

— (v1)

	3D
/	____ / ( ) ____ ( ) ____
	2025.09 ~ 2025.12 ( )
	v1 (2025 - 09 - 08)

1.

1 . 가 / (UR)  
2 / 가 AI  
3 : , ,

2. (KPI)

1  
2 • UR 82% (N {20,30,50}, 100 × 100 )  
• ( 0%) 99%  
• : UR x%  
3  
4 • : , 6가  
• : / ( : 100 × 100), 가  
• : Transformer policy + PPO(GAE), P S O  
• : / /3D / /

3.

- : Box state(s\_b) & Container state(s\_c)
- Plane Features(7 ): h, e\_l, e\_w, e\_-l, e\_-w, f\_l, f\_w
- Downsampling: 100 × 100 × 7 10 × 10 × 7 ( e\_l × e\_w )
- Action Order: Position Selection Orientation (chain rule )

4. ( )

4.1

- Box state s\_b: {b\_i=(l\_i, w\_i, h\_i)}
- Container state s\_c: heightmap + plane features(7 )

4.2

100 × 100 × 7 10 × 10 , e\_l × e\_w feature  
10 × 10 × 7 Flatten(100 × 7) + positional encoding

4.3 /가

- 2 : Box Encoder, Container Encoder (Transformer, d\_model=128, layers=2)
- 3 : Position, Selection, Orientation (Transformer)
- :  $(a|s) = p(a_p|s) \cdot s(a_s|a_p,s) \cdot o(a_o|a_p,a_s,s)$
- 가 :  $V(s)$

4.4 /

$r_i = g_{i-1} - g_i$ ,  $g_i = L \cdot W \cdot i - j l_j w_j h_j /$  : PPO+GAE( =0.99, =0.96, =0.12), Adam, lr(policy)=1e-5, lr(value)=1e-4

## 5. &

- 1 utils/preprocess.py (+tests)
- 2 envs/container\_sim.py (+tests)
- 3 agents/backbone.py
- 4 agents/heads.py (+tests)
- 5 agents/value\_head.py (+tests)
- 6 train/train\_ppo.py
- 7 configs/{env,model,train}.yaml
- 8 results/{logs,plots,ckpt}/
- 9 README.md ( / / )
- 10 (pytest, 1 , / )  
: (projects/), (docs/), (slides/), (figures/), (data/)

## 6. ( ) & (5 )

- 1 W1: / ( A)
  - 2 W2: / ( B)
  - 3 W3: 가 / ( C)
  - 4 W4: / ( D)
  - 5 W5: / / ( E)
  - 6 W6~: / / (All)
- A( . PM): / / ,
  - B( . ): envs/ + ,
  - C( . ): / , /
  - D(가 . ): value head, PPO,
  - E( . ): , KPI , /

## 7. &

- / : mixed precision,
- : gap shaping , invalid action penalty
- : N {20,30,50}

- : git - flow , pre - commit/pytest CI
- : /BC , (d\_model=96) fall - back

## 8. / ( )

- HW: Colab Pro/ GPU, ( )
- SW: Python 3.10, PyTorch, pytest, matplotlib
- : GitHub( / / ), Notion( ), Slack/ ( )

## 9.

- : UR , , ,
- / : DRL · Transformer , SOTA ,

· · · KPI · 가 ·