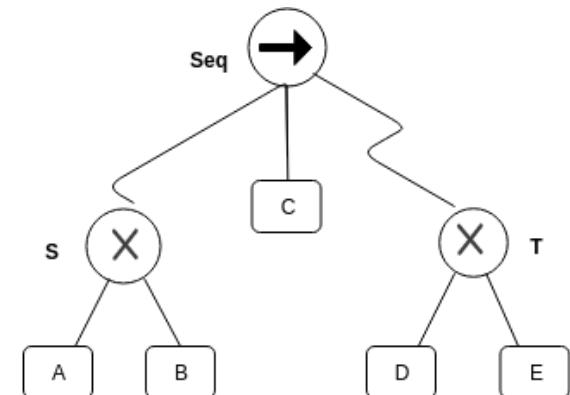
7. $LT = \emptyset$

- Situation 1 is full dependency ==> no consideration

- Situation 7 is empty. ==> no consideration

$$LT_S := \{X_i \mid \exists Y_j, X_i \rightsquigarrow Y_j \in LT\}$$

$$LT_T := \{Y_j \mid \exists X_i, X_i \rightsquigarrow Y_j \in LT\}$$



Algorithm – add long-term dependency

- Long-term dependency Situations

1. $LT = \{A \rightsquigarrow D, A \rightsquigarrow E, B \rightsquigarrow D, B \rightsquigarrow E\}$.

$LT_S = \{A, B\}, LT_T = \{D, E\}, |LT| = |S| \cdot |T|$.

2. $LT = \{A \rightsquigarrow D, A \rightsquigarrow E, B \rightsquigarrow E\}$.

$LT_S = \{A, B\}, LT_T = \{D, E\} LT_S = S$ and $LT_T = T, |LT| < |S| \cdot |T|$.

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$LT_S = \{A, B\}, LT_T = \{D, E\} LT_S = S$ and $LT_T = T, |LT| < |S| \cdot |T|$.

4. $LT = \{A \rightsquigarrow D, B \rightsquigarrow D\}$.

$LT_S = S, LT_T \subsetneq T$.

5. $LT = \{A \rightsquigarrow D, A \rightsquigarrow E\}$.

$LT_S \subsetneq S, LT_T = T$.

6. $LT = \{A \rightsquigarrow E\}$.

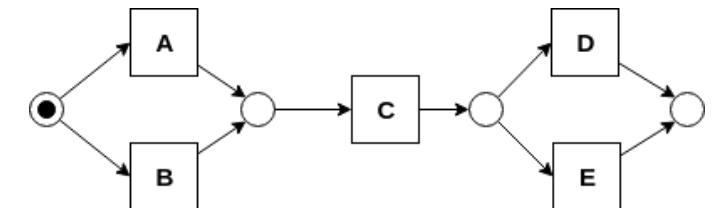
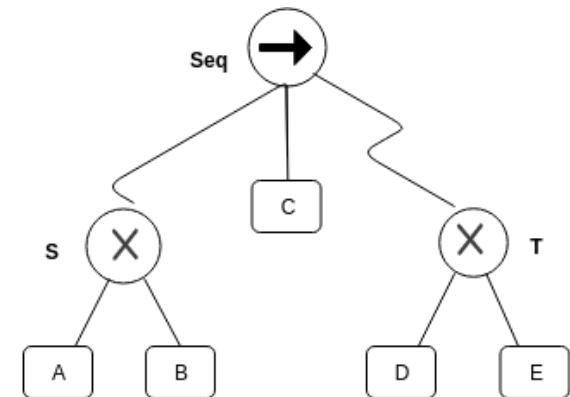
$LT_S \subsetneq S, LT_T \subsetneq T$.

7. $LT = \emptyset$

- Situation 1 is full dependency ==> no consideration
- Situation 7 is empty. ==> no consideration

$$LT_S := \{X_i \mid \exists Y_j, X_i \rightsquigarrow Y_j \in LT\}$$

$$LT_T := \{Y_j \mid \exists X_i, X_i \rightsquigarrow Y_j \in LT\}$$



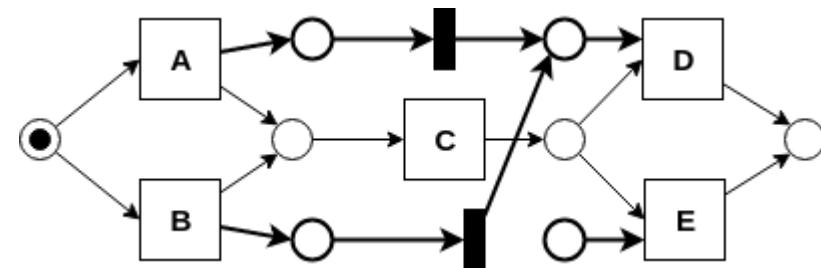
Algorithm – add long-term dependency

- Express on Petri net

4. $LT = \{A \rightsquigarrow D, B \rightsquigarrow D\}.$
 $LT_S = S, LT_T \subsetneq T.$

5. $LT = \{A \rightsquigarrow D, A \rightsquigarrow E\}.$
 $LT_S \subsetneq S, LT_T = T.$

6. $LT = \{A \rightsquigarrow E\}.$
 $LT_S \subsetneq S, LT_T \subsetneq T.$



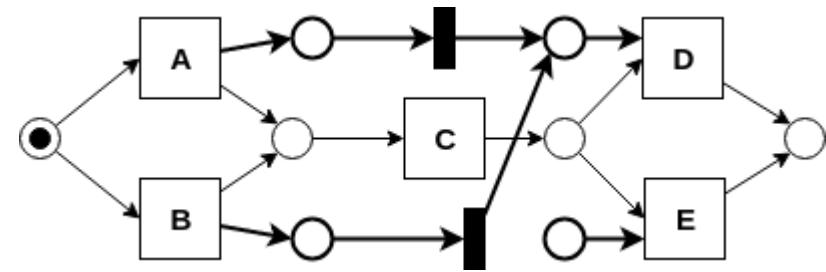
Algorithm – add long-term dependency

- Express on Petri net

4. $LT = \{A \rightsquigarrow D, B \rightsquigarrow D\}.$
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 $LT_S \subsetneq S, LT_T = T.$

6. $LT = \{A \rightsquigarrow E\}.$
 $LT_S \subsetneq S, LT_T \subsetneq T.$



Soundness

- ✓ Safeness.
- ✓ Proper completion.
- ✓ Option to complete.
- ✓ No dead parts.

Petri net – soundness

Soundness

- ✓ Safeness.
Places cannot hold multiple tokens at the same time.
- ✓ Proper completion.
If the sink place is marked, all other places are empty.
- ✓ Option to complete.
It is always possible to reach the final marking from any reachable marking.
- ✓ No dead parts.
For any transition, there exists a path from source to sink place through it.

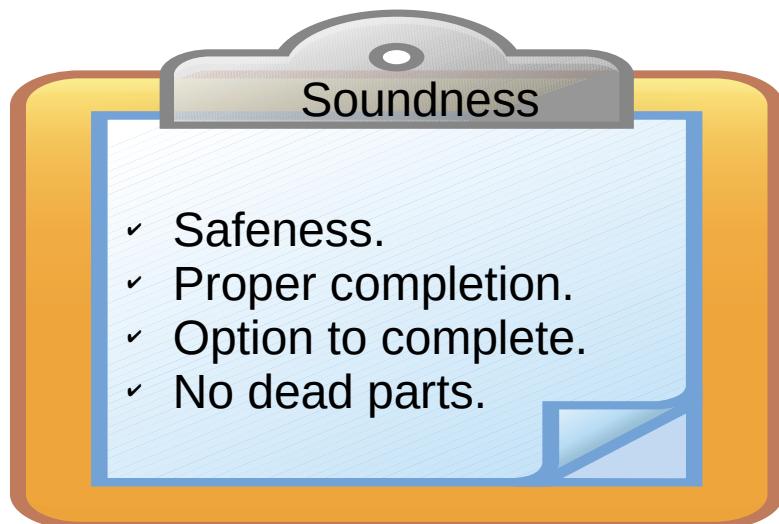
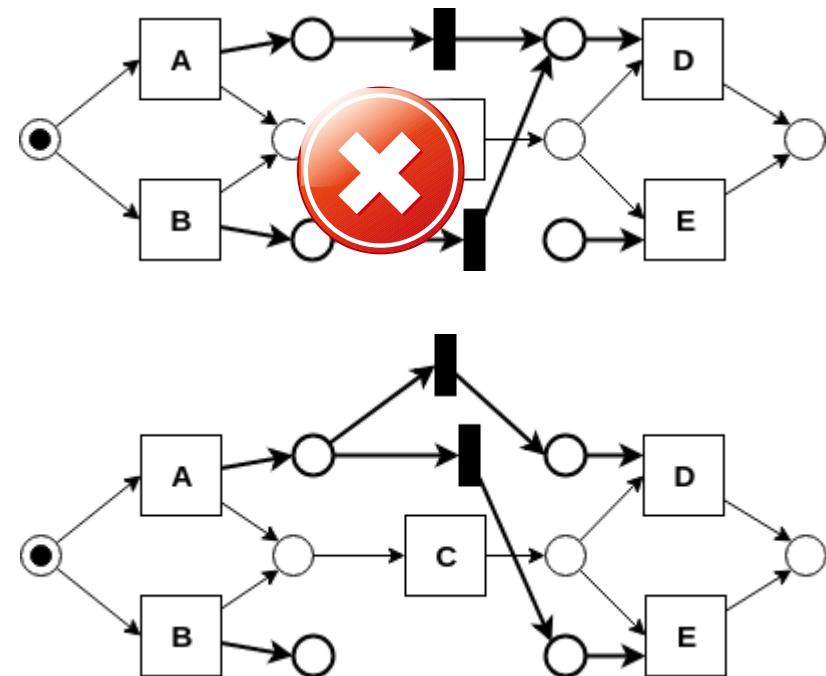
Algorithm – add long-term dependency

- Express on Petri net

4. $LT = \{A \rightsquigarrow D, B \rightsquigarrow D\}$.
 $LT_S = S, LT_T \subsetneq T$.

5. $LT = \{A \rightsquigarrow D, A \rightsquigarrow E\}$.
 $LT_S \subsetneq S, LT_T = T$.

6. $LT = \{A \rightsquigarrow E\}$.
 $LT_S \subsetneq S, LT_T \subsetneq T$.



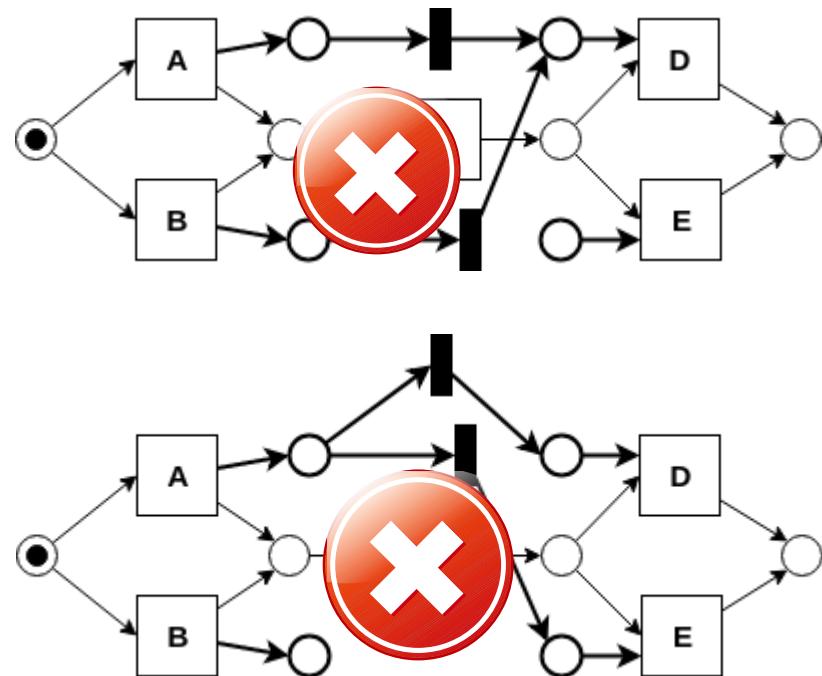
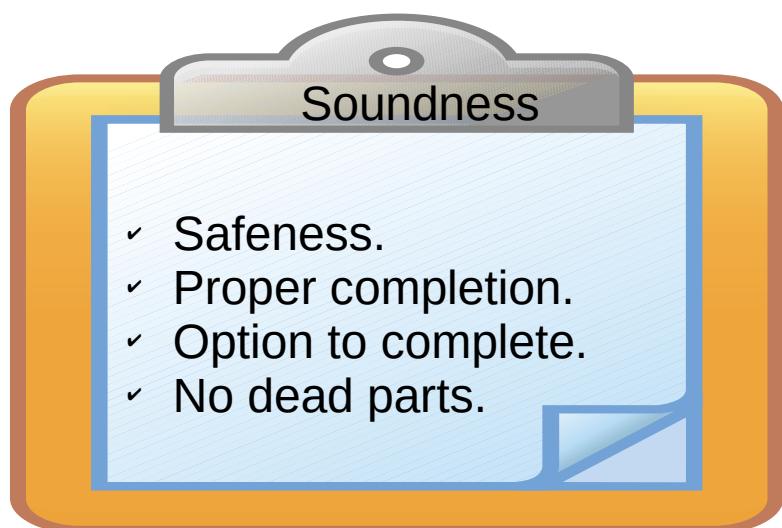
Algorithm – add long-term dependency

- Express on Petri net

4. $LT = \{A \rightsquigarrow D, B \rightsquigarrow D\}$.
 $LT_S = S, LT_T \subsetneq T$.

5. $LT = \{A \rightsquigarrow D, A \rightsquigarrow E\}$.
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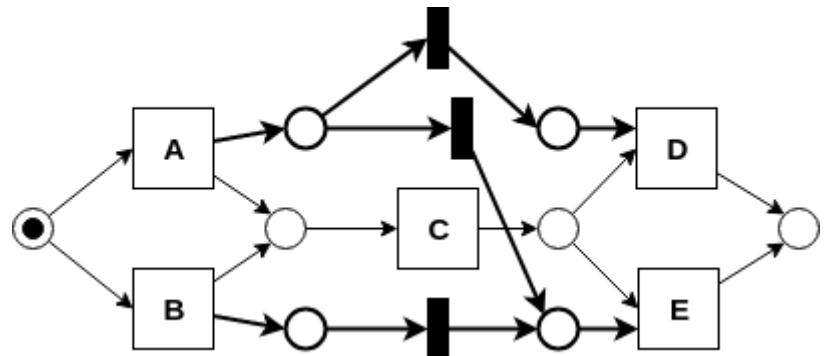


Soundness proof

Given $S = \{X_1, X_2, \dots, X_m\}$ and $T = \{Y_1, Y_2, \dots, Y_n\}$ with $LT = \{X_i \rightsquigarrow Y_j \mid 1 \leq i \leq m, 1 \leq j \leq n\}$. W.l.o.g., X_i is fired.

The marking distribution is

$$M(p_{X_i}) = 1; \quad \forall p_{X_{i'}} \in P_S, i' \neq i, M(p_{X_{i'}}) = 0$$



Type 1 $LT_S = S, LT_T = T$

soundness

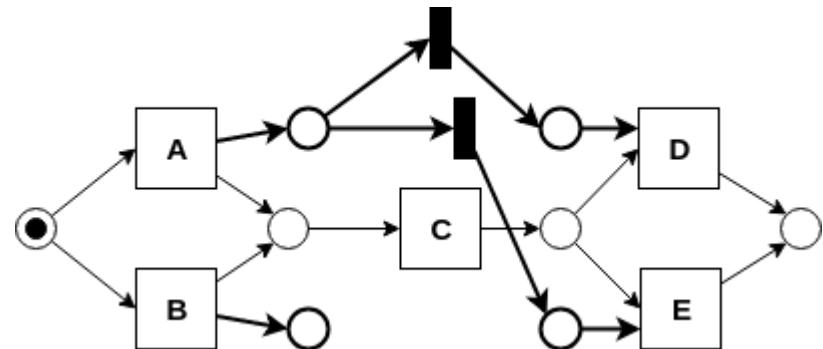
- ✓ Safeness.
 $\sum M(p_{X_i}) \leq 1, \sum M(p_{Y_j}) \leq 1$
- ✓ Proper completion.
After firing Y_j , $\sum M(p_{X_i}) = 0, \sum M(p_{Y_j}) = 0$
- ✓ Option to complete & No dead parts.
 $\forall X_i \in S$ is enabled at beginning
 $\forall X_i \in S$, since $LT_S = S \Rightarrow \exists Y_j \in T, X_i \rightsquigarrow Y_j$,
 ϵ is enabled with $p_{X_i} \rightarrow \epsilon \rightarrow p_{Y_j}$
 $\forall Y_j \in T$, since $LT_T = T \Rightarrow \exists X_i \in S, X_i \rightsquigarrow Y_j$

Soundness proof

Given $S = \{X_1, X_2, \dots, X_m\}$ and $T = \{Y_1, Y_2, \dots, Y_n\}$ with $LT = \{X_i \rightsquigarrow Y_j \mid 1 \leq i \leq m, 1 \leq j \leq n\}$. W.l.o.g., X_i is fired.

The marking distribution is

$$M(p_{X_i}) = 1; \quad \forall p_{X_{i'}} \in P_S, i' \neq i, M(p_{X_{i'}}) = 0$$



Type 2 $LT_S \subsetneq S, LT_T \subsetneq T$

soundness

- ## ✓ Safeness.

$$\sum M(p_{X_i}) \leq 1, \sum M(p_{Y_j}) \leq 1$$

- ✓ Proper completion.

After firing Y_j , $\sum M(p_{X_i}) = 0$, $\sum M(p_{Y_j}) = 0$

- ✓ Option to complete & No dead parts.

$\forall X_i \in S$ is enabled at beginning



if $LT_S \subsetneq S$, $\Rightarrow \exists X_i \in S, X_i \notin LT_S$, token remains

if $LT_T \subsetneq T$, $\Rightarrow \exists Y_i \in T, Y_i \notin LT_T$, token misses

Algorithm – add long-term dependency

- Long-term dependency Situations

1. $LT = \{A \rightsquigarrow D, A \rightsquigarrow E, B \rightsquigarrow D, B \rightsquigarrow E\}$.

$LT_S = \{A, B\}, LT_T = \{D, E\}, |LT| = |S| \cdot |T|$.

2. $LT = \{A \rightsquigarrow D, A \rightsquigarrow E, B \rightsquigarrow E\}$.

$LT_S = \{A, B\}, LT_T = \{D, E\} LT_S = S$ and $LT_T = T, |LT| < |S| \cdot |T|$.

3. $LT = \{A \rightsquigarrow D, B \rightsquigarrow E\}$.

$LT_S = \{A, B\}, LT_T = \{D, E\} LT_S = S$ and $LT_T = T, |LT| < |S| \cdot |T|$.

4. $LT = \{A \rightsquigarrow D, B \rightsquigarrow D\}$.

$LT_S = S, LT_T \subsetneq T$.

5. $LT = \{A \rightsquigarrow D, A \rightsquigarrow E\}$.

$LT_S \subsetneq S, LT_T = T$.

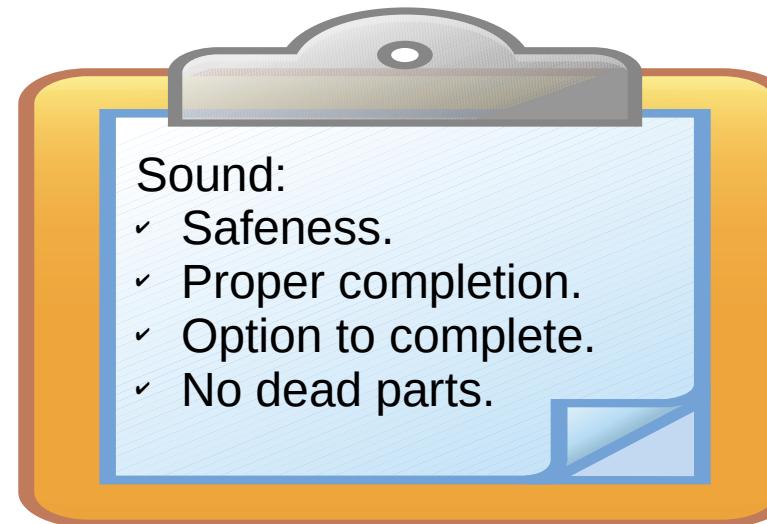
6. $LT = \{A \rightsquigarrow E\}$.

$LT_S \subsetneq S, LT_T \subsetneq T$.

7. $LT = \emptyset$

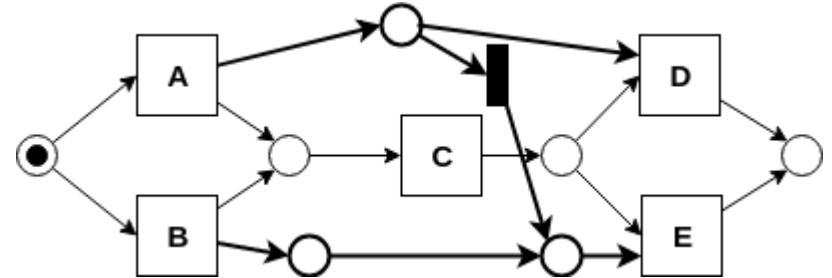
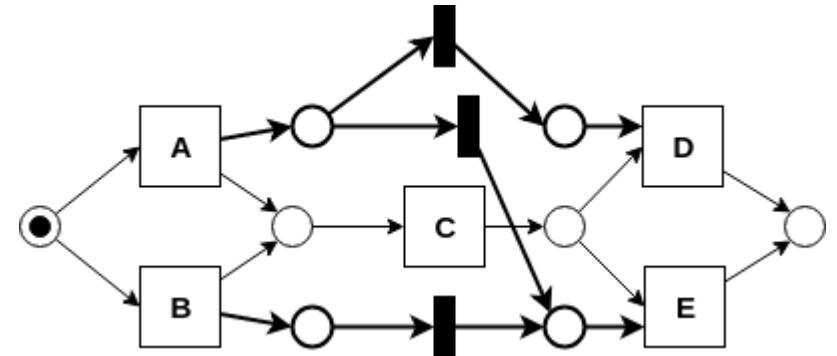
– Consider only

$$LT_S = S, LT_T = T, |LT| < |S| \cdot |T|$$

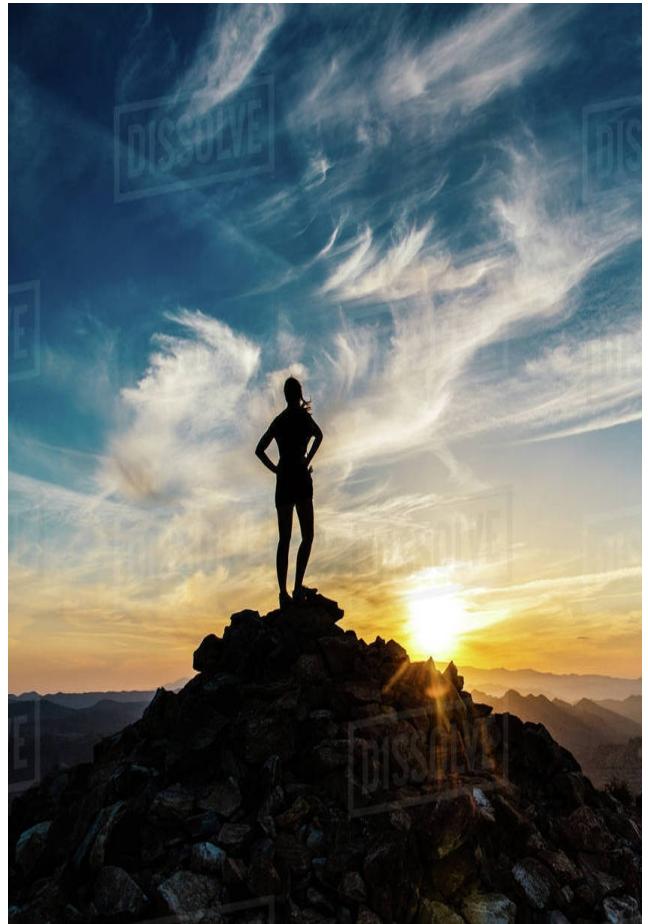


Post process

- Delete redundant silent transitions

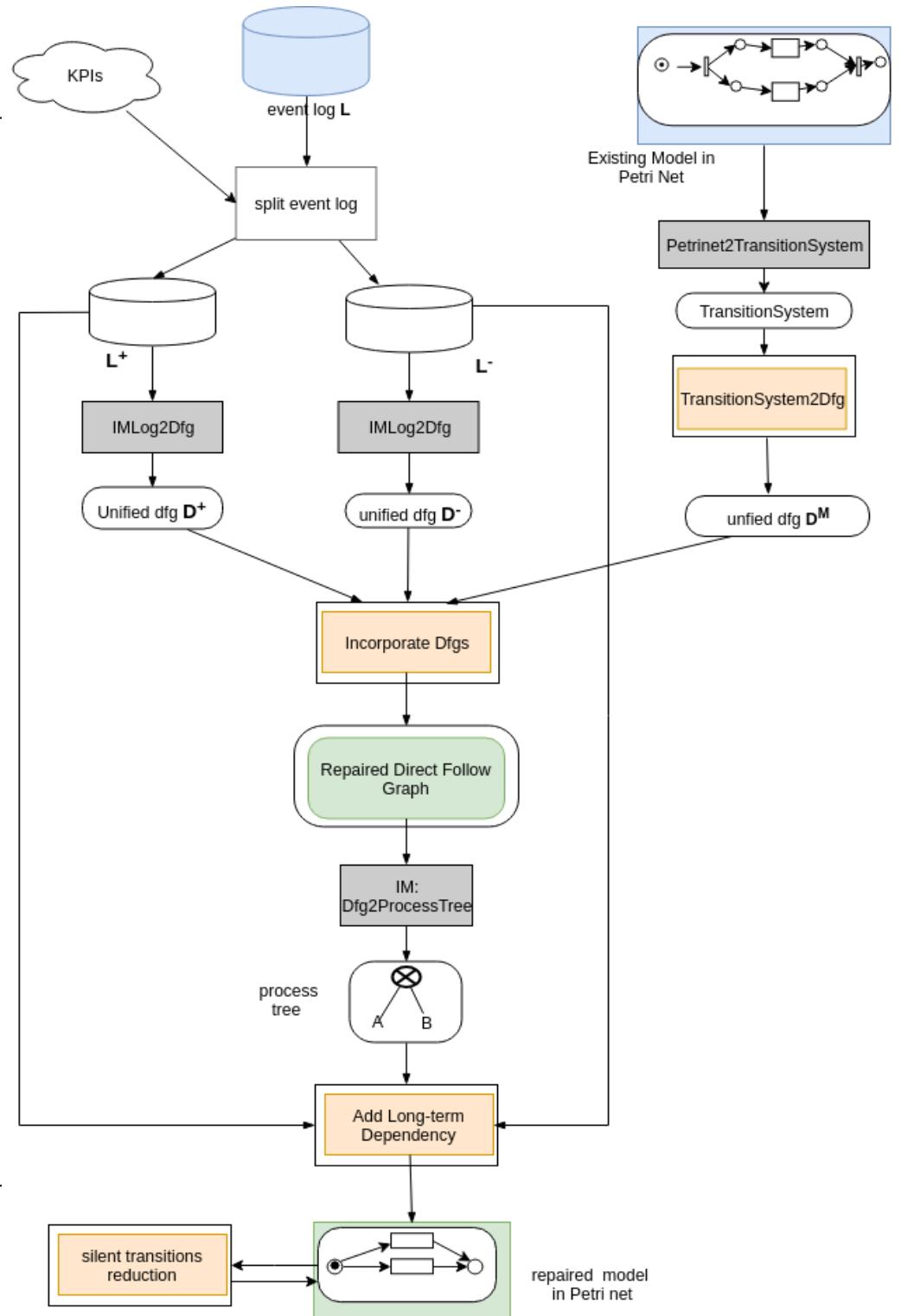


Algorithm – architecture



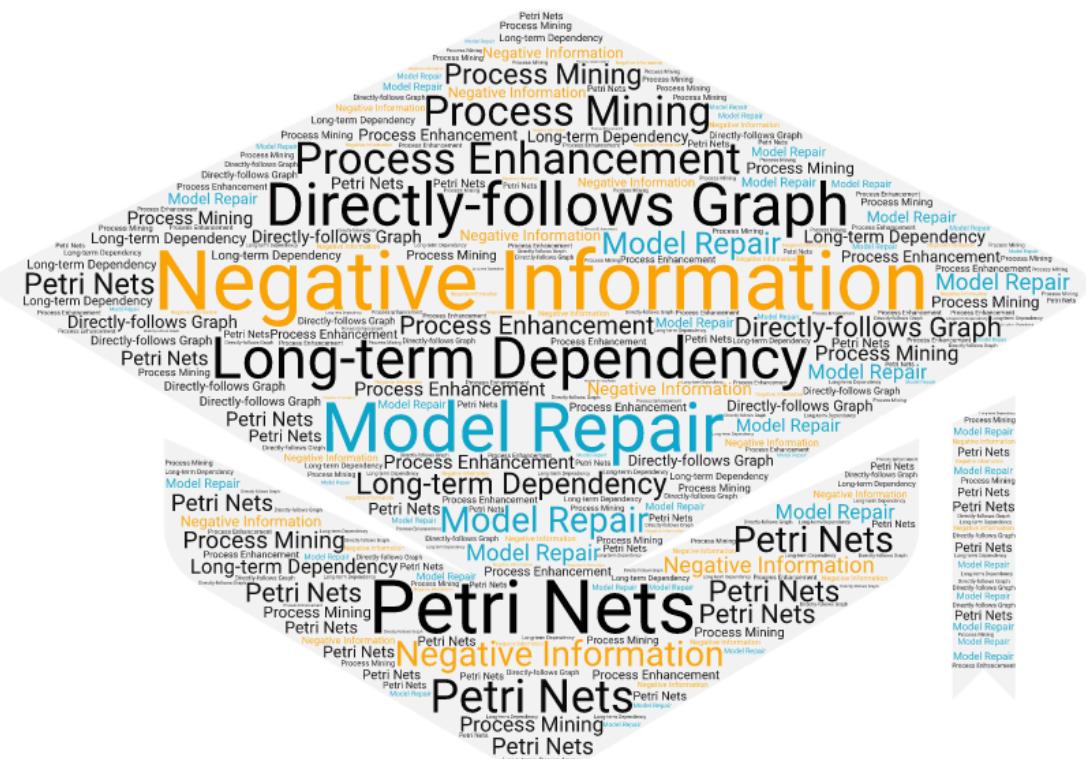
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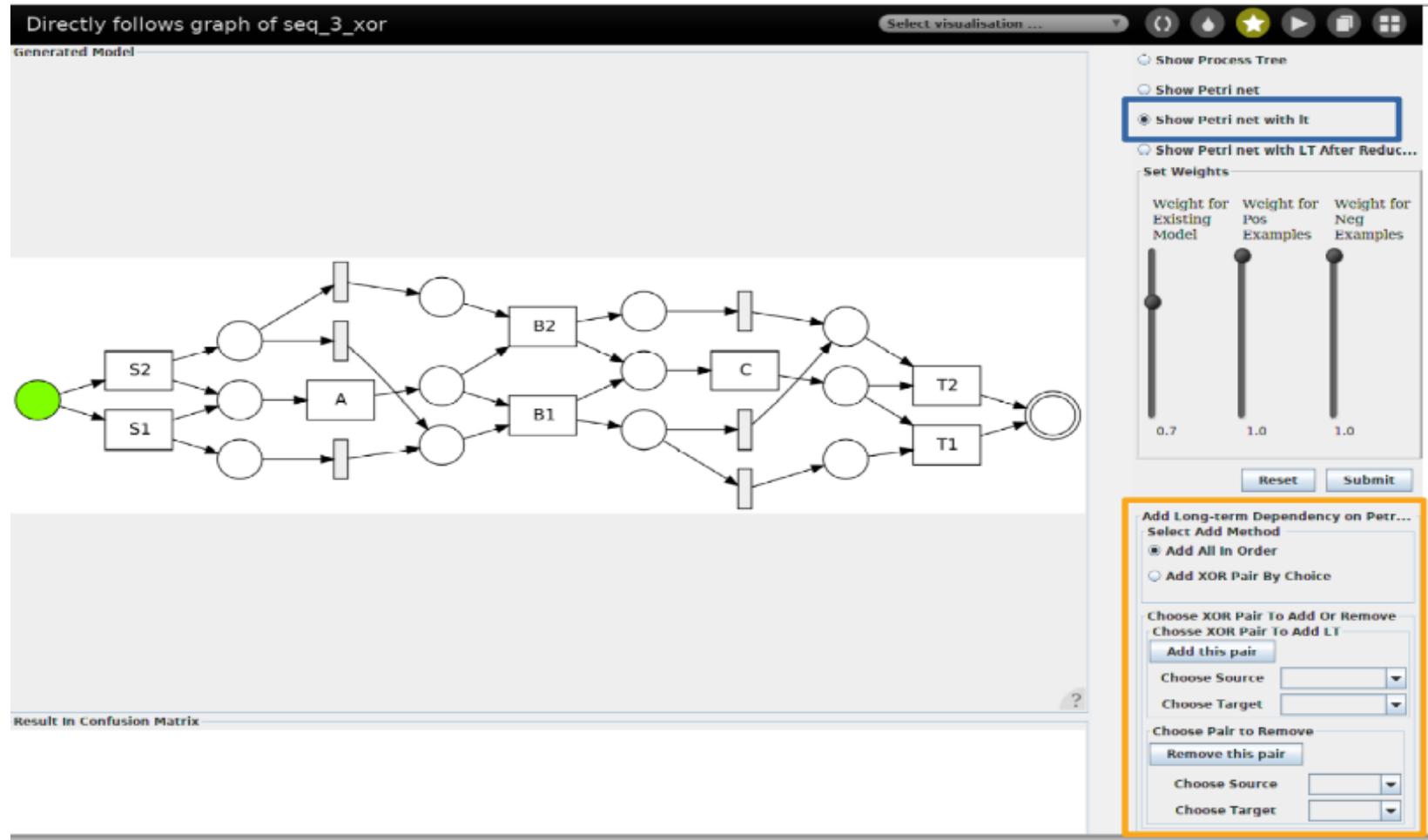


Outline

- Motivation for Research
 - Problem Definition
 - Approach
 - Demo Show
 - ProM
 - KNIME
 - Evaluation
 - Conclusion

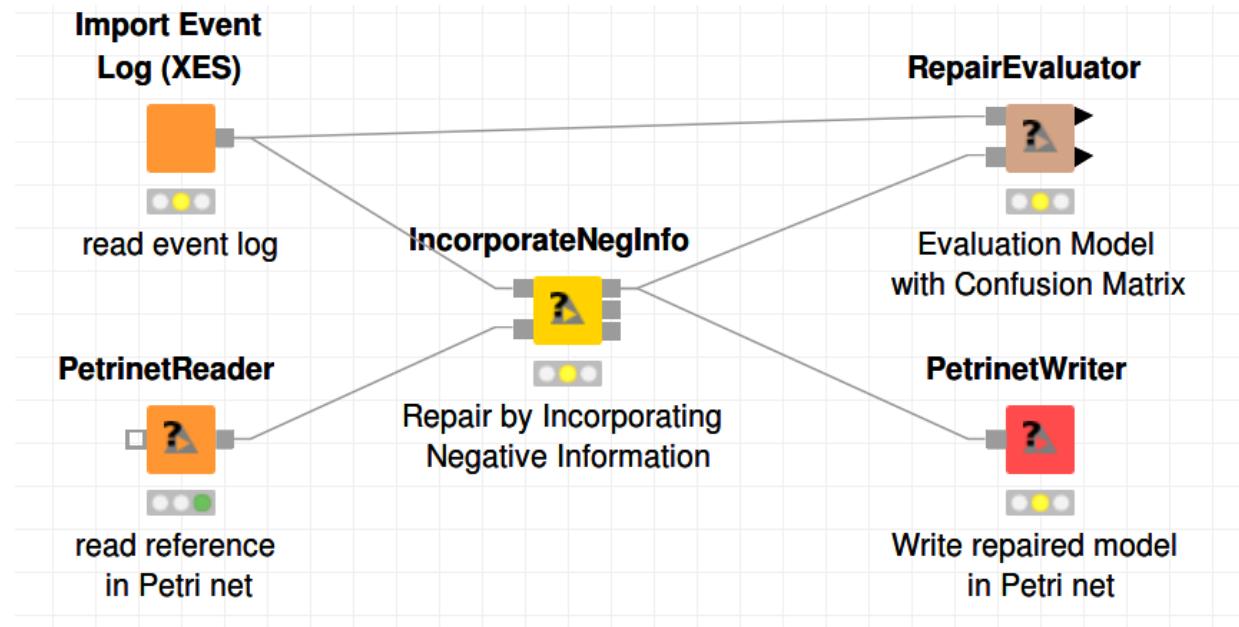


Demo



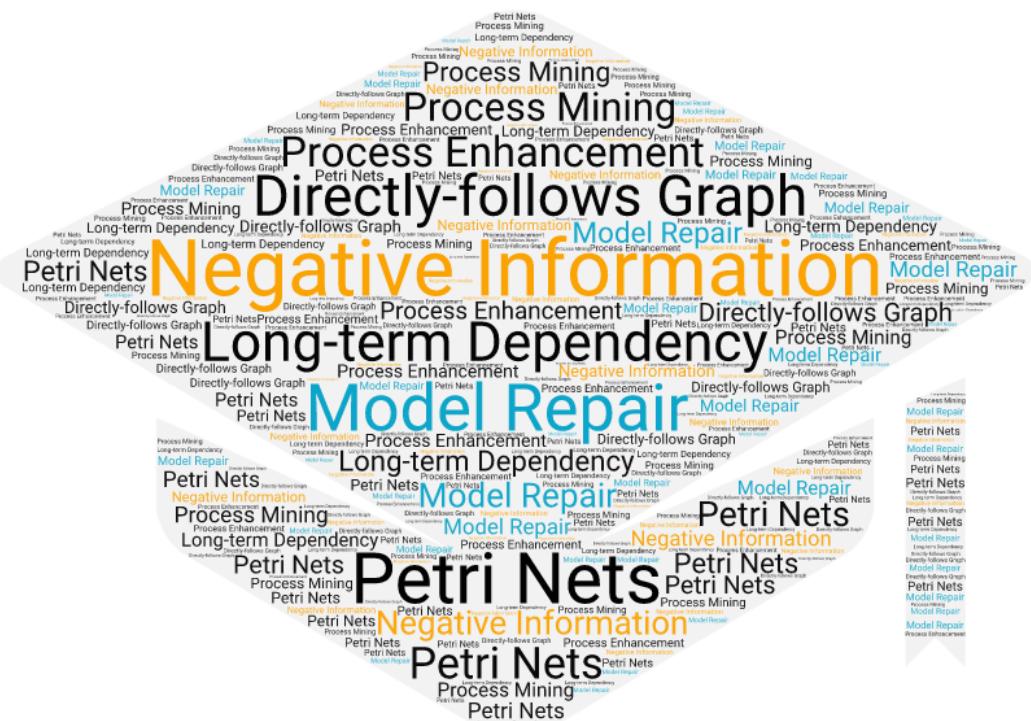
Demo

One more slide to show the workflow in KNIME?? But not here, right??

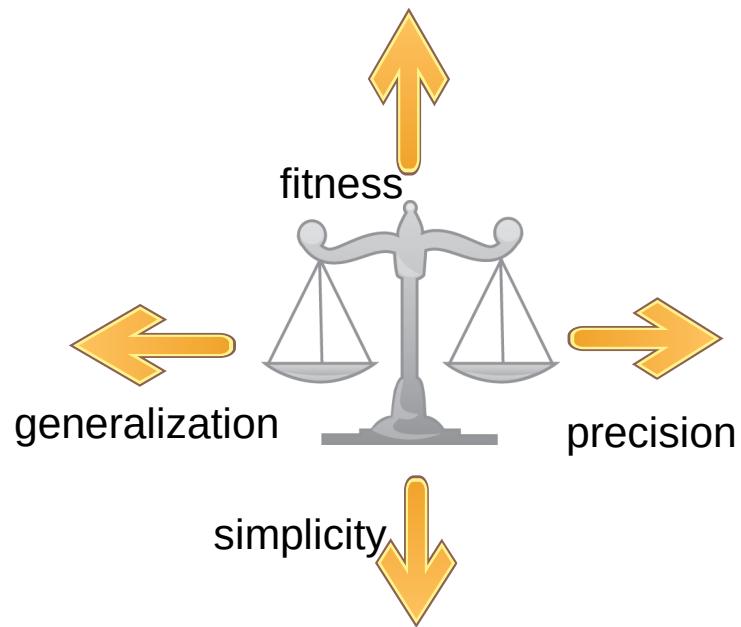


Outline

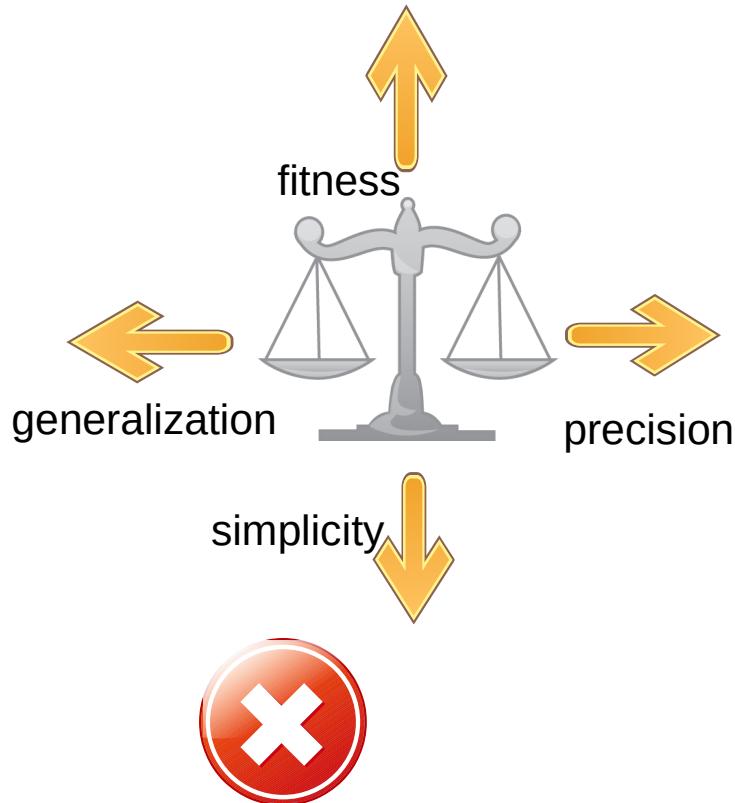
- Motivation for Research
- Problem Definition
- Approach
- Demo
- Evaluation
 - Synthetic data
 - Real life data
- Conclusion



Evaluation



Evaluation

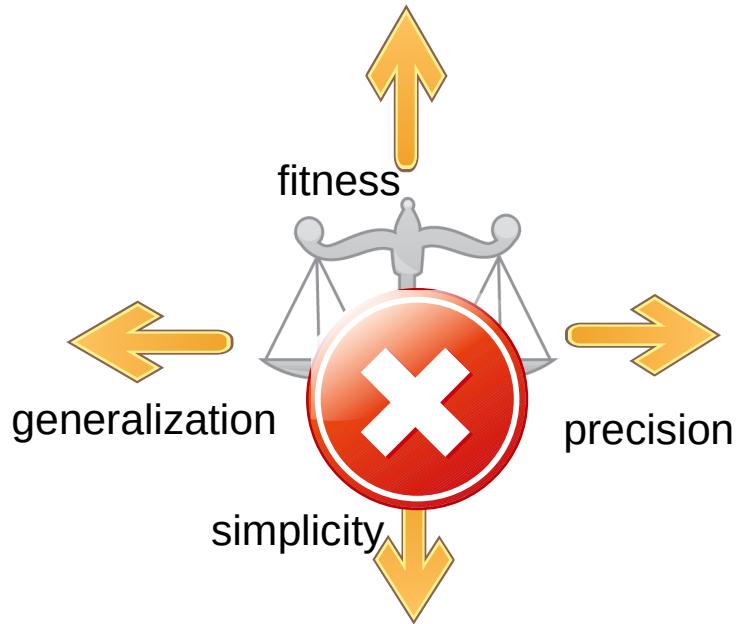


Confusion matrix

	Allowed behavior	Not allowed behavior
positive	TP	FN
negative	FP	TN



Evaluation



Confusion matrix

	Allowed behavior	Not allowed behavior
positive	TP	FN
negative	FP	TN

- Confusion matrix

- Recall

$$Recall = \frac{TP}{TP + FN}$$

- Precision

$$Precision = \frac{TP}{TP + FP}$$

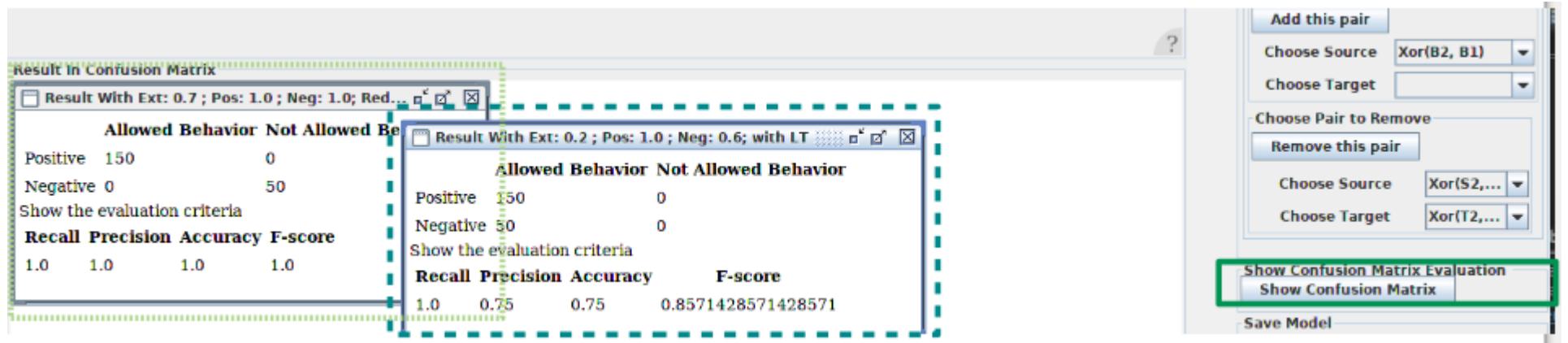
- Accuracy

$$Accuracy = \frac{TP + TN}{TP + TN + FP + FN}$$

- F1

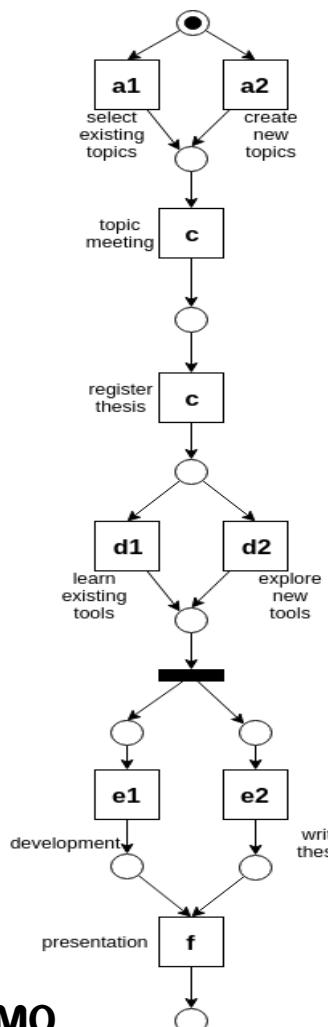
$$F_1 = \frac{2 * Recall * Precision}{Precision + Recall}$$

Demo --result

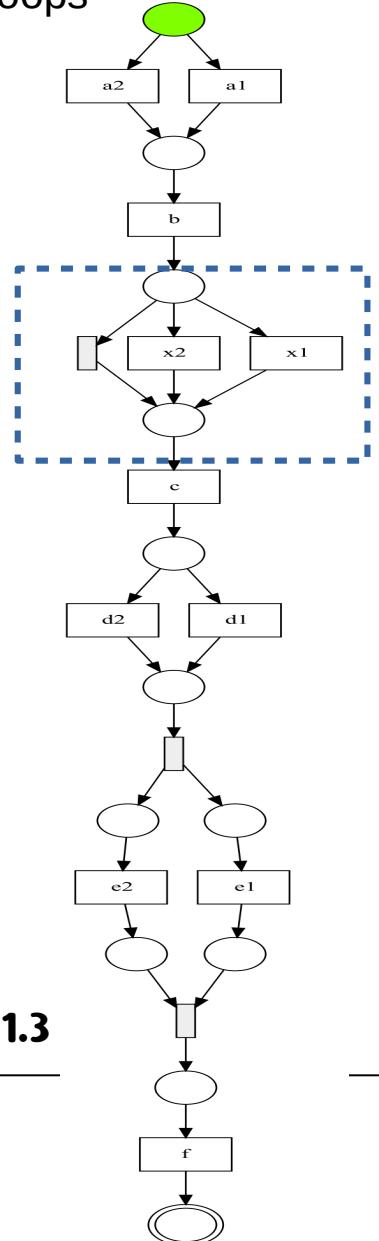


Demo --result

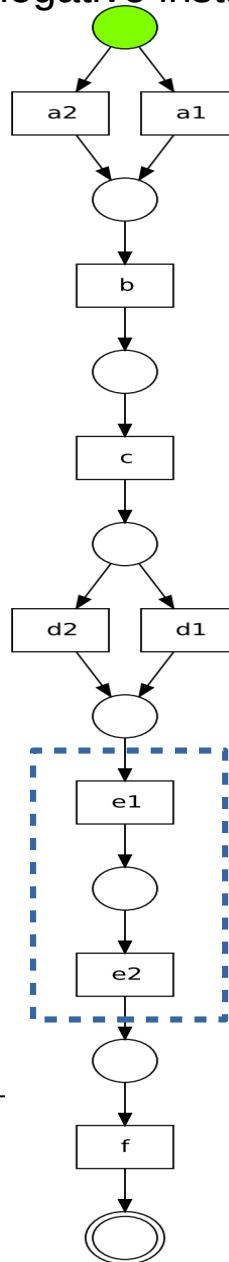
Overcome s1:
add subprocesses as loops



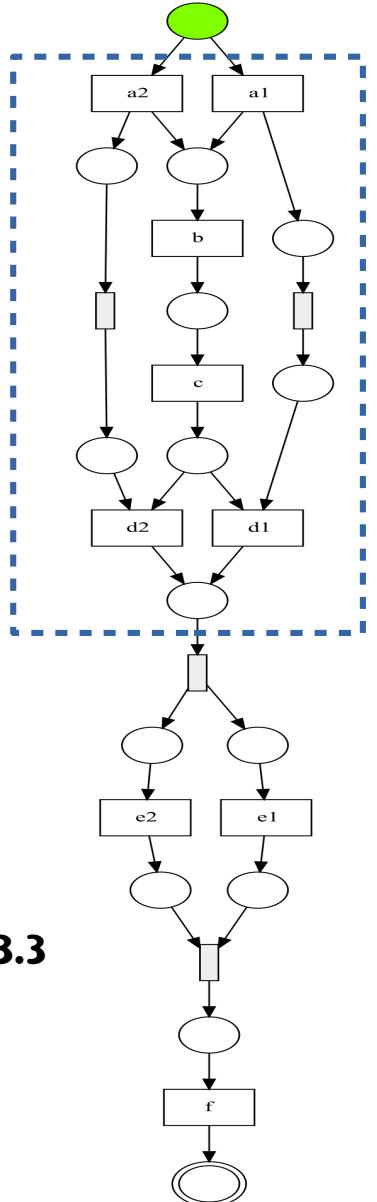
M1.3



Overcome s2:
Unable to adapt model
With negative instances



Overcome s3:
Unable to detect
long-term dependency



Demo --result

Situation	Method	Generated Model	Confusion matrix measurements							
			TP	FP	TN	FN	recall	precision	accuracy	F1
S1	IM-Infrequent Noise threshold: 20%	M1.1	50	50	0	0	1	0.5	0.5	0.667
	Fahland's Repair Model	M1.2	50	50	0	0	1	0.5	0.5	0.667
	Dfg-repair	M1.3	50	50	0	0	1	0.5	0.5	0.667
S2	IM/Fahland's	M0	60	45	0	0	1	0.571	0.571	0.727
	Dfg-repair	M2.3	50	5	40	10	0.833	0.909	0.857	0.870
S3	IM/Fahland repair	M0	100	100	0	0	1	0.5	0.5	0.667
	Dfg-repair	M3.3	100	0	100	0	1	1	1	1

Conclusion:

- ✓ Conquer shortcomings of current techniques in listed situations,
 - ✓ Better precision, accuracy, F1 score
-

Experiments -- Real life data

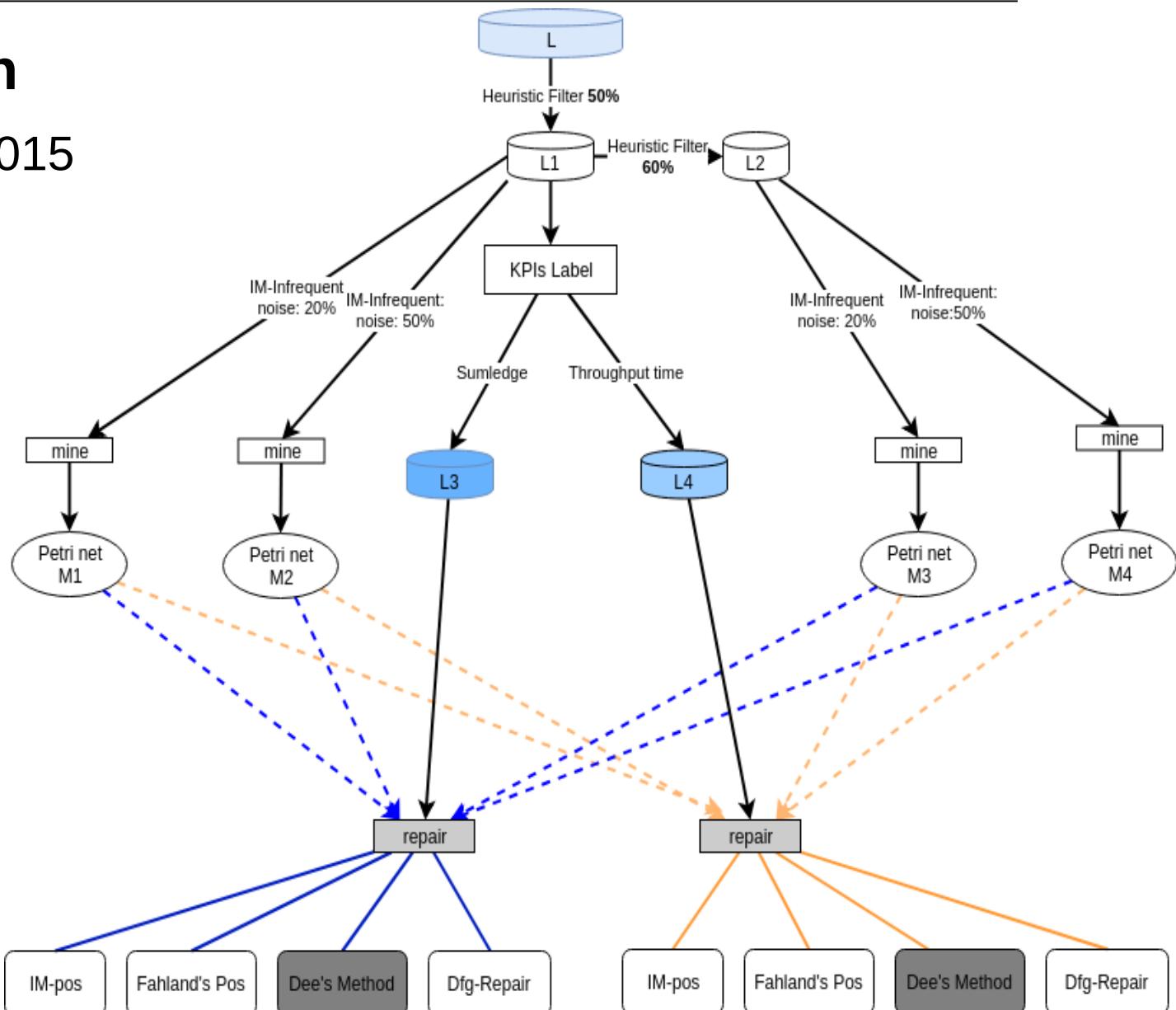
- Data description
 - BPI Challenge 2015

BPIC15_1.xes.xml:

1199 cases,

52217 events

398 event classes



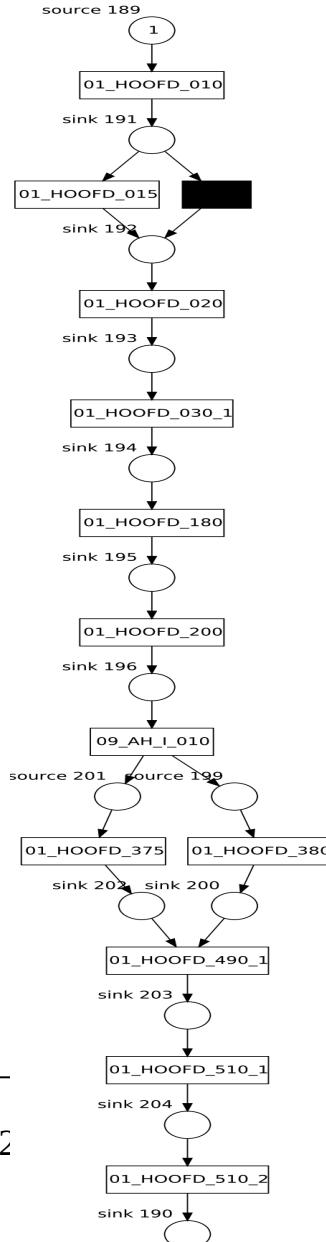
Experiments

- Event logs

ID	Description	Traces Num	Events Num	Event Class
D1	Heuristic filter 40%	495	9565	20
D2	Heuristic filter 60% on D1	378	4566	12
D3.1	Classify on Sumledge; Below 70% as positive	349	6744	20
D3.2	Classify on Sumledge; over 70% as negative	146	2811	20
D3.3	Union of D3.1 and D3.2	495	9565	20
D4.1	Classify on throughput time; Below 70% as positive	346	6719	20
D4.2	Classify on Sumledge; over 70% as negative	146	2846	20
D4.3	Union of D4.1 and D4.2	495	9565	20

Experiments

- Petri net Models



M3

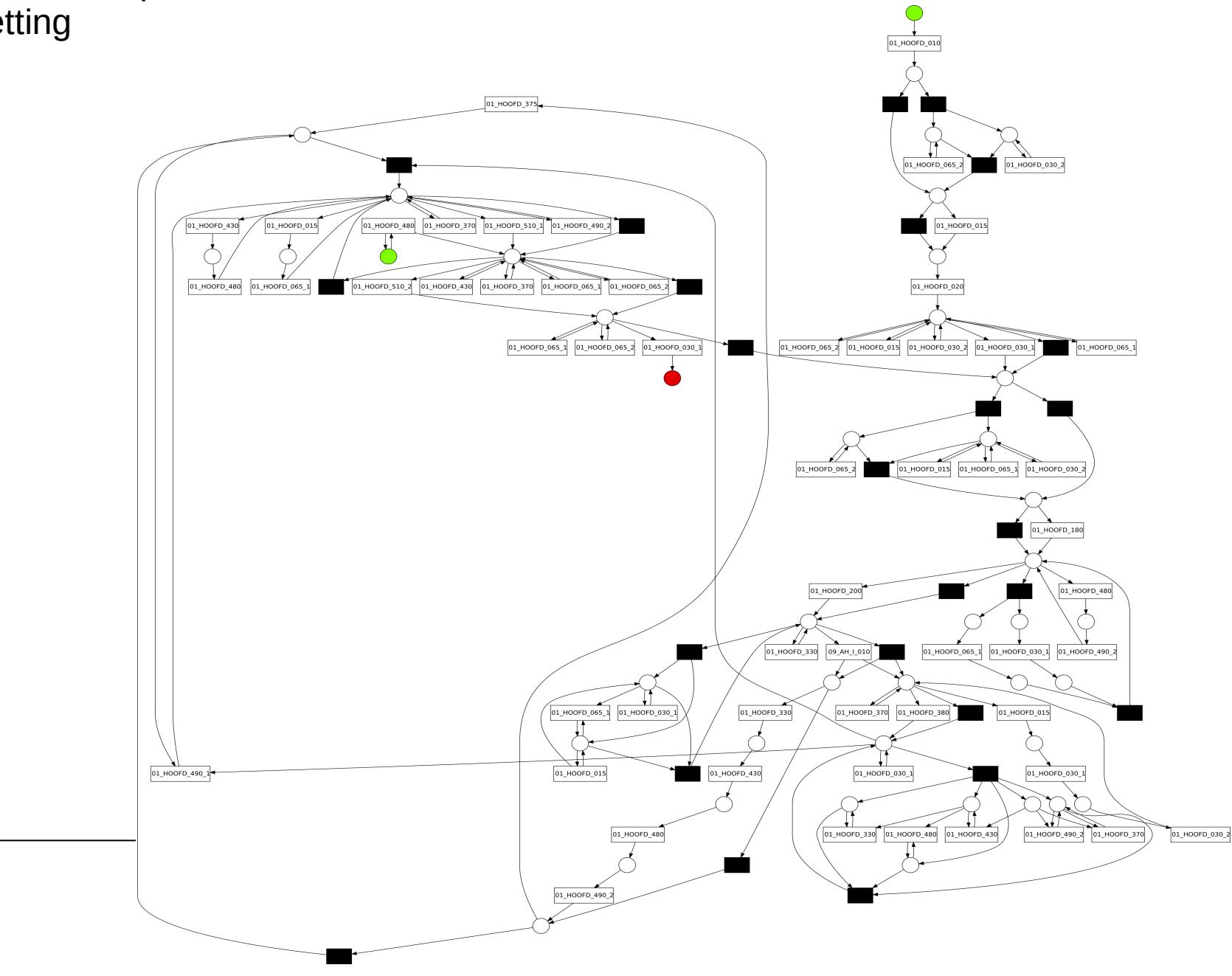
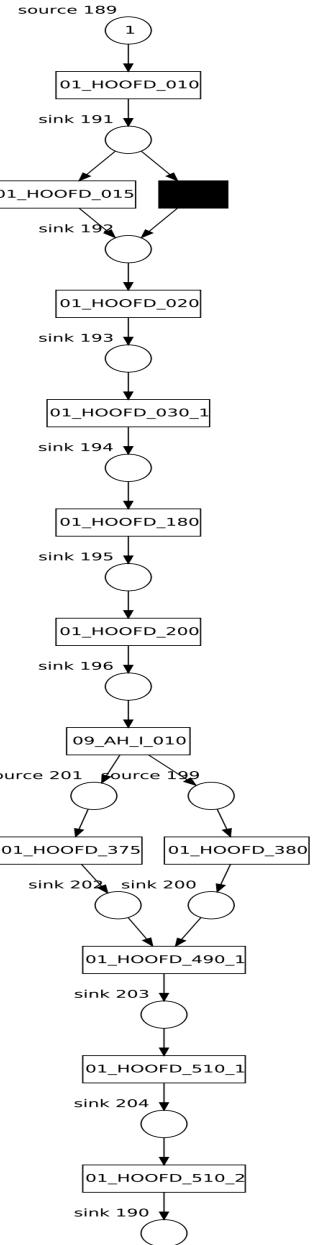
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Model ID	Data ID	Confusion matrix							
		TP	FP	TN	FN	recall	Precision	Accuracy	F1
M1	D3.3	112	40	106	237	0.321	0.737	0.440	0.447
	D4.3	131	21	128	215	0.379	0.862	0.523	0.526
M2	D3.3	106	39	107	243	0.304	0.731	0.430	0.429
	D4.3	125	20	129	221	0.361	0.862	0.513	0.509
M3	D3.3	0	0	146	349	0	NaN	0.295	0
	D4.3	0	0	149	346	0	NaN	0.301	0
M4	D3.3	0	0	146	349	0	NaN	0.295	0
	D4.3	0	0	149	346	0	NaN	0.301	0

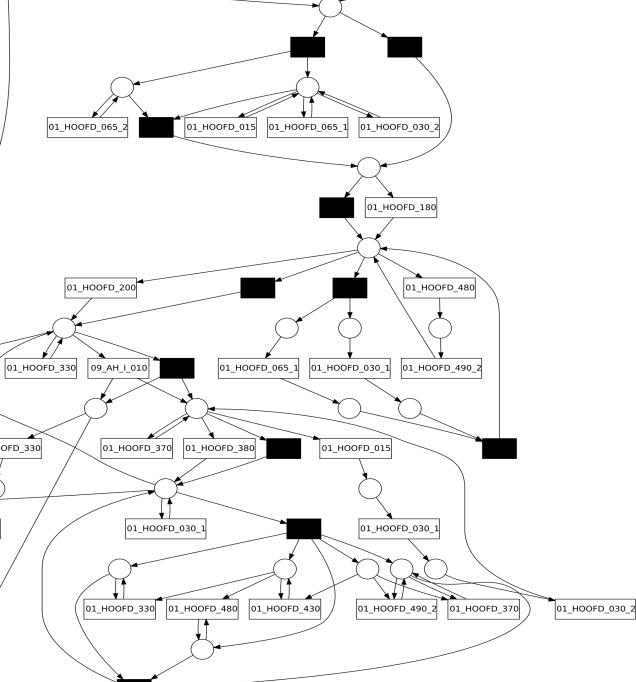
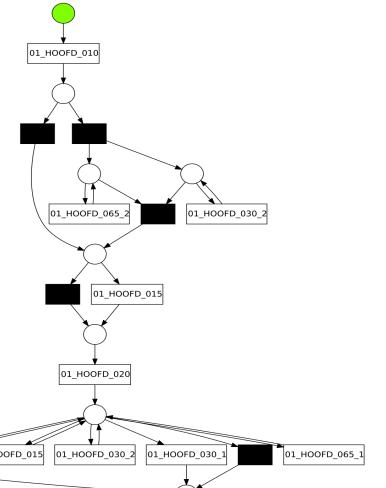
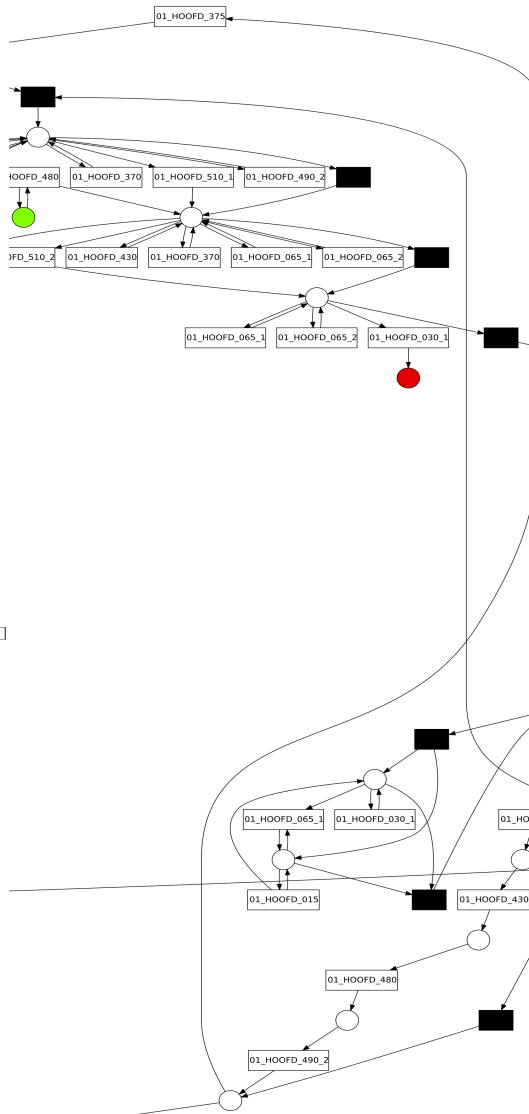
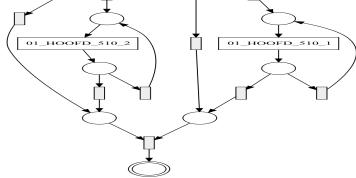
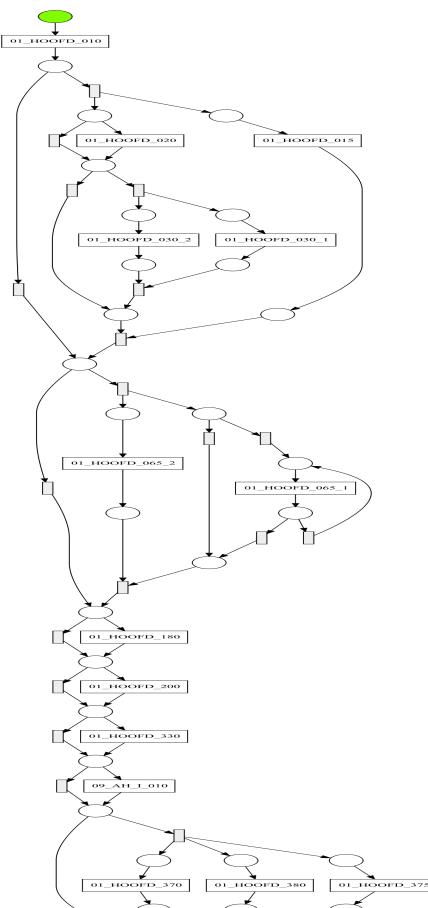
Experiments- result

Fahland's method to repair M3
with default setting



Experiments results

Dfg-repair with default setting



Simpler than
Fahland's method

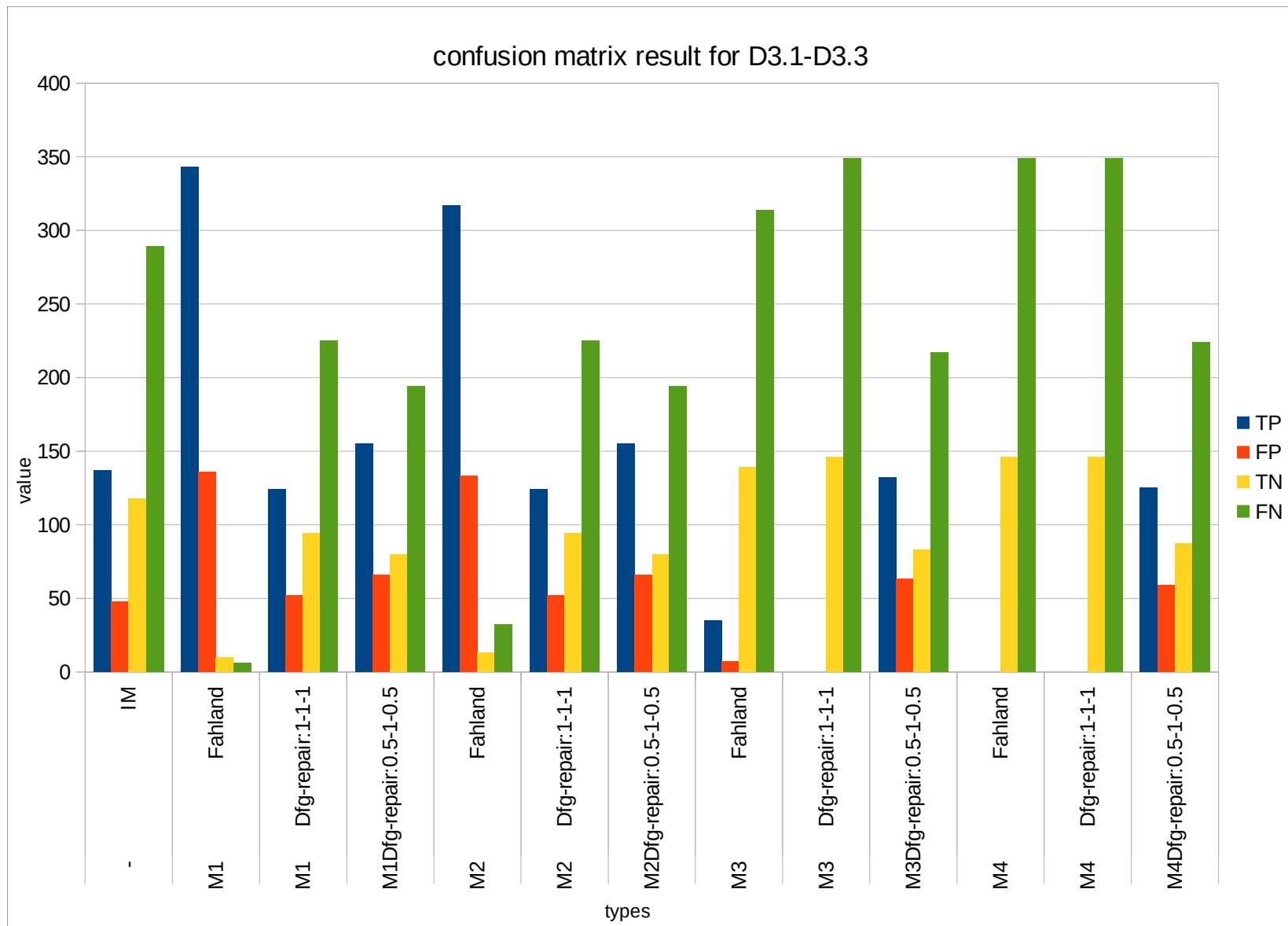
May 26, 2019

Experiment result

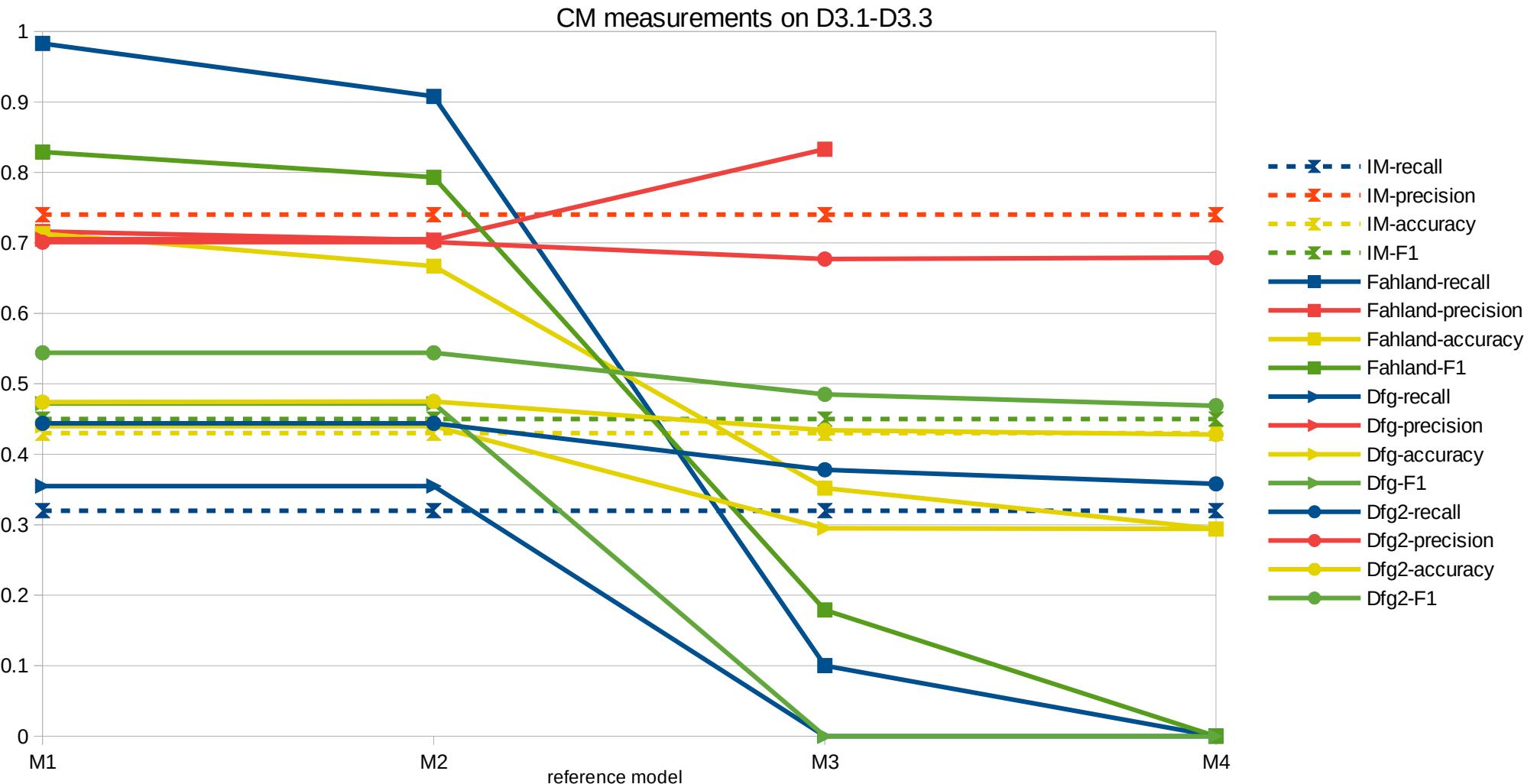
Table 6.5: Test Results on BPI15-M1 data

event log	reference model	method	confusion matrix metrics						
			TP	FP	TN	FN	recall	precision	accuracy
D3.1	-	IM	137	48	118	289	0.32	0.74	0.43
D3.1	M1	Fahland	343	136	10	6	0.983	0.716	0.713
D3.3	M1	Dfg-repair:1-1-1	124	52	94	225	0.355	0.705	0.44
D3.3	M1	Dfg-repair:0.5-1-0.5	155	66	80	194	0.444	0.701	0.474
D3.1	M2	Fahland	317	133	13	32	0.908	0.704	0.667
D3.3	M2	Dfg-repair:1-1-1	124	52	94	225	0.355	0.705	0.44
D3.3	M2	Dfg-repair:0.5-1-0.5	155	66	80	194	0.444	0.701	0.475
D3.1	M3	Fahland	35	7	139	314	0.100	0.833	0.352
D3.3	M3	Dfg-repair:1-1-1	0	0	146	349	0	NaN	0.295
D3.3	M3	Dfg-repair:0.5-1-0.5	132	63	83	217	0.378	0.677	0.434
D3.1	M4	Fahland	0	0	146	349	0	NaN	0.294
D3.3	M4	Dfg-repair:1-1-1	0	0	146	349	0	NaN	0.294
D3.3	M4	Dfg-repair:0.5-1-0.5	125	59	87	224	0.358	0.679	0.428
D4.1	-	IM	131	21	128	215	0.379	0.862	0.523
D4.1	M1	Fahland	325	133	16	21	0.939	0.710	0.689
D4.3	M1	Dfg-repair:1-1-1	139	36	113	207	0.402	0.794	0.509
D4.3	M1	Dfg-repair:0.5-1-0.5	172	48	101	174	0.497	0.782	0.552
D4.1	M2	Fahland	325	130	19	21	0.939	0.714	0.695
D4.3	M2	Dfg-repair:1-1-1	139	36	113	207	0.402	0.794	0.509
D4.3	M2	Dfg-repair:0.5-1-0.5	172	48	101	174	0.497	0.782	0.552
D4.1	M3	Fahland	10	20	129	336	0.029	0.333	0.281
D4.3	M3	Dfg-repair:1-1-1	0	0	346	149	0	NaN	0.303
D4.3	M3	Dfg-repair:0.5-1-0.5	182	49	164	100	0.526	0.788	0.70
D4.1	M4	Fahland	5	14	135	341	0.014	0.263	0.283
D4.3	M4	Dfg-repair:1-1-1	0	0	346	149	0	NaN	0.303
D4.3	M4	Dfg-repair:0.5-1-0.5	172	48	101	174	0.497	0.782	0.552

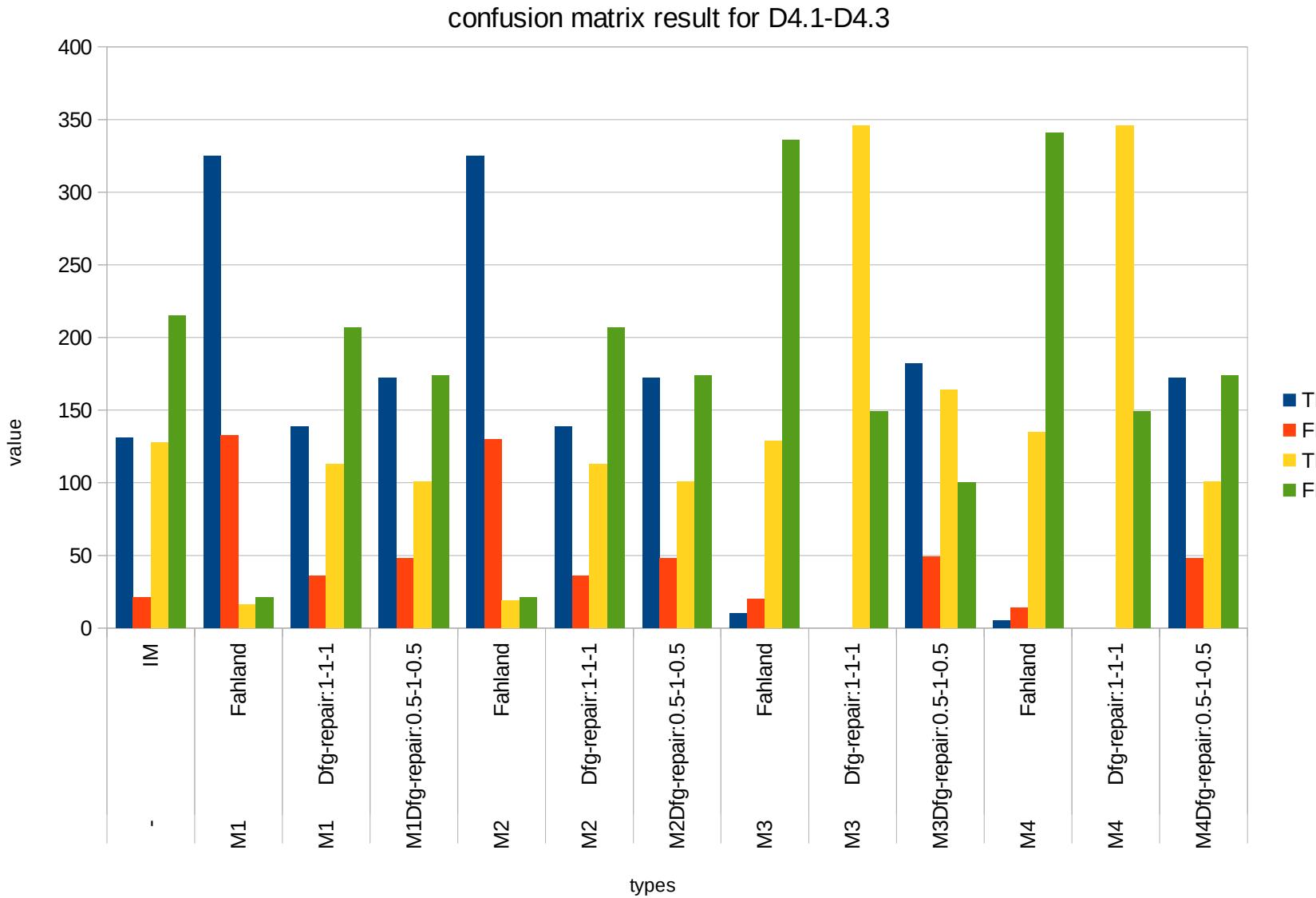
Experiment result



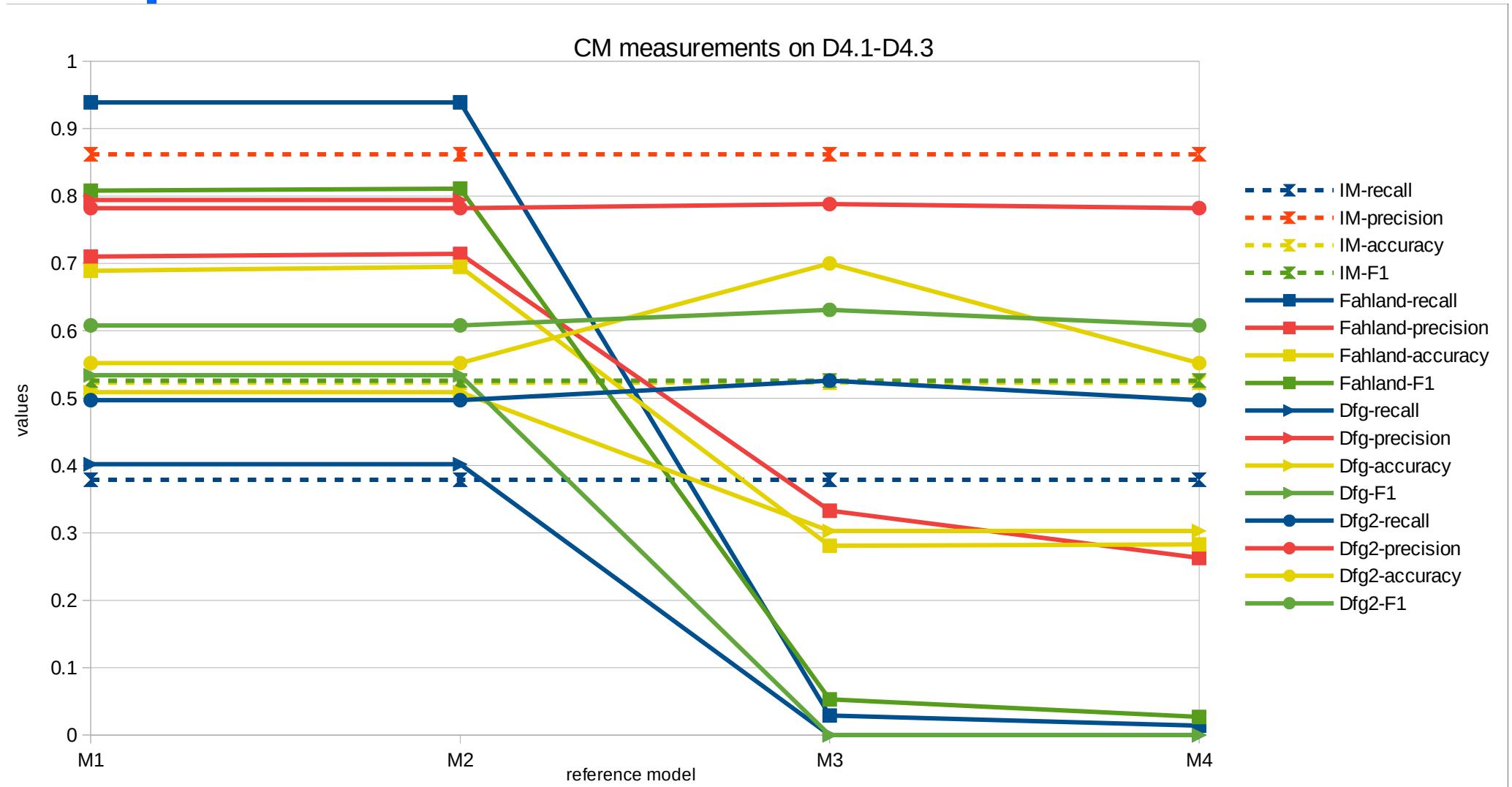
Experiment result



Experiment result



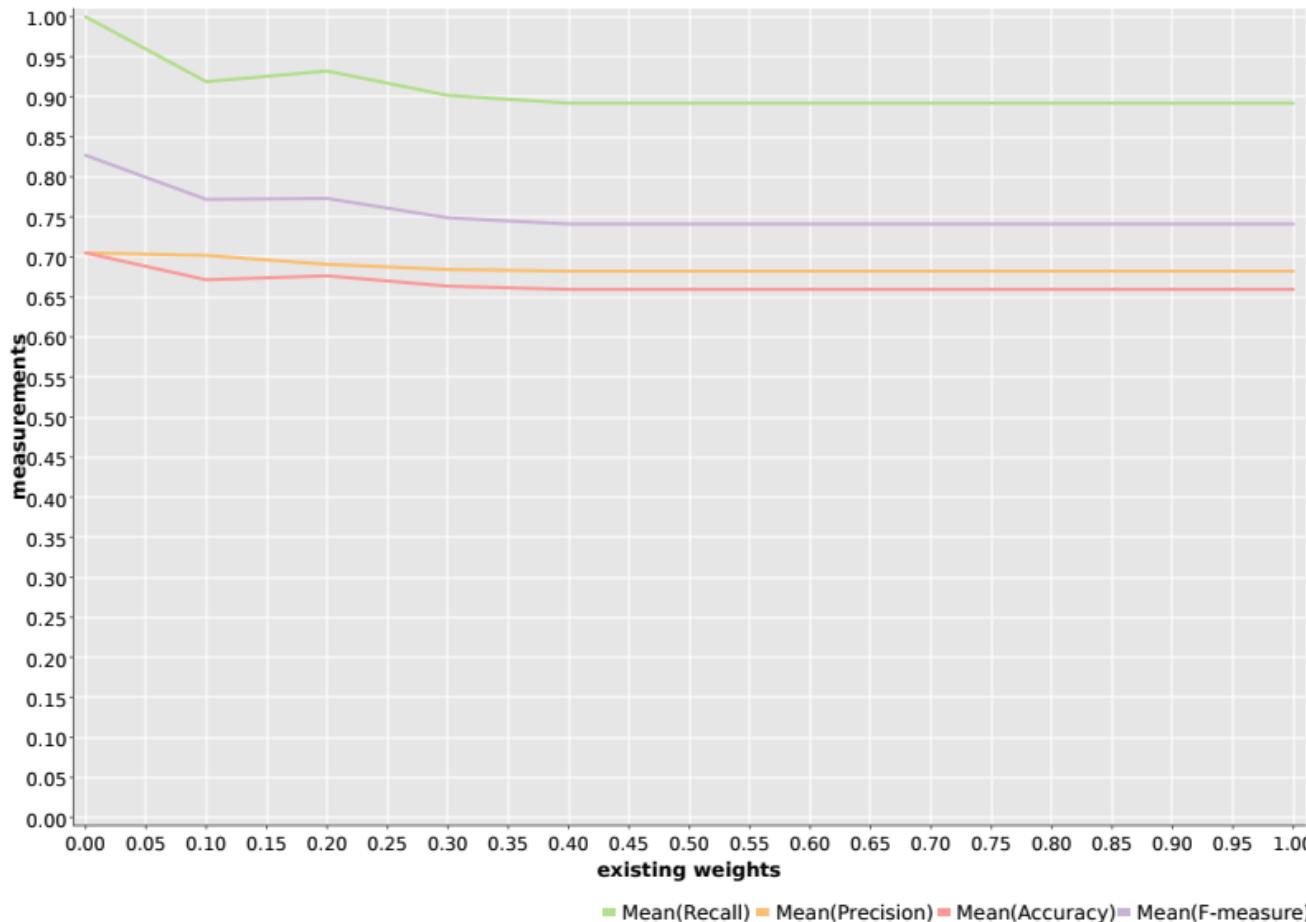
Experiment result



Experiment result

- Weight for the reference model

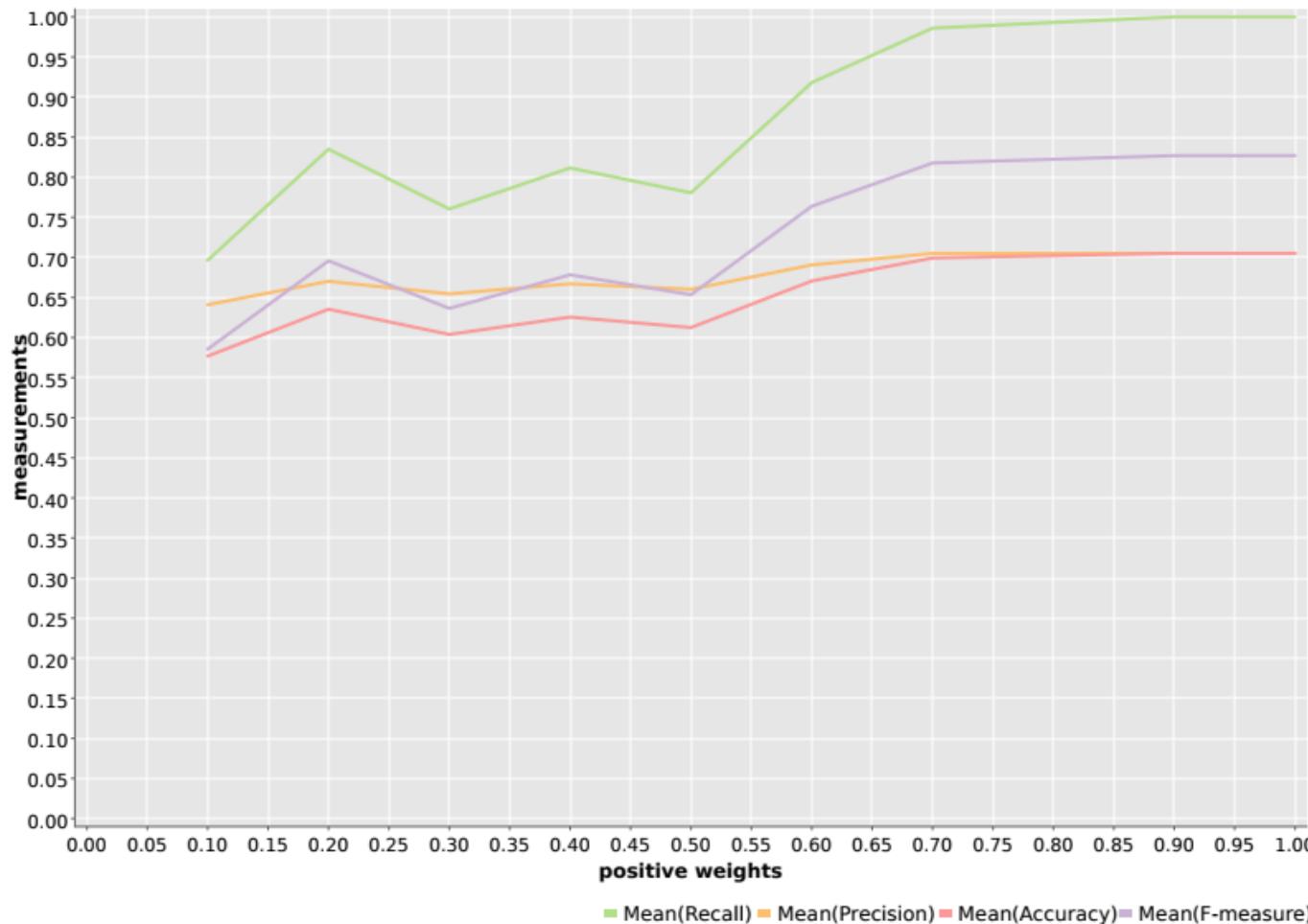
Measurements change with existing weight



Experiment result

- **Weight for positive instance**

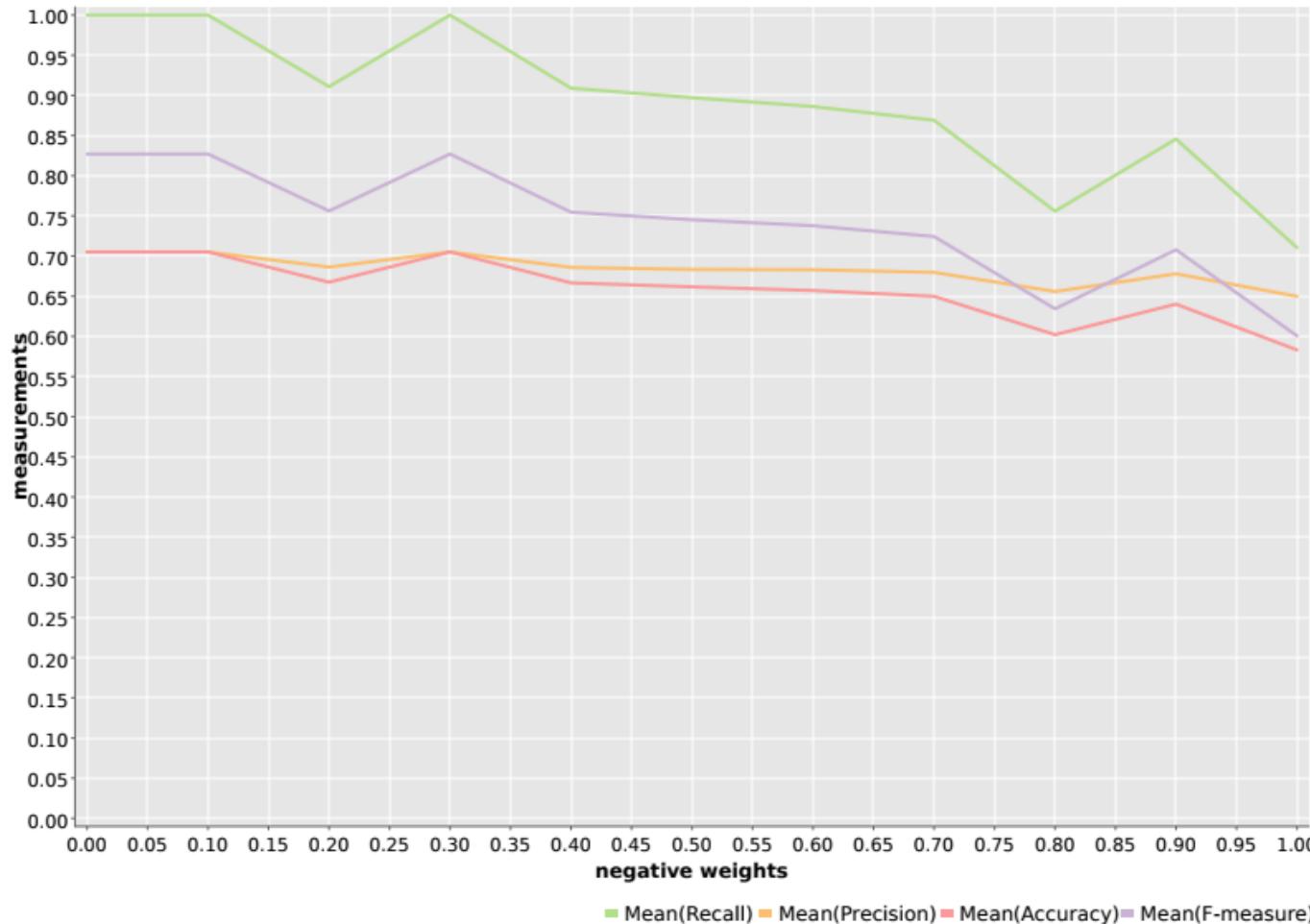
Measurements change with positive weight



Experiment result

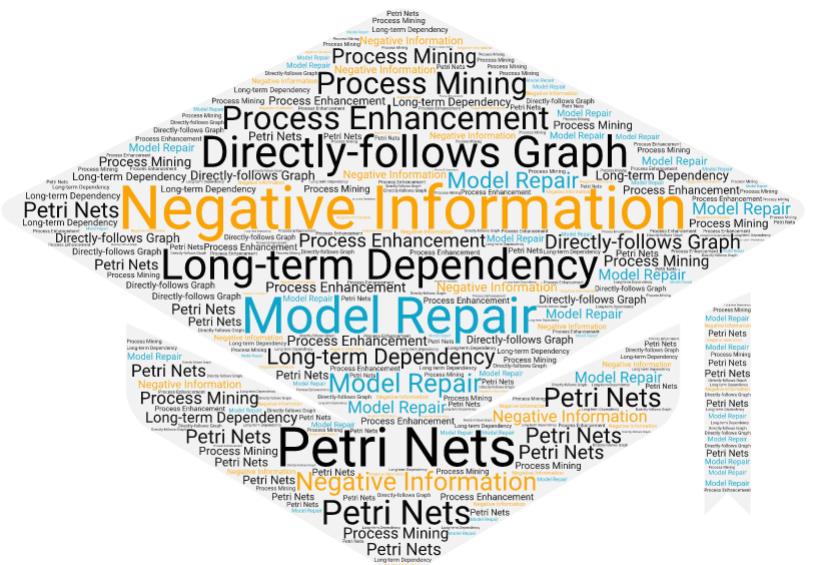
- Weight for negative instance

Measurements change with negative weight



Outline

- Motivation for Research
- Problem Definition
- Approach
- Demo
- Evaluation
- Conclusion



Conclusion

- Conquer the shortcomings
- Repair model with better precision, accuracy, F1
- Feasible to use in practice
- In observation, repaired model simpler, run faster

Further Work

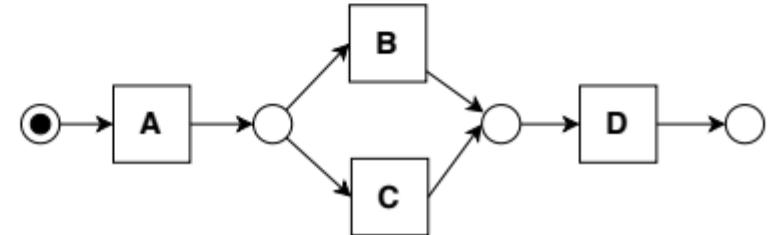
- Improve the balance rules
- Improve the rules for long-term dependency
- Drop process tree as intermediate model
- Extend to another choice relation

Questions & Answers

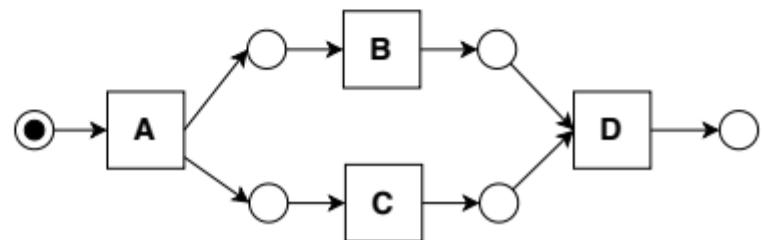


Why transition system

- Simple extraction can't get directly-follows graph

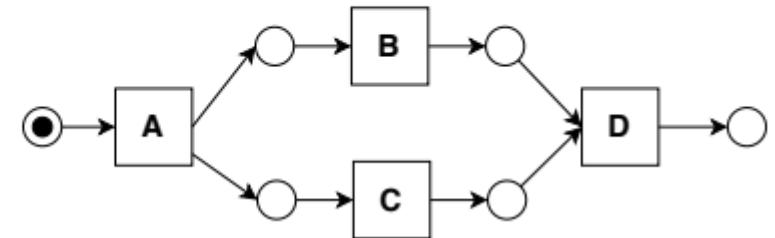
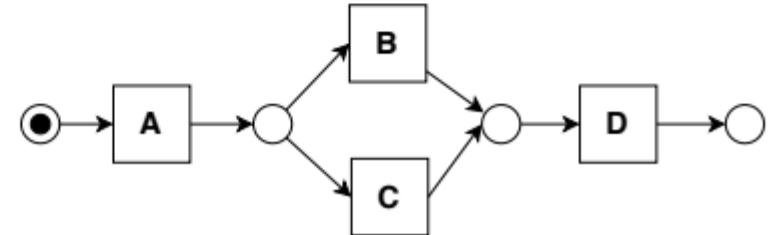


- Tool exists to transform a Petri net into Transition systems



Why transition system

- Simple extraction can't get directly-follows graph



- Tool exists to transform a Petri net into Transition systems

