



Software Engineering

Landscape depending parameter tuning for search-based software testing

Overview

1. Introduction
2. Fundamentals
3. Experimental
4. Adaptive parameter control
5. Evaluation
6. Conclusion
7. Conclusion



1. Introduction

2. Fundamentals

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Introduction

- Unit tests
- maximize coverage (line, branch, exception)
- lack of sufficient tests
- costly and time-consuming
- => use search-based software testing

Motivation

- Tools... => EvoSuite state-of-the-art
- may not terminate => search budget
- optimal only with optimal configuration
- No Free Lunch theorem
 - impossible to find optimal configuration for all problems
- EvoSuite's default configuration is fairly good, but not perfect

Research goal

- wide variety of problem-cases
- concept landscape depending
- adaptive parameter control
- increase coverage of EvoSuite

State-of-the-art



Challenges



Delimitation





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Search-based software testing

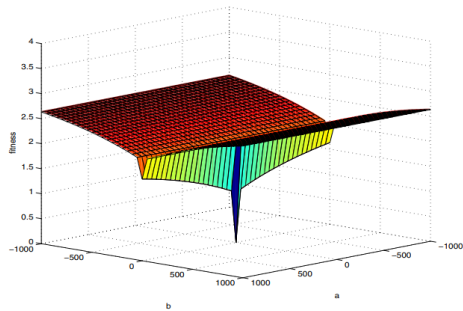
- tests for object oriented languages
- sequence of method calls
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Fitness function

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- function for e.g. coverage
- guidance for search algorithms
-
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```
1 void bar(int x) {  
2     if (x == 1) {  
3         // uncovered code  
4     }  
5 }
```

Fitness landscape



Genetic algorithm

Heading

- start with random population
- iterate till termination condition
- return last generation

Heading

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DynaMOSA

Heading

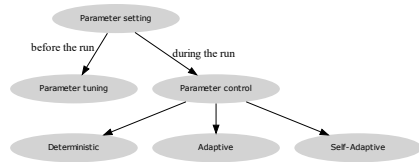
- start with random population
- multiple target
- keep track of target covering individuals

Heading

- iterate till termination condition
- update targets
- update archive
- select by rank
- return archive as last generation

Parameter tuning and control

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Corpus

SF110

- 110 open-source Java projects
- 23,894 Java Classes
-
-
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Panichella et al.

- 117 open-source Java projects
- 346 Java Classes
- non-trivial and complex
- often used

Prediction sample

- S_1
- 709 Java Classes
- randomly selected
- SF110

- 9.8 days on three machines

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Evaluation sample

- S_2
- 346 Java Classes
- the whole Panichella corpus
-

- 4.8 days on tree machines
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Sensitive sample

- S_3
- 20 Java Classes
- extracted from S_1
- high Standard Deviation

- 6.6 hours on tree machines

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Comparisons

- 30 repeats for every Java Class
- Mann-Whitney U-test
- Vargha-Delaney effect size \hat{A}_{12}
-

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A decorative background featuring a network of dashed lines and dots. The dots are positioned at various points, with some connected by lines, creating a geometric pattern. The lines are thin and light gray, while the dots are small and dark gray.

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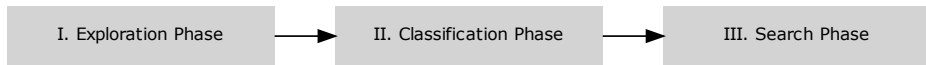
5. Evaluation

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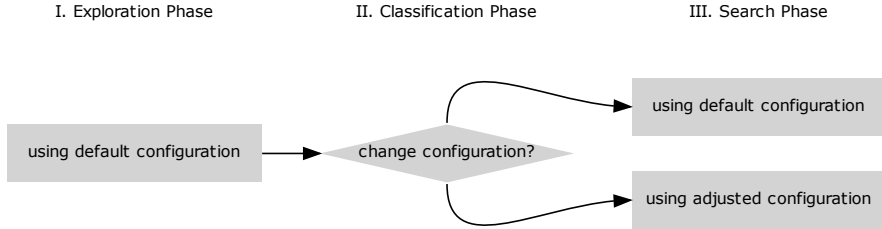
7. Conclusion

Concept

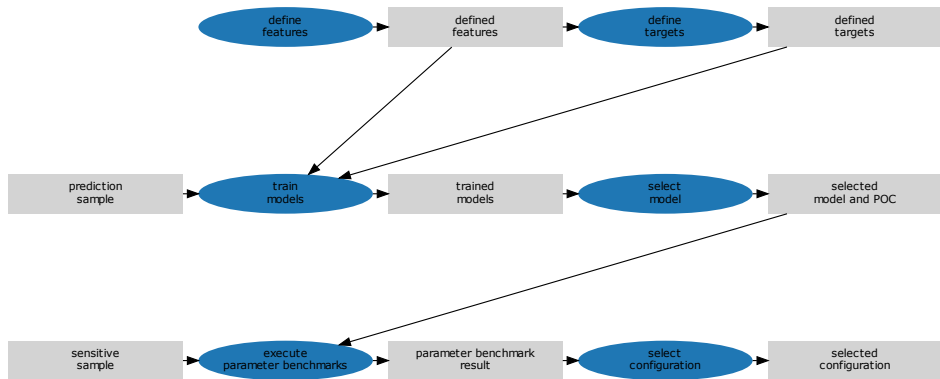
- use the beginning of the search to explore the search space
- classify the current search ("adjust" or "default")
- use configuration depending on class



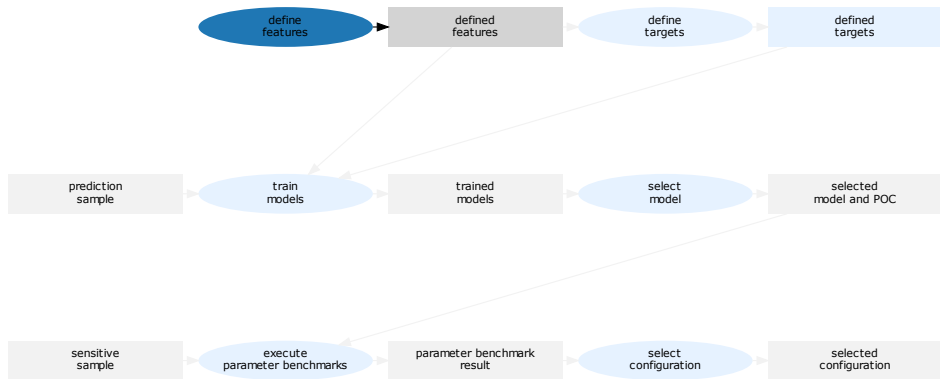
Configuration selection



Components



Landscape features

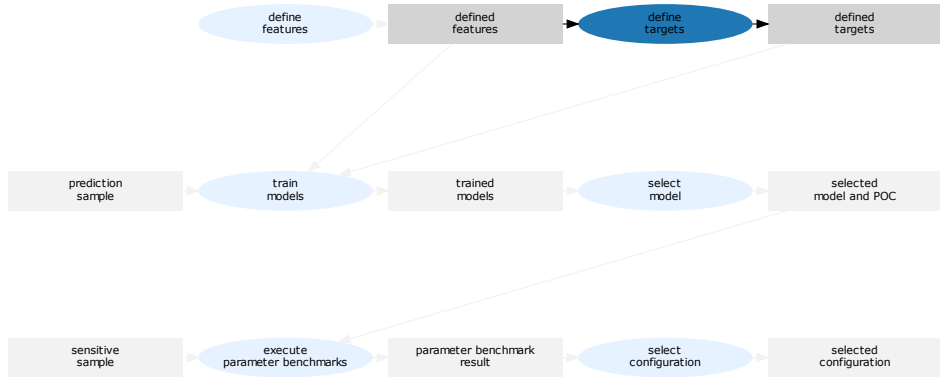


Landscape features



- Fitness and gradient
- Neutrality
- Neutrality Volume
- Information Content

Classification target



Target approximation



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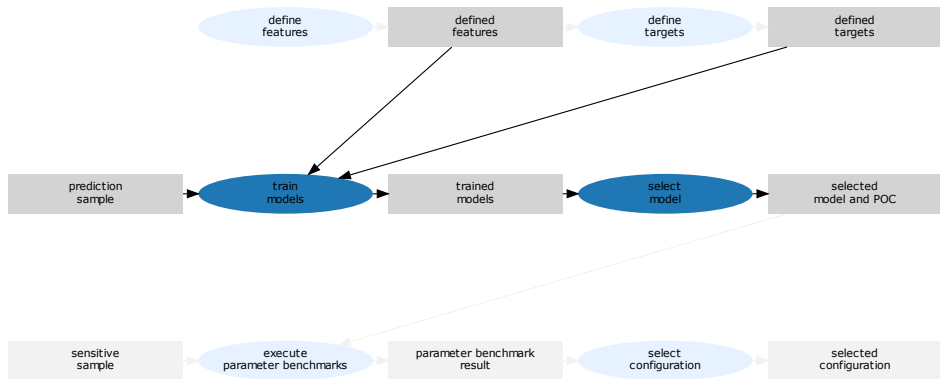
Targets

- Low end coverage $endcov. < 0.8$
- High standard deviation $stdev > 0.1$
- Relative low coverage $cov. < max(cov.) * 0.8$

Targets

target	n in class	description
$cov. < max(cov.) * 0.8$	447	End coverage less than 80% of the best execution
$endcov. < 0.8$	6687	End coverage less than 80%
$stdev > 0.1$	541	Standard deviation greater than 0.1
$stdev > 0$	6046	Standard deviation greater than 0.0
$p = 125$	1735	The median coverage with a population of 125 is greater than the median coverage with default settings
$stdev > 0.1 \ \& \ cov. < max(cov.) * 0.8$	256	The boolean "and" of the two targets
$stdev > 0 \ \& \ cov. < max(cov.) * 0.8$	447	The boolean "and" of the two targets
$stdev > 0.1 \ \& \ endcov. < 0.8$	391	The boolean "and" of the two targets
$pop = 125 \ \& \ cov. < max(cov.) * 0.8$	254	The boolean "and" of the two targets

Classification



Classification

Heading

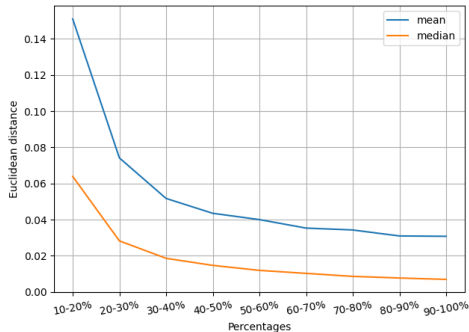
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Heading

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Length of Exploration Phase

- compare landscape features ever 10%
- using Euclidean distance
- trade-off between
 - time for exploration
 - time for adjusted configuration
- between 20 and 40% from search (percentage of classification)



Machine learning algorithm

Heading

- supervised learning
- fast classification
- few features
- decision tree

Heading

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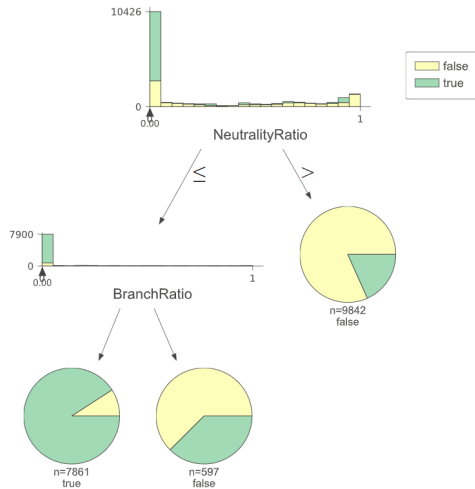
Hyper-parameter search

- only apply on as many as possible
 - $\text{TPR} > 80\%$
- only apply if positive effect
 - $\text{FPR} < 5\%$
- percentage of classification (POC)
- construction criteria (Gini Impurity, Entropy or Log-Loss)
- depth of decision tree

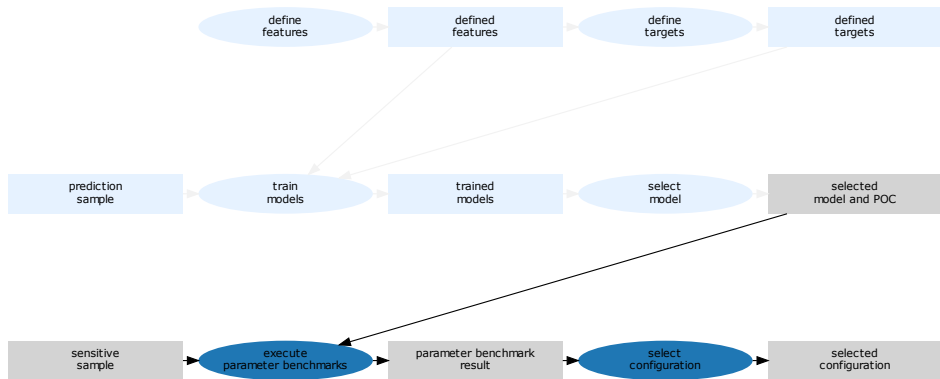
Component selection

Decision tree

- $stdev > 0.1 \& cov.max(cov.) * 0.8$
- depth of decision tree: 2
- Gini Impurity
- POC: 30%



Parameter selection



Parameter selection

Heading

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Heading

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Component selection

configuration	gen.	n	P_{adj}			\hat{P} for $k = 5$			n_+	n_-
			mut.	cross.	ins.	mut.	cross.	ins.		
default	853	9	0.95	0.68	0.05	1.0	0.87	0.0		
p = 25	1,263	13	0.96	0.69	0.04	1.0	1.0 ↗	0.0	0	0
p = 125	572	6	0.95	0.68	0.04	0.77	0.15	0.0	3	0
cr = 0.0	841	8	0.95	0.0	0.05	1.0	0.0	0.0	1	0
cr = 1.0	849	8	0.95	0.95	0.05	1.0	1.0 ↗	0.0	0	0
bias = 2.0	912	9	0.95	0.68	0.05	1.0	0.88 ↗	0.0	1	0
bias = 1.01	824	8	0.95	0.68	0.05	1.0	0.77	0.0	0	0
pti = 0.0	1,154	12	1.0	0.75	0.0	1.0	1.0 ↗	0.0	0	4
pti = 0.2	770	8	0.92	0.63	0.08	1.0	0.66	0.0	0	0
p = 10, pti = 5.0	912	9	0.58	0.13	0.42	0.69	0.0	0.31 ↗	3	0
p = 25, pti = 1.0	777	8	0.75	0.38	0.25	0.89	0.14	0.03 ↗	4	0



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