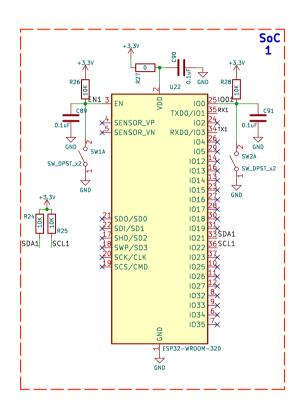
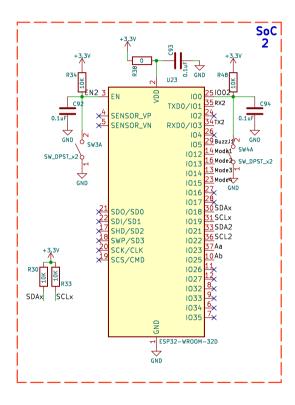
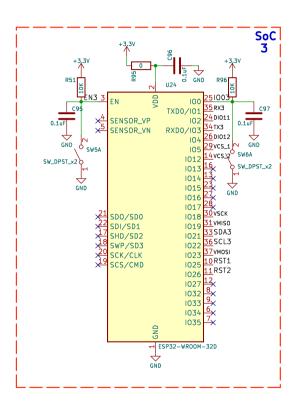


## **ESP 32**







Н 1002D | 002 AaD Aa AbD Ab ENZD ENZ ZZJID BuzzJ1 ode1D Mode1
ode2D Mode2
ode3D Mode3
ode4D Mode4 RX3DRX3 1001D 1001 EN1D EN1 EN3D EN3 RX2D RX2 3.3VD SE SCLID SCL1 SDAID SDA1 SDA3D SDA3 SCL3D SCL3 RX1D RX1D VCS\_2D\_VCS\_2 VSCKD\_VSCK VMISODVMISO VMOSIDVMOSI RST2D RST2 SCL3D SCL3 RST1D RST1 DIO11D DIO11 VCS\_1D\_VCS\_1 TX1DTX1 TX3D TX3
SDAXD SDAX
SCLXD SCLX
SDAZD SDAZ SCL2D SCL2

Dharma Bot KRS

Sheet: /SoC1/ File: soc.kicad\_sch

Title: SoC\_RemoteV2

Size: A4 Date: 2024-11-28
KiCad E.D.A. kicad 7.0.10

Rev: V3

ld: 6/4