

# Data Quality-Aware Graph Machine Learning



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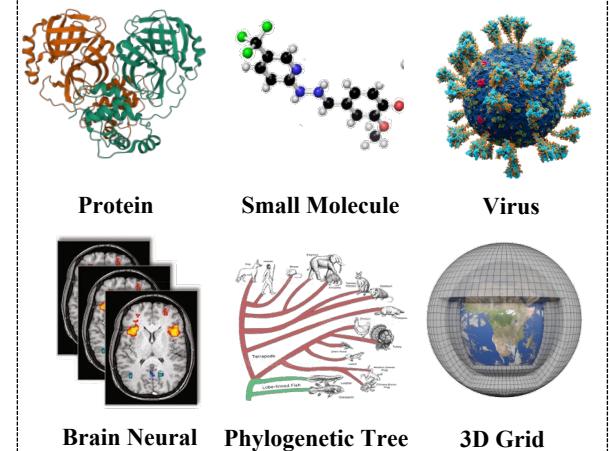


Tyler Derr<sup>1</sup>

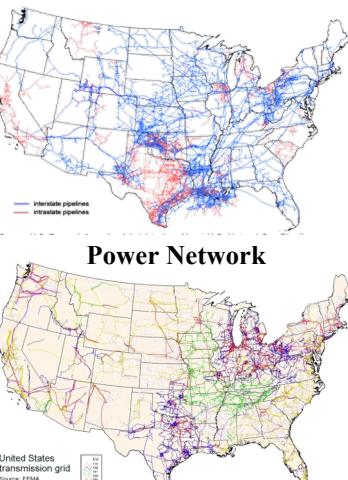
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North Carolina State University<sup>4</sup>  
University of Rochester<sup>5</sup>  
University of Oregon<sup>6</sup>

# Introduction and Background - Graph-Structured Data is Everywhere

**Scientific Graph**



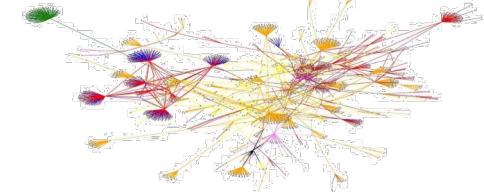
**Gas Network**



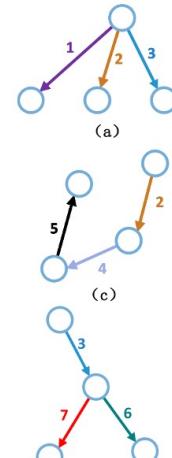
**Comcast Nationwide Fiber Optic Network**



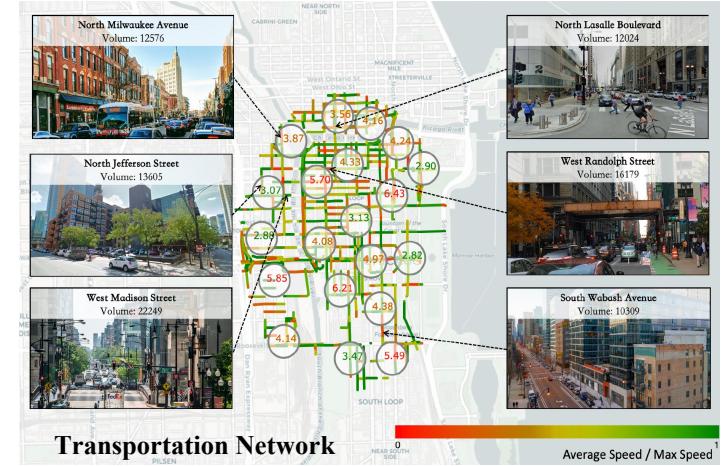
**Communication Network**



**Traffic Trace**

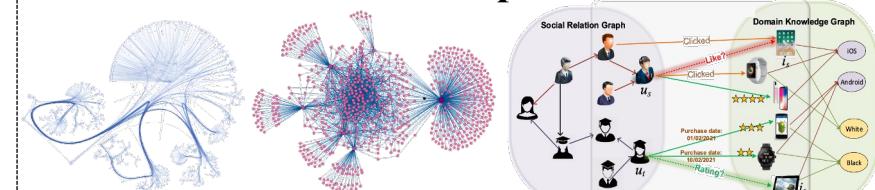


**Infrastructure Graph**



**Transportation Network**

**Social Interaction Graph**



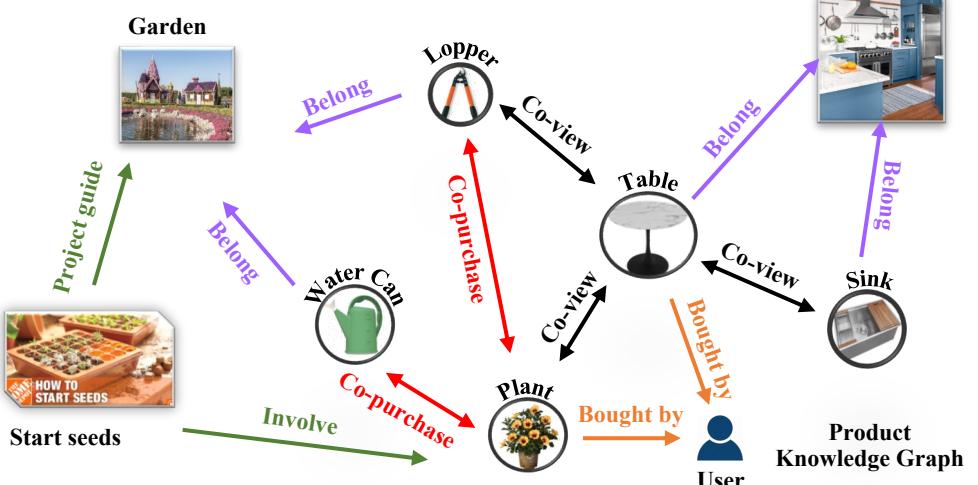
Citation Network, Transaction Network

User-Entity Interaction Graph

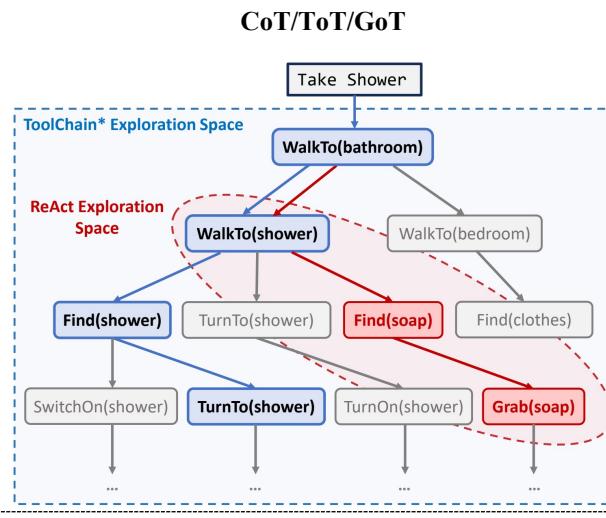


**Virtual Village with AI Agents**

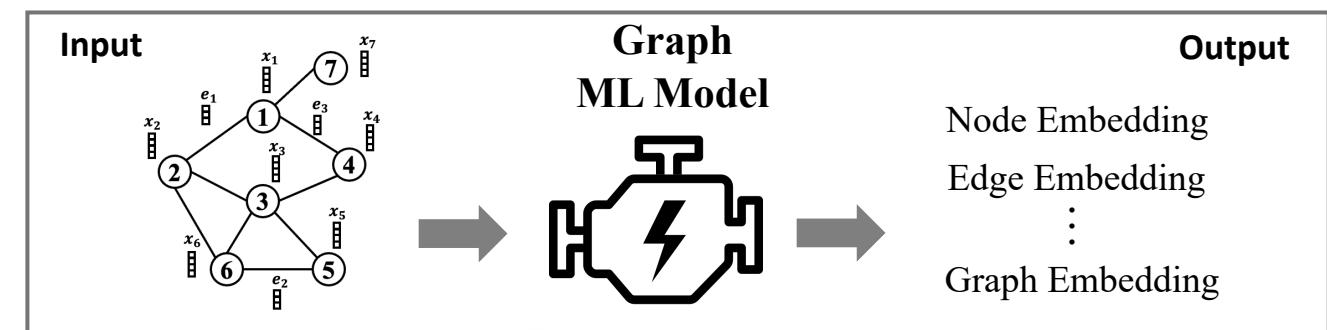
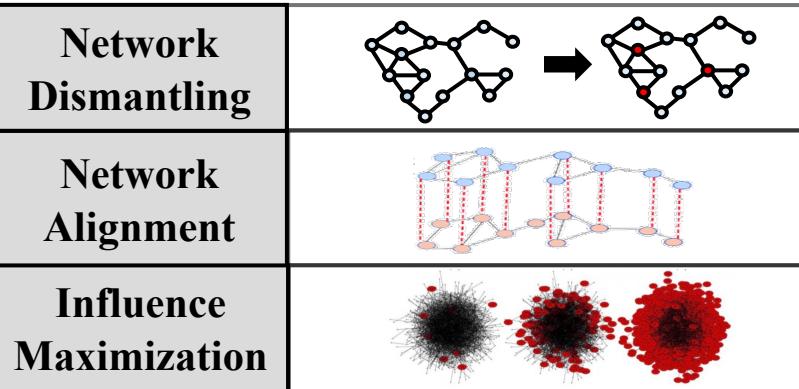
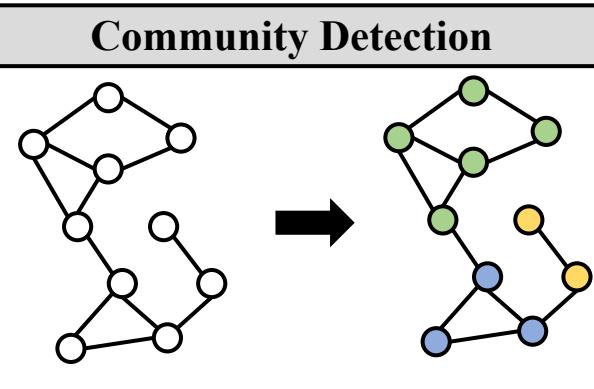
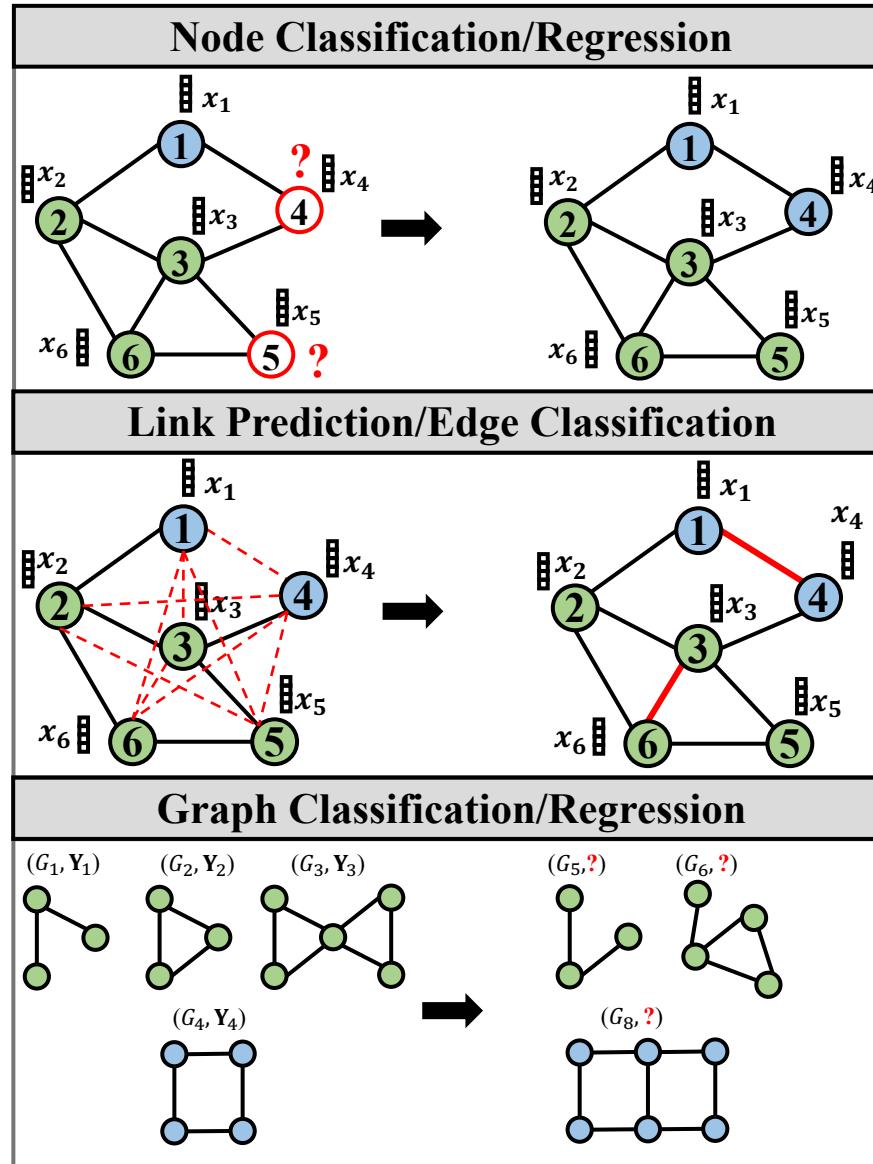
**Knowledge Graph**



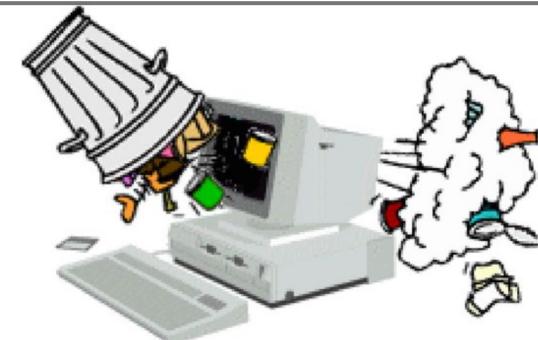
**Reasoning / Planning Graph**



# Introduction and Background - Graph-based Tasks and Graph Machine Learning



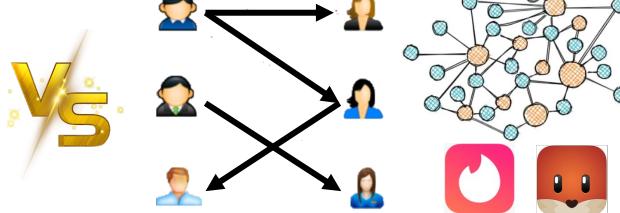
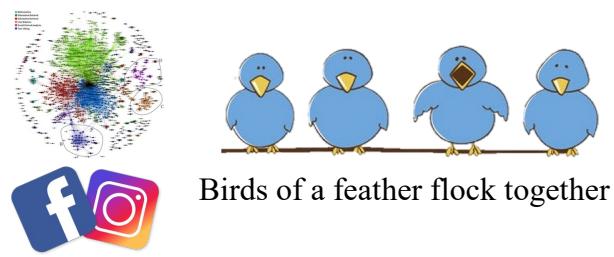
*Real-world  
graph data  
can have  
data quality  
challenges...*



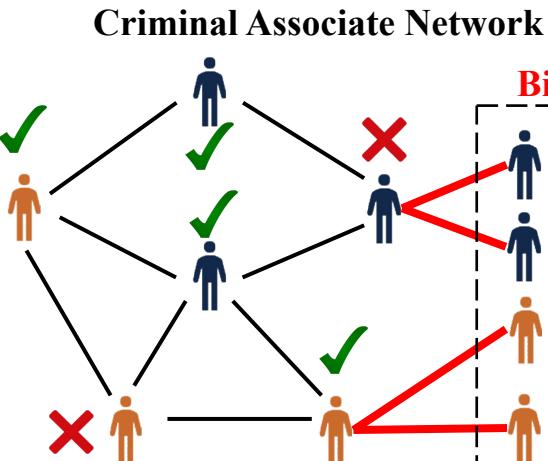
Garbage in, garbage out

# Introduction and Background – Real-world Graphs have Data Quality Issues

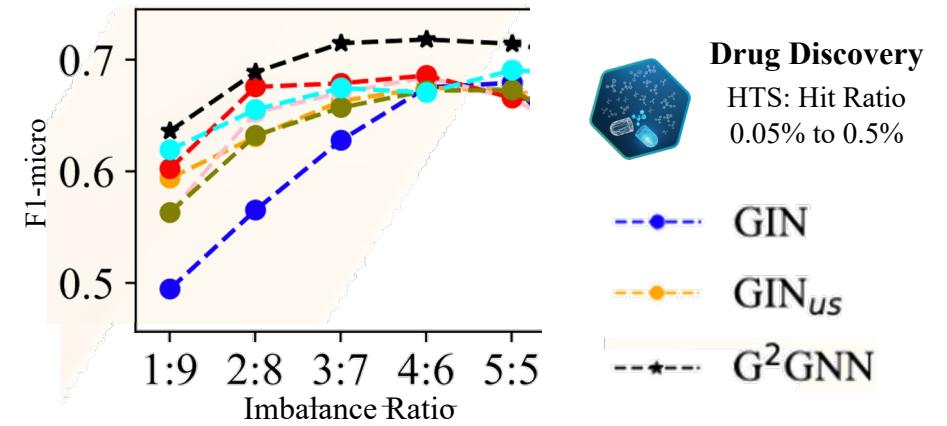
## Topological Issues e.g., Homophily vs Heterophily



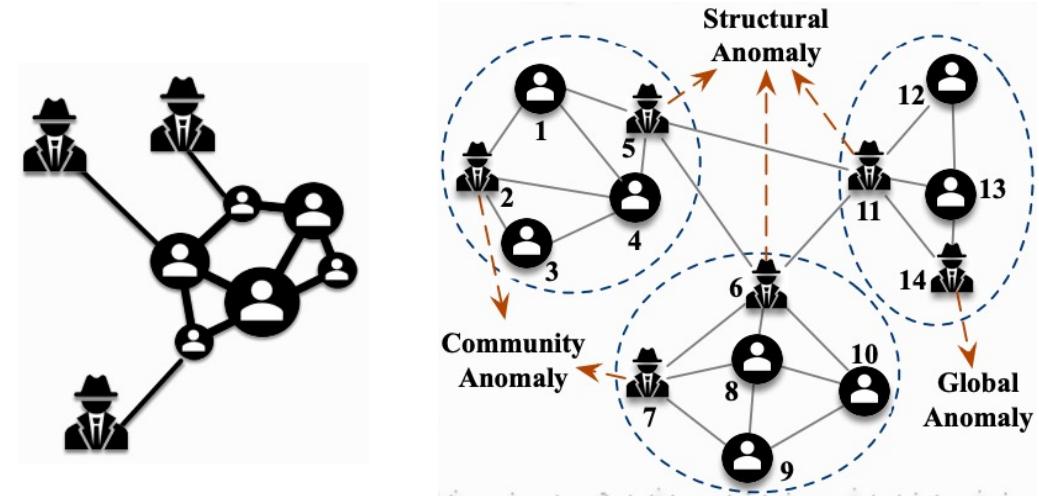
## Bias Issues e.g., bail decision making



## Imbalance Issues e.g., labeled data in chemistry



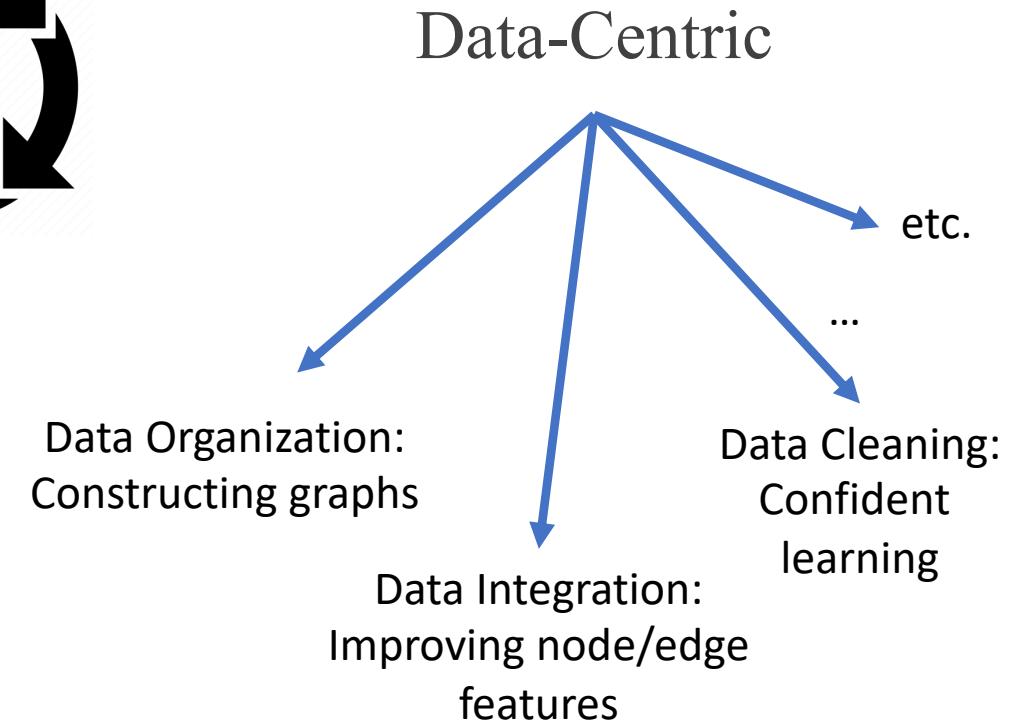
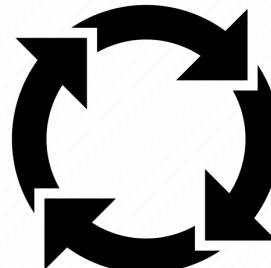
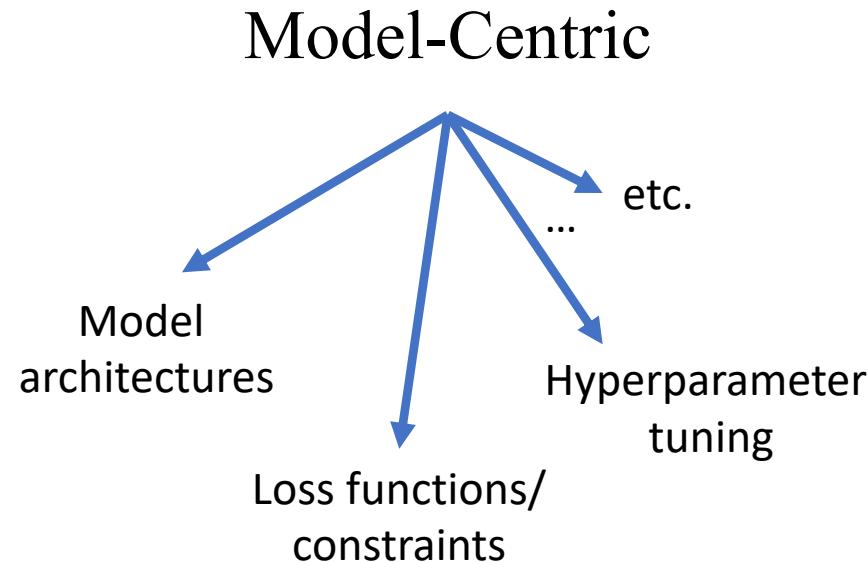
## Abnormal Graph Data



# Introduction and Background – Model- vs. Data-Centric Methods

Find the *best model* for  
the given *fixed dataset*

Realize the *best dataset* for  
the given *prediction task*



# Introduction and Background – Model- vs. Data-Centric Methods



Credit: MIT Introduction to Data-Centric AI course & Inspired by XKCD 2494 “Flawed Data”

# Data Quality-Aware Graph Machine Learning

- Introduction and Background
- Topology Issues
- Imbalance Issues
- Short Break
- Bias and Fairness Issues
- Limited Labeled Data Issues
- Abnormal Graph Data Issues
- Summary

# Outline

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- **Introduction and Background**
- Topology Issues
- Imbalance Issues
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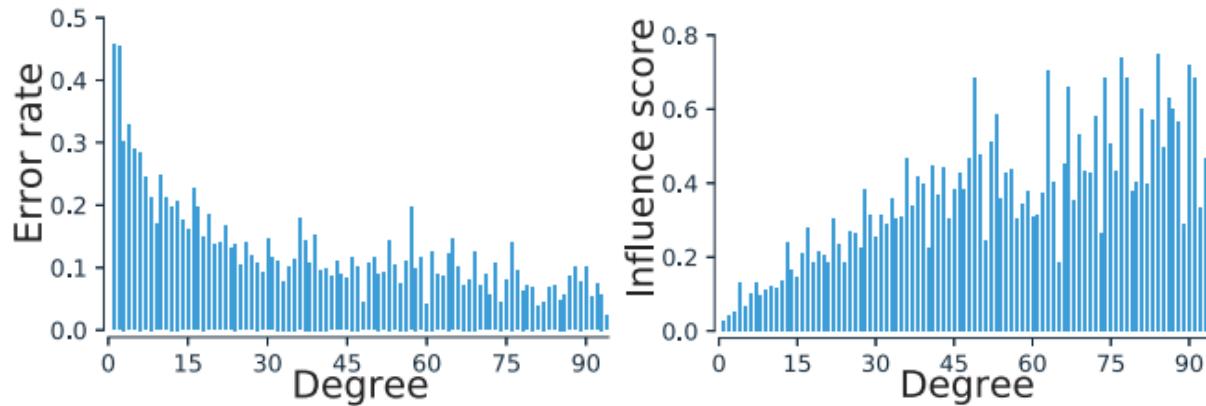
- Introduction and Background
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# Topology Issues

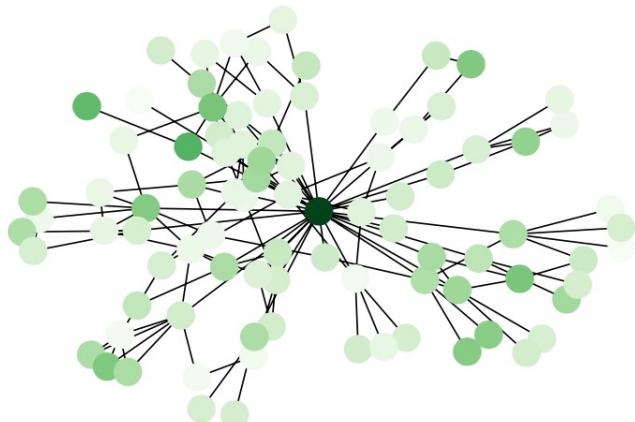
- Global Positional Issues
- Local Topology Issues
- Missing Graph Issues
- Future Directions and Q&A

# Topology Issues – Global Topology Issues – Labeled Node Influence

**Degree -> Influence**

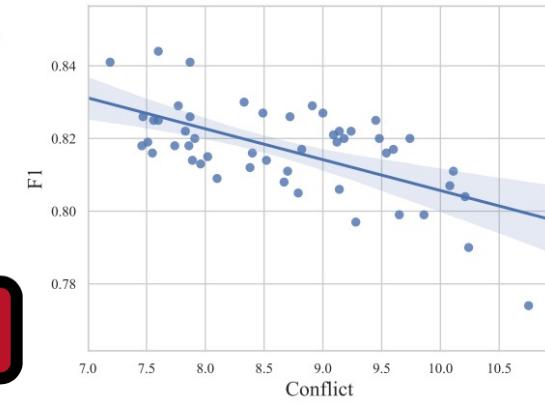
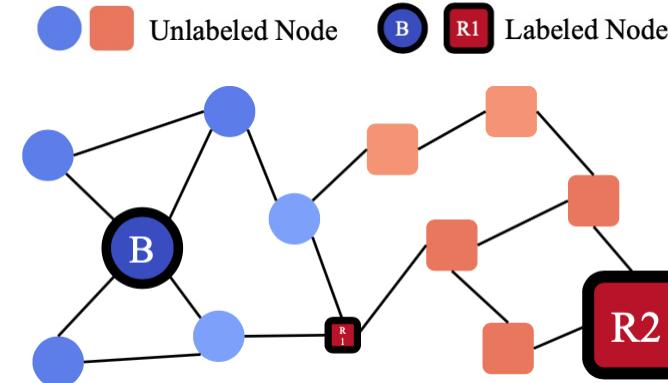


If  $d_i > d_j$ ,  $v_i$  has higher influence than  $v_j$  on training GNNs



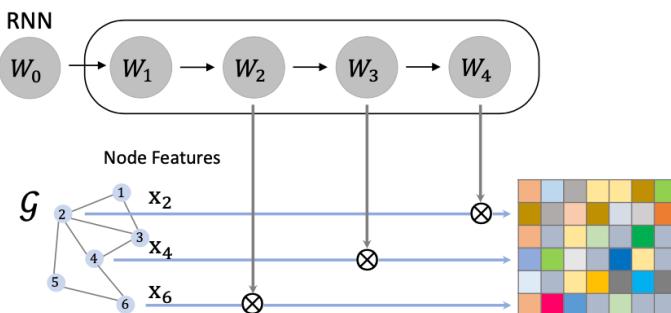
Darker colors - Higher influences.

**Position -> Influence**



$$\mathbf{x}_i^{l+1} = \sigma \left( \sum_{j \in \mathcal{N}_i} a_{ij} \left( \mathbf{W}^l + \boxed{\mathbf{W}_{d_j}^l} \right) \mathbf{x}_j^l \right)$$

Degree-dependent!



$$\mathbf{P} = \alpha(\mathbf{I} - (1 - \alpha)\mathbf{A}')^{-1}$$

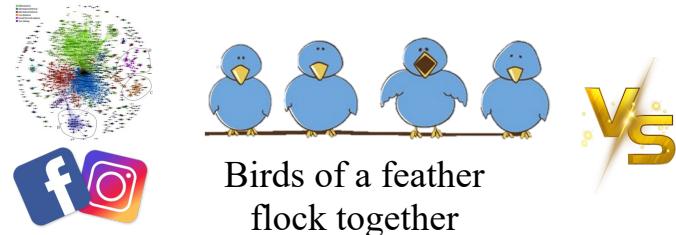
$$\boxed{\mathbf{T}_v} = \mathbb{E}_{\mathbf{x} \sim \mathbf{P}_{y_v}} \left( \sum_{j \in [1, k], j \neq y_v} |\mathcal{C}_j|^{-1} \sum_{i \in \mathcal{C}_j} \mathbf{P}_{i, x} \right)$$

$$L = -|\mathcal{L}|^{-1} \sum_{v \in \mathcal{L}} \boxed{w_v} \sum_{c=1}^k y_v^c \log p_v^c$$

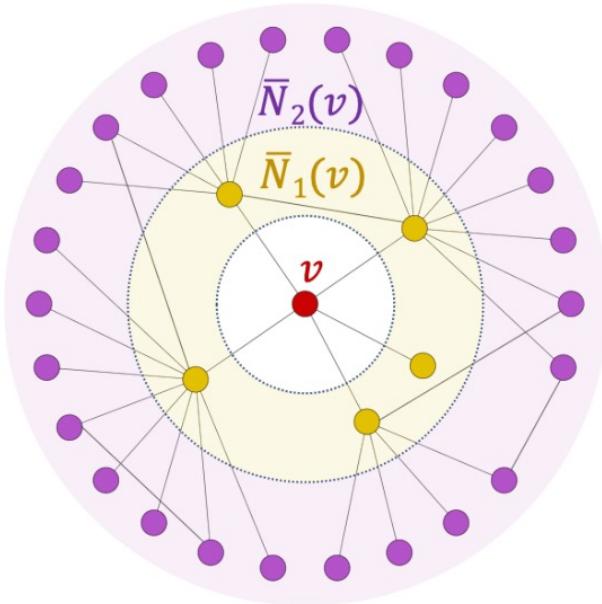
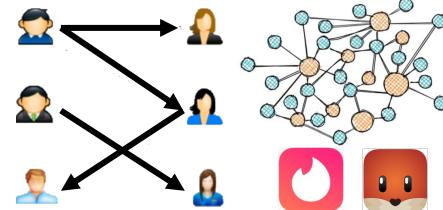
High T  
High Conflicts,  
low weight

# Topology Issue – Local Topology Issues – Heterophily/Homophily

## Homophily vs Heterophily



VS.



## Graph-level Homophily

$$h(\mathcal{G}, \{y_i; i \in \mathcal{V}\}) = \frac{1}{|\mathcal{E}|} \sum_{(j,k) \in \mathcal{E}} \mathbb{1}(y_j = y_k)$$

- Ego
- 1-order
- 2-order

## Ego-Neighbor Separation

$$\mathbf{r}_v^k = \text{COMBINE}(\mathbf{r}_v^{k-1}, \text{AGGR}(\{\mathbf{r}_u^{k-1}: u \in \mathcal{N}_v\}))$$

## Higher-order Neighbor

$$\mathbf{r}_v^k = \text{COMBINE}(\mathbf{r}_v^{k-1}, \text{AGGR}_1(\{\mathbf{r}_u^{k-1}: u \in \mathcal{N}_v^1\}), \text{AGGR}_2(\{\mathbf{r}_u^{k-1}: u \in \mathcal{N}_v^2\} \dots))$$

## Combination of Intermediate Representation

$$\mathbf{r}_v^k = \text{COMBINE}(\mathbf{r}_v^1, \mathbf{r}_v^2, \dots, \mathbf{r}_v^K)$$

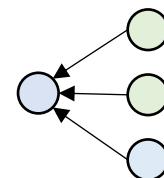
## Class belief propagation

$$\mathbf{B}^k = \mathbf{B}^0 + \underbrace{\mathbf{AB}^{k-1}\mathbf{H}}$$

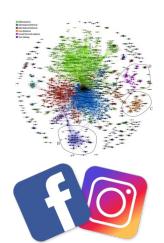
Transition  
among Graph

$$\mathbf{H} \in \mathbb{R}^{|Y| \times |Y|}$$

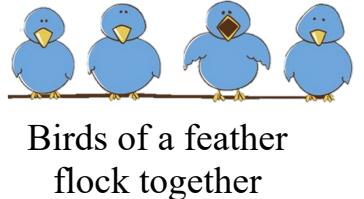
$$\mathbf{B} \in \mathbb{R}^{|V| \times |Y|}$$



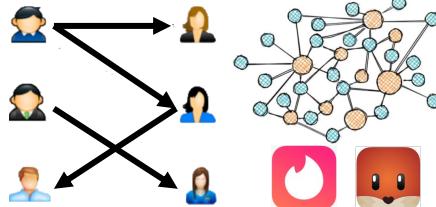
# Topology Issue – Local Topology Issues – Heterophily/Homophily



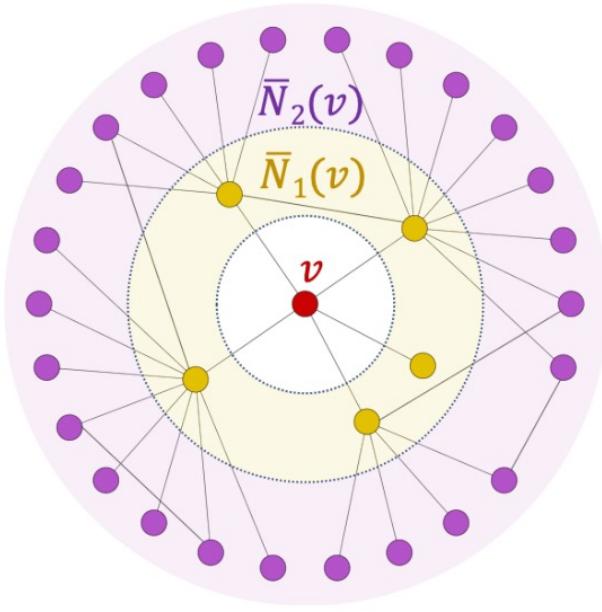
## Homophily vs Heterophily



VS.



Birds of a feather  
flock together



## Graph-level Homophily

$$h(\mathcal{G}, \{y_i; i \in \mathcal{V}\}) = \frac{1}{|\mathcal{E}|} \sum_{(j,k) \in \mathcal{E}} \mathbb{1}(y_j = y_k)$$

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## Higher-order Neighbor

$$\mathbf{r}_v^k = \text{COMBINE}(\mathbf{r}_v^{k-1}, \text{AGGR}_1(\{\mathbf{r}_u^{k-1}: u \in \mathcal{N}_v^1\}), \text{AGGR}_2(\{\mathbf{r}_u^{k-1}: u \in \mathcal{N}_v^2\} \dots))$$

## Combination of Intermediate Representation

$$\mathbf{r}_v^k = \text{COMBINE}(\mathbf{r}_v^1, \mathbf{r}_v^2, \dots, \mathbf{r}_v^K)$$

## Class belief propagation

$$\mathbf{B}^k = \mathbf{B}^0 + \underbrace{\mathbf{AB}^{k-1}\mathbf{H}}$$

Graph Transition  
Class Transition

$\mathbf{AB}^{k-1}$   
[0.1|0.1|0.8]  
○

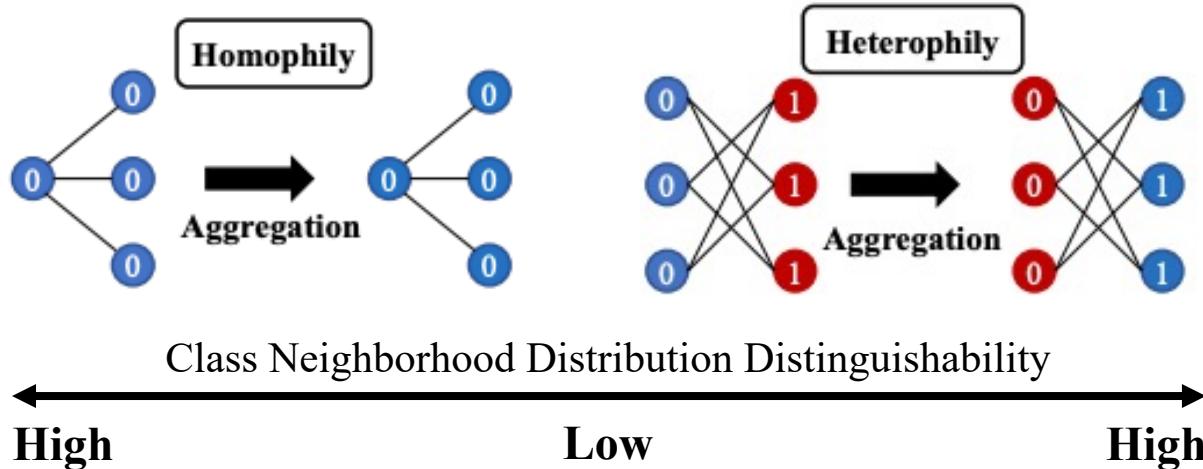
$$\mathbf{H} \in \mathbb{R}^{|\mathcal{Y}| \times |\mathcal{Y}|}$$

$$\mathbf{B} \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{Y}|}$$

$$\begin{bmatrix} 0.1 & 0.3 & 0.6 \\ 0.8 & 0.1 & 0.1 \\ 0.7 & 0.3 & 0 \end{bmatrix} \quad \mathbf{H}$$

# Topology Issue – Local Topology Issues – Heterophily/Homophily

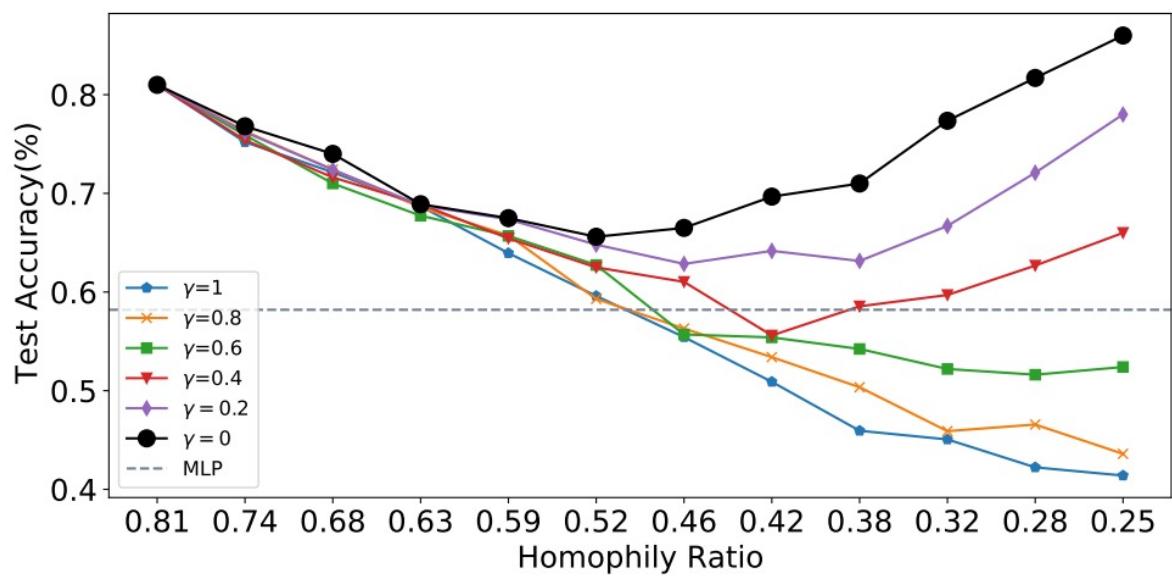
## Across Different Graphs



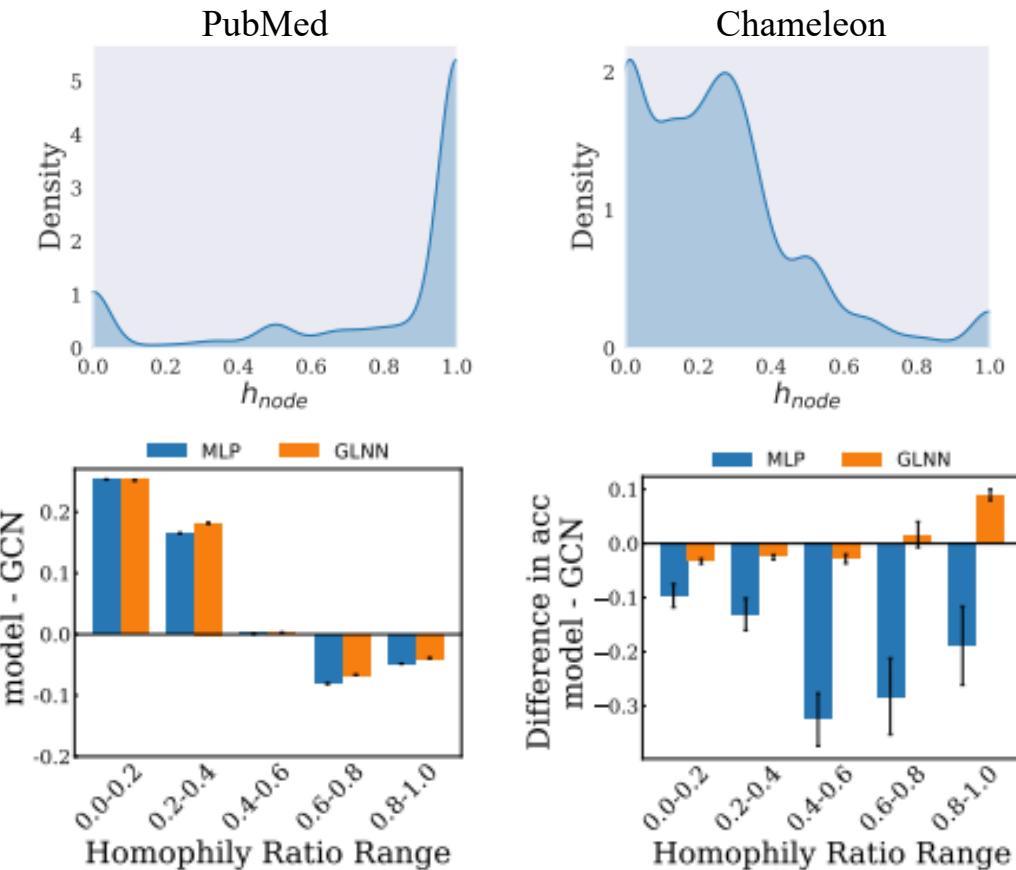
High

Low

High



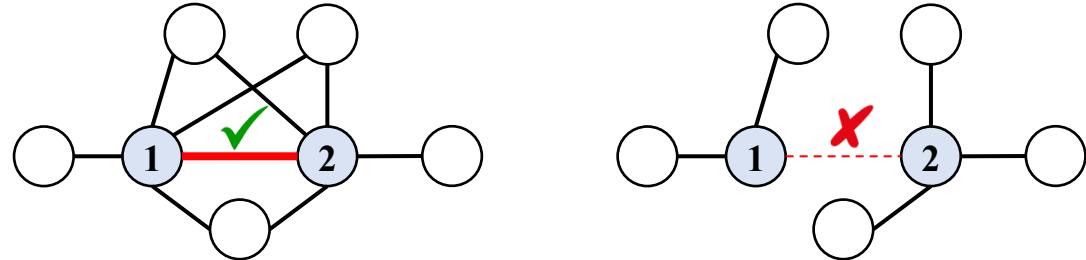
## Within the Same Graph



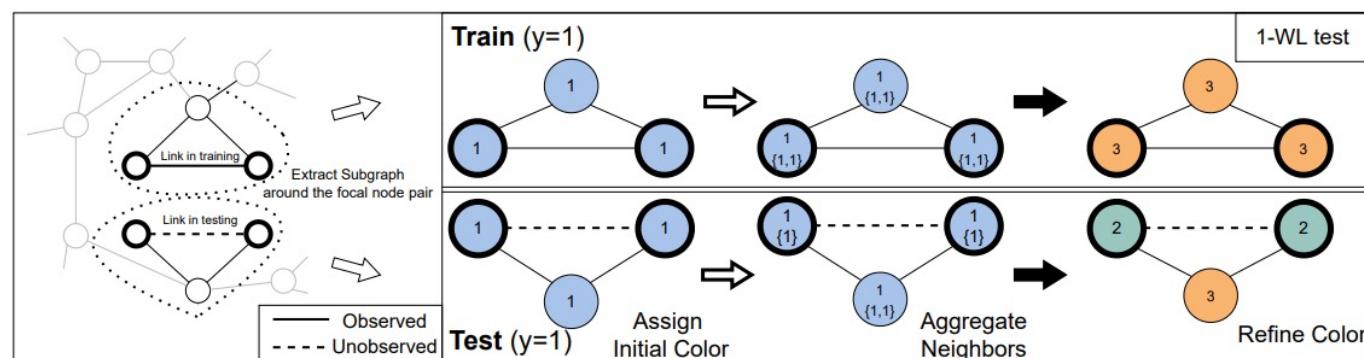
In **homophily** graph, GNNs > MLP on **homophily** nodes  
In **heterophily** graph, GNNs > MLP on **heterophily** nodes

# Topology Issue – Local Topology Issues – Training-to-Testing Topology Shift

## Link Prediction

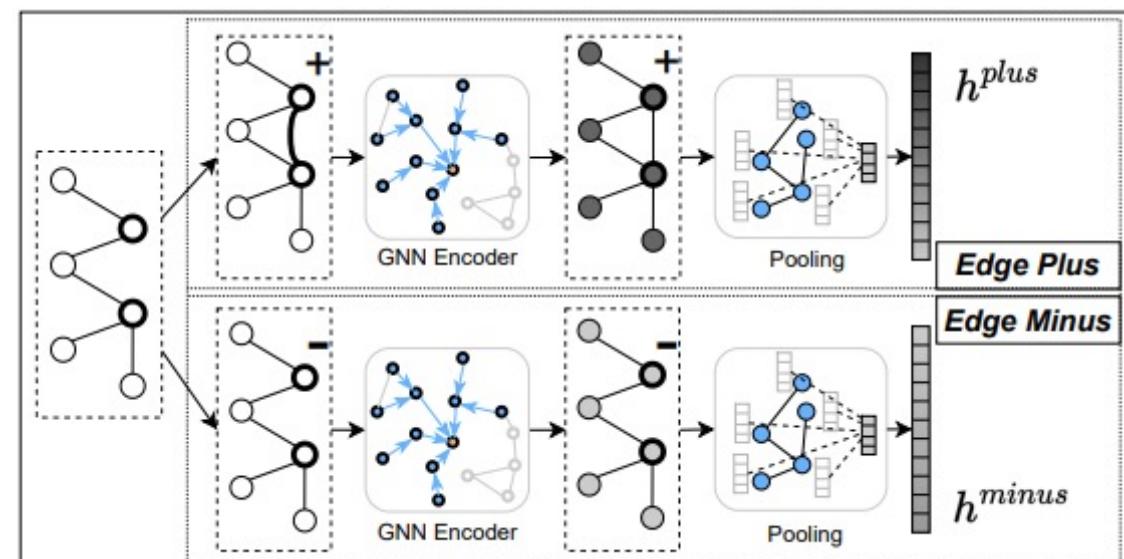
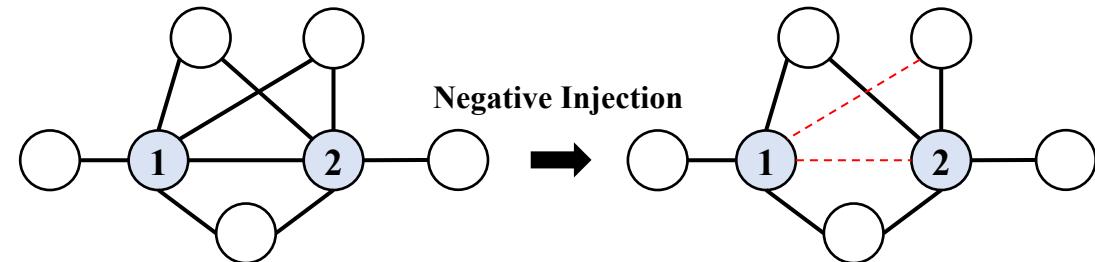


Local Subgraph → Predictor → Link



Focal Link is missing from training subgraph to testing subgraph

**Distribution Shift**



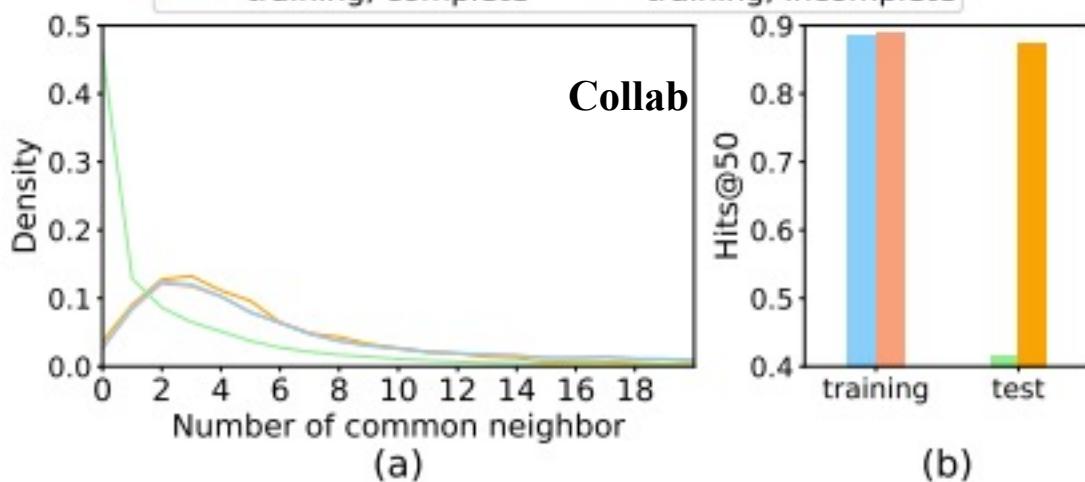
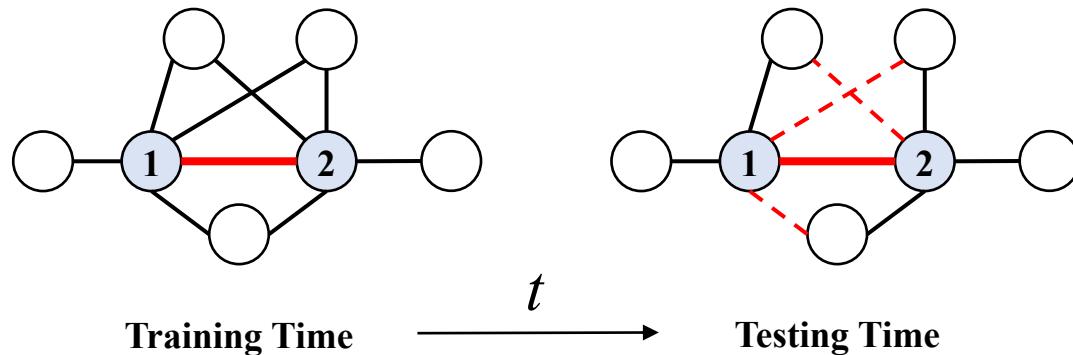
$$\mathbf{h}^{\text{mean}} = \frac{(\mathbf{h}^+ + \mathbf{h}^-)}{2}$$

$$\mathbf{h}^{\text{mean}} = w^+ \mathbf{h}^+ + w^- \mathbf{h}^-$$

$$w^+ = \sigma(\mathbf{q}^T \tanh(\mathbf{W}\mathbf{h}^+ + \mathbf{b}))$$

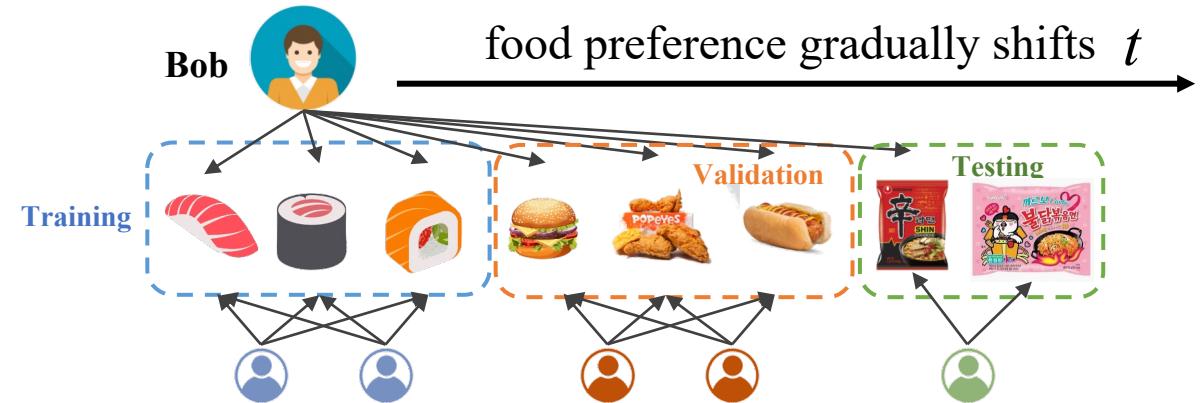
# Topology Issue – Local Topology Issues – # of Common Neighbor Shift

## Link-centric Perspective



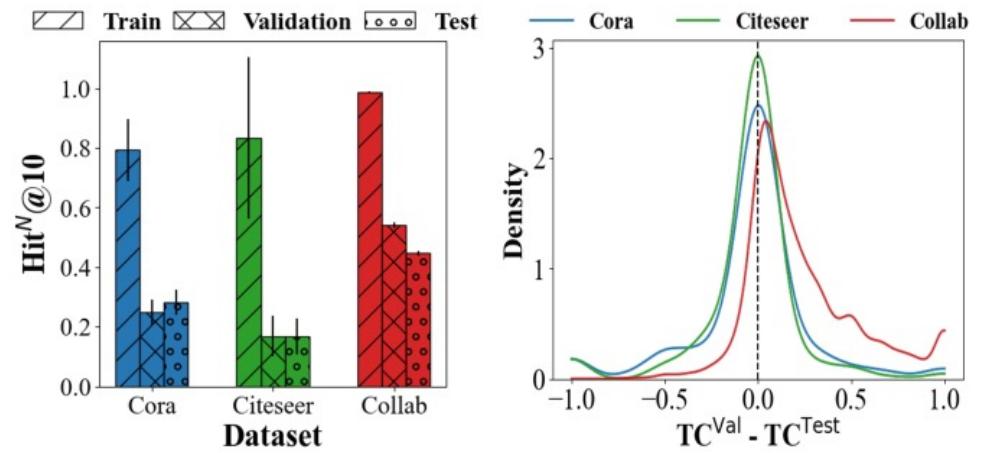
**Time-based Split**  
Testing edges have more testing edges around

## Node-centric Perspective



$\mathbf{TC^{Val}}$ : Common interaction between training and validation

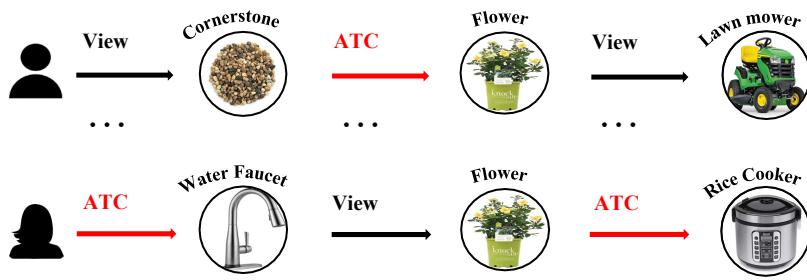
$\mathbf{TC^{Test}}$ : Common interaction between training and validation



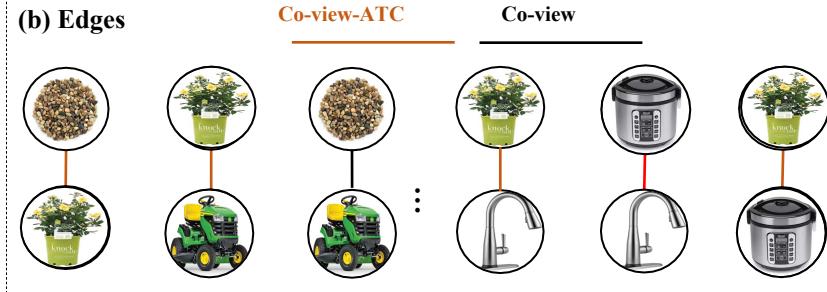
# Topology Issue – Missing Topology Issues

## User/Item Interaction

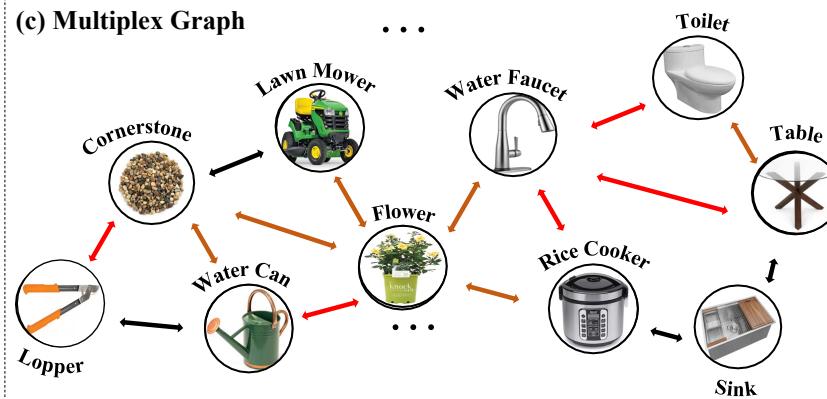
(a) User historical sequences



(b) Edges



(c) Multiplex Graph



## Multi-hop Reasoning

Q: In what year was the creator of the current arrangement of the Simpson's Theme born?

S<sub>1</sub>: The Simpson's Theme was re-arranged during season 2, and the current arrangement by Alf Clausen was introduced at the beginning of season 3

S<sub>2</sub>: Alf Heiberg Clausen (**born March 28, 1941**) is an American film and television composer.

A: March 28, 1941

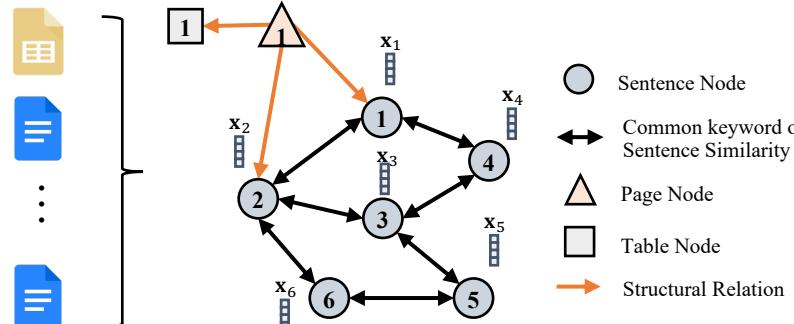
Q

S<sub>1</sub>

S<sub>2</sub>

A

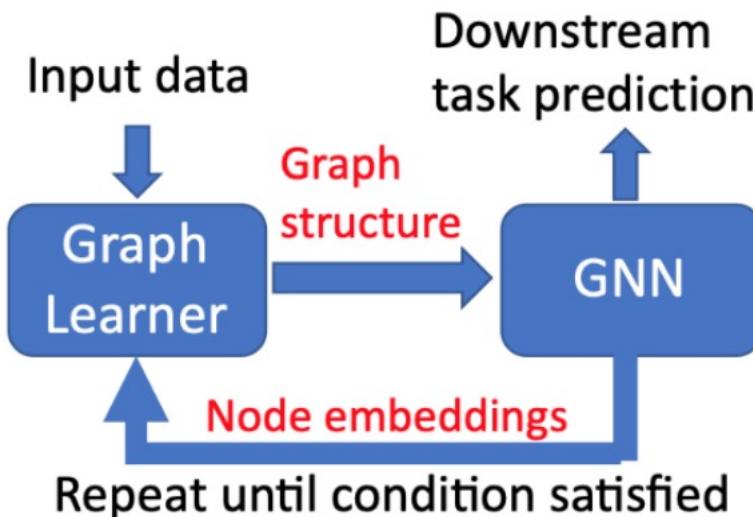
## Document Graph Construction



Sometimes Real-world Applications do not have Graphs!

But Graph can actually encode some useful information

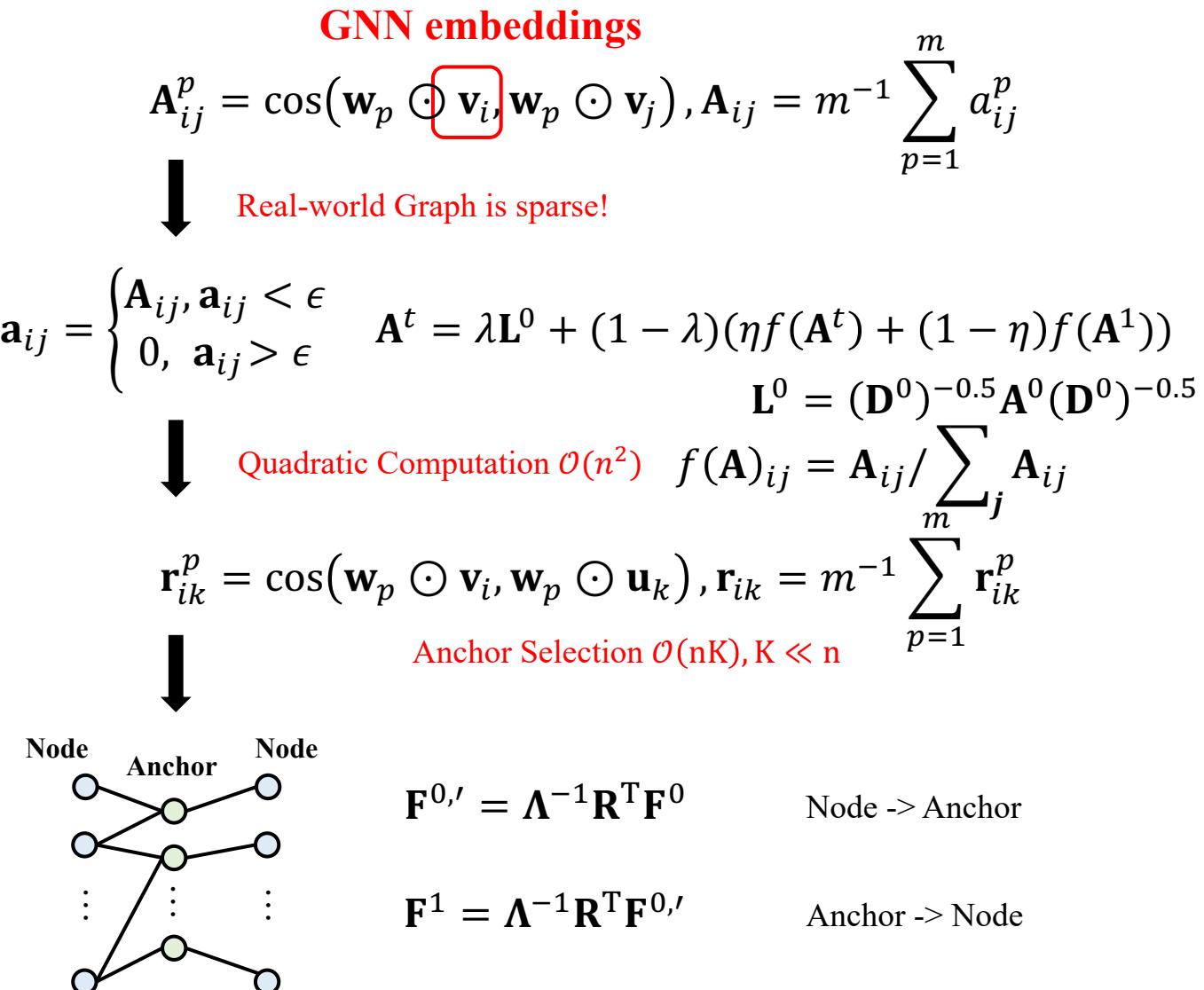
# Topology Issue – Missing Topology Issues



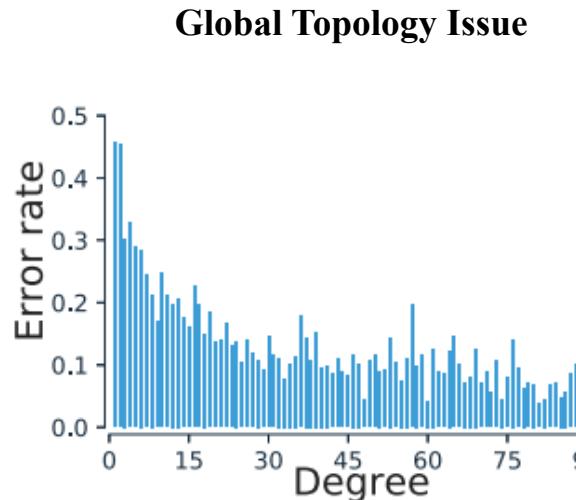
Better Graph Structure



Better Node Embeddings



# **Q&A and Future Work – Topology Issue**



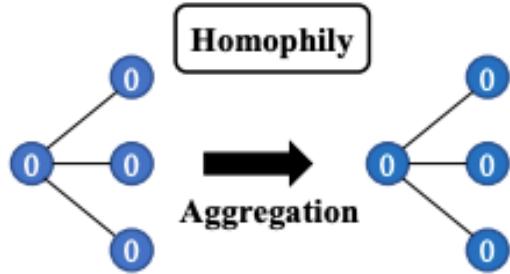
**Q:** In what year was the creator of the current arrangement of the Simpson's Theme born?

**S<sub>1</sub>** : The Simpson's Theme was re-arranged during season 2, and the current arrangement by Alf Clausen was introduced at the beginning of season 3

**S<sub>2</sub>:** Alf Heiberg Clausen (*born March 28, 1941*) is an American film and television composer.

A: March 28, 1941

Local Topology Issue



## Heterophily

## Class Neighborhood Distribution Distinguishability

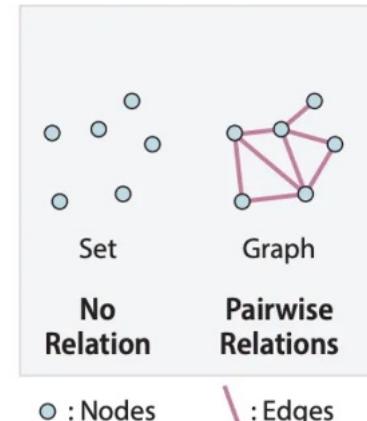
High



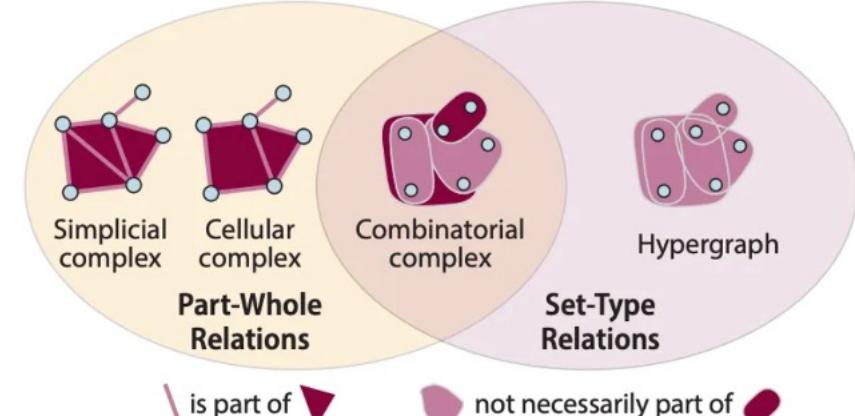
High

## **Topology Issue of Complex Graphs**

## Traditional Discrete Domains



## Domains of Topological Deep Learning



# Outline

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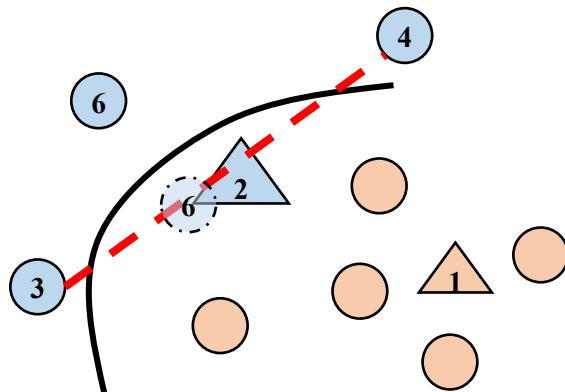
- Introduction and Background
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- **Imbalance Issues**
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# Imbalance Issues

- Node-level Imbalance
- Graph-level Imbalance
- Edge-level Imbalance
- Future Directions and Q&A

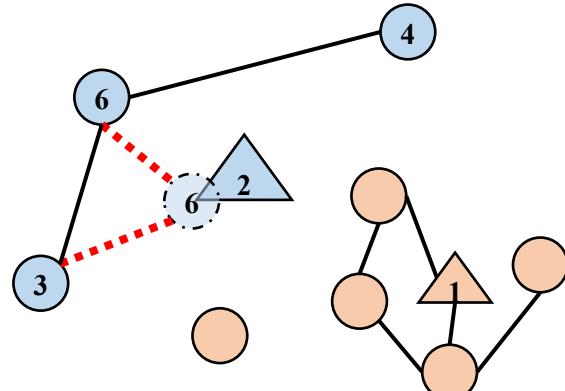
# Imbalance Issues – Node-level imbalance

**SMOTE**



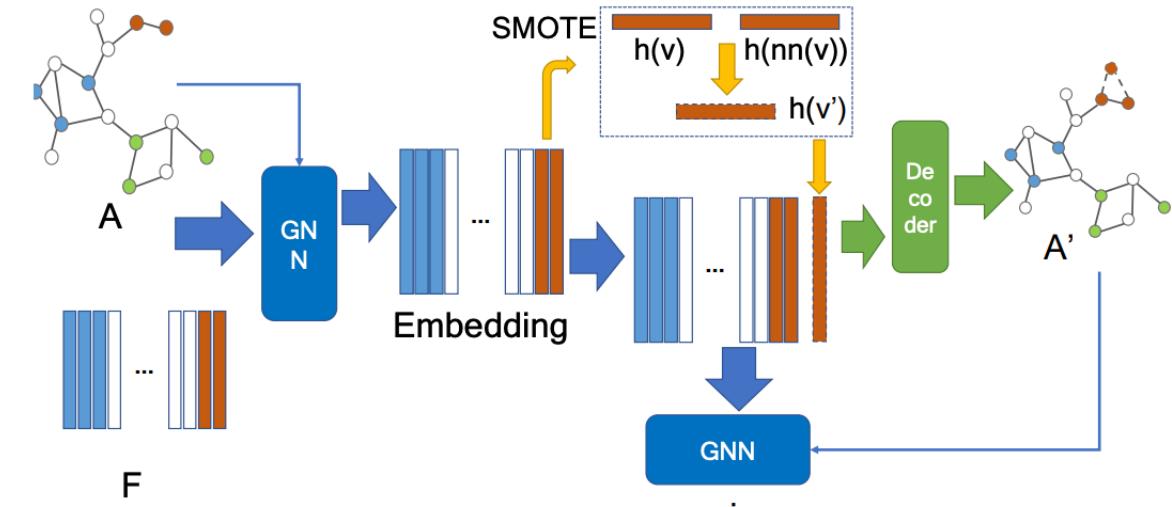
- Feature Interpolation
- Train – Major
- Train – Minor
- △ Test – Major
- △ Test – Minor

**Graph-structured data has both feature and edge**



- Feature Interpolation
- Edge Generation

**GraphSMOTE**



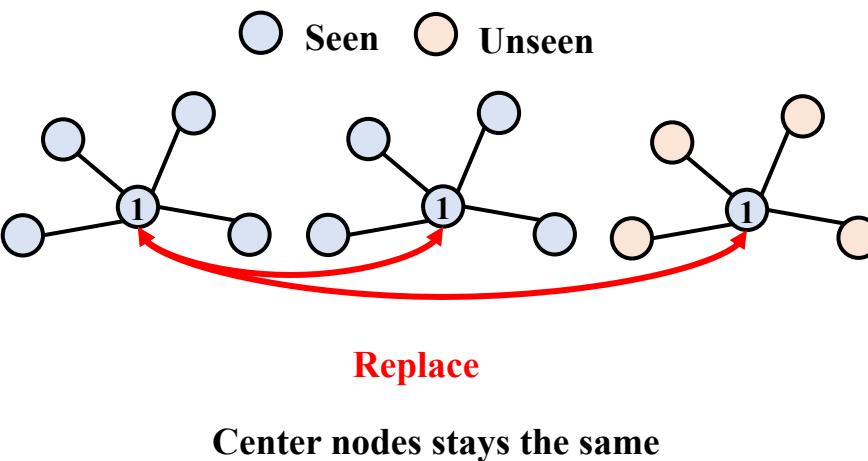
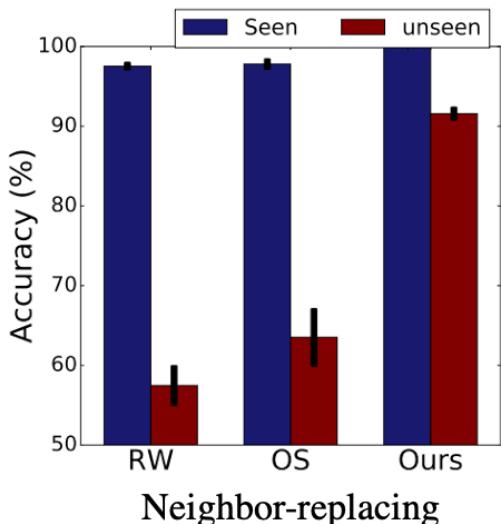
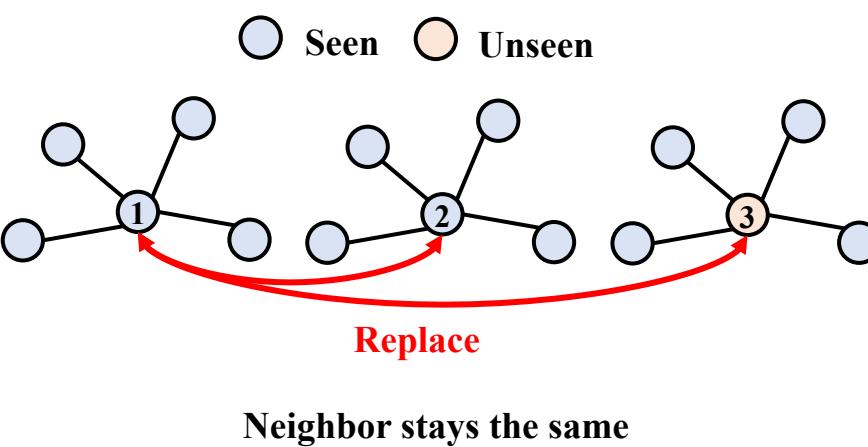
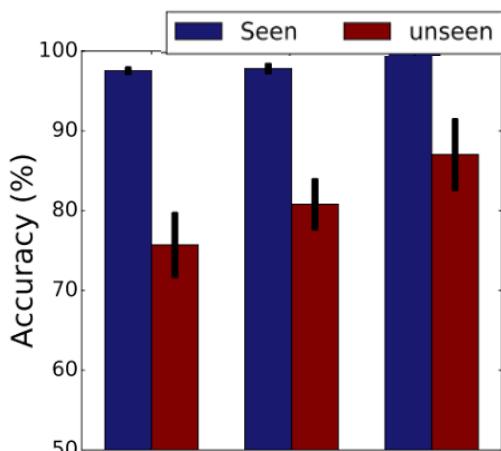
$$nn(v) = \operatorname{argmin}_u \|\mathbf{h}_u^1 - \mathbf{h}_v^1\|, \text{ s.t. } \mathbf{Y}_u = \mathbf{Y}_v$$

$$\mathbf{h}_{v'}^1 = (1 - \delta)\mathbf{h}_v^1 + \delta\mathbf{h}_{nn(v)}^1$$

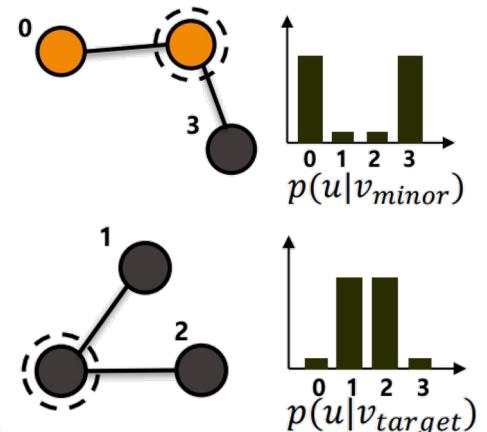
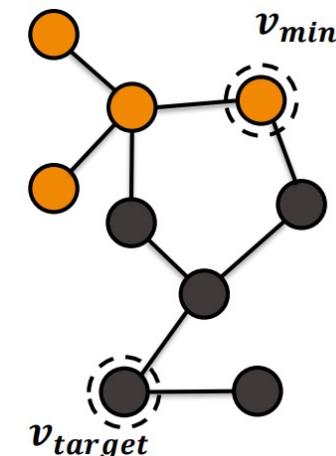
$$\mathbf{A}_{v'u} = \begin{cases} 1, & \text{if } \mathbf{E}_{v'u} \geq \eta \\ 0, & \text{otherwise} \end{cases} \quad \mathcal{L}_{edge} = \|\mathbf{E} - \mathbf{A}\|_F^2$$

$$\mathbf{E}_{vu} = \operatorname{softmax}(\sigma(\mathbf{h}_v^1 \mathbf{S} \mathbf{h}_u^1))$$

# Imbalance Issues – Node-level imbalance



## Neighborhood Memorization



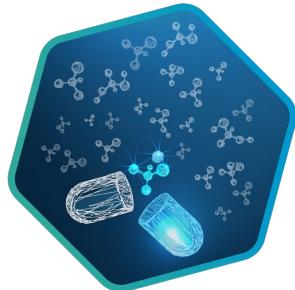
$$p(u|v_{mixed}) = \hat{\phi}p(u|v_{minor}) + (1 - \hat{\phi})p(u|v_{target})$$

$$0.5 < \hat{\phi} = \frac{1}{1 + e^{-\phi}} < 1 \quad \phi = KL(\sigma(\mathbf{o}_{minor}) || \sigma(\mathbf{o}_{target}))$$

$$\mathbf{o}_{minor} = |\mathcal{N}_v|^{-1} \sum_{u \in \mathcal{N}_v} \mathbf{o}_{minor}$$

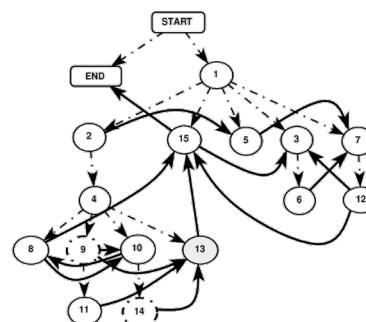
# Imbalance Issues – Graph-level imbalance

## Drug Discovery



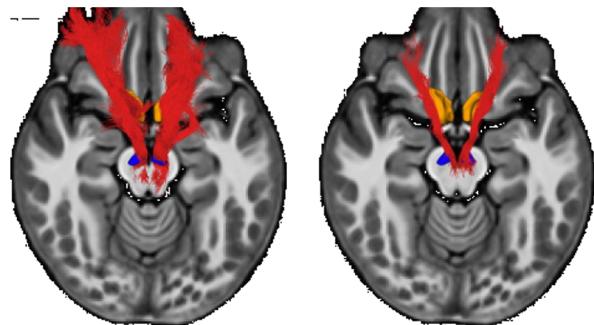
HTS Hit Ratio  
0.05% to 0.5%

## Malware Detection



0.01% Google, 2% Android,

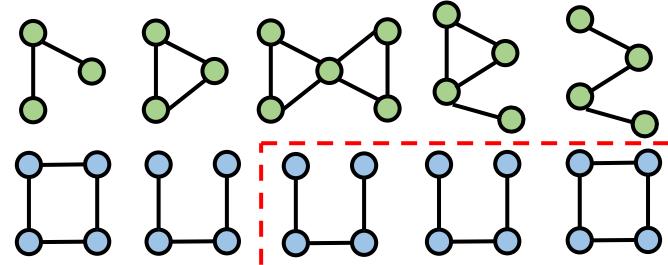
## ASD Brain Classification



Normal : Autism  
36 : 1

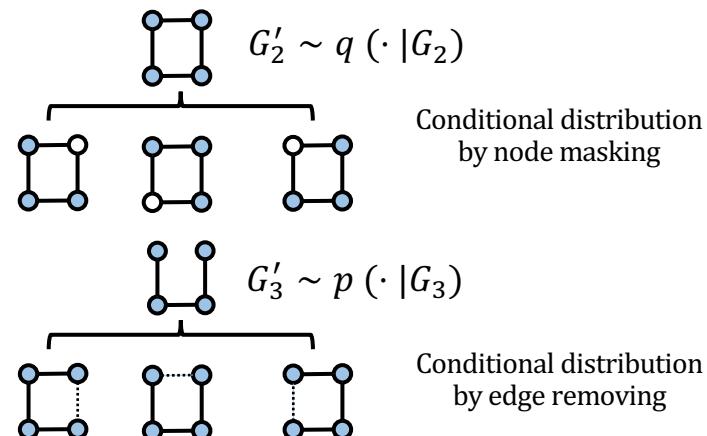
Autism Statistics. 2023

## Quantity Augmentation

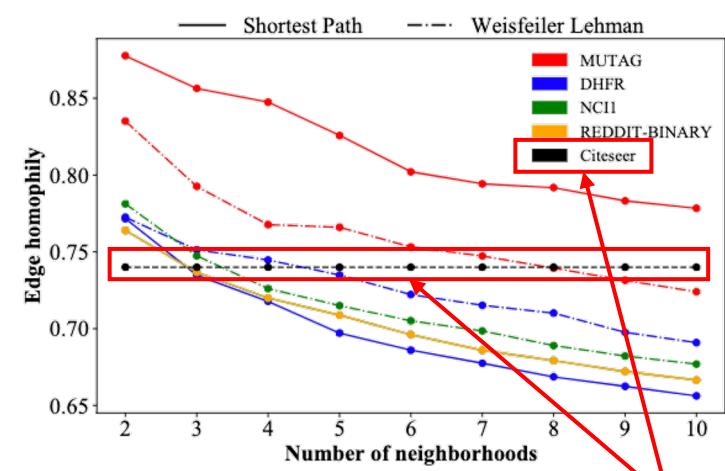
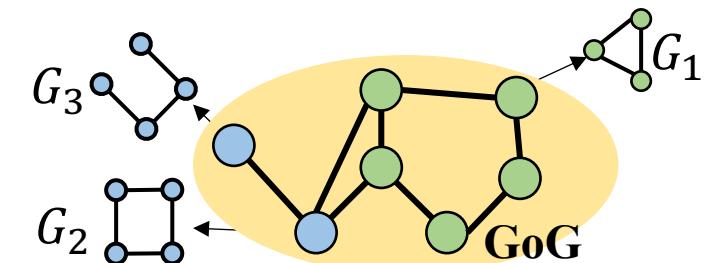


## Structure Augmentation

SPP - Structurally Similar Molecules tend to have similar properties

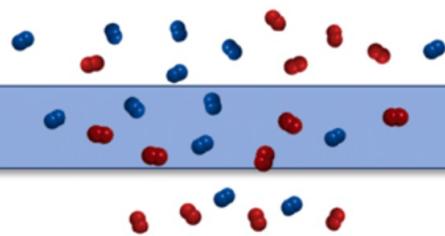


## Graph-of-Graphs (GoG)



Constructed GoG demonstrates high homophily!

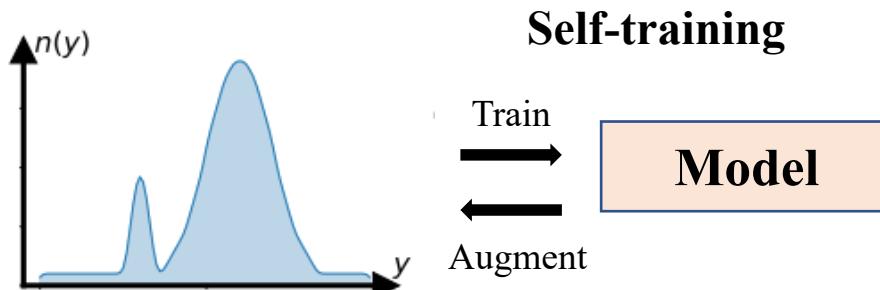
# Imbalance Issues – Graph-level imbalance



● : O<sub>2</sub> (3.46Å)  
● : N<sub>2</sub> (3.64Å)

70 years, ~600 polymers, oxygen permeability ,  
Polymer Gas Separation Membrane Database

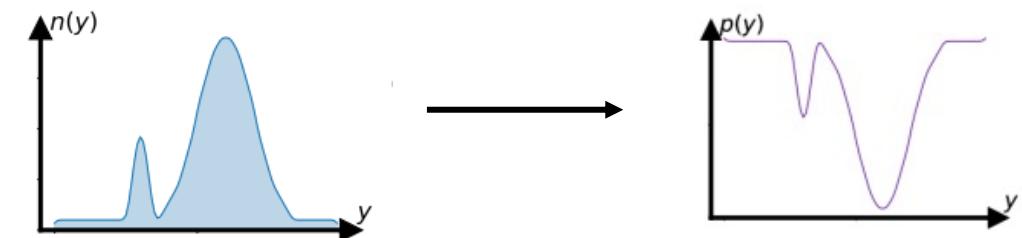
## Imbalance Graph Regression!



- (1) Use Model to predict on unlabeled graphs and select those high-quality-one

$$\sigma_i = \frac{1}{\text{Var} \left( \{f(g(G_{(i,j)}))\}_{j=1,2,\dots,B} \right)}.$$

- (2) Sample more for label interval with less training samples



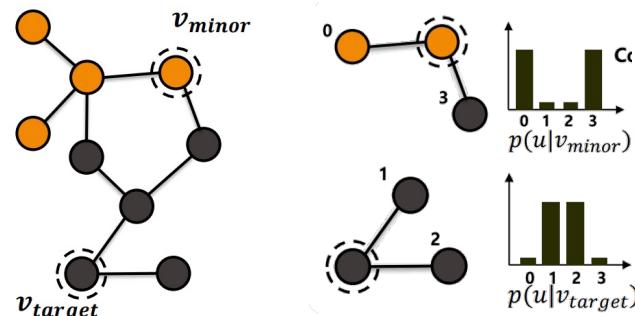
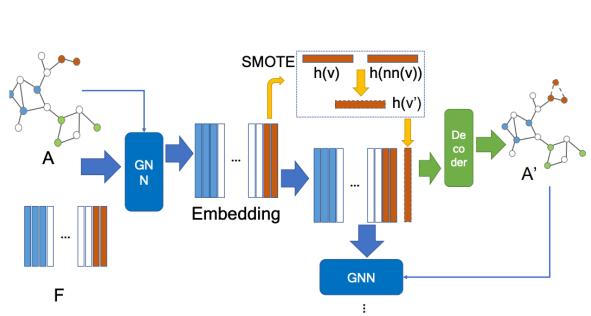
- (3) Anchor-based Mix-up

$a_i, \mathbf{z}_i$ : anchor-label  
and embedding

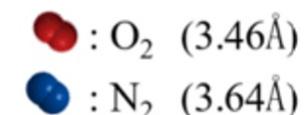
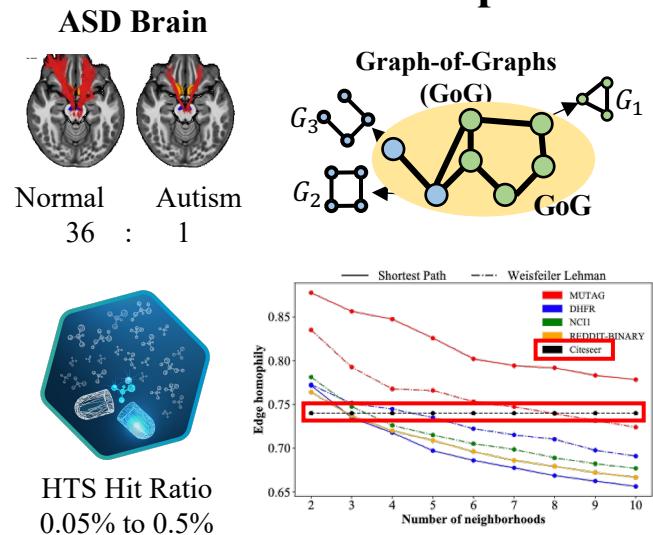
$$\begin{cases} \tilde{\mathbf{h}}_{(i,j)} &= \lambda \cdot \mathbf{z}_i + (1 - \lambda) \cdot \mathbf{h}_j, \\ \tilde{y}_{(i,j)} &= \lambda \cdot a_i + (1 - \lambda) \cdot y_j, \end{cases}$$

# Q&A and Future Work – Imbalance Issues

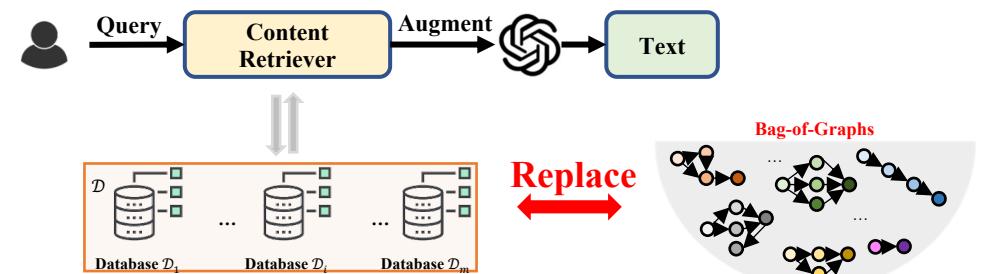
## Node-level Imbalance



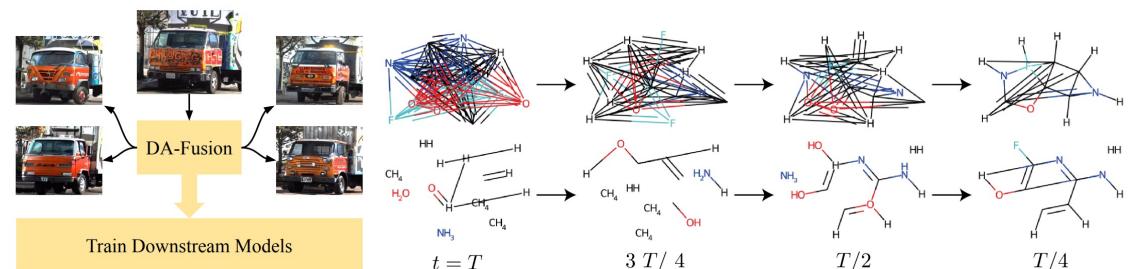
## Graph-level Imbalance



## Retrieval Additional Supervision



## Generate Additional Supervision



## Short Break (4 min)

# Outline

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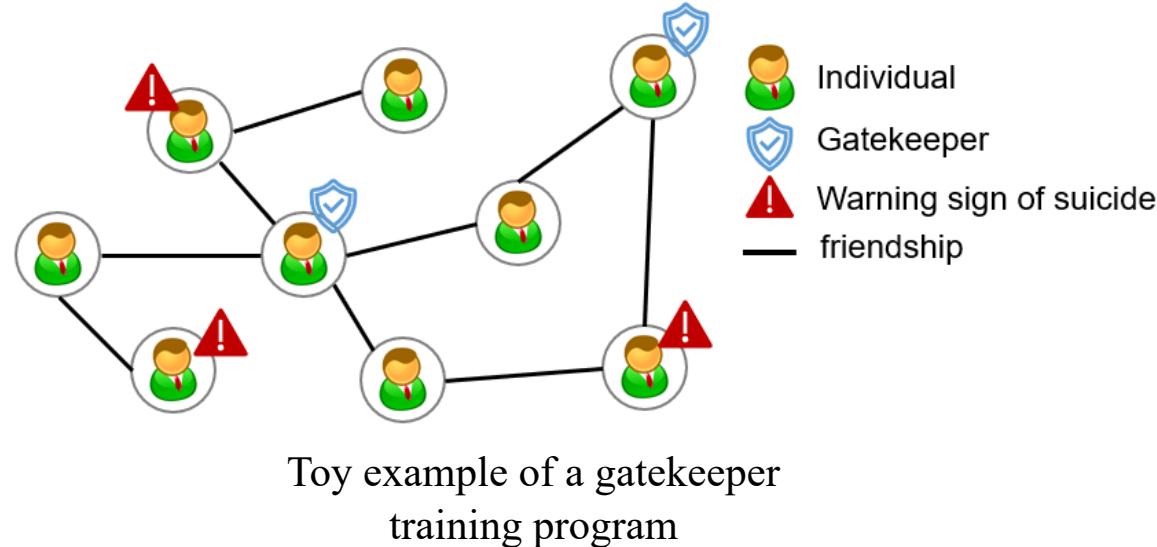
- Introduction and Background
- Topology Issues
- Imbalance Issues
- Short Break
- **Bias and Fairness Issues**
- Limited Labeled Data Issues
- Abnormal Graph Data Issues
- Summary

# Bias and Fairness Issues - Suicide Prevention

- Why suicide prevention?



Gatekeeper training  
programs



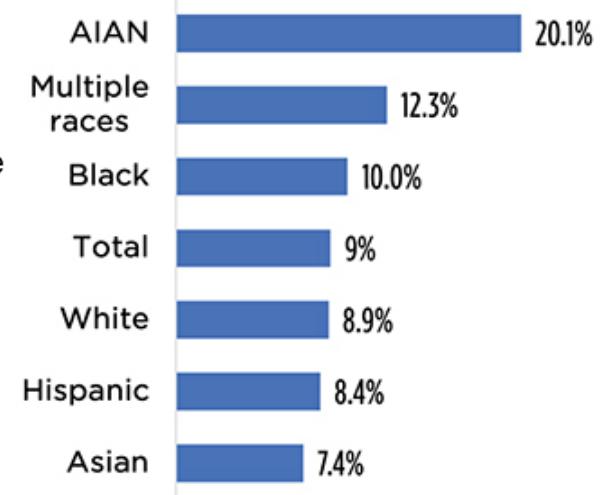
Toy example of a gatekeeper training program

- Existing prevention strategies **disproportionately** affect different groups

- Key question

- How to correct the bias and ensure fairness on graphs?

Percentage of high schoolers reporting a suicide attempt in the past 12 months, by race/ethnicity



Suicide attempts  
by race/ethnicity

# Bias and Fairness Issues - Fairness Definition

- **Principle**
  - Lack of favoritism from one side or another
- **Rich fairness definitions**
  - Group fairness
    - Statistical parity
    - Equal opportunity
    - Equalized odds
    - Accuracy parity
    - ...
  - Individual fairness
  - Counterfactual fairness
  - Degree fairness (on graphs)



## Fairness definition

Group fairness

Individual fairness

Counterfactual fairness

Degree fairness

## Two sides

Two demographic groups

Two data points

A data point and its counterfactual version

Two group of nodes with same degree

- **Group Fairness on Graphs**
- Individual Fairness on Graphs
- Degree Fairness on Graphs
- Future Directions and Q&A

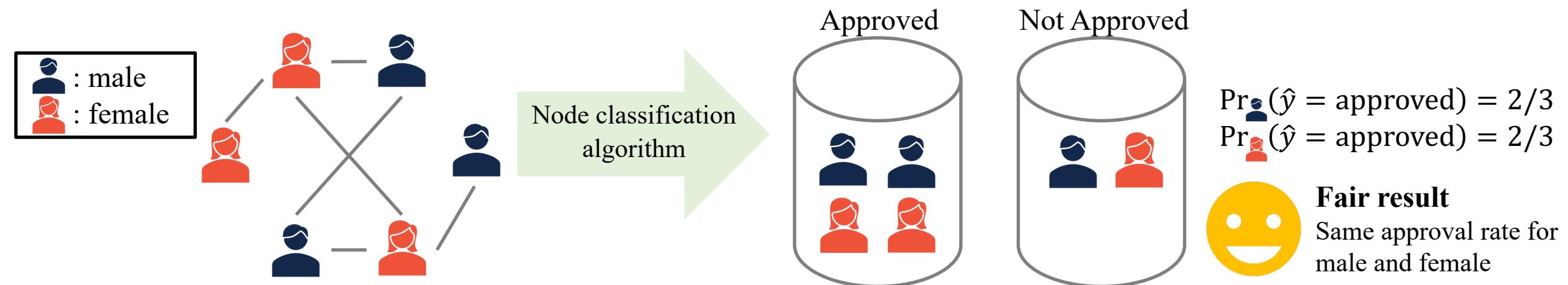
# Group Fairness: Statistical Parity

- Statistical parity = equal acceptance rate

$$\Pr_+(\hat{y} = c) = \Pr_-(\hat{y} = c)$$

- $\hat{y}$ : model prediction
- $\Pr_+$ : probability for the protected group
- $\Pr_-$ : probability for the unprotected group
- Also known as demographic parity, disparate impact

- Example: clinical trial participation



# Group Fairness: Equal Opportunity

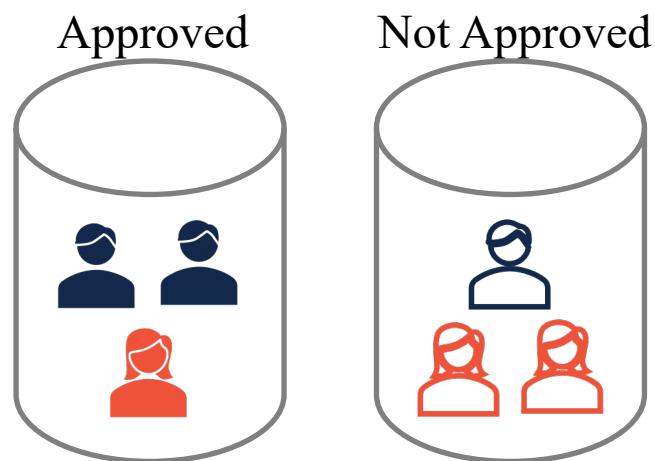
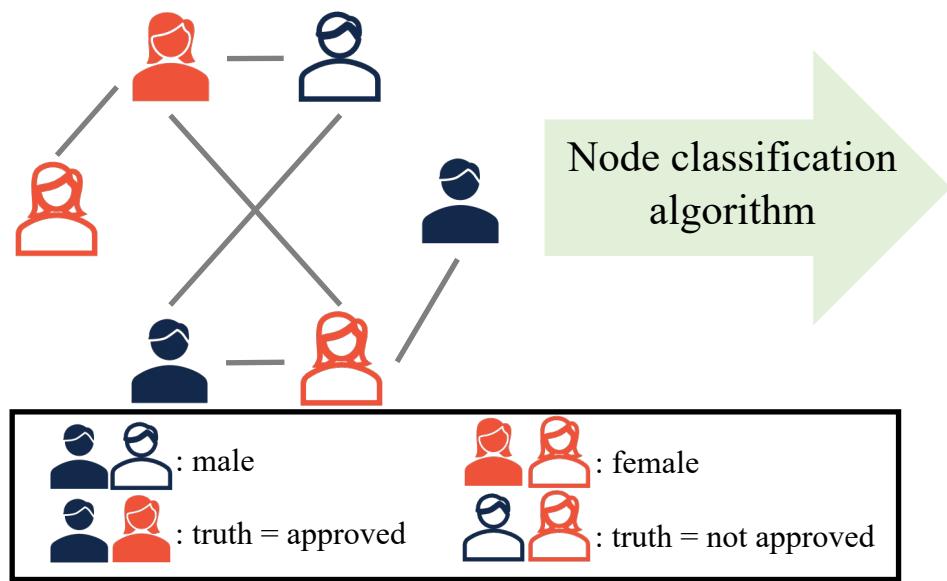
- Equal opportunity = equal true positive rate

$$\Pr_+(\hat{y} = c | y = c) = \Pr_-(\hat{y} = c | y = c)$$

- $y$ : true label
- $\hat{y}$ : model prediction
- $\Pr_+$ : probability for the protected group
- $\Pr_-$ : probability for the unprotected group

If hold for all classes, it is called **equalized odds**

- Example: clinical trial participation



$$\Pr_{\text{blue}}(\hat{y} = \text{approved} | \text{blue}) = 1$$
$$\Pr_{\text{red}}(\hat{y} = \text{approved} | \text{red}) = 1$$



**Fair result**

Same true positive rate for male and female

# Adversarial Learning for Fair Representation Learning

- **Statistical parity**

- Independence between the learned embedding  $\mathbf{z}$  and a sensitive attribute  $a$   
 $\mathbf{z}_u \perp a_u, \forall \text{ node } u$

where  $a_u$  is the sensitive value of node  $u$

- **Formulation**

- Mutual information minimization

$$I(\mathbf{z}_u, a_u) = 0, \forall \text{ node } u$$

- Analogous to statistical parity in classification task
- Fail to predict  $a_u$  using  $\mathbf{z}_u$   ← no information about  $a_u$  in  $\mathbf{z}_u$

- **Solution**

- Adversarial learning
- Encoder: encode node into low-dimensional embedding space for downstream tasks
- Discriminator: fail to predict  $a_u$  using  $\mathbf{z}_u$

Corresponding to  
'adversarial'

# Limitation #1: Full Access to Sensitive Attribute Information

- **Adversarial learning**

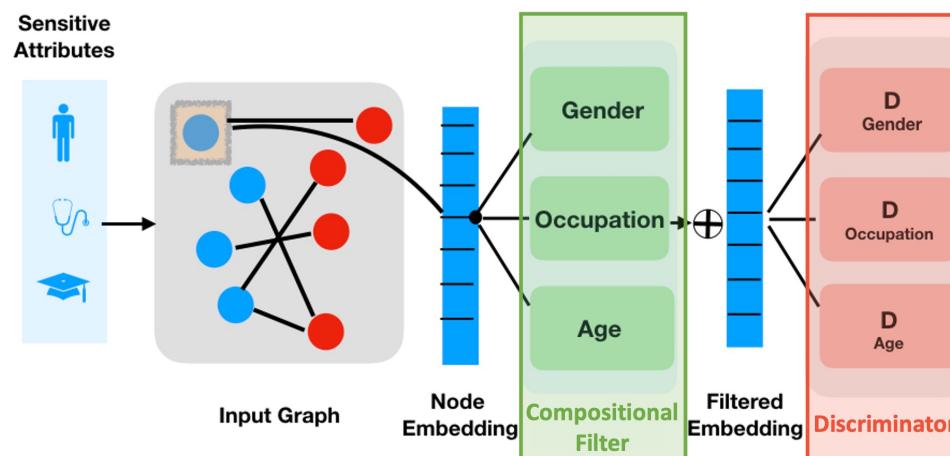
- Minimize a task-specific loss function to learn ‘**good**’ representations
- Maximize the error of predicting sensitive feature to learn ‘**fair**’ representations

- **Limitations**

- Require the sensitive attribute of all training nodes to train a good discriminator
- Ignore the fact that sensitive information is hard to obtain due to privacy

- **Question**

- What if we only have **limited** sensitive attribute information?



# FairGNN: Additional Supervision Signal

## • Observation

- Adversarial learning is unstable to train  $\leftarrow$  even worse with limited sensitive attribute
- Failure to converge may also cause discrimination

## • Key idea

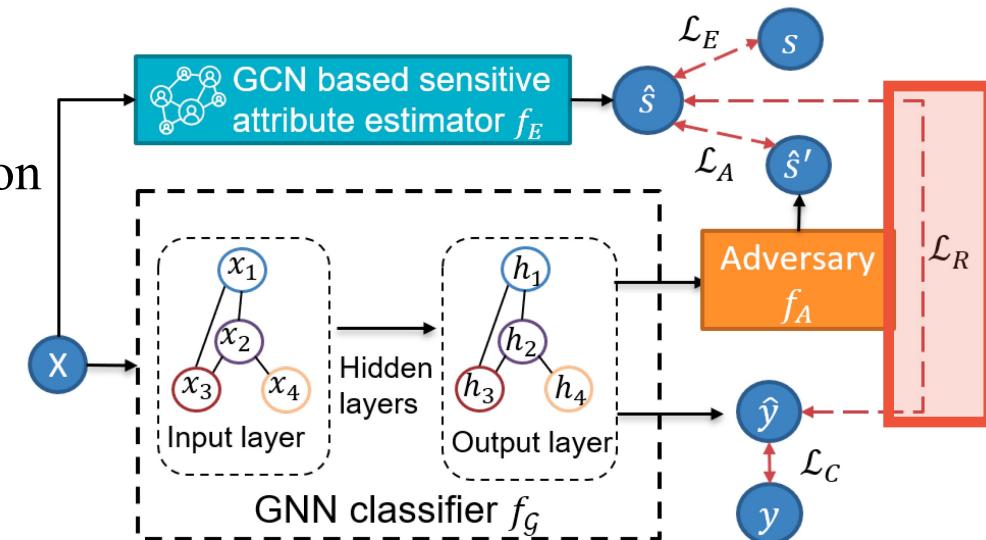
- Additional prerequisite of independence for additional supervision
- Independence  $\rightarrow$  zero covariance

## • Solution

- Pseudo sensitive attribute from a sensitive attribute estimator
  - Not embedding from encoder
  - Offer pseudo-label for covariance minimization
- Absolute covariance minimizer to minimize absolute covariance between model prediction  $\hat{y}$  and pseudo sensitive attribute  $\hat{s}$

$$\mathcal{L}_R = |\text{cov}(\hat{s}, \hat{y})| = |\mathbb{E}[(\hat{s} - \mathbb{E}[\hat{s}])(\hat{y} - \mathbb{E}[\hat{y}])]|$$

- Absolute covariance to avoid minimizing negative covariance



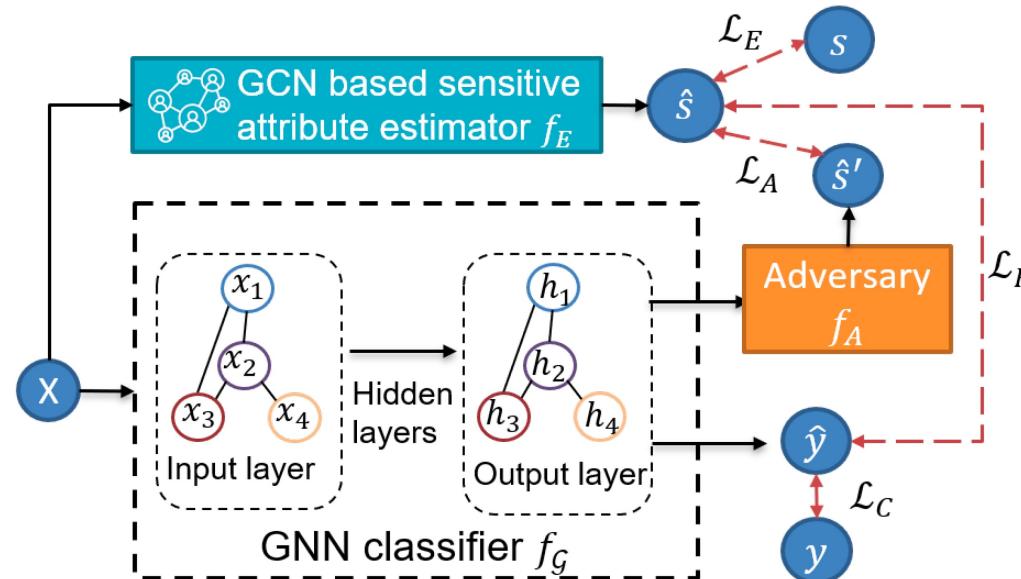
# FairGNN: Overall Framework

- Overall loss function

$$\mathcal{L} = \mathcal{L}_C + \mathcal{L}_E - \alpha \mathcal{L}_A + \beta \mathcal{L}_R$$

- Intuition

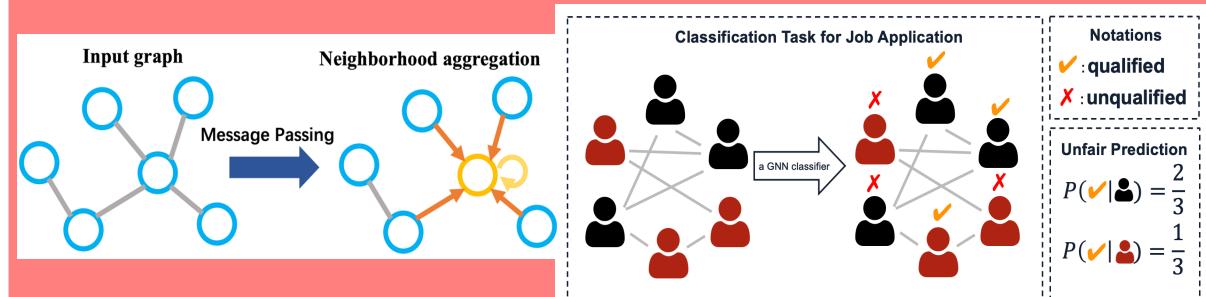
- $\mathcal{L}_C$ : classification loss (e.g., cross entropy) for learning representative node representation
- $\mathcal{L}_E$ : sensitive attribute estimation loss for generating accurate pseudo sensitive attribute information
- $\mathcal{L}_A$ : adversarial loss for debiasing the learned node representation
- $\mathcal{L}_R$ : covariance minimizer to stabilize the adversary training



# BeMap: Fair Topology View Generation

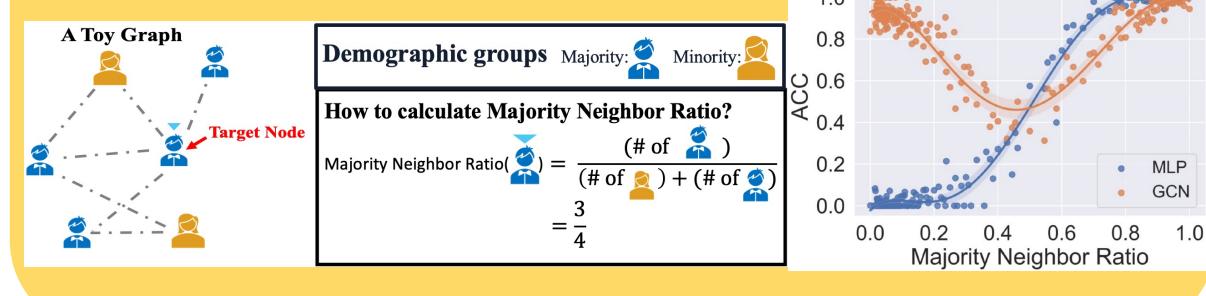
## • Motivation

- Message passing could be unfair



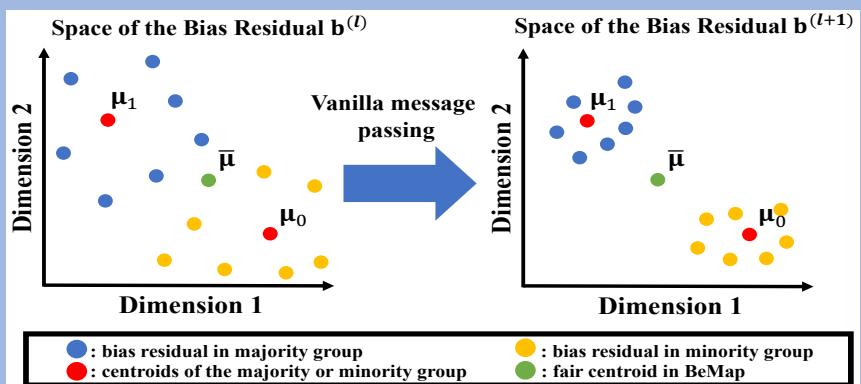
## • Empirical evidence

- Predict node sensitive attribute using embeddings learned from GCN and MLP (no MP)



## • Theoretical analysis

node embedding = fair embedding + bias residual



## • Method: BeMap

- (In every training epoch) neighbor sampling for balanced neighborhood and MP on it
- Up to 80% bias reduction
- Comparable or even better classification accuracy
- More details in the paper

# Bias and Fairness Issues

- Group Fairness on Graphs
- Individual Fairness on Graphs
- Degree Fairness on Graphs
- Future Directions and Q&A

# Individual Fairness

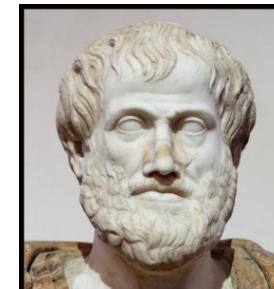
- **Definition**

- Similar individuals should have similar outcomes
- Rooted in Aristotle's conception of justice as consistency

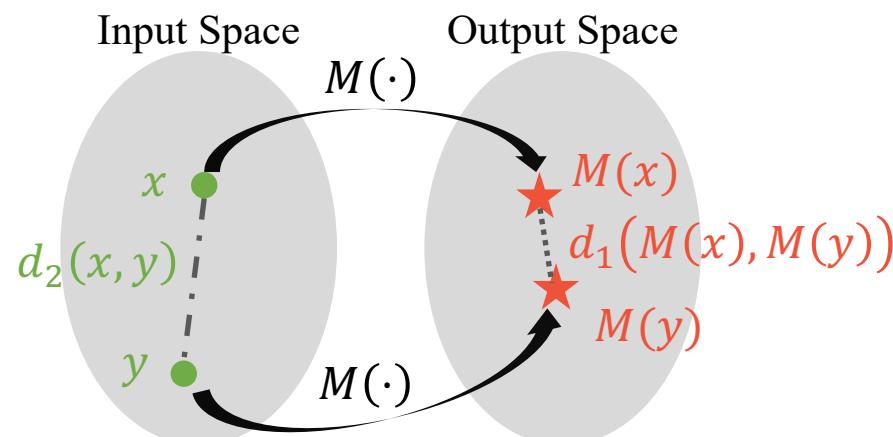
- **Formulation: Lipschitz inequality (most common)**

$$d_1(M(x), M(y)) \leq L d_2(x, y)$$

- $M$ : a mapping from input to output
- $d_1$ : distance metric for output
- $d_2$ : distance metric for input
- $L$ : a constant scalar



"Equality consists in the same treatment of similar persons, and no government can stand which is not founded upon justice."



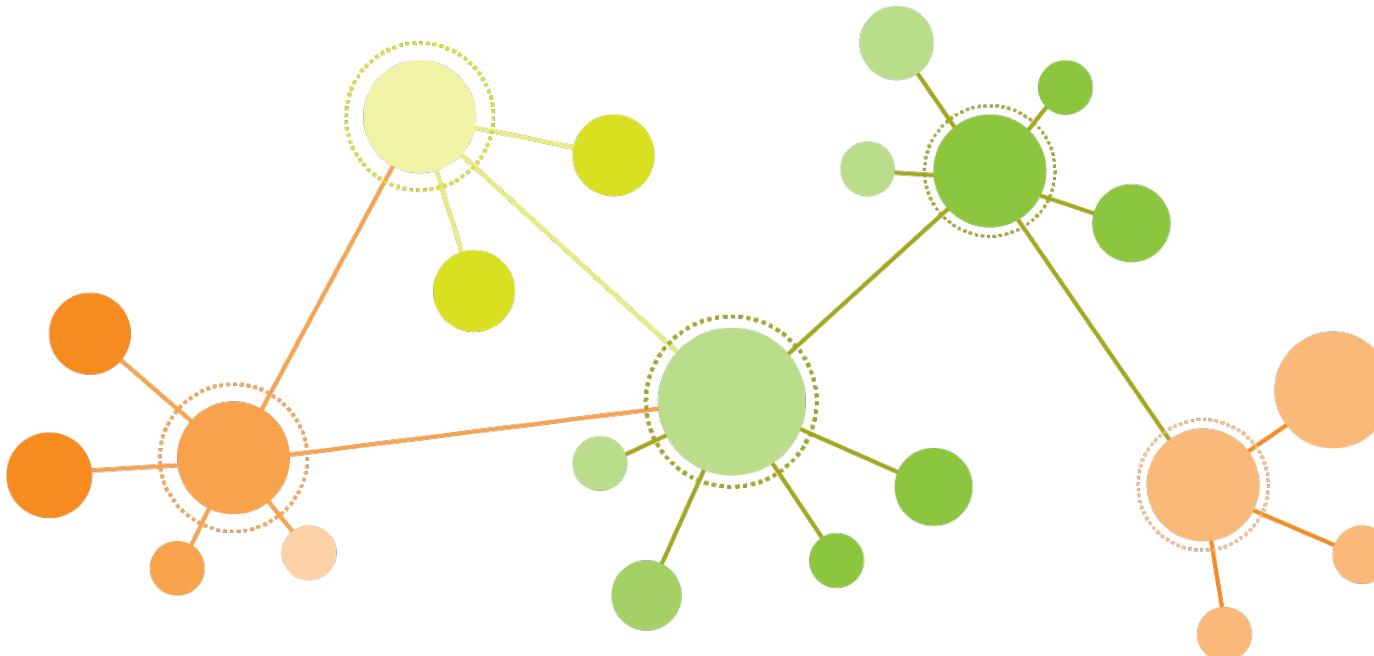
# InFoRM: Individual Fairness on Graph Mining

- Research questions

**RQ1. Measure:** how to quantitatively measure individual bias?

**RQ2. Algorithms:** how to ensure individual fairness?

**RQ3. Cost:** what is the cost of individual fairness?



# InFoRM Measure: Quantifying Individual Bias

- **Principle**

- Similar nodes → similar mining results

- **Mathematical formulation**

$$\|\mathbf{Y}[i, :] - \mathbf{Y}[j, :]\|_F^2 \leq \frac{\epsilon}{\mathbf{S}[i, j]} \quad \forall i, j = 1, \dots, n$$

Similarity between node  $i$  and node  $j$

(1) For any node pair  $(i, j)$   
 $\|\mathbf{Y}[i, :] - \mathbf{Y}[j, :]\|_F^2 \mathbf{S}[i, j] \leq \epsilon$

(2) Sum it up for all node pairs

- If  $\mathbf{S}[i, j]$  is high,  $\frac{\epsilon}{\mathbf{S}[i, j]}$  is small → push  $\mathbf{Y}[i, :]$  and  $\mathbf{Y}[j, :]$  to be more similar
- Inequality should hold for **every** pairs of nodes  $i$  and  $j$  → too restrictive

- **Relaxed criteria**

$$\sum_{i=1}^n \sum_{j=1}^n \|\mathbf{Y}[i, :] - \mathbf{Y}[j, :]\|_F^2 \mathbf{S}[i, j] \leq m\epsilon$$

||

$$2\text{Tr}(\mathbf{Y}^T \mathbf{L}_S \mathbf{Y}) \leq \delta$$

Overall individual bias of the graph

- $m$ : number of edges in the graph
- $\delta = m\epsilon$

# Alternative Measure: Ranking-Based Individual Fairness

- Key challenge in InFoRM measure

- Lipschitz condition (used in InFoRM)

$$d_1(M(x), M(y)) \leq L d_2(x, y)$$

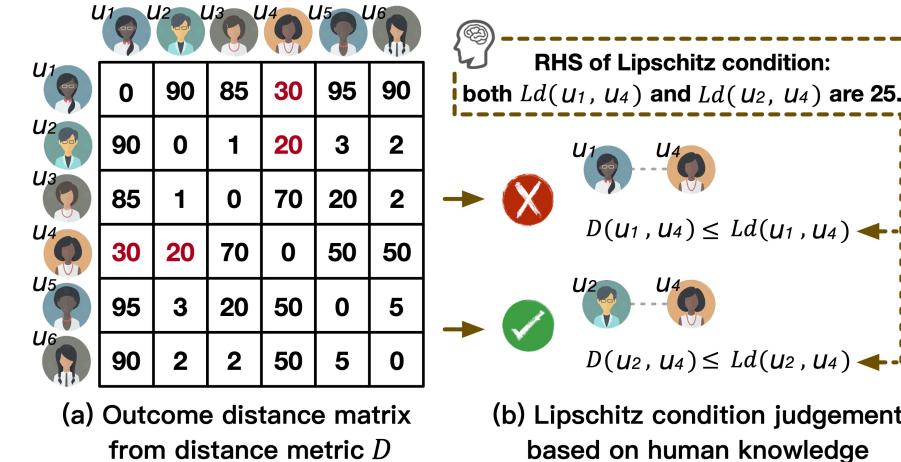
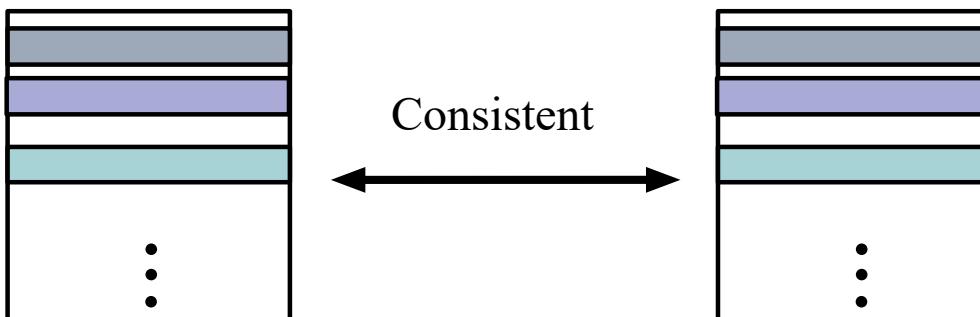
- Distance comparison fails to calibrate between different individuals

- Definition

- Given

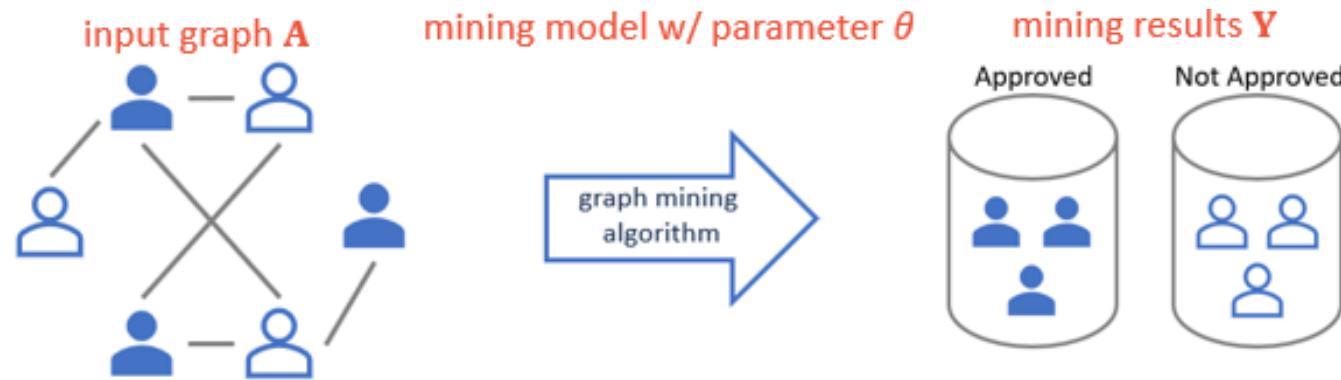
- (1) the node similarity matrix  $\mathbf{S}_G$  of the input graph  $G$
- (2) the similarity matrix  $\mathbf{S}_{\hat{\mathbf{Y}}}$  of the GNN output  $\hat{\mathbf{Y}}$
- $\hat{\mathbf{Y}}$  is individually fair if, for each node  $i$ , it satisfies that

ranking list derived by  $\mathbf{S}_G[i, :] =$  ranking list derived by  $\mathbf{S}_{\hat{\mathbf{Y}}}[i, :]$



# InFoRM Measure: Mitigating Individual Bias

- Graph mining workflow



- Debiasing methods

- Debiasing the input graph:  $\min_{\mathbf{Y}} J = \frac{\|\tilde{\mathbf{A}} - \mathbf{A}\|_F^2 + \alpha \text{Tr}(\mathbf{Y}^T \mathbf{L}_S \mathbf{Y})}{\text{topology consistency}}$   
s. t.  $\partial_{\mathbf{Y}} l(\tilde{\mathbf{A}}, \mathbf{Y}, \theta) = 0$
- Debiasing the mining model:  $\min_{\mathbf{Y}} J = \frac{l(\mathbf{A}, \mathbf{Y}, \theta) + \alpha \text{Tr}(\mathbf{Y}^T \mathbf{L}_S \mathbf{Y})}{\text{task-specific loss function}}$
- Debiasing the mining results:  $\min_{\mathbf{Y}} J = \frac{\|\mathbf{Y} - \bar{\mathbf{Y}}\|_F^2 + \alpha \text{Tr}(\mathbf{Y}^T \mathbf{L}_S \mathbf{Y})}{\text{mining results consistency}}$

Individual bias  
(InFoRM measure)

# InFoRM Cost: Characterizing Individual Bias

- **Main focus**
  - Debiasing the mining results (model-agnostic)

- **Given**
  - A graph with  $n$  nodes and adjacency matrix  $\mathbf{A}$
  - A node-node similarity matrix  $\mathbf{S}$
  - Vanilla mining results  $\bar{\mathbf{Y}}$
  - Debiased mining results  $\mathbf{Y}^* = (\mathbf{I} + \alpha\mathbf{S})^{-1}\bar{\mathbf{Y}}$
- If  $\|\mathbf{S} - \mathbf{A}\|_F = \Delta$ , we have

$$\|\bar{\mathbf{Y}} - \mathbf{Y}^*\|_F \leq 2\alpha\sqrt{n} \left( \textcolor{green}{\Delta} + \textcolor{blue}{\sqrt{\text{rank}(\mathbf{A})}} \textcolor{orange}{\sigma_{\max}(\mathbf{A})} \right) \|\bar{\mathbf{Y}}\|_F$$

- **Key factors**
  - The number of nodes  $n$  (i.e., size of the input graph)
  - The difference  $\Delta$  between  $\mathbf{A}$  and  $\mathbf{S}$
  - The rank of  $\mathbf{A}$  → could be small due to (approximate) low-rank structures in real-world graphs
  - The largest singular value of  $\mathbf{A}$  → could be small if  $\mathbf{A}$  is normalized

# Bias and Fairness Issues

- Group Fairness on Graphs
- Individual Fairness on Graphs
- **Degree Fairness on Graphs**
- Future Directions and Q&A

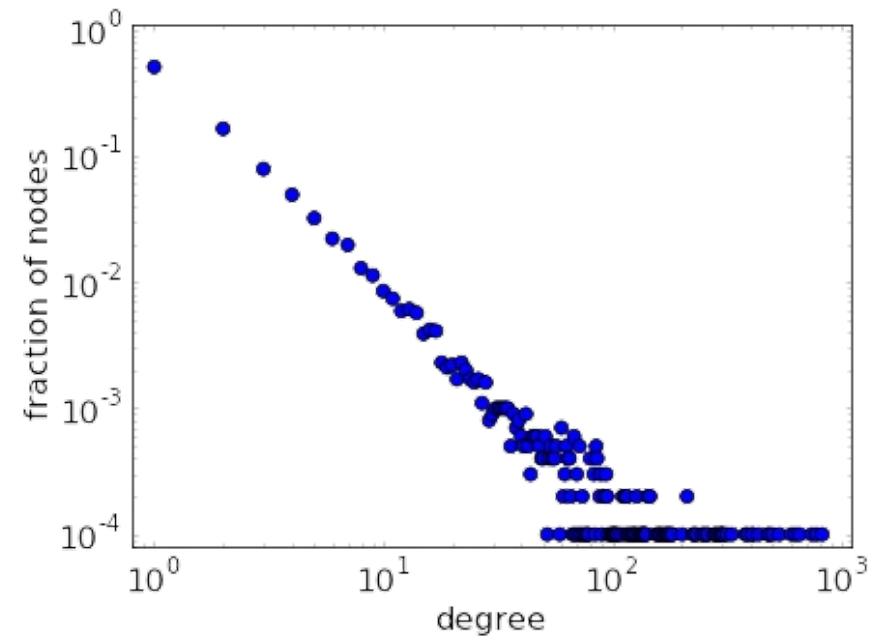
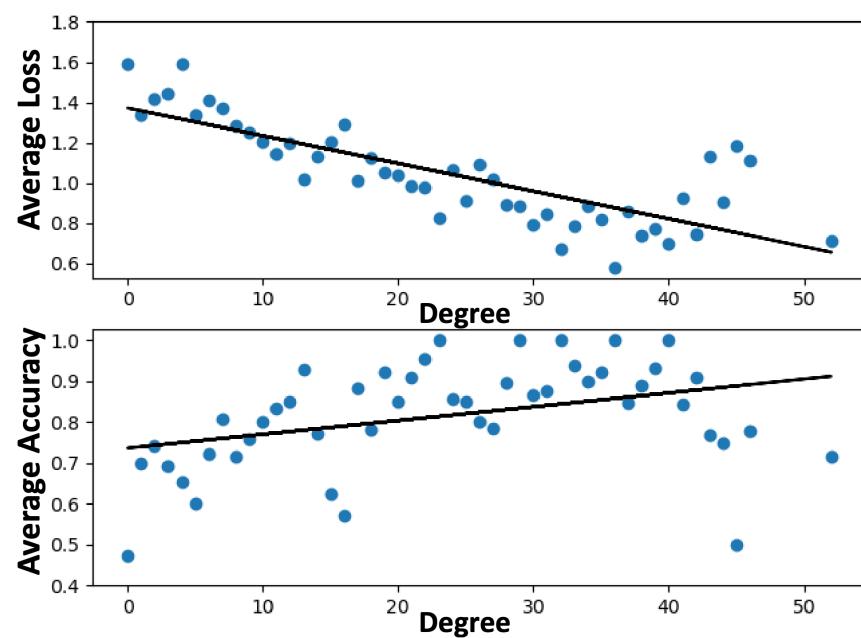
# Degree Fairness: Definition and Motivation

- **Definition**

- Nodes of different degrees should have balanced utility on a graph mining task

- **Example: online advertising**

- (A small portion of) celebrities often enjoy high-quality model performance
- (A large portion of) grassroot users often suffer from bad model performance



# Degree Unfairness: Pitfall of Graph Neural Networks

- Given

- (1)  $\mathcal{G} = (\mathbf{A}, \mathbf{X})$
- (2) Any test node  $i$  in  $\mathcal{G}$  with label  $c$
- (3) A graph learning model  $M$  which output (before softmax)  $\mathbf{Z}$
- (4) Any wrong prediction  $c' \neq c$

- Our results

- Misclassification rate

$$\Pr(\Pr(\hat{y} = c|i, M) > \Pr(\hat{y} = c'|M, i)) \leq \frac{1}{1 + R_{i,c'}}$$

where  $R_{i,c'} = \frac{(\mathbb{E}[\mathbf{Z}[i,c'] - \mathbf{Z}[i,c]])^2}{\text{Var}[\mathbf{Z}[i,c'] - \mathbf{Z}[i,c]]}$  (reciprocal of measure of dispersion from economics)

- $R_{i,c'}$  is positively correlated with the degree of node  $i$

- Conclusion

- high-degree nodes often have **lower misclassification rate!**

# Causes #1: High-Degree Nodes with High Influence in Node Embeddings

- **Given**

- $\mathcal{V}_{\text{labeled}}$ : a set of labeled nodes  $\mathcal{V}_{\text{labeled}}$
- $\mathbf{W}^{(L)}$ : the weight of  $L$ -th layer in an  $L$ -layer GCN
- $d_i$ : degree of node  $i$
- $\mathbf{x}_i$ : input node feature of node  $i$
- $\mathbf{h}_i^{(L)}$ : output embeddings of node  $i$  learned by the  $L$ -layer GCN

- **Influence of node  $i$  on GCN training**

$$S(i) = \sum_{k \in \mathcal{V}_{\text{labeled}}} \left\| \mathbb{E} \left[ \frac{\partial \mathbf{h}_i^{(L)}}{\partial \mathbf{x}_k} \right] \right\| \propto \sqrt{d_i} \|\mathbf{W}^{(L)}\| \sum_{k \in \mathcal{V}_{\text{labeled}}} \sqrt{d_k}$$

- **Remark**

- For two nodes  $i$  and  $j$ , if  $d_i > d_j$ , then  $S(i) > S(j)$   
→ Node with higher degree will have higher influence on GCN training

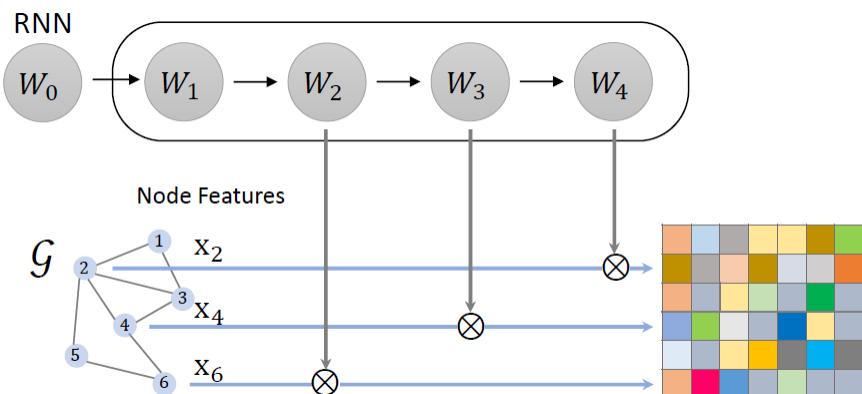
# Solution #1: Degree-Specific Graph Convolution

- Key idea
  - Degree-specific weights to encode degree information
- Given
  - $d_i$ : the degree of node  $i$
  - $\mathbf{W}_{d_j}^{(l)}$ : the degree-specific weight w.r.t. degree of node  $j$

## Degree-specific graph convolution

$$\mathbf{h}_i^{(l+1)} = \sigma \left( \sum_{j \in \mathcal{N}_i \cup \{i\}} a_{ij} \left( \mathbf{W}^{(l)} + \mathbf{W}_{d_j}^{(l)} \right) \mathbf{h}_j^{(l)} \right)$$

- DEMO-Net  $\rightarrow \mathbf{W}_{d_j}^{(l)}$  is generated randomly
- SL-DSGCN  $\rightarrow \mathbf{W}_{d_j}^{(l)}$  is generated using a recurrent neural network



## Causes #2: High-Degree Nodes with High Influence in Gradient

- **Gradient of loss w.r.t. weight**

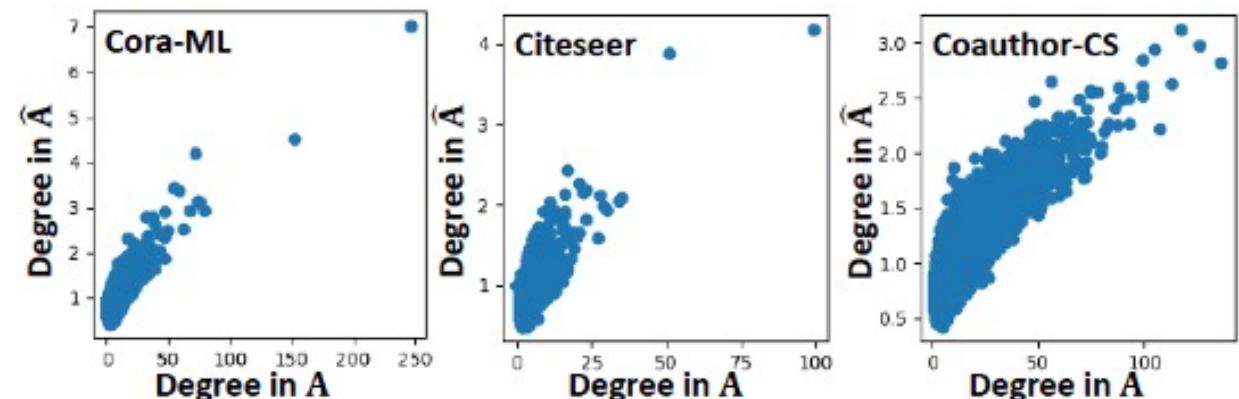
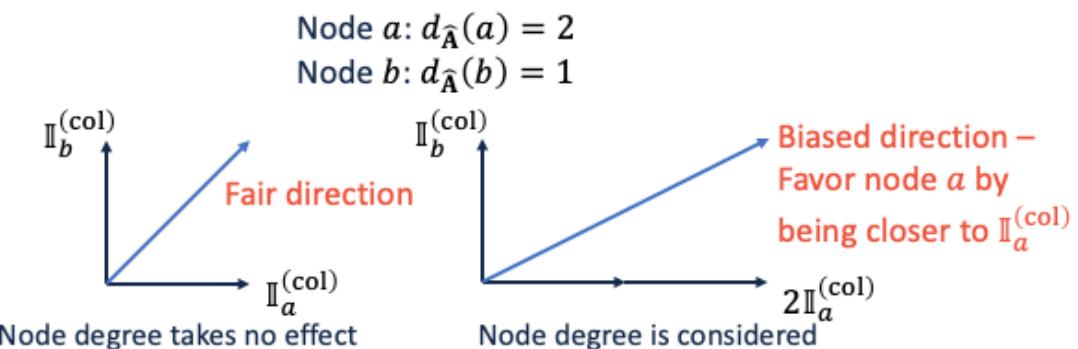
$$\frac{\partial J}{\partial \mathbf{W}^{(l)}} = \sum_{i=1}^n d_{\hat{\mathbf{A}}}(i) \mathbb{I}_i^{(\text{col})} = \sum_{j=1}^n d_{\hat{\mathbf{A}}}(j) \mathbb{I}_j^{(\text{row})}$$

Row sum in  $\hat{\mathbf{A}}$       Column sum in  $\hat{\mathbf{A}}$

- $\hat{\mathbf{A}} = \tilde{\mathbf{D}}^{-\frac{1}{2}}(\mathbf{A} + \mathbf{I})\tilde{\mathbf{D}}^{-\frac{1}{2}} \rightarrow$  symmetric normalization kernel
- $\mathbb{I}_i^{(\text{col})}$  and  $\mathbb{I}_j^{(\text{row})} \rightarrow$  the directions for gradient descent
- $d_{\hat{\mathbf{A}}}(i)$  and  $d_{\hat{\mathbf{A}}}(j) \rightarrow$  the importance of the direction
- High degree  $\rightarrow$  more focus on that direction

- **Symmetric normalization**

- Normalize the largest eigenvalue but not degree
- High degree in  $\mathbf{A} \rightarrow$  high degree in  $\hat{\mathbf{A}}$



# Solution #2: Graph Normalization

- **Key idea**

- Mitigate impacts of node degree by normalizing it to constant (i.e., 1)
- Normalize the graph to a doubly stochastic graph

- **Sinkhorn-Knopp (SK) algorithm**

- Iteratively normalize row and columns
- (**Our result**) SK always finds the **unique** doubly stochastic form of symmetric normalization kernel

- **Fair gradient computation**

$$\left( \frac{\partial J}{\partial \mathbf{W}^{(l)}} \right)_{\text{fair}} = (\mathbf{H}^{(l-1)})^T \hat{\mathbf{A}}_{\text{DS}}^T \frac{\partial J}{\partial \mathbf{E}^{(l)}}$$

- $\hat{\mathbf{A}}_{\text{DS}}$  → doubly-stochastic normalization of  $\hat{\mathbf{A}}$

- **RawlsGCN family**

- RawlsGCN-Graph: during **data pre-processing**, compute  $\hat{\mathbf{A}}_{\text{DS}}$  and treat it as the input of GCN
- RawlsGCN-Grad: during **optimization (in-processing)**, treat  $\hat{\mathbf{A}}_{\text{DS}}$  as a normalizer to equalize the importance of node influence

# Bias and Fairness Issues

- Group Fairness on Graphs
- Individual Fairness on Graphs
- Degree Fairness on Graphs
- **Future Directions and Q&A**

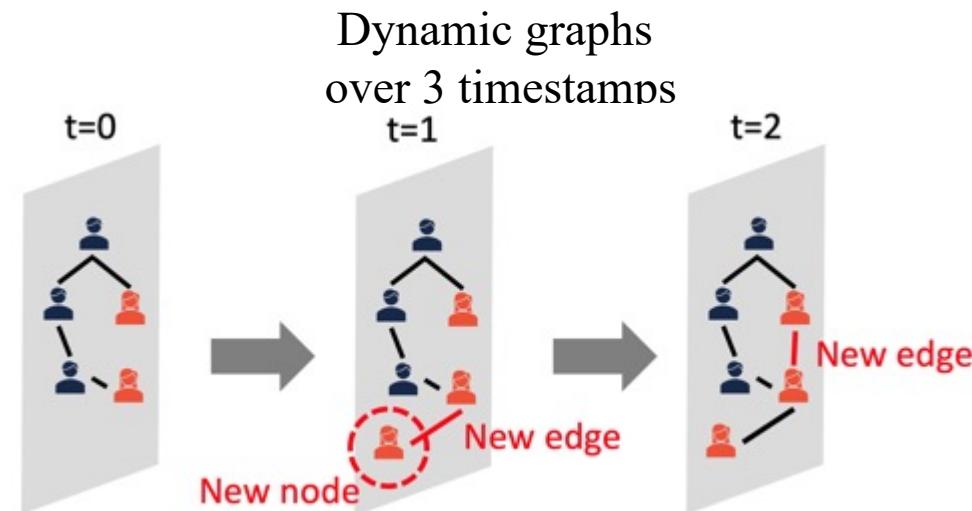
# Future Direction #1: Fairness beyond Plain and Static Graphs

- **Observation**

- Real-world graphs are often dynamic and/or multi-sourced

- **Research questions**

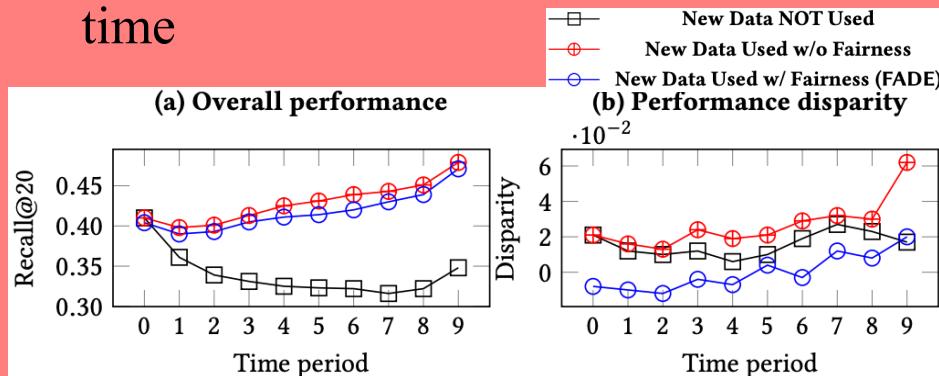
- How to ensure fairness for multiple type of nodes/edges or multi-graphs?
- How to efficiently update the fair mining results at each timestamp?
- How to characterize the impact of graph dynamics and multiple sources over the bias measure?



# Preliminary Work: Dynamic Group Fairness in Recommender Systems

## • Observation

- performance disparity is getting larger over time



## • Theory

- Fine-tuning is better than re-training for fairness over time

### Re-training

- (1)  $L_{t_{\text{test}}}^{\text{rt}}$  = real loss of re-training at test time; (2)  $L_{t_{\text{test}}}^*$  = optimal loss at time  $t_{\text{test}}$ ; (3)  $m_0$  = #. edges at time 0; (4)  $m_t$  = #. edge changes at time  $t$ ; (5)  $0 < \gamma < 1$

$$L_{t_{\text{test}}}^{\text{rt}} \leq L_{t_{\text{test}}}^* + 2 \frac{m_0 d_{0,t_{\text{test}}} + \sum_{t=1}^{t_{\text{test}}-1} m_t d_{1,t_{\text{test}}}}{m_0 + (t_{\text{test}} - 1)m_1} + 4 \sqrt{\frac{1}{m_0 + (t_{\text{test}} - 1)m_1} \log \frac{2}{\delta}}$$

### Fine-tuning

- Similar settings as re-training but  $L_{t_{\text{test}}}^{\text{ft}}$  = real loss of fine-tuning at test time

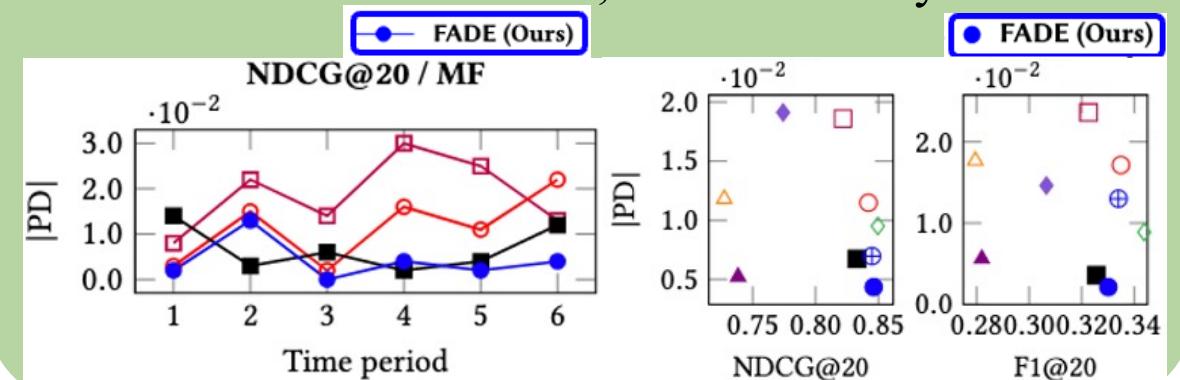
$$L_{t_{\text{test}}}^{\text{ft}} \leq L_{t_{\text{test}}}^* + 2 \frac{(1-\gamma) \left( 2 \sum_{t=0}^{t_{\text{test}}-1} \gamma^{t_{\text{test}}-t-1} d_{t,t_{\text{test}}} + 4 \sqrt{\left( \frac{\gamma^{2t_{\text{test}}-2}}{m_0} + \frac{1-\gamma^{2t_{\text{test}}-2}}{(1-\gamma^2)m_1} \right) \log \frac{2}{\delta}} \right)}{1 - \gamma^{t_{\text{test}}}}$$

## • Method: FADE

- Model-agnostic
- Fine-tuning with newly observed data
- Periodically re-training to keep historical information
- Linear complexity w.r.t. # new data

## • Results

- Fairness over time, small accuracy decrease



# Future Direction #2: Fairness on Graphs → Fairness with Graphs

- **Fairness on graphs**

- Graph as data
- Nodes = entities
- Social networks → nodes = users
- Citation networks → nodes = papers
- Web graph → nodes = webpages

- **Fairness with graphs**

- Graph as context
- Nodes = models/datasets/modalities

- **Example: supply chain**

1. Demand + supply for medical resources
2. Models to allocate medical resources



- How can we leverage demand + supply + model collectively for fair supply chain?

# Future Direction #3: Benchmark and Evaluation Metrics

- **Observation**

- No consensus on the experimental settings for fair graph learning
- Which data to compare? What sensitive attribute to consider?
- Which evaluation metrics for each type of fairness?

- **Consequences**

- Different settings for different research works
- Hardly fair comparison among fair graph learning methods
- Hardly deployable methods in real-world scenarios

- **Call for community effort**

- Evaluation benchmark for consistent experimental settings and fair comparison
- Collection of large-scale, realistic, but challenging dataset for evaluation

# Outline

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- Introduction and Background
- Topology Issues
- Imbalance Issues
- Short Break
- Bias and Fairness Issues
- **Limited Labeled Data Issues**
- Abnormal Graph Data Issues
- Summary

# Limited Labeled Data Issues

- Graph Data Augmentations
- Self-supervised Learning on Graphs

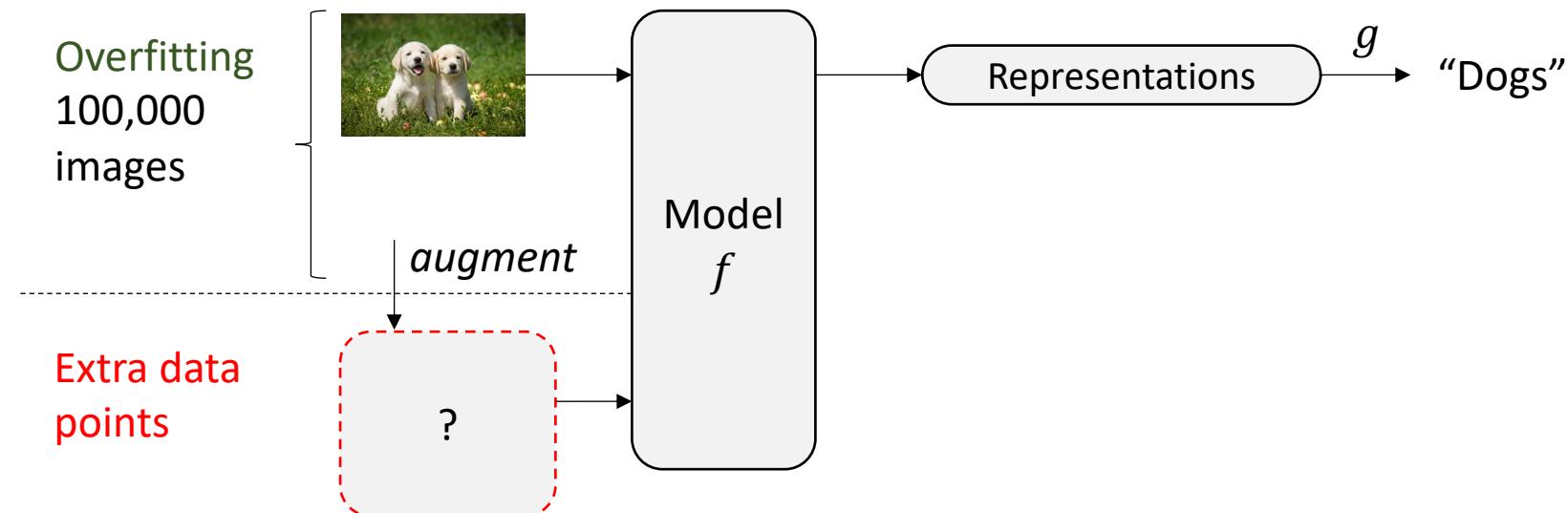
# Data Augmentation

Wikipedia: Techniques used to *increase the amount of data by adding *slightly modified* copies of already existing data or *newly created* synthetic data from existing data.*

- Why data augmentation?
  - It helps reduce overfitting when training a machine learning model.
  - The acquisition of labeled graph data can be expensive.

# Data Augmentation

Wikipedia: Techniques used to **increase the amount of data** by adding *slightly modified* copies of already existing data or *newly created* synthetic data **from existing data**.



# Data Augmentation

Wikipedia: Techniques used to **increase the amount of data** by adding *slightly modified* copies of already existing data or *newly created* synthetic data **from existing data**.

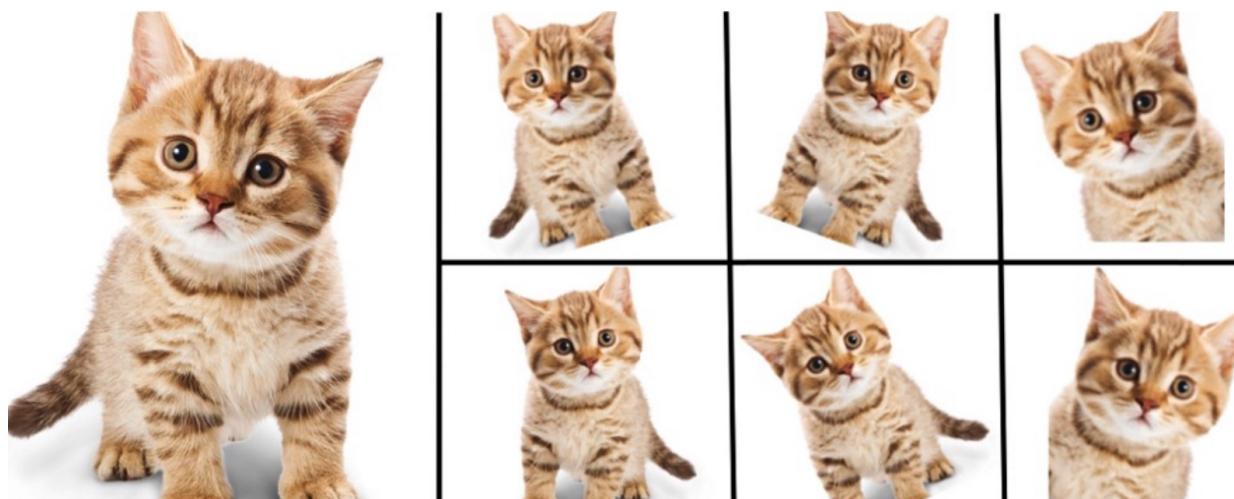


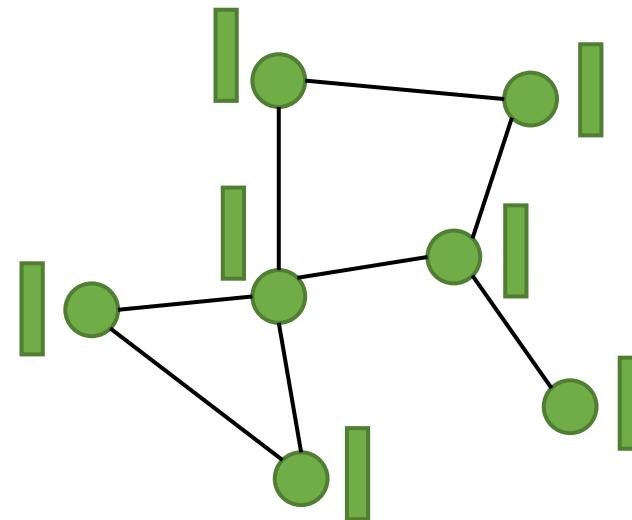
Image sources:

<https://www.kdnuggets.com/2018/05/data-augmentation-deep-learning-limited-data.html>

<https://amitness.com/2020/05/data-augmentation-for-nlp/>

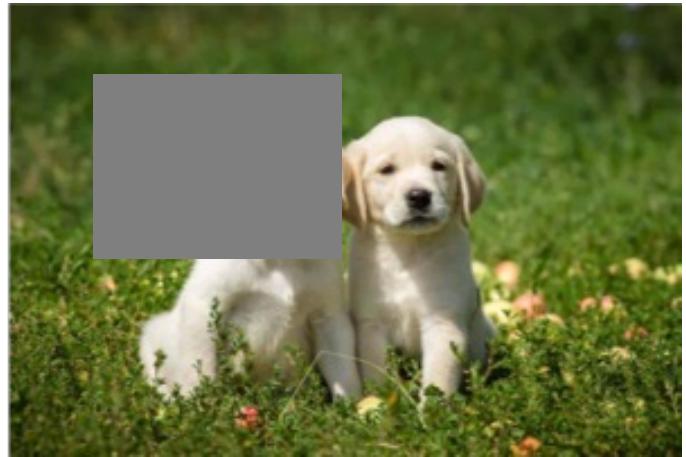
# Graph Data Augmentation

- Structure Augmentation
  - Drop/add nodes/edges, etc.
- Feature Augmentation
  - Mask off features, etc.
- Label Augmentation
  - Label propagation, etc.



# Graph Data Augmentation

- Rule-based augmentations
  - Designed based on heuristic rules
  - Usually efficient and scalable
  - Simple and easy to implement
    - Commonly used in self-supervised learning
- Learned augmentations
  - Involve learning during augmentation
  - Augmented data better fits GML models
    - Better performances in supervised learning



# Rule-based Graph Data Augmentation Approaches

Methodology	Representative Works	Task Level			Augmented Data		
		Node	Graph	Edge	Structure	Feature	Label
Rule-based GDA	Stochastic Dropping/Masking	DropEdge [87]	✓			✓	
		DropNode [27]		✓			✓
		NodeDropping [127]		✓		✓	
		Feature Masking [100]	✓				✓
		Feature Shuffling [106]	✓				✓
		DropMessage [23]	✓	✓			✓
		Subgraph Masking [127]		✓	✓		✓
	Subgraph Cropping/Substituting	GraphCrop [111]		✓		✓	
		M-Evolve [145]		✓		✓	
		MoCL [97]		✓		✓	✓
	Virtual Node	Graphomer [125]		✓		✓	
		GNN-CM <sup>+</sup> /CM [45]			✓	✓	
	Mixup	Graph Mixup [115]	✓	✓			✓
		ifMixup [37]		✓		✓	✓
		Graph Transparent [85]		✓		✓	✓
		G-Mixup [39]		✓		✓	✓
	SMOTE	GraphSMOTE [140]	✓			✓	
		GATSMOTE [75]	✓			✓	
		GNN-CL [70]	✓			✓	
	Diffusion	GDA [60]	✓			✓	
	Counterfactual Augmentation	CFLP [141]		✓		✓	✓
	Attribute Augmentation	LA-GNN [74]	✓			✓	
		SR+DR [93]	✓			✓	
	Pseudo-labeling	Label Propagation [147]	✓				✓
		PTA [21]	✓				✓

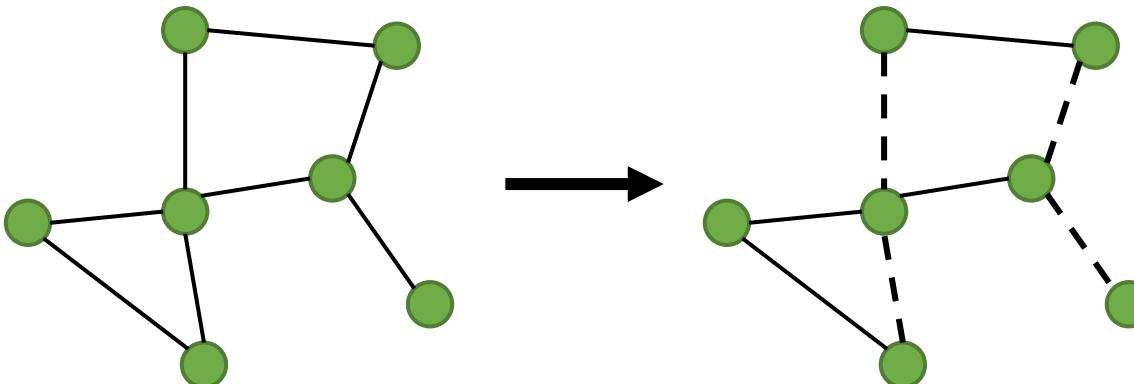
# DropEdge

- Dropout on edges: randomly remove some edges at the beginning of every training epoch.

$$\tilde{\mathbf{A}} = \mathbf{M} \odot \mathbf{A}$$

$$\mathbf{M} \in \{0, 1\}^{N \times N} \text{ s.t. } M_{i,j} = \text{Bernoulli}(\varepsilon)$$

- Prevents overfitting and over-smoothing.



# Other Stochastic Masking/Dropping Methods

- Node Dropping
  - Randomly removing part of the nodes.
- Feature Masking
  - Randomly mask off node features.
  - Random row-shuffling on node feature matrix  $\mathbf{X}$ .
- Subgraph Masking
  - Randomly mask off a connected subgraph.

Feng, et al. Graph Random Neural Networks for Semi-supervised Learning on Graphs. NeurIPS 2020.

You, et al. Graph Contrastive Learning with Augmentations. NeurIPS 2020.

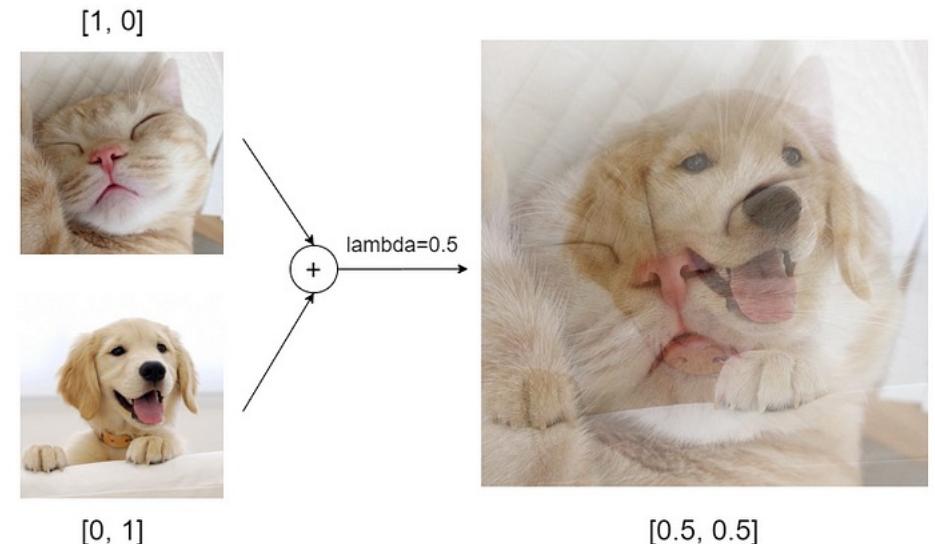
Thakoor, et al. Large-scale Representation Learning on Graphs via Bootstrapping. ICLR 2022.

Velickovic, et al. Deep Graph Infomax. ICLR 2019.

# Mixup

- Mixup: generates a weighted combination of random pairs from the training data.

$$\begin{aligned}\tilde{\mathbf{x}} &= \lambda \mathbf{x}_i + (1 - \lambda) \mathbf{x}_j, \\ \tilde{\mathbf{y}} &= \lambda \mathbf{y}_i + (1 - \lambda) \mathbf{y}_j.\end{aligned}$$



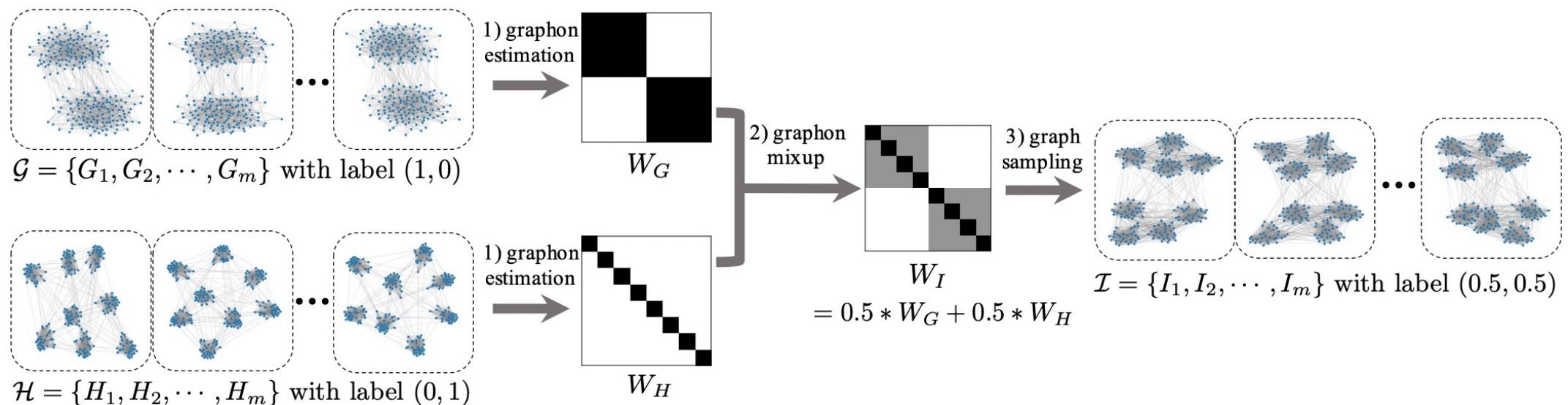
- Manifold Mixup: interpolating hidden states.

Zhang, et al. Mixup: Beyond Empirical Risk Minimization. ICLR 2018.

Verma, et al. Manifold Mixup: Better Representations by Interpolating Hidden States. ICML 2019.

Image source: <https://medium.com/@wolframalphav1.0/easy-way-to-improve-image-classifier-performance-part-1-mixup-augmentation-with-codes-33288db92de5>

# G-Mixup



1. Graphon estimation:
2. Graphon Mixup:
3. Graph Generation:
4. Label Mixup:

$$\mathcal{G} \rightarrow W_{\mathcal{G}}, \mathcal{H} \rightarrow W_{\mathcal{H}}$$

$$W_{\mathcal{I}} = \lambda W_{\mathcal{G}} + (1 - \lambda) W_{\mathcal{H}}$$

$$\{I_1, I_2, \dots, I_m\} \stackrel{\text{i.i.d}}{\sim} \mathbb{G}(K, W_{\mathcal{I}})$$

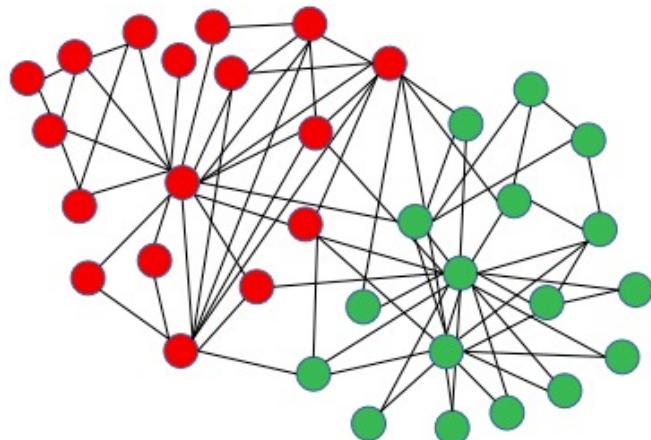
$$\mathbf{y}_{\mathcal{I}} = \lambda \mathbf{y}_{\mathcal{G}} + (1 - \lambda) \mathbf{y}_{\mathcal{H}}$$

# Learned Graph Data Augmentation Approaches

		Proposed Approaches		
		GAug [140]	GLCN [47]	LDS [28]
Learned GDA	Graph Structure Learning	ProGNN [50]	Eland [141]	
	Graph Adversarial Training	RobustTraining [125]		✓
		AdvT [18]	✓	✓
		FLAG [63]	✓	✓
		GraphVAT [25]	✓	✓
		GREA [71]	✓	✓
		AdvCA [97]	✓	✓
		AutoGDA [144]	✓	✓
		GraphAug [79]	✓	✓
		JOAO [130]	✓	✓
		MolCLE [116]	✓	✓

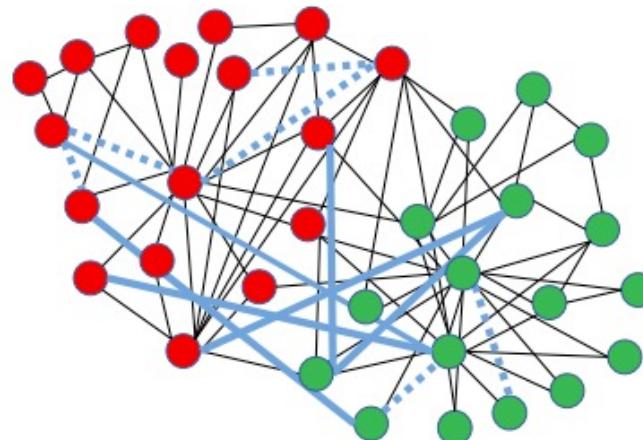
# Limitations of Rule-based Approaches

Do not leverage task information and could hurt the downstream performance



(a) Original graph.

F1 Score: 92.4



(b) Random mod.

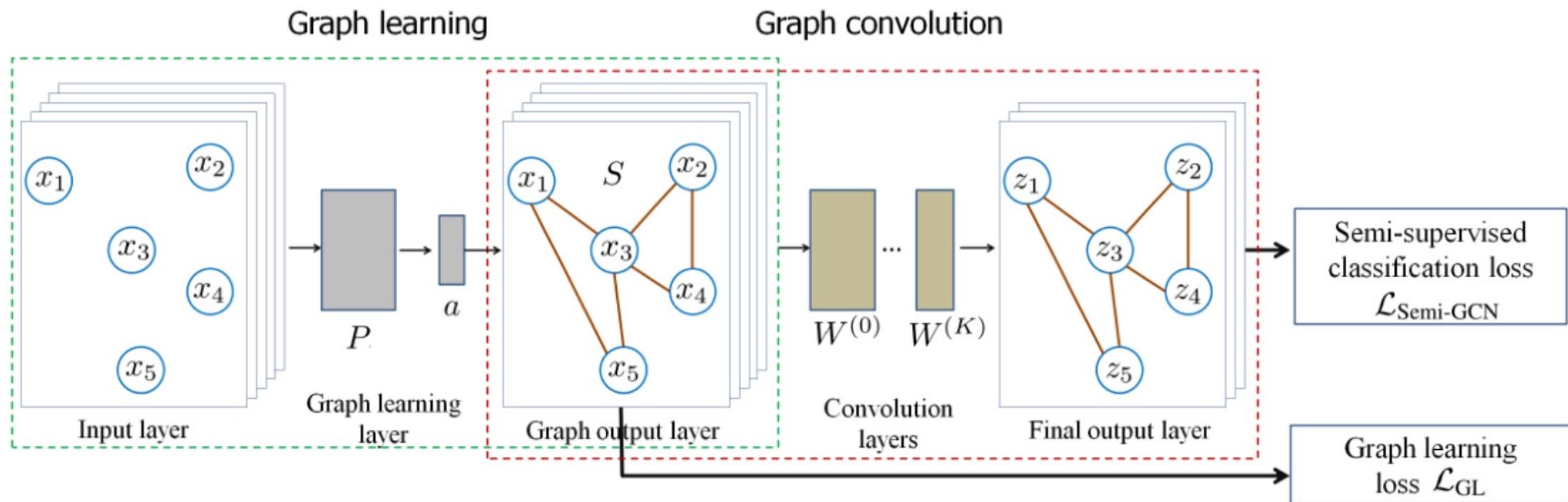
F1 Score: 91.0

# Learned Graph Data Augmentation Approaches

- Graph Structure Learning
  - Augment data with good graph structures
- Adversarial Training
  - Augment data with adversarial examples
- Rationalization
  - Augment data by changing graph environment
- Automated Augmentation
  - Automatically combine different augmentations

# Graph Structure Learning

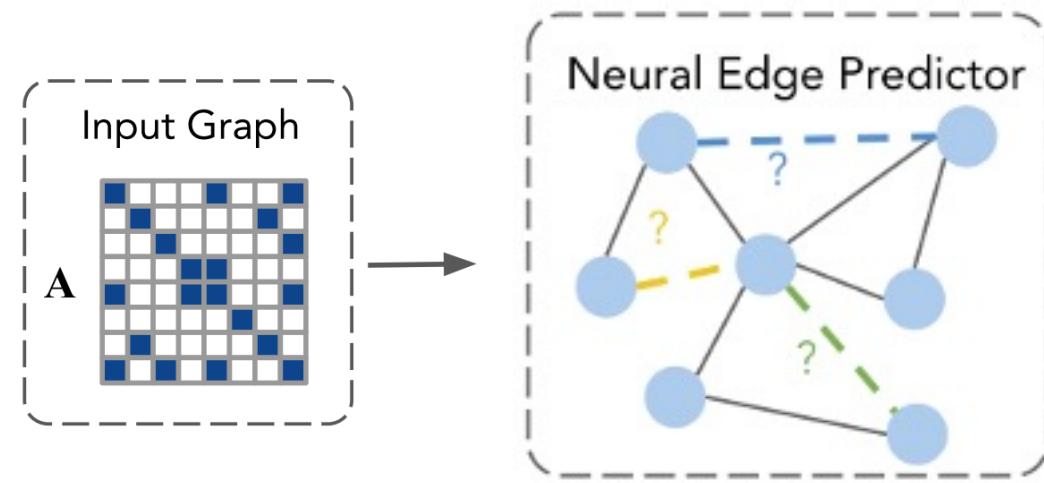
## Graph Learning + Graph Convolution



# GAug: Neural Edge Predictor

What are better graph structures?

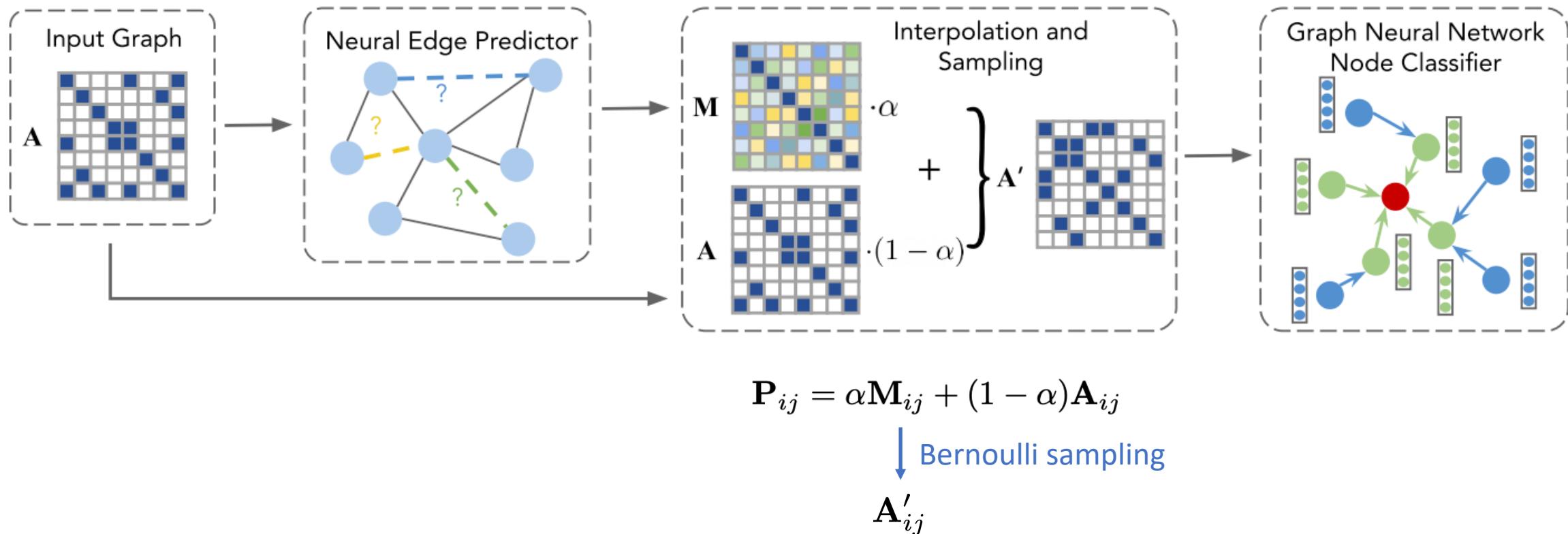
- “Noisy” edges should be removed  
Inter-class edges
- “Missing” edges should be added  
Intra-class edges



$$\mathbf{M} = \sigma(\mathbf{Z}\mathbf{Z}^T), \text{ where } \mathbf{Z} = f_{GCL}^{(1)}\left(\mathbf{A}, f_{GCL}^{(0)}(\mathbf{A}, \mathbf{X})\right)$$

$M$  models node similarities

# GAug: Interpolation and Sampling



# Graph Self-supervised Learning

- Graph Self-Supervised Learning aims to learn generalizable node/edge/graph representations without using any human-annotated labels
  - Graph Generative Modeling
    - Learn generalizable representations by reconstructing the node features or/and graph structure

# Graph Self-supervised Learning

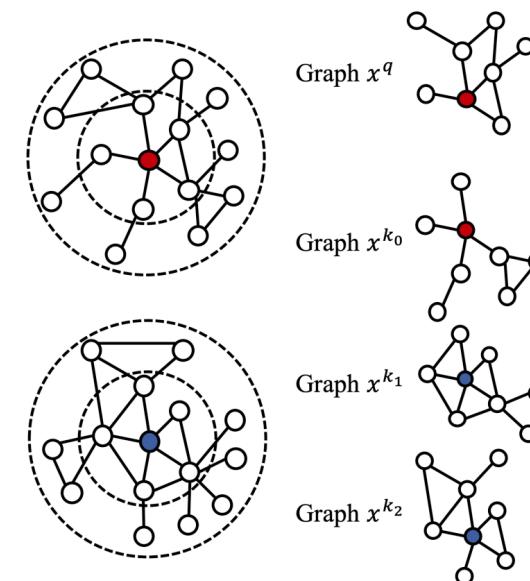
- Graph Self-Supervised Learning aims to learn generalizable node/edge/graph representations **without** using any human-annotated labels

- **Graph Generative Modeling**

- Learn generalizable representations by **reconstructing** the node features or/and graph structure

- **Graph Contrastive Learning (GCL)**

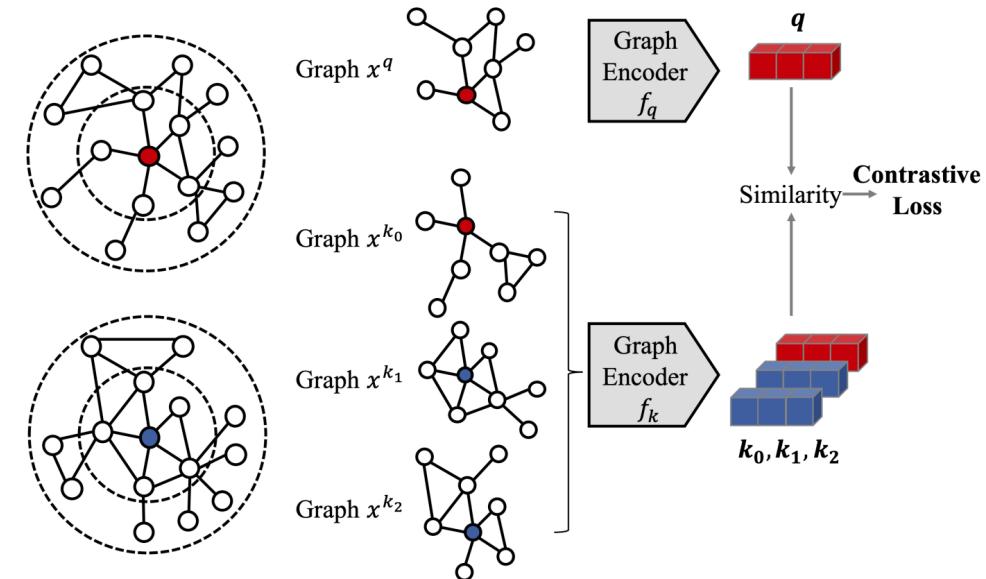
- Create different views from the unlabeled input graph via data augmentation



# Graph Self-supervised Learning

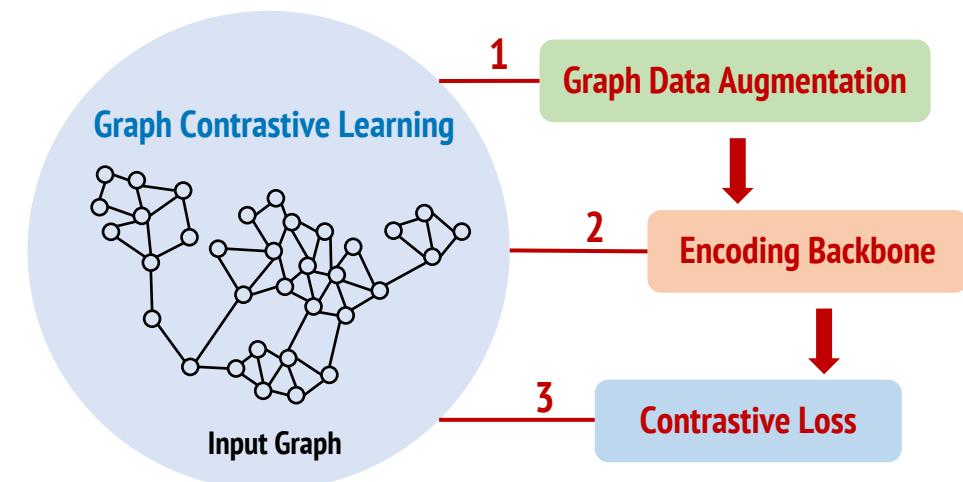
- Graph Self-Supervised Learning aims to learn generalizable node/edge/graph representations **without** using any human-annotated labels

- Graph Generative Modeling
  - Learn generalizable representations by **reconstructing** the node features or/and graph structure
- Graph Contrastive Learning (GCL)
  - Create different views from the unlabeled input graph via data augmentation
  - Maximize the agreement between representations of different augmented views of the same instance



# Typical Unsupervised Graph Contrastive Learning

- **Graph Data Augmentation**
  - Create different views of each instance (e.g., node, subgraph)
  - Arbitrary graph data augmentation (e.g., edge dropping, feature masking)
- **Encoding Backbone**
  - Encode different augmented views
  - Shallow GNNs (e.g., 2-layer GCN)
- **Contrastive Loss**
  - Maximize the agreement between representations learned from different augmented views
  - Instance-level contrastive learning



# Outline

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- Introduction and Background
- Topology Issues
- Imbalance Issues
- Short Break
- Bias Issue
- Limited Labeled Data Issues
- **Abnormal Graph Data Issues**
- Summary

# Abnormal Graph Data Issues

- Missing Features
- Adversarially Attacked Data

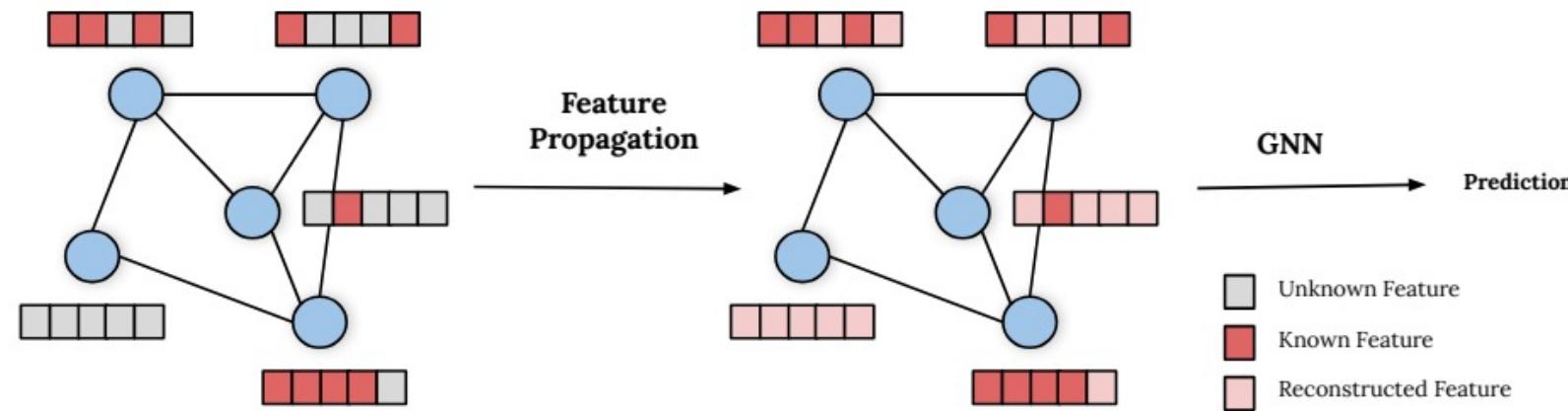
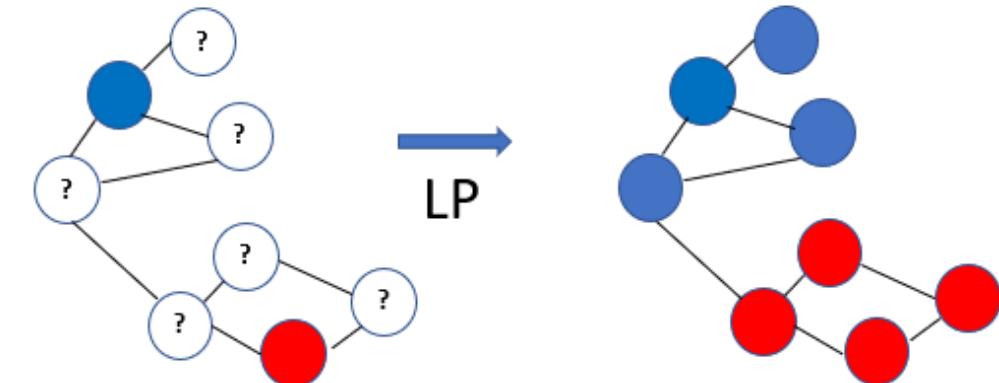
# Missing Data

There are various solutions to deal with **missing labels**:

- Label propagation (LP)
- Self-supervised learning
- Unsupervised learning
- ...

What if we have **missing features**?

- Feature propagation



# Missing Data

What if we have **missing features**?

- Feature propagation

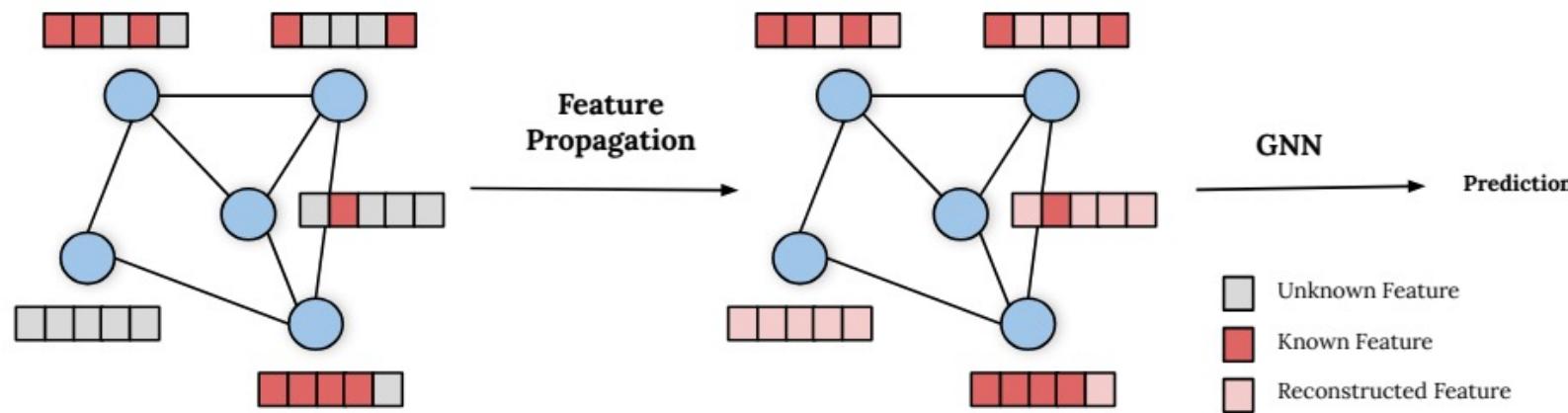
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## Algorithm 1 Feature Propagation

---

```
1: Input: feature vector  $\mathbf{x}$ , diffusion matrix  $\tilde{\mathbf{A}}$ 
2:  $\mathbf{y} \leftarrow \mathbf{x}$ 
3: while  $\mathbf{x}$  has not converged do
4:    $\mathbf{x} \leftarrow \tilde{\mathbf{A}}\mathbf{x}$             $\triangleright$  Propagate features
5:    $\mathbf{x}_k \leftarrow \mathbf{y}_k$           $\triangleright$  Reset known features
6: end while
```

---



# Missing Data

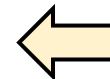
## Comparison of Feature Propagation to Label Propagation

### Feature Propagation:

- Propagates features (continuous)
- Prediction is made by a GNN on top of the propagated features
- Uses features, and a low % of them being present is enough for good performance

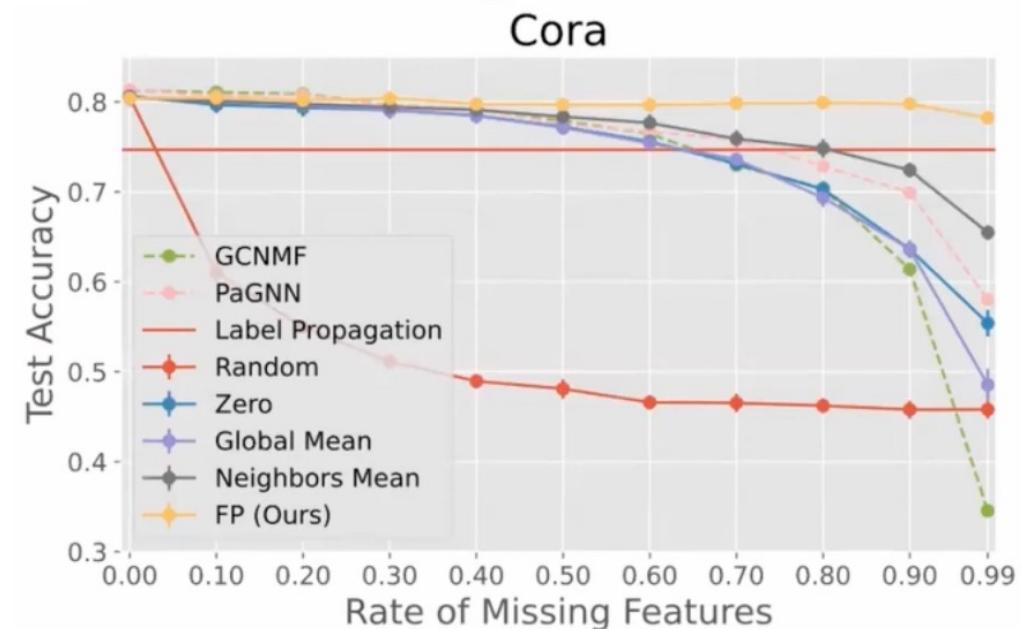
### Experiment Results

Across different levels of missing features,  
Feature Propagation achieves the best performance



### Label Propagation:

- Propagates class labels (discrete)
- Prediction is obtained directly from propagating class labels
- Feature-agnostic

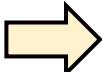


# Missing Data

Beyond missing features on graphs, can we solve the general missing data problem?

Data Matrix with Missing Values					Labels
	$F_1$	$F_2$	$F_3$	$F_4$	$Y$
$O_1$	0.3	0.5	NA	0.1	$y_1$
$O_2$	NA	NA	0.6	0.2	$y_2$
$O_3$	0.3	NA	NA	0.5	?

Two ways of approaching missing data problems:

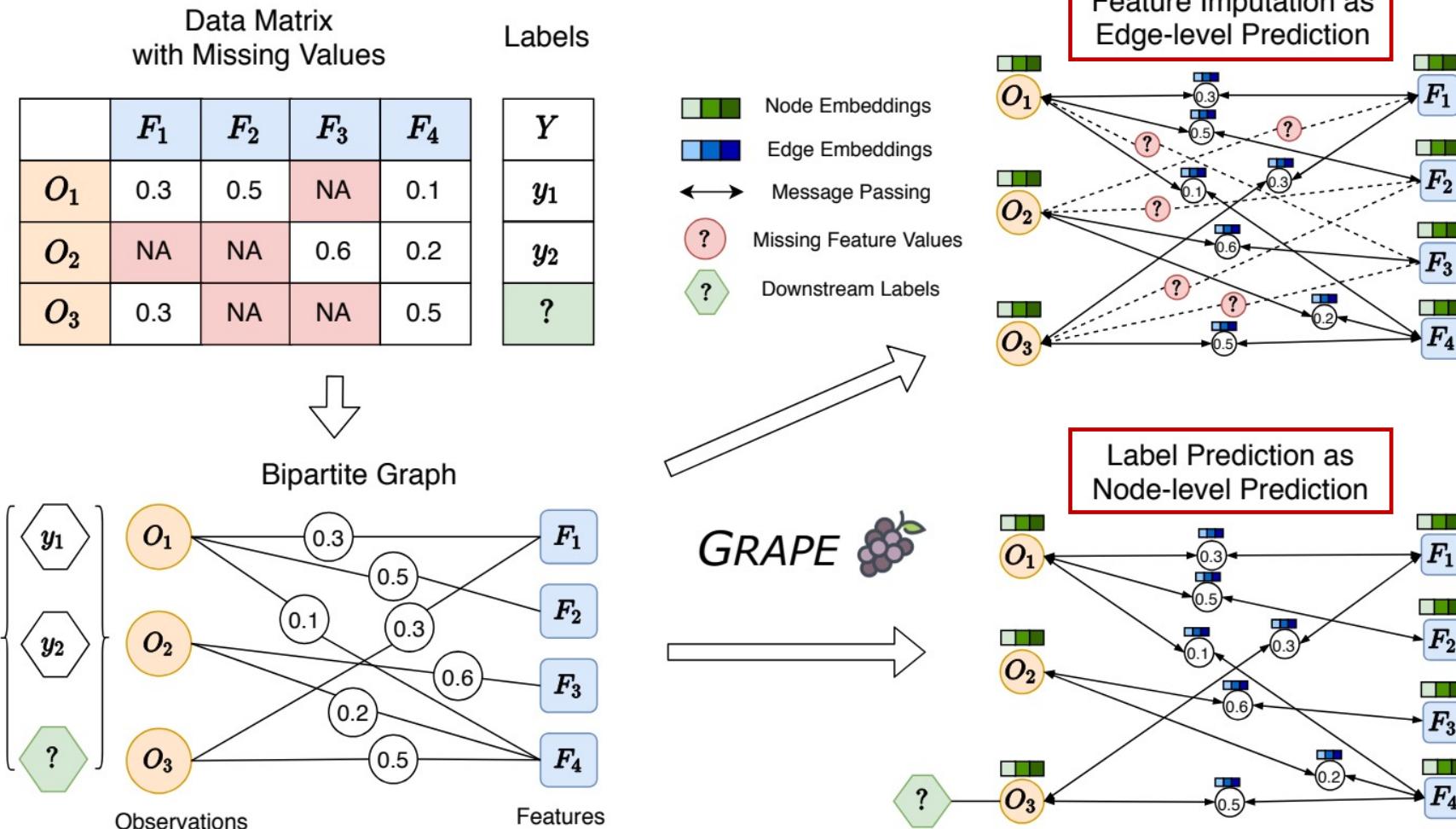
- 
- **Feature imputation:** missing feature values are estimated based on observed values
  - **Label prediction:** downstream labels are learned directly from incomplete data

## Issues:

- Existing methods fail to make full use of feature values from other observations
- Existing methods tend to make biased assumptions about the missing values by initializing them with special default values

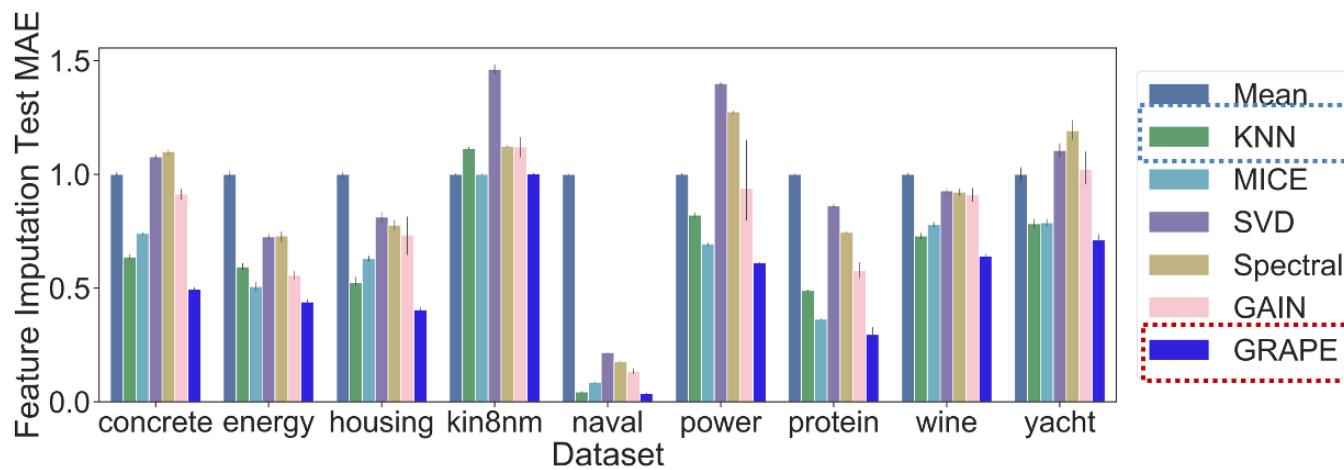
# Missing Data

GRAPE: reformulate the tasks as graph tasks

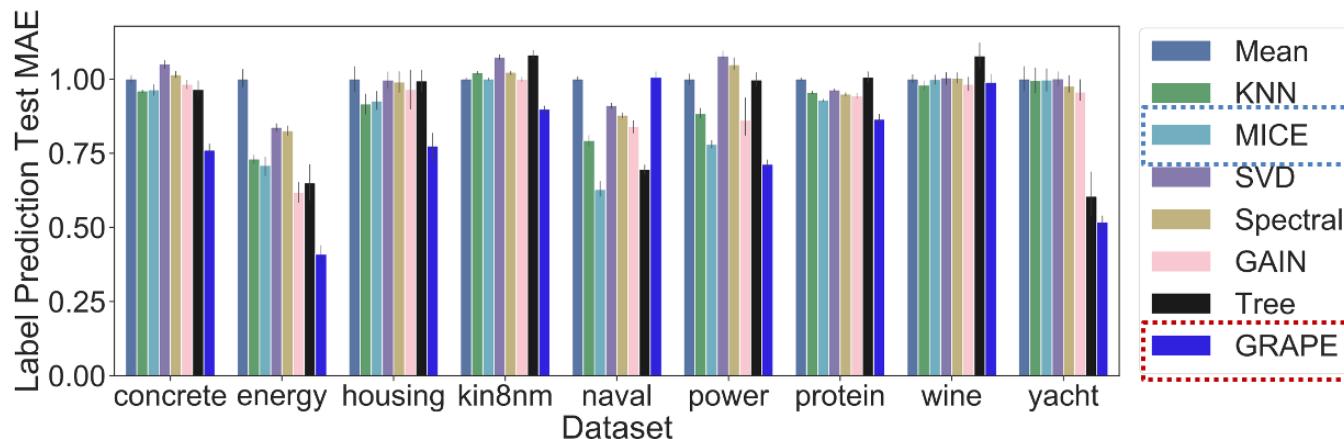


# Missing Data

GRAPE yields 20% lower mean absolute error for feature imputation,  
and 10% lower MAE for label prediction



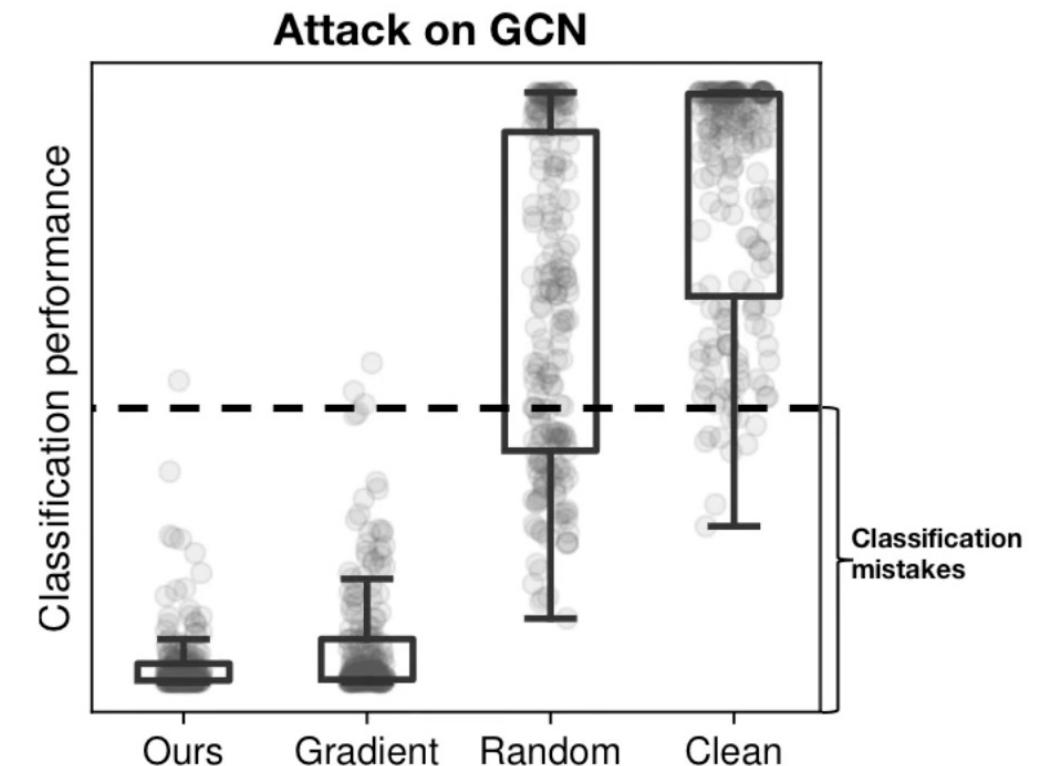
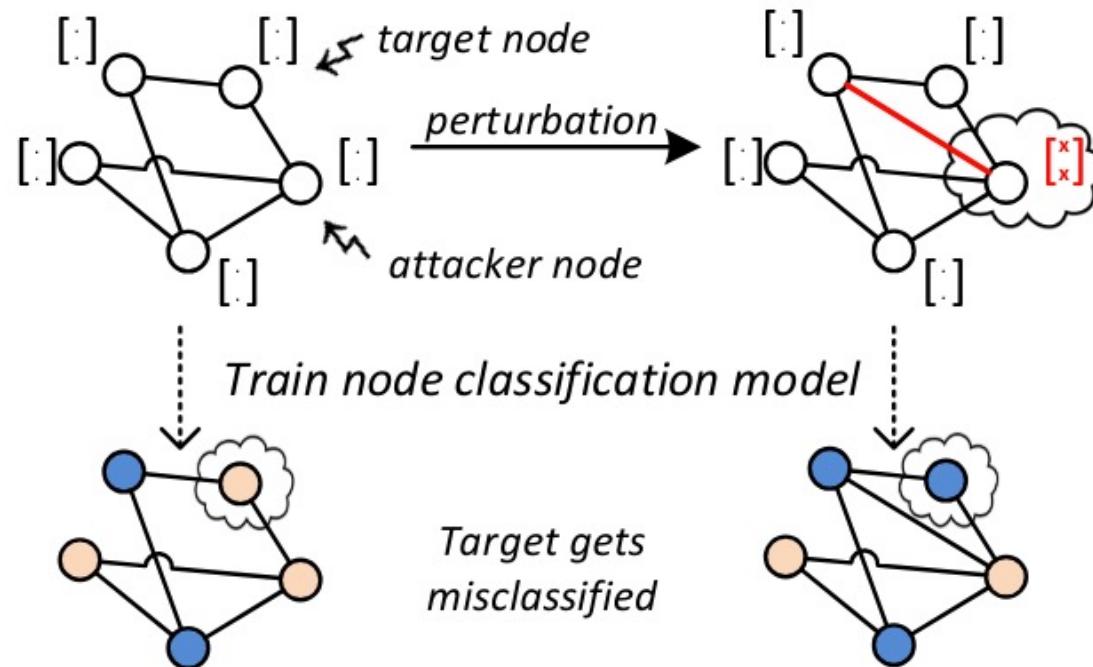
Feature  
imputation:  
**20% lower  
MAE than best  
baseline (KNN)**



Label  
prediction:  
**10% lower  
MAE than best  
baseline (MICE)**

# Adversarial Attacked Data

**Observation:** Small perturbations of the graph structure and node features lead to misclassification of the target



# Adversarial Attacked Data

Can we leverage small data perturbations to **improve performance?**

Yes, adversarial training

Adversarial training is the process of crafting adversarial data points, and then injecting them into training data

$$\min_{\theta} \quad E_{(x,y) \sim \mathcal{D}} \left[ \max_{\|\delta\|_p \leq \epsilon} L(f_{\theta}(x + \delta), y) \right]$$

↓

Find the optimal perturbation sample to achieve maximum loss

Find the optimal model parameters to resist the attack of perturbation sample

D: distribution

$\|\cdot\|_p$ :  $l_p$ -norm distance metric

$\epsilon$ : perturbation budget

# Adversarial Attacked Data

Can we leverage small data perturbations to **improve performance?**  
Yes, adversarial training

Node Classification

Backbone	ogbn-products			ogbn-proteins			ogbn-arxiv		
	Test Acc	-	-	Test ROC-AUC	-	-	Test Acc	-	-
GCN	-	-	-	<b>72.51</b> ±0.35	-	-	71.74±0.29	-	-
+FLAG	-	-	-	71.71±0.50	-	-	<b>72.04</b> ±0.20	-	-
GraphSAGE	78.70±0.36	-	-	<b>77.68</b> ±0.20	-	-	71.49±0.27	-	-
+FLAG	<b>79.36</b> ±0.57	-	-	76.57±0.75	-	-	<b>72.19</b> ±0.21	-	-
GAT	79.45±0.59	-	-	-	-	-	73.65±0.11	-	-
+FLAG	<b>81.76</b> ±0.45	-	-	-	-	-	<b>73.71</b> ±0.13	-	-
DeeperGCN	80.98±0.20	-	-	85.80±0.17	-	-	71.92±0.16	-	-
+FLAG	<b>81.93</b> ±0.31	-	-	<b>85.96</b> ±0.27	-	-	<b>72.14</b> ±0.19	-	-

# Adversarial Attacked Data

Can we leverage small data perturbations to **improve robustness?**

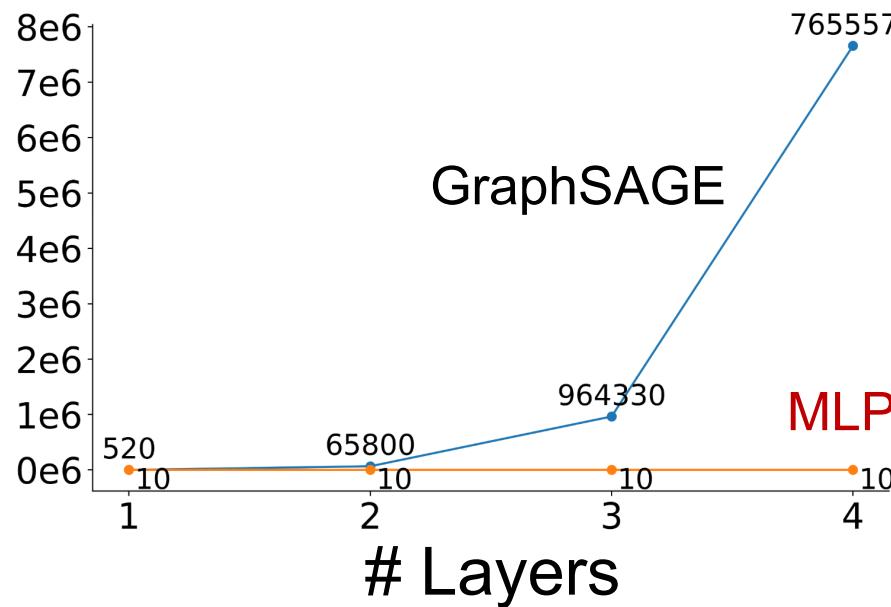
Yes, adversarial training

A **use case**: training an MLP on graphs

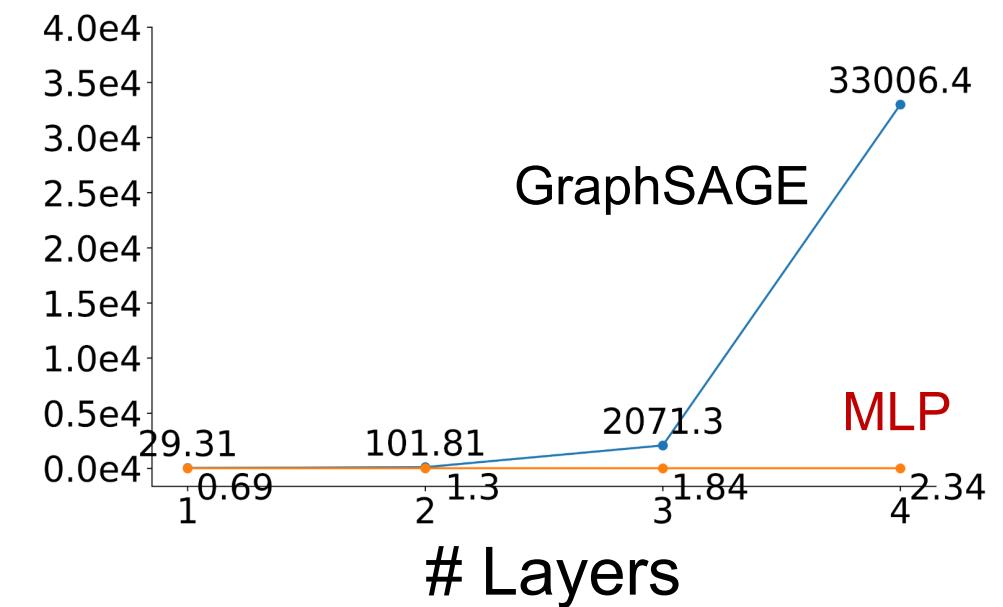
**Reason**: to avoid the computation-intensive message passing mechanism



# Nodes Fetched



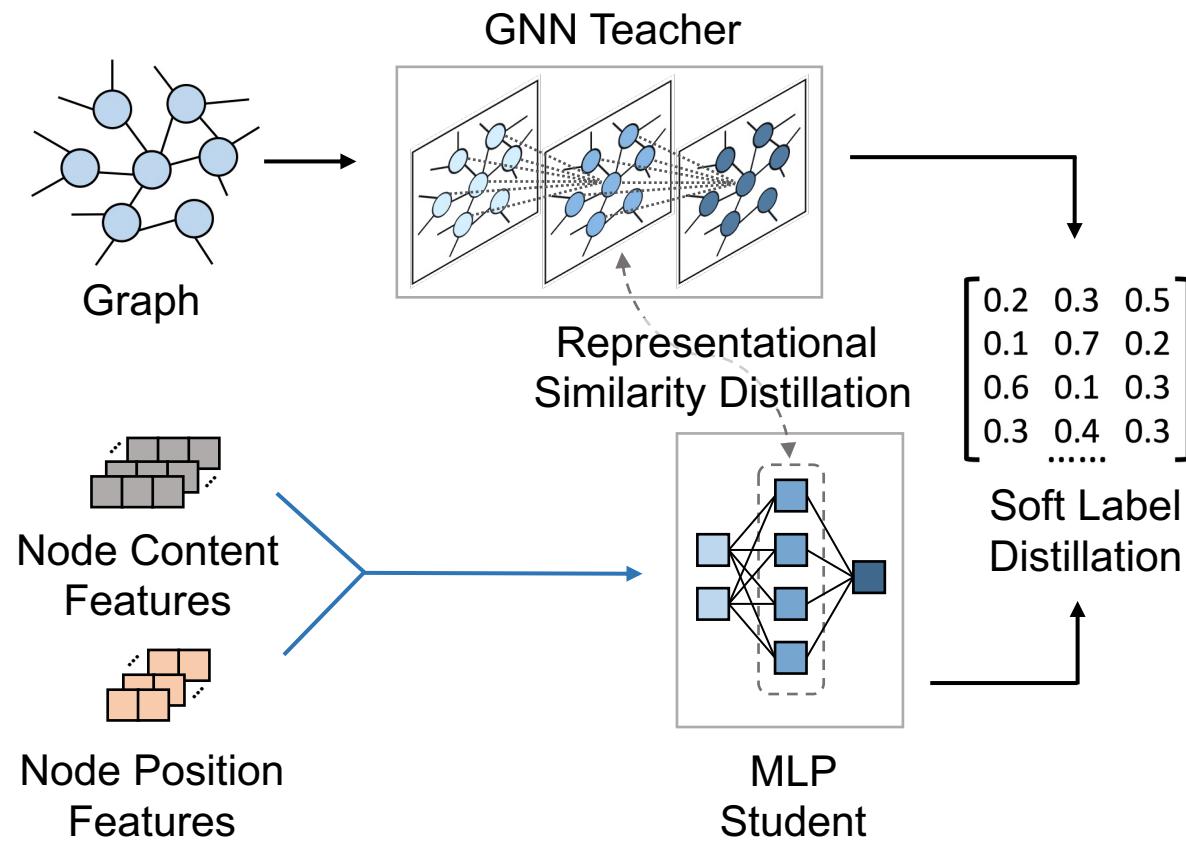
Inference Time (ms)



# Adversarial Attacked Data

Can we leverage small data perturbations to **improve robustness**?  
Yes, adversarial training

A use case: training an MLP on graphs

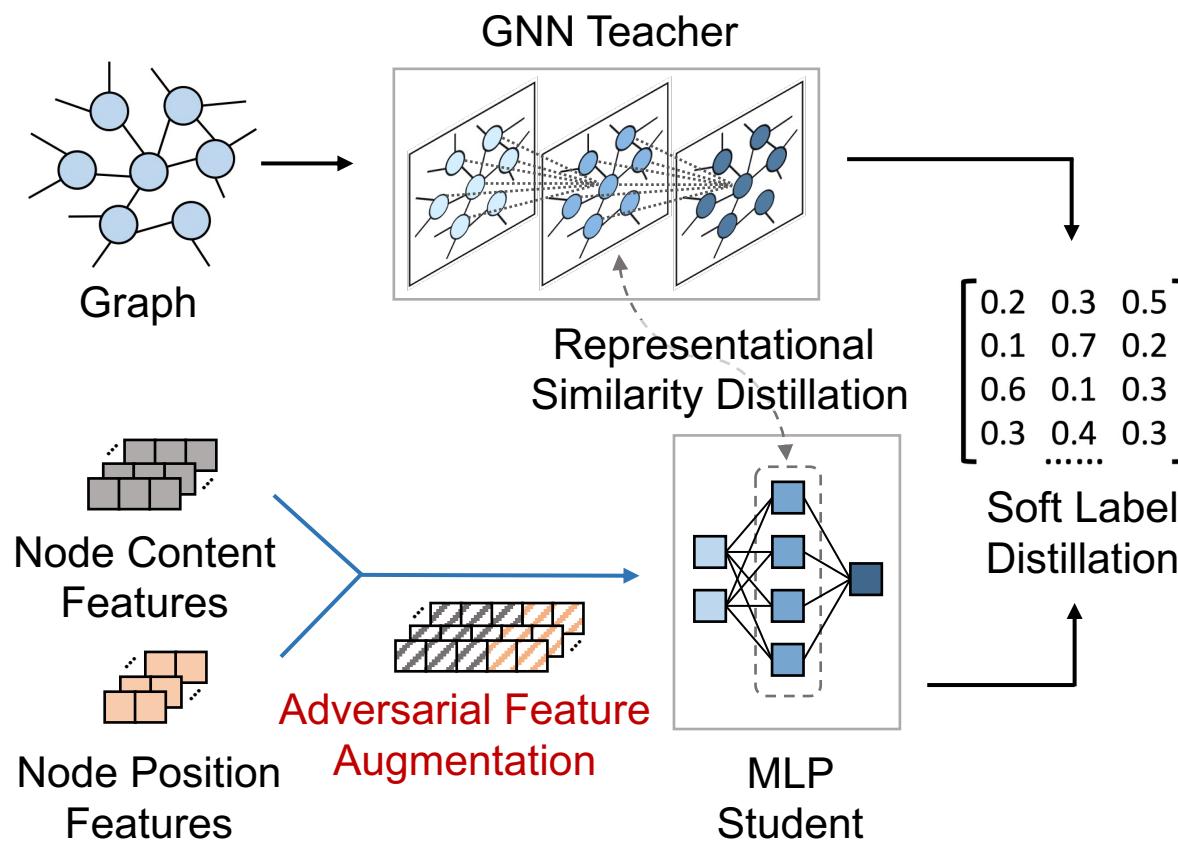


The problem of training an MLP on graphs:  
**sensitive to features**

# Adversarial Attacked Data

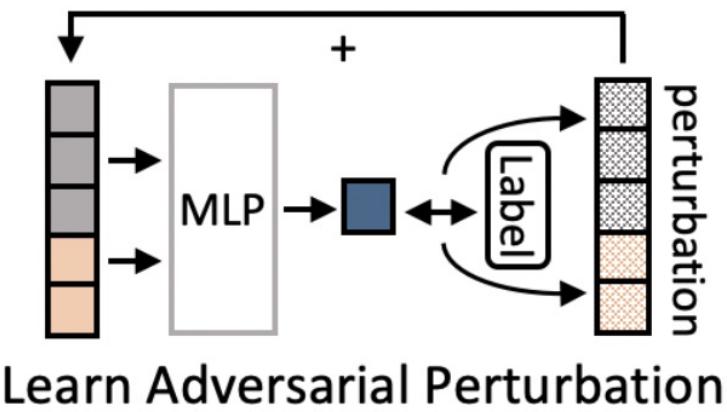
Can we leverage small data perturbations to **improve robustness**?  
Yes, adversarial training

A use case: training an MLP on graphs



The problem of training an MLP on graphs:  
sensitive to features

Overcome this problem with adversarial training

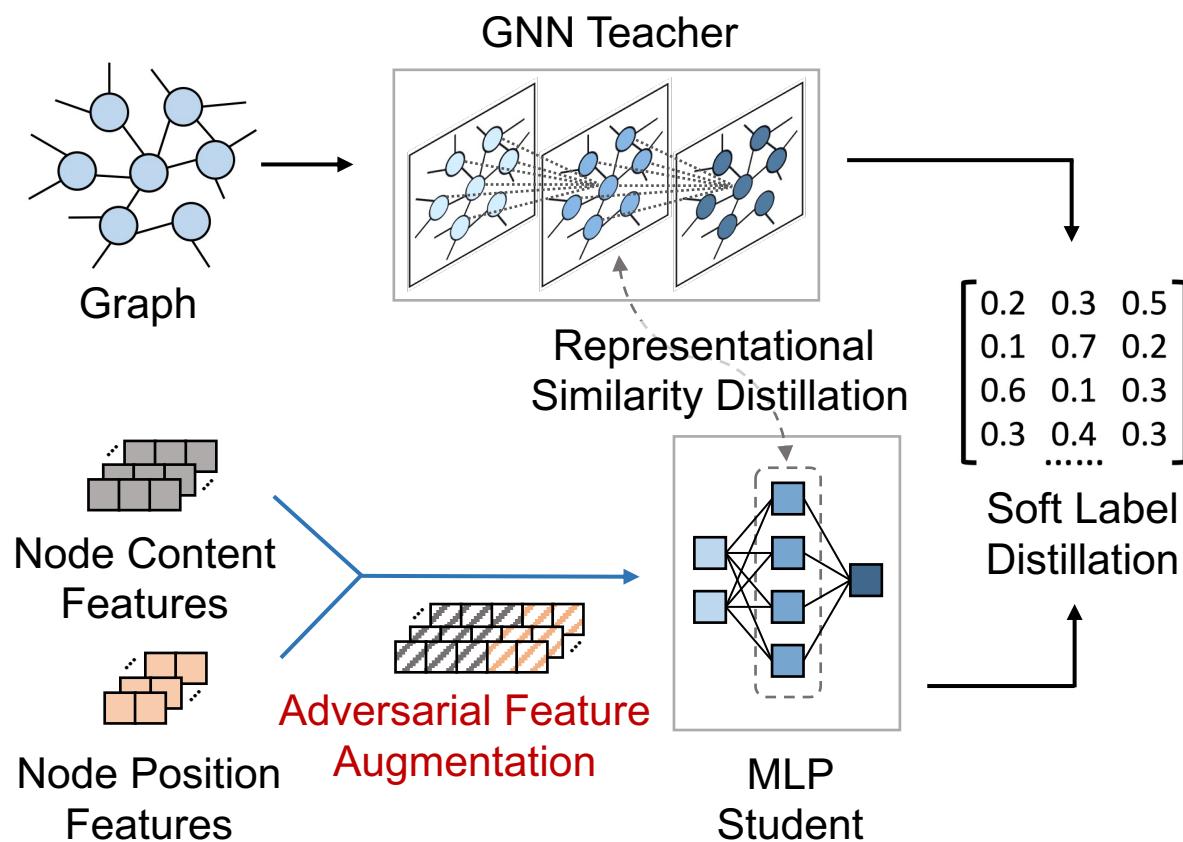


Learn Adversarial Perturbation

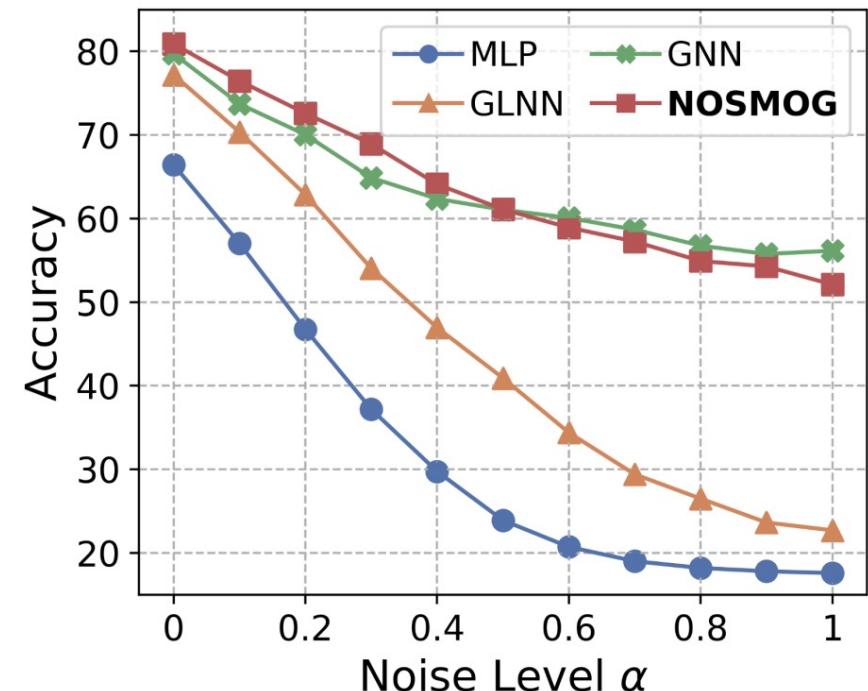
# Adversarial Attacked Data

Can we leverage small data perturbations to **improve robustness**?  
Yes, adversarial training

A use case: training an MLP on graphs



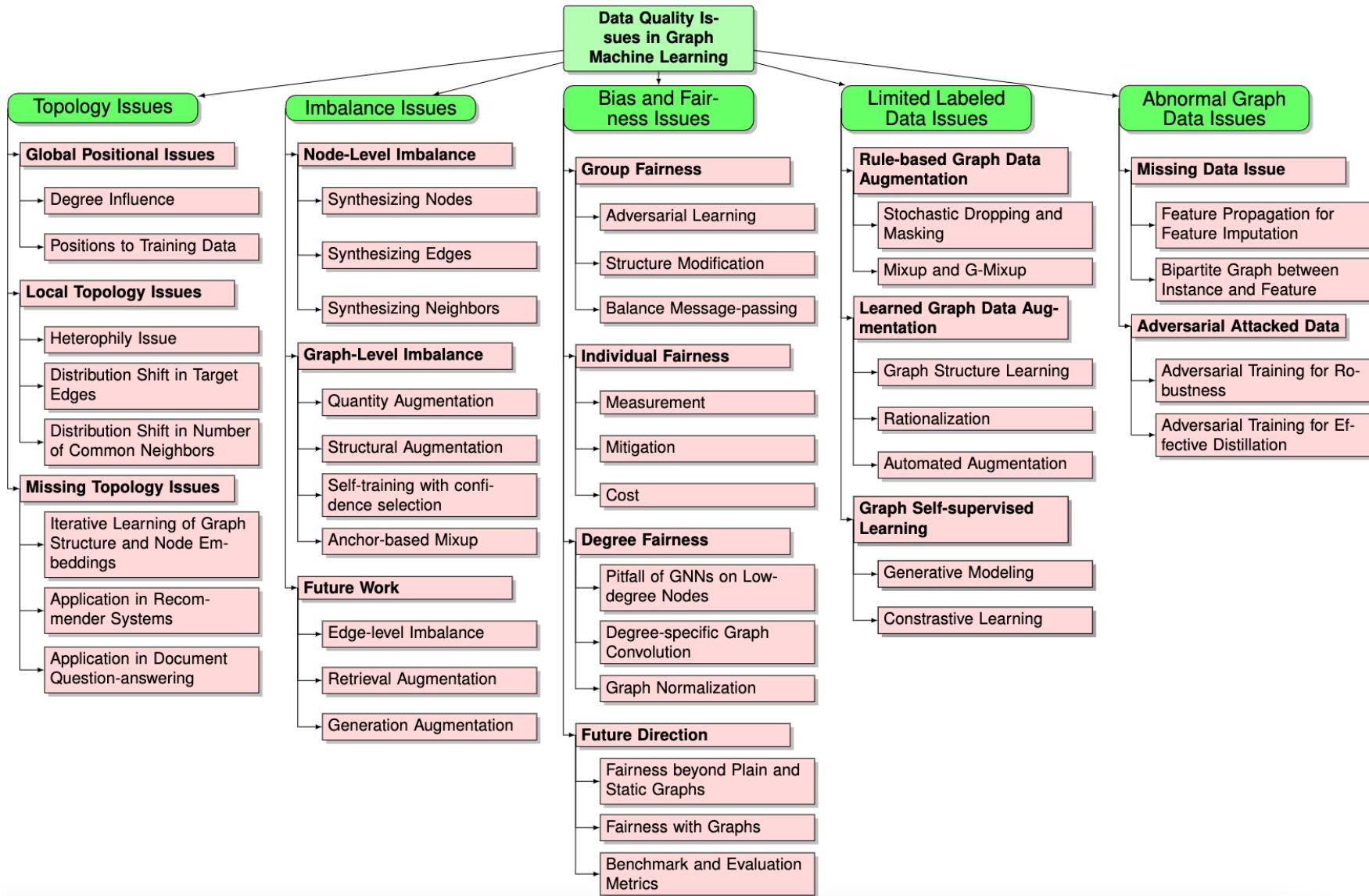
NOSMOG is as robust as GNNs



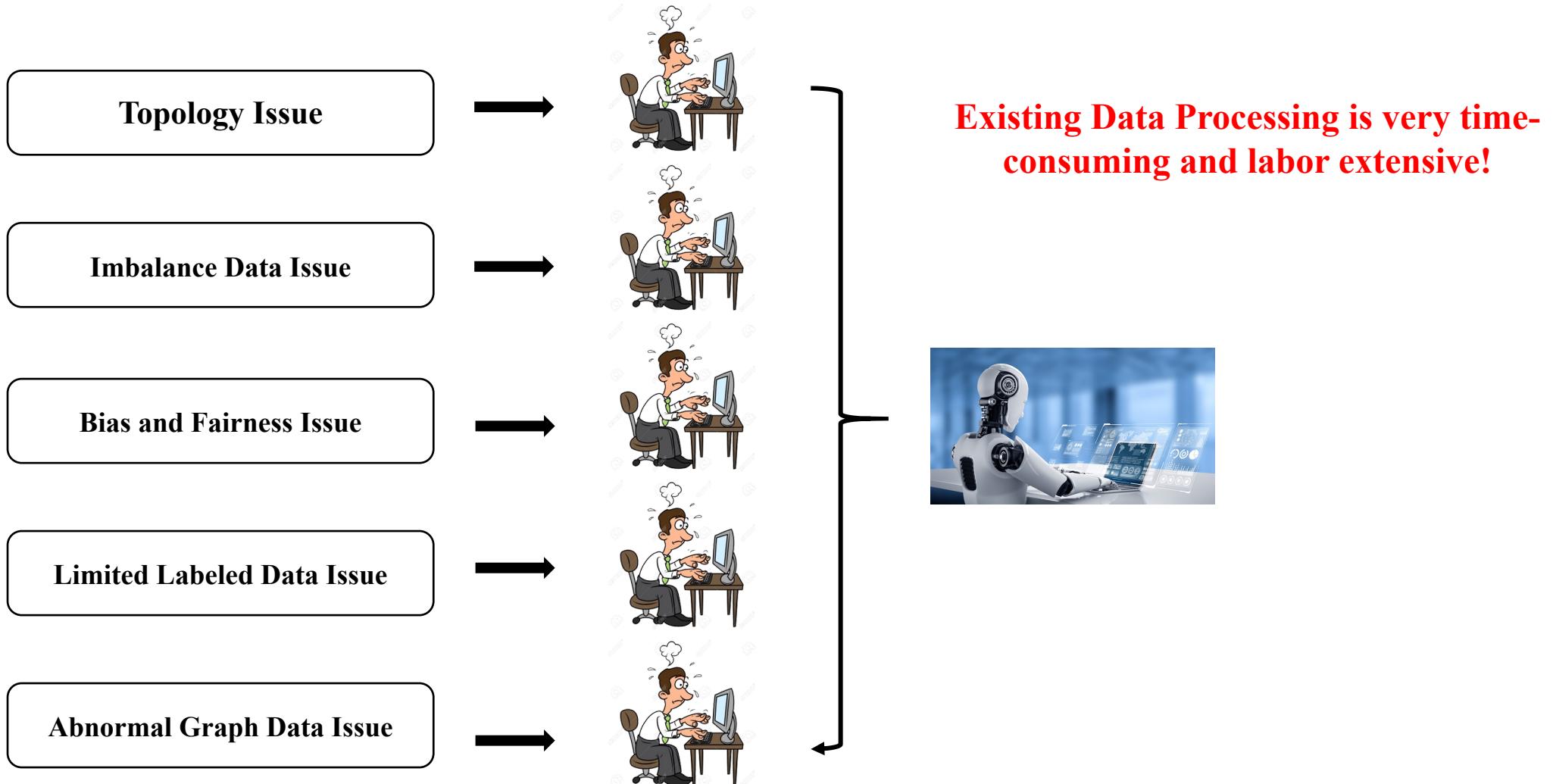
# Summary

- Introduction and Background
- Topology Issues
- Imbalance Issues
- Short Break
- Bias Issue
- Limited Labeled Data Issues
- Abnormal Graph Data Issues
- **Summary**

# Summary

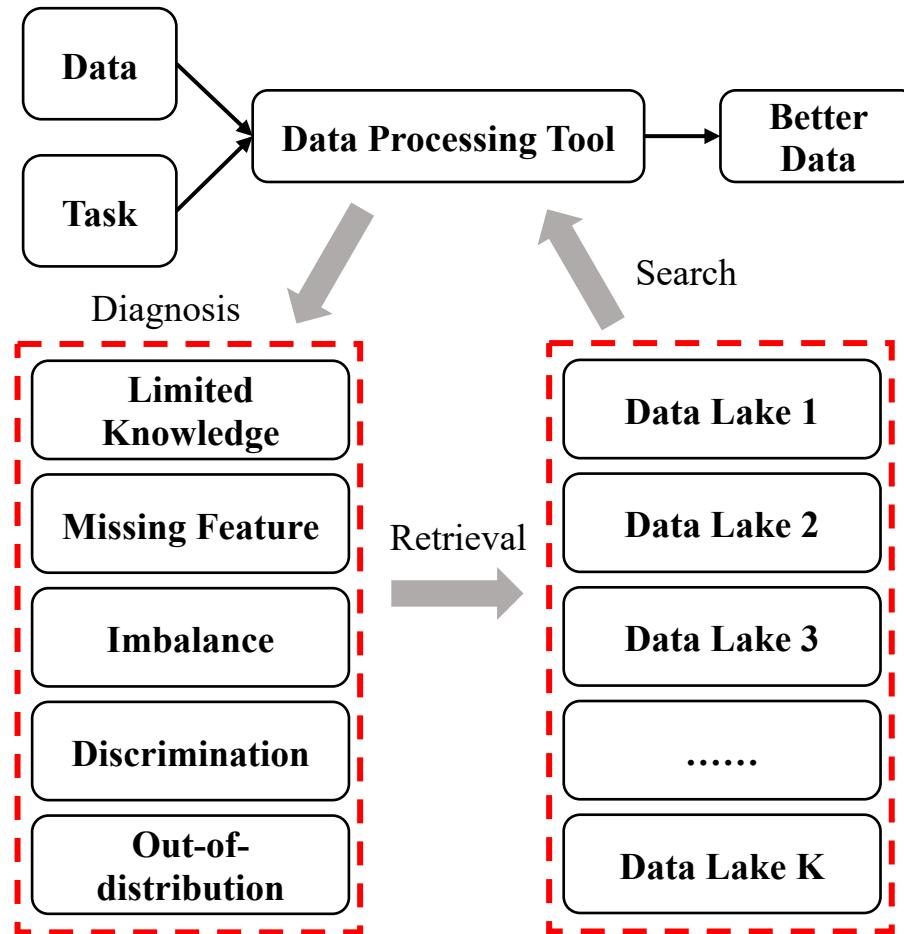


# Future Directions

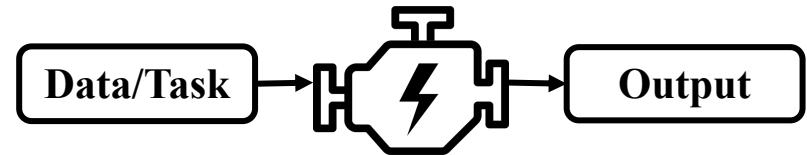


# Summary

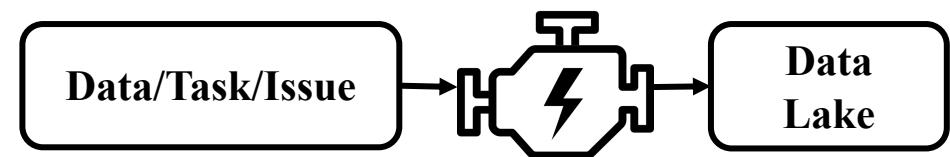
## Intelligent Data Processing Tool



## Diagnose



## Retrieval



## Search

