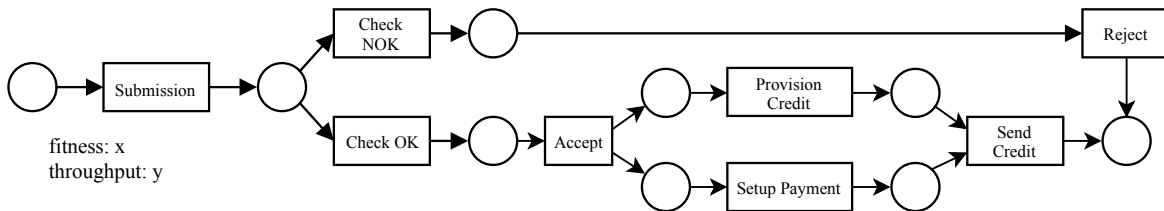
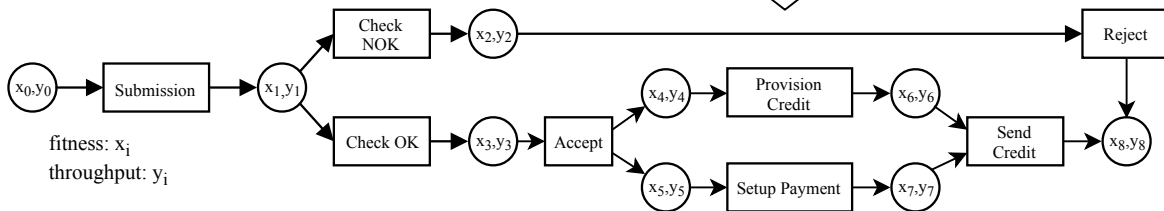


Basic



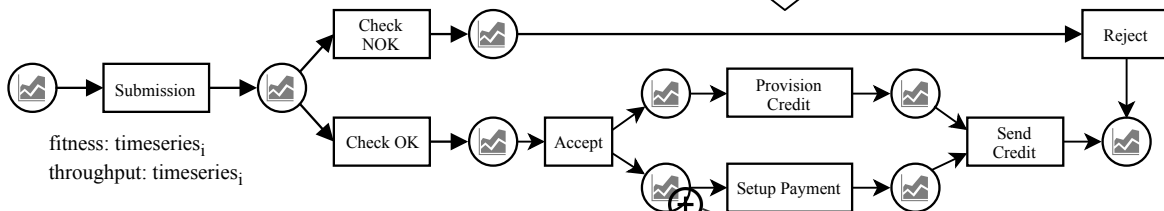
Localization over control-flow

Better



Localization over time

Goal



more dimensions

