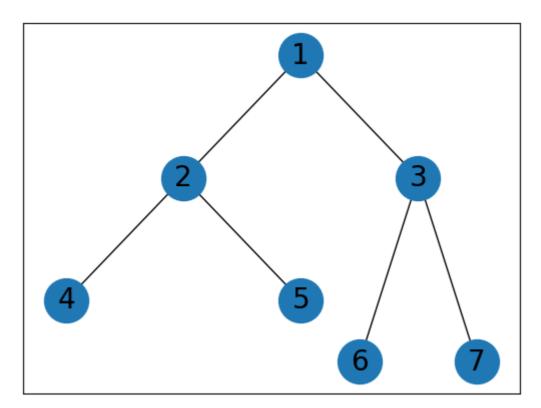
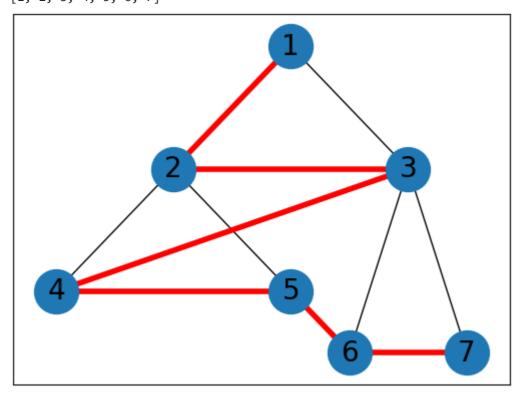
```
In [ ]: import networkx as nx
        import matplotlib.pyplot as plt
        def bfs(graph, sn):
            visited = set()
            queue = [sn]
            tp = []
            while queue:
                node = queue.pop(0)
                if node not in visited:
                    tp.append(node)
                    visited.add(node)
                    neighbors = graph.neighbors(node)
                    for i in neighbors:
                         if i not in visited:
                             queue.append(i)
            return tp
In [8]: def visualize_graph(graph, tp=None):
            pos = {
                1: (0, 0),
                2: (-1, -1),
                3: (1, -1),
                4: (-2, -2),
                5: (0, -2),
                6: (0.5, -2.5),
                7: (1.5, -2.5)
            nx.draw_networkx(graph, pos, with_labels=True, node_size=1000, font_size=20)
            if tp:
                edges = [(tp[i], tp[i+1]) for i in range(len(tp)-1)]
                 nx.draw_networkx_edges(graph, pos, edgelist=edges, edge_color='r', width
            plt.show()
In [9]: def input_graph():
            G = nx.Graph()
            num_edges = int(input("Enter the number of edges: "))
            print("Enter teh souce destination")
            for i in range(num_edges):
                edge = input().split()
                source, destination = int(edge[0]), int(edge[1])
                G.add_edge(source, destination)
            return G
        g = input_graph()
        visualize_graph(g)
        sn = int(input("Enter the starting node : "))
        print("BFS traversal:")
        tp = bfs(g, sn)
        print(tp)
        visualize graph(g, tp)
```



BFS traversal: [1, 2, 3, 4, 5, 6, 7]



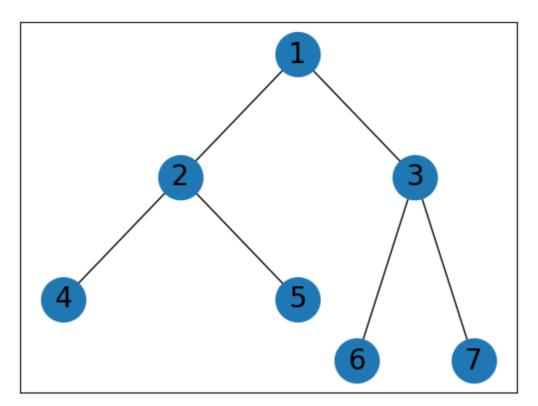
Depth first search

```
import networkx as nx
import matplotlib.pyplot as plt
def dfs(graph, sn):
    visited = set()
    stack = [sn]
    tp = []
    while stack:
```

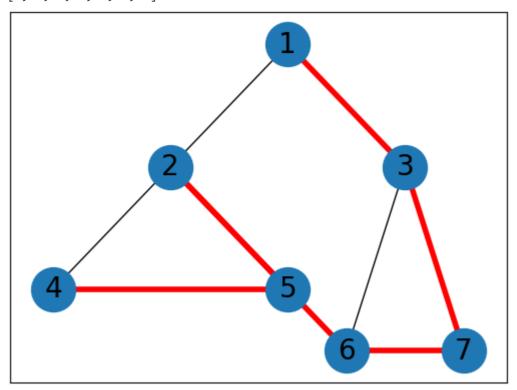
```
if node not in visited:
                     tp.append(node)
                     visited.add(node)
                     neighbors = graph.neighbors(node)
                     for neighbor in neighbors:
                          if neighbor not in visited:
                              stack.append(neighbor)
             return tp
In [6]: def visualize_graph(graph, tp=None):
             pos = {
                 1: (0, 0),
                 2: (-1, -1),
                 3: (1, -1),
                 4: (-2, -2),
                 5: (0, -2),
                 6: (0.5, -2.5),
                 7: (1.5, -2.5)
             nx.draw_networkx(graph, pos, with_labels=True, node_size=1000, font_size=20)
             if tp:
                 edges = [(tp[i], tp[i+1]) for i in range(len(tp)-1)]
                 nx.draw_networkx_edges(graph, pos, edgelist=edges, edge_color='r', width
             plt.show()
In [10]: def input_graph():
             G = nx.Graph()
             num_edges = int(input("Enter the number of edges: "))
             print("Enter the source destination")
             for _ in range(num_edges):
                 edge = input().split()
                 source, destination = int(edge[0]), int(edge[1])
                 G.add_edge(source, destination)
             return G
         graph = input_graph()
         visualize_graph(graph)
         sn = int(input("Enter the starting node : "))
         print("DFS traversal:")
         tp = dfs(graph, sn)
         print(tp)
         visualize_graph(graph, tp)
```

Enter the source destination

node = stack.pop()



DFS traversal: [1, 3, 7, 6, 2, 5, 4]



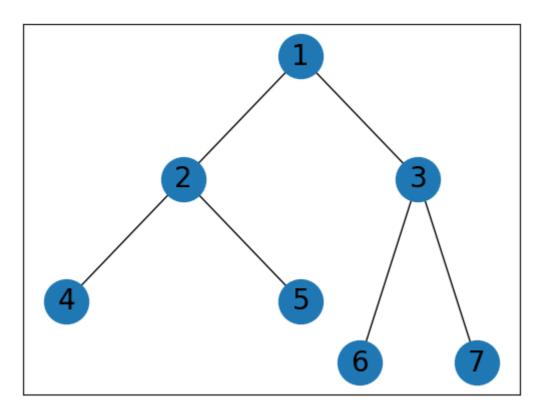
depth limied search

```
import networkx as nx
import matplotlib.pyplot as plt

def dls(graph, sn, dept):
    visited = set()
    stack = [(sn, 0)]
    tp = []
```

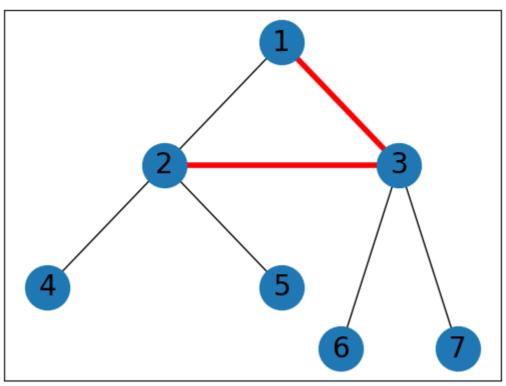
```
while stack:
                  node, depth = stack.pop()
                  if depth <= dept:</pre>
                      if node not in visited:
                          tp.append(node)
                          visited.add(node)
                          neighbors = graph.neighbors(node)
                          for i in neighbors:
                              stack.append((i, depth + 1))
              return tp
In [14]: def visualize_graph(graph, tp=None):
             pos = {
                  1: (0, 0),
                  2: (-1, -1),
                  3: (1, -1),
                 4: (-2, -2),
                  5: (0, -2),
                  6: (0.5, -2.5),
                  7: (1.5, -2.5)
             nx.draw_networkx(graph, pos, with_labels=True, node_size=1000, font_size=20)
             if tp:
                  edges = [(tp[i], tp[i+1]) for i in range(len(tp)-1)]
                  nx.draw_networkx_edges(graph, pos, edgelist=edges, edge_color='red', wid
             plt.show()
In [16]: def input_graph():
             G = nx.Graph()
             num_edges = int(input("Enter the number of edges: "))
             print("Enter the source destination")
             for _ in range(num_edges):
                  edge = input().split()
                  source, destination = int(edge[0]), int(edge[1])
                  G.add_edge(source, destination)
              return G
         graph = input_graph()
         visualize_graph(graph)
         sn = int(input("Enter the starting node : "))
         dept = int(input("Enter the dept limit: "))
         print("DFS traversal with depth limit:")
         tp = dls(graph, sn, dept)
         print(tp)
         visualize_graph(graph, tp)
```

Enter the source destination



DFS traversal with depth limit:

[1, 3, 2]



In []: