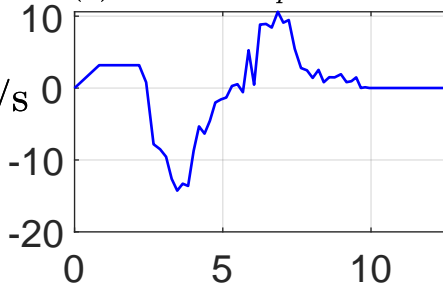
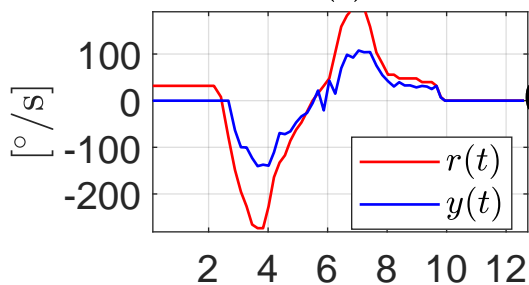
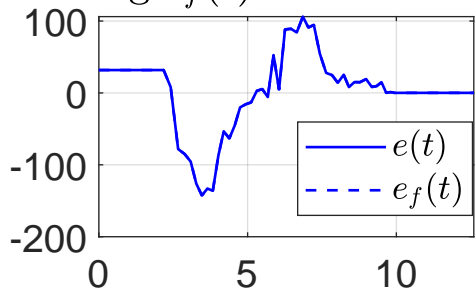


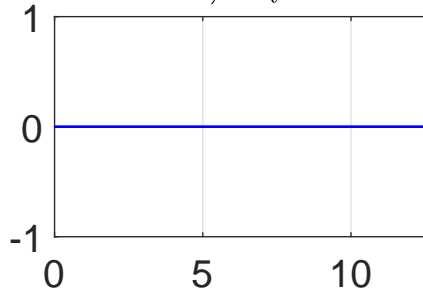
Vinkelhastighet $y(t)$ og referanse $r(t)$ P-del, $K_p = 0.1$



Reguleringsavvik $e(t)$
og $e_f(t)$ med $\alpha = 1$



I-del, $K_i = 0$



Pådrag $u(t)$ og max/min-grensene. D-del, $K_d = 0$

