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#1514434

Autómatas PIA

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class tupla_transicion:
     def __init__(self, _estado, _caracter , _direccion):
          self.estado = _estado
          self.caracter = _caracter
          self.direccion = _direccion
class turing_machine:
     def __init__(self, transicion, string_cinta):
          if isinstance(transicion, dict):
               self.tabla transicion = transicion
          self.cinta = list(string cinta)
          self.current state = 's'
          self.current_position = 0
     def strart(self):
          result = False
          if self.current state == 's':
               while (self.current state!= 'Alto' and self.current state!= 'Si' and
self.current_state!= 'No' and self.current_state !='Error'):
                    car = self.cinta[self.current_position]
                    tupla = "('" + self.current_state + "', '" + car + "')"
                    if tupla in self.tabla transicion:
                         accion = self.tabla transicion[tupla]
                         if isinstance(accion, tupla_transicion):
                              self.current_state = accion.estado
                              print(self.cinta[self.current_position], accion.caracter,
accion.direccion, accion.estado)
                              self.cinta[self.current position] = accion.caracter
                              if accion.direccion == 'l':
                                  self.current position = self.current position - 1
                              else:
                                  if accion.direccion == 'r':
                                       self.current_position = self.current_position + 1
                                  else:
                                       if accion.direccion != 'o':
                                            #salida si hay error
                                            self.current_state = 'Error'
          if self.current_state!= 'Alto' or self.current_state!= 'Si' or
self.current state!= 'No':
               result = True
          return result
MT = dict()
# a^n b^4n
MT["('s', 'a')"] = tupla_transicion('1', 'a', 'r')
MT["('s', 'b')"] = tupla_transicion('2', 'b', '1')
MT["('3', 'b')"] = tupla_transicion('2', 'b', '1')

MT["('1', 'a')"] = tupla_transicion('1', 'a', 'r')

MT["('1', 'b')"] = tupla_transicion('2', 'b', 'o')

MT["('2', 'a')"] = tupla_transicion('3', 'a', 'r')

MT["('2', 'b')"] = tupla_transicion('Si', 'b', 'o')

MT["('3', 'a')"] = tupla_transicion('No', 'a', 'o')

MT["('3', 'b')"] = tupla_transicion('No', 'b', 'o')
stri = 'abbbbbb'
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tm = turing_machine(MT,stri)
result = tm.strart()
print(result)
print(tm.current state, tm.current position)
MT2 = dict()
# a^n b^n Maquina 2
MT2["('s', 'a')"] = tupla_transicion('1', 'c', 'r')
MT2["('1', 'a')"] = tupla transicion('1', 'a', 'r')
MT2["('1', 'd')"] = tupla_transicion('1', 'd', 'r')
MT2["('1', 'b')"] = tupla transicion('2', 'd', 'l')
MT2["('2', 'd')"] = tupla_transicion('2', 'd', '1')
MT2["('2', 'a')"] = tupla_transicion('2', 'a', '1')
MT2["('2', 'c')"] = tupla_transicion('s', 'c', 'r')
MT2["('s', 'a')"] = tupla_transicion('3', 'd', 'r')
MT2["('3', 'd')"] = tupla_transicion('3', 'd', 'l')
MT2["('3', 'b')"] = tupla transicion('Si', 'b', 'l')
stri2 = 'ab'
tm2 = turing machine(MT2, stri2)
result2 = tm2.strart()
print(result2)
print(tm2.current_state, tm2.current_position)
MT3 = dict()
# a b^n Maquina 3
MT3["('s', 'a')"] = tupla_transicion('1', 'a', 'r')
MT3["('s', 'b')"] = tupla_transicion('2', 'b', '1')
MT3["('1', 'a')"] = tupla_transicion('1', 'a', 'r')
MT3["('1', 'b')"] = tupla_transicion('2', 'b', 'o')
MT3["('2', 'a')"] = tupla_transicion('Alto', 'a', 'r')
MT3["('2', 'b')"] = tupla_transicion('Si', 'b', 'o')
stri3 = 'abbbbb'
tm3 = turing_machine(MT3,stri3)
result3 = tm3.strart()
print(result3)
print(tm3.current_state, tm3.current_position)
```