view_frames Result

Recorded at time: 1769487249.437658

map

Broadcaster: default_authority
Average rate: 10.2
Buffer length: 5.0
Most recent transform: 89.695
Oldest transform: 84.695

odom

Broadcaster: default_authority
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 88.7
Oldest transform: 83.8

base_link

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

chassis_link

base_foot_link

Broadcaster: default_authority
Average rate: 50.246
Buffer length: 4.06
Most recent transform: 88.756
Oldest transform: 84.696

Broadcaster: default_authority
Average rate: 50.246
Buffer length: 4.06
Most recent transform: 88.756
Oldest transform: 84.696

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Average rate: 50.246
Buffer length: 4.06
Most recent transform: 88.756
Oldest transform: 84.696

Broadcaster: default_authority
Average rate: 50.246
Buffer length: 4.06
Most recent transform: 88.756
Oldest transform: 84.696

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

left_back_steering_link

left_front_steering_link

right_back_steering_link

right_front_steering_link

camera_link

lidar_post

Broadcaster: default_authority
Average rate: 50.246
Buffer length: 4.06
Most recent transform: 88.756
Oldest transform: 84.696

Broadcaster: default_authority
Average rate: 50.246
Buffer length: 4.06
Most recent transform: 88.756
Oldest transform: 84.696

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Average rate: 50.246
Buffer length: 4.06
Most recent transform: 88.756
Oldest transform: 84.696

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

left_back_wheel_link

left_front_wheel_link

right_back_wheel_link

right_front_wheel_link

camera_link_optical

laser_frame