SIT 329 Advanced Embedded Systems

Task 5.1P

Ques 1. Short Introduction on what the embedded systems is supposed to do.

Ans 1: In this embedded system, the code is designed to create a temperature and humidity monitoring device with the following key features:

- 1. Sensor Reading: It uses a DHT22 sensor to measure temperature and humidity at regular intervals (every 5 seconds).
- 2. Data Logging: The system logs temperature and humidity readings along with timestamps using a Real-Time Clock (RTC).
- 3. Temperature-based LED indicator: An LED blinks at different frequencies based on the current temperature:
- a. Fast blink (20Hz) when temperature is above 25 degrees.
- b. Slow blink (0.5Hz) when temperature is below 10 degrees.
- c. Medium blink (1Hz) for temperature between 10-25 degrees.
- 4. Serial Output: The system prints sensor readings, timestamps, and LED blink frequencies to the serial monitor for monitoring and debugging.

This setup allows for continuous environmental monitoring with a visual indicator (LED) of the current temperature range, making it useful for applications like basic weather stations, greenhouse monitoring, or home automation.

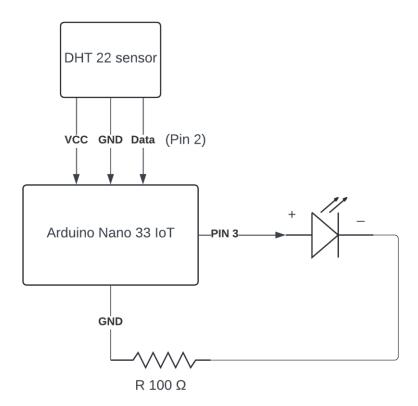
Ques 2: A table detailing the events expected and the frequency of these events if known. Indicate any timing risks in design of your interrupt service routines.

Event	Frequency	Timing Risk
Temperature/Humidity	Every 5 seconds (0.2Hz)	Low Risk: The read interval is
Reading		set to 5000ms, which should
		provide ample time for sensor
		reading and processing.
LED Blinking (High	20Hz (when temp > 25)	Moderate Risk: Fast Blinking
Temperature)		could interfere with other
		operations if not managed
		properly.
LED Blinking (Low	0.5 Hz (when temp < 10)	Low risk: This slow blinking
Temperature)		should not interfere with other
		operations.
RTC Timekeeping	Continuous (typically 1Hz)	Low Risk: RTC operations are
		usually handled by hardware
		and don't significantly impact
		CPU time.

Timing Risks in Interrupt Service Routine Design:

- 1. Sensor Reading Delay: The DHT22 sensor requires a specific timing protocol for communication. If the 'readSensor()' function takes too long, it could potentially delay other critical operations.
- 2. Serial Communication: Printing data to the serial monitor within the main loop could introduce delays, especially if large amounts of data are being transmitted frequently.
- 3. LED Blinking Implementation: The current implementation uses 'millis()' for non-blocking LED control, which is good practice. However, at high frequencies (20Hz), it may consume more CPU cycles checking and updating the LED state.
- 4. Lack of True Interrupts: The code does not use hardware interrupts for sensor reading or LED control. Instead, it relies on polling in the main loop, which could lead to missed events or delayed responses if the loop becomes blocked or delayed.
- 5. Potential for Long-Running Operations: if additional processing is added to the 'readSensor()' function in the future, it could lead to delays in the main loop execution, potentially affecting the LED blinking timing and sensor reading frequency.

Ques 3: Hardware system block diagram showing the connections and components. Indicate which pins are to be used, and any additional electronics required, e.g., resistors.



Ques 5: Code submission

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Task5.1_Khushi | Arduino IDE 2.3.0
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      Task5.1_Khushi.ino Task5.1_khushi.cpp
              #include <DHT.h>
              #include <RTCZero.h>
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              #define DHTPIN 2
              #define DHTTYPE DHT22
              #define LEDPIN 3
              #define TEMP_HIGH 25
                                         // Temperature threshold for high
              #define TEMP_LOW 10
              DHT dht(DHTPIN, DHTTYPE);
              RTCZero rtc;
              const unsigned long readInterval = 5000; // 5 seconds in milliseconds
              unsigned long previousMillis = 0;
              unsigned long ledBlinkInterval = 0; // Interval for LED
              bool ledState = false;
              unsigned long ledPreviousMillis = 0; // To keep track of LED blink timing
              void setup() {
                Serial.begin(9600);
                 Serial.println("Starting setup...");
                 pinMode(LEDPIN, OUTPUT);
                dht.begin();
```

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     Task5.1_Khushi.ino Task5.1_khushi.cpp
                Serial.println("DHT sensor initialized.");
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               rtc.begin();
               rtc.setTime(0, 0, 0); // Set initial time: hours, minutes, seconds
               Serial.println("RTC initialized.");
               Serial.println("Setup complete. Waiting for sensor data...");
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             void loop() {
  unsigned long currentMillis = millis();
               if (currentMillis - previousMillis >= readInterval) {
                 previousMillis = currentMillis;
                 readSensor();
               if (ledBlinkInterval > 0) {
                 if (currentMillis - ledPreviousMillis >= ledBlinkInterval) {
                   ledPreviousMillis = currentMillis;
                   ledState = !ledState;
                   digitalWrite(LEDPIN, ledState);
                 digitalWrite(LEDPIN, LOW);
             void readSensor() {
```

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       Task5.1_Khushi.ino Task5.1_khushi.cpp
                 float temperature = dht.readTemperature();
                 float humidity = dht.readHumidity();
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                if (isnan(temperature) || isnan(humidity)) {
                   Serial.println("Failed to read from DHT sensor!");
                  return;
                 unsigned long currentTime = rtc.getEpoch();
                 Serial.print("Timestamp: ");
                 Serial.print(currentTime);
                 Serial.print(" - Temperature: ");
                 Serial.print(temperature);
                 Serial.print(" C, Humidity: ");
                 Serial.print(humidity);
                 Serial.println(" %");
                 if (temperature > TEMP_HIGH) {
                   ledBlinkInterval = 50; // 20Hz -> 50ms interval
                   Serial.println("LED Blink Frequency: 20Hz");
                 } else if (temperature < TEMP_LOW) {</pre>
                   ledBlinkInterval = 2000; // 0.5Hz -> 2000ms interval
                   Serial.println("LED Blink Frequency: 0.5Hz");
                 } else {
                   ledBlinkInterval = 1000; // 1Hz -> 1000ms interval
                   Serial.println("LED Blink Frequency: 1Hz");
```

Ques 6: Video Demonstration

https://youtu.be/2i 29w10H4Y