# M3P21 Geometry II: Algebraic Topology

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## 0 Some underlying geometric notions

## 0.1 Introduction

Combines topological spaces with algebraic objects, groups.

Lecture 1 Friday 11/01/19

- How to show that a torus is not homeomorphic to a sphere?
- How to show that  $\mathbb{R}^n \ncong \mathbb{R}^m$  if  $n \neq m$ ?

Content is fundamental groups and homology. We will follow chapter one and two from

• A Hatcher, Algebraic topology, 2002

Prerequisites are the following.

- Point set topology. Topological spaces, continuous maps, product and quotient topologies, Hausdorff spaces, etc.
- Basic group theory. Normal subgroups and quotients, isomorphism theorems, free groups, presentation of groups, etc.

## 0.2 Homotopy

Let X, Y be topological spaces and I = [0, 1].

**Definition 0.1.** A homotopy is a continuous map  $F: X \times I \to Y$ . For every  $t \in I$  we obtain a continuous map

$$\begin{array}{cccc} f_t: & X & \to & Y \\ & x & \mapsto & f_t\left(x\right) = F\left(x,t\right) \end{array}.$$

**Definition 0.2.** Two continuous maps  $f_0, f_1: X \to Y$  are **homotopic** if there exists a homotopy  $F: X \times I \to Y$  such that

$$f_0(x) = F(x,0), \qquad f_1(x) = F(x,1),$$

for all  $x \in X$ . We write  $f_0 \cong f_1$ .

(Exercise: this is an equivalence relation)

**Definition 0.3.** Let  $A \subseteq X$  be a subspace. A **retraction** of X onto A is a continuous map  $r: X \to A$  such that

- r(X) = A, and
- $\bullet$   $r \mid_A = id_A$ .

**Example 0.4.** If  $X \neq \emptyset$ ,  $p \in X$ , then X retracts to p by the constant map  $X \to \{p\}$ .

**Definition 0.5.** A **deformation retraction** of X onto  $A \subseteq X$  is a retraction that is homotopic to the identity. That is, there is a continuous map

$$\begin{array}{cccc} F: & X \times I & \rightarrow & A \\ & (x,t) & \mapsto & f_t \left( x \right) \end{array},$$

such that  $f_0 = id_X$  and  $f_1 : X \to A$  is the deformation retraction.

**Example 0.6.** The closed n-dimensional n-disc

$$D^n = \{ x \in \mathbb{R}^n \mid |x| \le 1 \}$$

deformation retracts to  $(0,\ldots,0)\in\mathbb{R}^n$ . Let  $f_t(x)=t\cdot x$ . t=1 gives  $f_1=id_{D^n}$  and t=0 gives  $f_0:D^n\to(0,\ldots,0)$ .

Example 0.7. Let  $S^n$  be the *n*-sphere,

$$\partial D^{n+1} = S^n = \{ x \in \mathbb{R}^n \mid |x| = 1 \}.$$

The cylinder  $S^n \times I$  deformation retracts to  $S^n \times \{0\}$ , by defining  $f_t(x,r) = (x,t \cdot r)$ .

An observation is if X is a topological space, and  $f: X \to \{p\}$  for  $p \in X$  is a deformation retraction of X to p, then X is path connected. Indeed, if  $F: X \times I \to X$  is a homotopy from  $id_X$  to f and  $x \in X$  is a point, then this gives a path

$$\begin{array}{ccc}
I & \to & X \\
t & \mapsto & F(x,t)
\end{array}$$

that connects x to p. This implies that not all retractions are deformation retractions.

**Example 0.8.** A retraction that is not a deformation retraction. Take a space that is not path connected and retract it to a point. Let  $X = \{0, 1\}$  with discrete topology.  $x \mapsto 0$  is a retraction, but not a deformation retraction because X is not path connected.

**Definition 0.9.** A continuous map  $f: X \to Y$  is a **homotopy equivalence** if there is a continuous map  $g: Y \to X$  such that  $fg \cong id_Y$  and  $gf \cong id_X$ . If there exists a homotopy equivalence between X and Y, X and Y are **homotopy equivalent** or they have the same **homotopy type**.

**Lemma 0.10.** A deformation retraction  $f: X \to A$  is a homotopy equivalence.

*Proof.* Let  $i: A \hookrightarrow X$  be the inclusion map. Then  $fi = id_A$  and  $if = f \cong id_X$  by definition.

**Example 0.11.** The disc with two holes is equivalent to  $\infty$ .

**Example 0.12.**  $\mathbb{R}^n$  deformation retracts to a point, by  $f_t(x) = t \cdot x$ .

Definition 0.13.

- X is **contractible** if it is homotopy equivalent to a point.
- A continuous map is **nullhomotopic** if it is homotopy equivalent to a constant map.

#### 0.3 Cell complexes

**Example 0.14.** The torus  $S^1 \times S^1$  is the union of a point, two open intervals, and the open disc  $Int(D^2)$ .

These are called **cells**. Can think of discs  $D^n$  glued together.

Lecture 2 Tuesday 15/01/19

**Definition 0.15.** A CW-complex, or cell complex, is a topological space X such that there exists a decomposition

$$X = \bigcup_{n \in \mathbb{N}} X^n,$$

where the  $X^n$  are constructed inductively in the following way.

- $X^n$  is a discrete set.
- For each  $n \geq 0$  there is an collection of closed n-discs  $\{D_n^n\}$  together with continuous maps

$$\phi_{\alpha}: \partial D_{\alpha}^n \to X^{n-1},$$

such that

$$X^n = \frac{X^{n-1} \sqcup \bigsqcup_{\alpha} D^n_{\alpha}}{\sim},$$

where  $x \sim \phi_{\alpha}(x)$  for all  $x \in \partial D_{\alpha}^{n}$  for all  $\alpha$ .

• A subset  $U \subseteq X$  is open if and only if  $U \cap X^n$  is open for all n.

Remark 0.16.

• As a set,

$$X^n = X^{n-1} \sqcup \bigsqcup_{\alpha} e_{\alpha}^n,$$

where each  $e_{\alpha}^{n}$  is homeomorphic to an open n-disc. These  $e_{\alpha}^{n}$  are called the n-cells of X.

• If  $X = X^m$  for some m, then X is called **finite dimensional**. The minimal m such that  $X = X^m$  is the **dimension** of X.

## Example 0.17.

- [0,1] is a CW-complex.
- $\bullet$   $\mathbb R$  is a CW-complex.
- $S^1$  is a CW-complex.
- A graph is a CW-complex.
- $S^n = D^n/\partial D^n$  is a CW-complex. See worksheet 1.

Can also decompose CW-complexes.

- The sphere  $S^2$  is one 0-cell, one 1-cell, and two 2-cells.
- The torus  $S^1 \times S^1$  is one 0-cell, two 1-cells, and one 2-cell.
- The Möbius strip is two 0-cells, three 1-cells, and one 2-cell.
- The Klein bottle is one 0-cell, two 1-cells, and one 2-cell.

**Definition 0.18.** If X is a CW-complex with finitely many cells the **Euler characteristic**  $\chi(X)$  of X is the number of even cells minus the number of odd cells.

A fact is that  $\chi(X)$  does not depend of the choice of cells decomposition.

#### Example 0.19.

- $\chi(S^n) = 0$  if n is odd and  $\chi(S^n) = 2$  if n is even.
- $\chi(S^1 \times S^1) = 0$ .

This is the generalisation of the following observation by Leonhard Euler. Let P be a convex polyhedron, where

- V is the number of vertices of P,
- $\bullet$  E is the number of edges of P, and
- F is the number of faces of P.

Then V - E + F = 2.

**Example 0.20.** A topological space that is not a CW-complex.  $X = \{0, 1\}$  with trivial topology does not contain any closed points. A fact is that CW-complexes are always Hausdorff.

## 1 The fundamental group

## 1.1 Paths and homotopy

Let X be a topological space. A **path** is a continuous map  $f: I \to X$ , where I = [0, 1].

**Definition 1.1.** Two paths  $f_0$ ,  $f_1$  are **homotopic** if there exists a homotopy between  $f_0$  and  $f_1$  preserving the endpoints, that is a continuous map

$$F: I \times I \to X (s,t) \mapsto f_t(s) ,$$

such that

$$f_t(0) = f_0(0), \qquad f_t(1) = f_0(1),$$

for all  $t \in I$ , and

$$F(s,0) = f_0(s), \qquad F(s,1) = f_1(s),$$

for all  $s \in I$ .

**Example 1.2.** Let  $X \subseteq \mathbb{R}^n$  be a convex set. Then all the paths in X are homotopic if they have the same endpoints.

*Proof.* Let  $f_0, f_1: I \to X$  be two paths such that  $f_0(0) = f_1(0)$  and  $f_0(1) = f_1(1)$ . Define

$$f_t(s) = (1 - t) f_0(s) + t f_1(s).$$

**Lemma 1.3.** Being homotopic is an equivalence relation on the set of paths with fixed endpoints. We will write  $f_0 \cong f_1$  for two homotopic paths  $f_0$  and  $f_1$ .

Proof.

- f is homotopic to f.
- If  $f_0$  is homotopic to  $f_1$  by a homotopy  $f_t$ , then  $f_1$  is homotopic to  $f_0$  by the homotopy  $f_{1-t}$ .
- If  $f_0$  is homotopic to  $f_1$  by a homotopy  $f_t$  and  $f_1 = g_0$  is homotopic to  $g_1$  by a homotopy  $g_t$ , then  $f_0$  is homotopic to  $g_1$  by the homotopy

$$h_t = \begin{cases} f_{2t} & 0 \le t \le \frac{1}{2} \\ g_{2t-1} & \frac{1}{2} \le t \le 1 \end{cases}.$$

Then

$$H: \quad \begin{array}{ccc} I \times I & \to & X \\ & (s,t) & \mapsto & h_t \left( s \right) \end{array}$$

is continuous because its restriction to the closed subsets  $I \times [0, 1/2]$  and  $I \times [1/2, 1]$  is continuous, since if the restriction to two closed subsets is continuous then the restriction to the union of these subsets is continuous.

Let X be a topological space and I = [0,1]. If  $f: I \to X$  is a path, [f] is the class of all paths on X homotopic to f.

**Definition 1.4.** Let  $f, g: I \to X$  be two paths such that f(1) = g(0). The **product path**  $f \cdot g$  is the path

$$(f \cdot g)(s) = \begin{cases} f(2s) & 0 \le s \le \frac{1}{2} \\ g(2s-1) & \frac{1}{2} \le s \le 1 \end{cases}.$$

Lecture 3 Wednesday 16/01/19

A convention is that whenever we write  $f \cdot g$  we implicitly assume f(1) = g(0).

**Lemma 1.5.** Let  $f_0, f_1, g_0, g_1$  be paths on X such that  $f_1 \cong f_0$  and  $g_0 \cong g_1$ . Then  $f_0 \cdot g_0 \cong f_1 \cdot g_1$ .

Proof.

$$I \times I \rightarrow X$$
  
 $(s,t) \mapsto (f_t \cdot g_t)(s)$ 

is a homotopy between  $f_0 \cdot g_0$  and  $f_1 \cdot g_1$ .

Remark 1.6. Let  $\phi:[0,1]\to[0,1]$  be continuous such that  $\phi(0)=0$  and  $\phi(1)=1$ . If  $f:I\to X$  is a path, then  $f\circ\phi\cong f$ . This is a **reparametrisation**.

Proof. Define

$$\phi_t(s) = (1 - t)\phi(s) + ts,$$

then  $f \circ \phi_t$  is a homotopy between  $f \circ \phi$  and f.

For  $x \in X$ , let the **constant path** at x be

$$\begin{array}{cccc} c_x: & I & \to & X \\ & s & \mapsto & x \end{array}.$$

For a path  $f: I \to X$ , define

$$\begin{array}{cccc} f^{-1}: & I & \to & X \\ & s & \mapsto & f\left(1-s\right) \end{array}.$$

**Lemma 1.7.** Let  $f, g, h: I \to X$  be paths. Then

- 1.  $(f \cdot g) \cdot h \cong f \cdot (g \cdot h)$ ,
- 2.  $f \cdot c_{f(1)} \cong f$  and  $c_{f(0)} \cdot f \cong f$ , and
- 3.  $f \cdot f^{-1} \cong c_{f(0)}$  and  $f^{-1} \cdot f \cong c_{f(1)}$ .

Proof.

1.  $((f \cdot q) \cdot h) \circ \phi = f \cdot (q \cdot h)$ , where

$$\phi\left(s\right) = \begin{cases} \frac{s}{2} & s \in \left[0, \frac{1}{2}\right] \\ s - \frac{1}{4} & s \in \left[\frac{1}{2}, \frac{3}{4}\right], \\ 2s - 1 & s \in \left[\frac{3}{4}, 1\right] \end{cases}$$

so  $(f \cdot g) \cdot h \cong f \cdot (g \cdot h)$  by reparametrisation.

2. Again reparametrisation, by

$$\psi\left(s\right) = \begin{cases} 2s & s \in \left[0, \frac{1}{2}\right] \\ 1 & s \in \left[\frac{1}{2}, 1\right] \end{cases}, \qquad \chi\left(s\right) = \begin{cases} 0 & s \in \left[0, \frac{1}{2}\right] \\ 2s - 1 & s \in \left[\frac{1}{2}, 1\right] \end{cases}.$$

3. Define

$$H(s,t) = \begin{cases} f(\max\{1-2s,t\}) & s \in [0,\frac{1}{2}] \\ f(\max\{2s-1,t\}) & s \in [\frac{1}{2},1] \end{cases}.$$

H is continuous, and

$$H(s,0) = f^{-1} \cdot f, \qquad H(s,1) = c_{f(1)}.$$

The inverse is similar.

**Definition 1.8.** A loop with basepoint  $x_0 \in X$  is a path  $f: I \to X$  such that  $f(0) = f(1) = x_0$ .

**Definition 1.9.** Denote by  $\pi_1(X, x_0)$  the set of homotopy classes [f] of loops  $f: I \to X$  with basepoint  $x_0$ .

**Proposition 1.10.**  $\pi_1(X, x_0)$  is a group with product  $[f][g] = [f \cdot g]$  and neutral element  $c_{x_0} : I \to X$ , the constant path at  $x_0$ .

*Proof.* Follows directly from Lemma 1.5 and Lemma 1.7.

**Definition 1.11.**  $\pi_1(X, x_0)$  is the fundamental group of X at  $x_0$ .

**Example 1.12.** Let  $X \subseteq \mathbb{R}^n$  be a convex set and  $x_0 \in X$ . Then  $\pi_1(X, x_0) = 0$ .

*Proof.* X is convex gives that all loops are homotopic to each other.

### Example 1.13.

- The fundamental group of a space X with the trivial topology is trivial, since X is simply connected, because all maps  $f: I \to X$  are continuous, so path connected and all paths are homotopic.
- The fundamental group of a space X with the discrete topology is trivial, since  $f: I \to X$  continuous gives f constant.

Assume  $x_0, x_1 \in X$  such that  $x_0$  and  $x_1$  are in the same path component of X. Let  $h: I \to X$  be a path such that  $h(0) = x_0$  and  $h(1) = x_1$ . Define

$$\beta_h: \quad \pi_1\left(X, x_1\right) \quad \to \quad \pi_1\left(X, x_0\right) \\ \left[f\right] \quad \mapsto \quad \left[h \cdot f \cdot h^{-1}\right] \ .$$

This is well-defined by Lemma 1.5.

**Proposition 1.14.**  $\beta_h: \pi_1(X, x_1) \to \pi_1(X, x_0)$  is an isomorphism.

*Proof.* It is a homomorphism.

$$\beta_h\left[f\cdot g\right] = \left[h\cdot f\cdot g\cdot h^{-1}\right] = \left[h\cdot f\cdot h^{-1}\right] \left[h\cdot g\cdot h^{-1}\right] = \beta_h\left[f\right]\cdot\beta_h\left[g\right],$$

and  $\beta_h[c_{x_1}] = [c_{x_1}]$ . It is bijective with  $(\beta_h)^{-1} = \beta_{h^{-1}}$ .

If X is path connected, we often write  $\pi_1(X)$  instead of  $\pi_1(X, x_0)$ .

**Definition 1.15.** X is simply connected if it is path connected and  $\pi_1(X) = 0$ .

**Proposition 1.16.** X is simply connected if and only if there exists a unique homotopy class of paths between any two points of X.

Proof.

- $\implies$  There exists a path between any two points. Let f, g be two paths from  $x_0$  to  $x_1$  for  $x_0, x_1 \in X$ .  $f \cdot g^{-1} \cong g \cdot g^{-1}$  gives  $f \cong f \cdot g^{-1} \cdot g \cong g \cdot g^{-1} \cdot g \cong g$ .
- $\iff$  X is path connected.  $x_1 = x_0$  gives that all loops at  $x_0$  are homotopic to each other, so  $\pi_1(X) = 0$ .

## 1.2 The fundamental group of the circle

Goal is to show that  $\pi_1(S^1) \cong \mathbb{Z}$ .

Lecture 4 Friday 18/01/19

**Definition 1.17.** A covering space of a space X is a space  $\widetilde{X}$  and a continuous map  $p:\widetilde{X}\to X$  such that for each  $x\in X$  there is an open  $x\in U\subseteq X$  such that

- $p^{-1}(U) = \bigcup_{j \in J} \widetilde{U_j}$ , where  $\widetilde{U_j} \subseteq \widetilde{X}$  is open,
- $\widetilde{U_i} \cap \widetilde{U_j} = \emptyset$  if  $i \neq j$ , and
- $p \mid_{\widetilde{U_i}} : \widetilde{U_j} \to U_i$  is a homeomorphism for all  $j \in J$ .

Such a U is called **evenly covered**. The  $\widetilde{U}_i$  are called **sheets**.

### Example 1.18.

$$p: \ \mathbb{R} \ \to \ S^1$$
$$s \ \mapsto \ (\cos(2\pi s, \sin(2\pi s)))$$

**Definition 1.19.** Let  $p: \widetilde{X} \to X$  be a covering space. A **lift** of a continuous map  $f: Y \to X$  is a continuous map  $\widetilde{f}: Y \to \widetilde{X}$  such that  $p \circ \widetilde{f} = f$ , so

$$Y \xrightarrow{\widetilde{f}} \widetilde{X} \downarrow_{p}.$$

**Proposition 1.20** (Unique lifting property). Let  $p: \widetilde{X} \to X$  be a covering space and  $f: Y \to X$  be a continuous map. If there are two lifts  $\widetilde{f}_1, \widetilde{f}_2: Y \to \widetilde{X}$  of f such that  $\widetilde{f}_1(y) = \widetilde{f}_2(y)$  for some  $y \in Y$  and if Y is connected, then  $\widetilde{f}_1 = \widetilde{f}_2$ .

*Proof.* Let  $y \in Y$  and  $U \subseteq X$  be an evenly covered neighbourhood of f(y). Then

$$p^{-1}\left(U\right) = \bigcup_{i} \widetilde{U_{j}}.$$

Let  $\widetilde{U_1}$  be the sheet such that  $\widetilde{f_1}(y) \in \widetilde{U_1}$ , and let  $\widetilde{U_2}$  be the sheet such that  $\widetilde{f_2}(y) \in \widetilde{U_2}$ . Let  $N \subseteq Y$  be open and  $y \in N$  such that  $\widetilde{f_1}(N) \subseteq \widetilde{U_1}$  and  $\widetilde{f_2}(N) \subseteq \widetilde{U_2}$ . We have  $p \circ \widetilde{f_1} = p \circ \widetilde{f_2}$ .

$$\widetilde{f}_{1}\left(y\right) = \widetilde{f}_{2}\left(y\right) \qquad \Longleftrightarrow \qquad \widetilde{U}_{1} = \widetilde{U}_{2} \qquad \Longleftrightarrow \qquad \widetilde{f}_{1}\mid_{N} = \widetilde{f}_{2}\mid_{N}.$$

Let

$$A = \left\{ y \in Y \mid \widetilde{f}_1(y) = \widetilde{f}_2(y) \right\},\,$$

so A is open and  $Y \setminus A$  is open. Thus  $A \neq \emptyset$  gives A = Y.

**Proposition 1.21** (Homotopy lifting property). Let  $p: \widetilde{X} \to X$  be a covering space and  $F: Y \times I \to X$  be a continuous map such that there exists a lift  $\widetilde{f}_0: Y \times \{0\} \to \widetilde{X}$  of  $F\mid_{Y \times \{0\}}$ . Then there is a unique lift  $\widetilde{F}: Y \times I \to \widetilde{X}$  of F such that  $\widetilde{F}\mid_{Y \times \{0\}} = \widetilde{f}_0$ .

*Proof.* Let  $y_0 \in Y$  and  $t \in I$ . There are open  $y_0 \in N_t \subseteq Y$  and  $t \in (a_t, b_t) \subseteq I$  such that  $F(N_t \times (a_t, b_t)) \subseteq U \subseteq X$ , where  $U \subseteq X$  is open and evenly covered. Compactness of I gives that there exist

$$0 = t_0 < \dots < t_m = 1,$$

and there exists  $y_0 \in N \subseteq Y$  open such that  $F(N \times [t_i, t_{i+1}]) \subseteq U_i \subseteq X$ , where  $U_i \subseteq X$  is open and evenly covered. We inductively construct a lift  $\widetilde{F}|_{N \times I}$  of  $F|_{N \times I}$ .

- $\widetilde{F}|_{N\times[0,0]} = \widetilde{f}_0|_{N\times[0,0]}$  exists.
- Assume the lift has been constructed on  $N \times [0, t_i]$ . Let  $\widetilde{U_i} \subseteq \widetilde{X}$  be such that  $p \mid_{\widetilde{U_i}} : \widetilde{U_i} \to U_i$  such that  $\widetilde{F}(y_0, t_i) \subseteq \widetilde{U_i}$ . After shrinking N, may assume  $\widetilde{F}(N \times \{t_i\}) \subseteq \widetilde{U_i}$ . Define  $\widetilde{F}$  on  $N \times [t_i, t_{i+1}]$  to be composition of F with the homeomorphism  $p^{-1} : U_i \to \widetilde{U_i}$ .

After finitely many steps we obtain a lift  $\widetilde{F}: N \times I \to \widetilde{X}$ , where  $y_0 \in N \subseteq Y$  is open, so for each  $y \in Y$  there is a neighbourhood  $N_y \subseteq Y$  such that  $F|_{N_y \times I}: N_y \times I \to X$  lifts. For all  $y \in Y$ ,  $\{y\} \times I$  is connected and can be lifted, so Proposition 1.20 gives that the lift of  $N \times I$  is unique. Thus there is a unique lift  $\widetilde{F}: Y \times I \to \widetilde{X}$ .

**Example 1.22.** Let X be a topological space and A be discrete. Then  $p: X \times A \to X$  is a covering space. This is the **trivial covering**. (Exercise: show the unique lifting property and the homotopy lifting property for the trivial covering)

**Corollary 1.23.** Let  $f: I \to X$  be a path,  $f(0) = x_0$ , and  $p: \widetilde{X} \to X$  be a covering space. For each  $\widetilde{x_0} \in p^{-1}(x_0)$ , there is a unique lift  $\widetilde{f}: I \to \widetilde{X}$  such that  $\widetilde{f}(0) = \widetilde{x_0}$ .

*Proof.* Proposition 1.21 for Y a point.

**Theorem 1.24.** Let  $x_0 = (1,0) \in S^1$ .  $\pi_1(S^1, x_0)$  is the infinite cyclic group generated by the homotopy class of the loop

$$\omega: I \to S^1$$
  
 $s \mapsto (\cos(2\pi s), \sin(2\pi s))$ .

Remark 1.25.

•  $[\omega]^n = [\omega_n]$ , where

$$\omega_n(s) = (\cos(2\pi ns), \sin(2\pi ns)).$$

•

$$p: \begin{tabular}{ll} $p:$ & $\mathbb{R}$ & $\to$ & $S^1$ \\ & s & \mapsto & (\cos{(2\pi s)}\,,\sin{(2\pi s)}) \end{tabular}$$

is a covering space.

•  $\omega_n$  lifts to

$$\widetilde{\omega_n}: I \to \mathbb{R}$$
 $s \mapsto ns$ ,

such that  $\widetilde{\omega_n}(0) = 0$  and  $\widetilde{\omega_n}(1) = n$ .

Proof of Theorem 1.24.

- If  $f: I \to S^1$  be a loop at  $x_0$ , then the homotopy lifting property gives that there exists a lift  $\widetilde{f}: I \to \mathbb{R}$  such that  $\widetilde{f}(0) = 0$ . Since  $p\left(\widetilde{f}(1)\right) = f(1) = x_0$ , then  $\widetilde{f}(1) = n$  for some  $n \in \mathbb{Z}$ .  $\widetilde{\omega_n}: I \to \mathbb{R}$  is another path such that  $\widetilde{\omega_n}(0) = 0$  and  $\widetilde{\omega_n}(1) = n$ , so  $\widetilde{f} \cong \widetilde{\omega_n}$ . Let  $F: I \times I \to \mathbb{R}$  be a homotopy equivalence between  $\widetilde{f}$  and  $\widetilde{\omega_n}$ . Then  $p \circ F: I \times I \to S^1$  gives a homotopy between  $p \circ \widetilde{f} = f$  and  $p \circ \widetilde{\omega_n} = \omega_n$ .
- Let  $m, n \in \mathbb{Z}$  and assume  $\omega_m \cong \omega_n$ . Let  $F: I \times I \to S^1$  be a homotopy.

$$F(0,t) = \omega_m(t)$$
,  $F(1,t) = \omega_n(t)$ ,  $F(s,0) = F(s,1) = x_0$ ,

for all  $s,t\in I$ . The unique lifting property gives that  $\widetilde{\omega_n},\widetilde{\omega_m}:I\to\mathbb{R}$  are unique lifts such that  $\widetilde{\omega_n}(0)=0=\widetilde{\omega_m}(0)$ . The homotopy lifting property gives that F lifts uniquely to a homotopy  $\widetilde{F}:I\times I\to\mathbb{R}$  between  $\widetilde{\omega_n}$  and  $\widetilde{\omega_m}$ , and  $\widetilde{F}(s,1)\in\mathbb{Z}$  for all  $s\in I$ . Thus  $\widetilde{F}(s,1)=n=m$ , so  $\omega_m\cong\omega_n$  if and only if n=m.

Lecture 5

Tuesday 22/01/19

Lecture 6 Wednesday

23/01/19

Lecture 5 is a problem class.

**Theorem 1.26.** Every non-constant polynomial  $p \in \mathbb{C}[z]$  has a root in  $\mathbb{C}$ .

Proof. May assume

$$p(z) = z^n + a_1 z^{n-1} + \dots + a_n.$$

Assume p has no roots in  $\mathbb{C}$ . For each  $r \in \mathbb{R}_{>0}$  we obtain a loop

$$f_r: I \to \mathbb{C}$$

$$s \mapsto \frac{p(re^{2\pi is})/p(r)}{|p(re^{2\pi is})/p(r)|},$$

so  $|f_r(s)| = 1$ .  $f_r(0) = 1$  and  $f_r(1) = 1$ , so  $f_r$  is a loop based at 1.  $f_0$  is the constant loop at 1.  $f_r(s)$  depends continuously on r, so  $f_r \cong f_0$  for all  $r \in \mathbb{R}_{\geq 0}$  and  $[f_r] = [f_0] = 0 \in \pi_1(S^1)$ . Fix  $r \in \mathbb{R}_{\geq 0}$  such that r > 1 and  $r > |a_1| + \cdots + |a_n|$ . For |z| = r we have

$$|z^n| > (|a_1| + \dots + |a_n|) |z^{n-1}| \ge |a_1 z^{n-1}| + \dots + |a_n| \ge |a_1 z^{n-1} + \dots + |a_n|$$

Hence, for  $0 \le t \le 1$  the polynomial  $p_t(z) = z^n + t(a_1 z^{n-1} + \dots + a_n)$  has no root z with |z| = r. Define

$$F_r\left(t,s\right) = \frac{p_t\left(re^{2\pi is}\right)/p_t\left(r\right)}{\left|p_t\left(re^{2\pi is}\right)/p_t\left(r\right)\right|}.$$

 $F_r\left(0,s\right)=\omega_n\left(s\right)$  and  $F_r\left(1,s\right)=f_r\left(s\right)$ , so  $\left[\omega_n\right]=\left[f_r\right]=0\in\pi_1\left(S^1\right)$ . Theorem 1.24 gives that n=0, so p is constant.

See Hatcher Theorem 1.9 and Theorem 1.10 for more applications.

**Proposition 1.27.** Let X, Y be topological spaces,  $x_0 \in X$ , and  $y_0 \in Y$ . Then

$$\pi_1(X \times Y, (x_0, y_0)) \cong \pi_1(X, x_0) \times \pi_1(Y, y_0).$$

Proof. A map

$$\begin{array}{ccc} f: & Z & \rightarrow & X \times Y \\ & z & \mapsto & (g\left(z\right), h\left(z\right)) \end{array}$$

is continuous if and only if  $g: Z \to X$  and  $h: Z \to Y$  are continuous. For Z = I,

 $\{ \text{ loops in } X \times Y \text{ based at } (x_0, y_0) \} \longleftrightarrow \{ \text{ loops in } X \text{ based at } x_0 \} \times \{ \text{ loops in } Y \text{ based at } y_0 \}.$ 

Two loops

$$f_1: I \rightarrow X \times Y$$
  $f_2: I \rightarrow X \times Y$   $s \mapsto (g_1(s), h_1(s))$ ,  $s \mapsto (g_2(s), h_2(s))$ 

are homotopic if and only if  $g_1 \cong g_2$  and  $h_1 \cong h_2$ , so there is a bijection

$$\pi_1(X \times Y, (x_0, y_0)) \cong \pi_1(X, x_0) \times \pi_1(Y, y_0).$$

 $f_1 \cdot f_2 = (g_1 \cdot g_2, h_1 \cdot h_2)$  and the constant loop is mapped to the constant loop, so this is also a group isomorphism.

**Example 1.28.** The torus  $S^1 \times S^1$  has

$$\pi_1\left(S^1\times S^1\right)\cong\pi_1\left(S^1\right)\times\pi_1\left(S^1\right)\cong\mathbb{Z}^2.$$

## 1.3 Induced homomorphisms

Let X, Y be topological spaces,  $x_0 \in X$ , and  $\phi: X \to Y$ . An observation is that  $\phi$  induces a homomorphism

$$\phi_*: \quad \pi_1\left(X, x_0\right) \quad \to \quad \pi_1\left(Y, \phi\left(x_0\right)\right) \\ \left[f\right] \quad \mapsto \quad \left[\phi \circ f\right] \quad .$$

 $\phi_*$  is well-defined, since if  $f_t$  is a homotopy between the loops  $f_0$  and  $f_1$  based at  $x_0$ , then  $\phi \circ f_t$  is a homotopy of loops between  $\phi \circ f_0$  and  $\phi \circ f_1$ . Moreover,

$$\phi \circ (f \cdot g) = (\phi \circ f) \cdot (\phi \circ g),$$

and  $\phi$  maps the constant path at  $x_0$  to the constant path at  $\phi(x_0)$ , so  $\phi$  is a homomorphism.

## Proposition 1.29.

1. Let  $\psi: X \to Y$  and  $\phi: Y \to Z$  be continuous maps between topological spaces,  $x_0 \in X$ , and

$$\psi_*: \pi_1(X, x_0) \to \pi_1(Y, \psi(x_0)), \qquad \phi_*: \pi_1(Y, \psi(x_0)) \to \pi_1(Z, (\phi \cdot \psi)(x_0)),$$

(/ //\*

 $(\phi \circ \psi)_* : \pi_1(X, x_0) \to \pi_1(Z, (\phi \cdot \psi)(x_0)).$ 

Then  $(\phi \circ \psi)_* = \phi_* \circ \psi_*$ .

2. Let  $id_X: X \to X$  be the identity then

$$(id_X)_*: \pi_1(X, x_0) \to \pi_1(X, x_0)$$

is the identity.

Proof.

1. Let  $f: I \to X$  be a loop at  $x_0$ , then

$$\left(\phi\circ\psi\right)_{*}\left([f]\right)=\left[\left(\phi\circ\psi\right)\circ f\right]=\left[\phi\circ\left(\psi\circ f\right)\right]=\phi_{*}\left(\left[\psi\circ f\right]\right)=\phi_{*}\left(\psi_{*}\left([f]\right)\right)=\left(\phi_{*}\circ\psi_{*}\right)\left([f]\right).$$

2.  $(id_X)_*([f]) = [id_X \circ f] = [f].$ 

These two observations yield in particular that if  $\phi: X \to Y$  is a homeomorphism with inverse  $\psi: Y \to X$ , then

$$\phi_*: \pi_1(X, x_0) \to \pi_1(Y, \phi(x_0))$$

is an isomorphism with inverse  $\psi_*$ .

**Proposition 1.30.** If  $n \geq 2$ , then  $\pi_1(S^n) = 0$ .

## A Quotient topology

Recall that if X is a set with equivalence relation  $\sim$ , there is a quotient set  $X/\sim$ . The quotient map

$$\pi: X \to \frac{X}{\sim}$$

$$x \mapsto [x]$$

is characterised by the following universal property. For every map  $g: X \to Y$  such that

$$a \sim b \implies g(a) = g(b),$$

there exists a unique  $f: X/\sim Y$  such that  $g=f\cdot \pi$ , so



Let X be a topological space and  $\sim$  be an equivalence relation on X. We define a topology on  $X/\sim$  by

$$U \subseteq \frac{X}{\sim}$$
 open  $\iff$   $\pi^{-1}(U)$  open.

Remark A.1.

• This is the largest topology on  $X/\sim$  such that  $\pi$  is continuous. Exercise 1 states that if Z is a topological space and  $f:X/\sim\to Z$  is a map, then f is continuous if and only if  $f\circ\pi:X\to Z$  is continuous. This implies that the topological quotient  $\pi:X\to X/\sim$  is characterised by the following universal property. For any topological space Z and a continuous  $g:X\to Z$  such that

$$a \sim b \implies g(a) = g(b),$$

there exists a unique continuous map  $f: X/\sim \to Z$  such that  $gf\cdot \pi$ , so



- The quotient map is in general not open. For example, if  $\pi:[0,1]\to S^1$ , then  $[0,1]\subset[0,1)$  is open but  $\pi([0,1))\subseteq S^1$  is not open.
- If X is Hausdorff, in general  $X/\sim$  is not Hausdorff.
- If  $\sim$  is the trivial relation, then  $\pi: X \to X/\sim$  is a homeomorphism. Exercise 3 states that if X,Y are topological spaces, X is compact, Y is Hausdorff, and  $\pi: X \to Y$  is surjective and continuous, then  $\pi$  is a quotient, that is there exists  $\sim$  on X and  $\pi: X \to Y \cong X/\sim$  is a quotient map.
- In particular, if  $\pi: X \to Y$  is bijective, then  $\pi$  is a homeomorphism. Exercise 4, 5, 6 states that if f is continuous and surjective,  $f(\partial D^n)$  is a point, and f is a bijection on  $D^n \setminus \partial D^n$ , then

$$\begin{array}{c|c}
D^n \\
\downarrow \\
D^n \\
\hline
\partial D^n \\
\hline
\end{array} S^1$$