

1,

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(i)

$$\begin{aligned} \mathcal{L}_{\pi_{\theta_1}}(\pi_{\theta_1}) &= \eta(\pi_{\theta_1}) + \sum_{s \in \mathcal{S}} d_{\mu}^{\pi_{\theta_1}}(s) \sum_{a \in \mathcal{A}} \pi_{\theta_1}(a|s) A^{\pi_{\theta_1}}(s, a) = \eta(\pi_{\theta_1}) + \sum_{s \in \mathcal{S}} d_{\mu}^{\pi_{\theta_1}}(s) \sum_{a \in \mathcal{A}} \pi_{\theta_1}(a|s) (Q^{\pi_{\theta_1}}(s, a) - V^{\pi_{\theta_1}}(s)) \\ &= \eta(\pi_{\theta_1}) + \sum_{s \in \mathcal{S}} d_{\mu}^{\pi_{\theta_1}}(s) (V^{\pi_{\theta_1}}(s) - V^{\pi_{\theta_1}}(s)) = \eta(\pi_{\theta_1}) \end{aligned}$$

(ii)

$$\begin{aligned} \nabla_{\theta} \mathcal{L}_{\pi_{\theta_1}}(\pi_{\theta}) \big|_{\theta=\theta_1} &= \nabla_{\theta} \eta(\pi_{\theta}) + \sum_{s \in \mathcal{S}} d_{\mu}^{\pi_{\theta_1}}(s) \nabla_{\theta} \sum_{a \in \mathcal{A}} A^{\pi_{\theta_1}}(s, a) \pi_{\theta}(a|s) \big|_{\theta=\theta_1} \\ &= \nabla_{\theta_1} \eta(\pi_{\theta_1}) + \sum_{s \in \mathcal{S}} d_{\mu}^{\pi_{\theta_1}}(s) \nabla_{\theta_1} (V^{\pi_{\theta_1}}(s) - V^{\pi_{\theta_1}}(s)) = \nabla_{\theta_1} \eta(\pi_{\theta_1}) \end{aligned}$$

2,

(a)

$$\mathcal{L}(\theta, \lambda) = -(\nabla_{\theta} \mathcal{L}_{\theta_k}(\theta) \big|_{\theta=\theta_k})^T (\theta - \theta_k) + \lambda \left( \frac{1}{2} (\theta - \theta_k)^T H (\theta - \theta_k) - \delta \right)$$

$$\nabla_{\theta} \mathcal{L}(\theta, \lambda) = -(\nabla_{\theta} \mathcal{L}_{\theta_k}(\theta) \big|_{\theta=\theta_k}) + \lambda H (\theta - \theta_k) = 0 \Rightarrow \theta = \theta_k + \frac{1}{\lambda} H^{-1} (\nabla_{\theta} \mathcal{L}_{\theta_k}(\theta) \big|_{\theta=\theta_k})$$

$$\text{Let } V = \nabla_{\theta} \mathcal{L}_{\theta_k}(\theta) \big|_{\theta=\theta_k}$$

$$D(\lambda) = \min_{\theta \in \mathbb{R}^d} \mathcal{L}(\theta, \lambda) = -V^T \left( \frac{1}{\lambda} H^{-1} V \right) + \frac{\lambda}{2} \left( \frac{1}{\lambda} H^{-1} V \right)^T H \left( \frac{1}{\lambda} H^{-1} V \right) - \lambda \delta$$

$$= -V^T \frac{1}{\lambda} H^{-1} V + \frac{1}{2\lambda} V^T H^{-1} V - \lambda \delta = -\frac{1}{2\lambda} V^T H^{-1} V - \lambda \delta$$

$$\frac{\partial D(\lambda)}{\partial \lambda} = \frac{1}{2\lambda^2} V^T H^{-1} V - \delta = 0 \Rightarrow \lambda^* = \left( \frac{1}{2\delta} V^T H^{-1} V \right)^{\frac{1}{2}}$$

$$(b) \mathcal{L}(\theta, \lambda^*) = -V^T (\theta - \theta_k) + \left( \frac{1}{2\delta} V^T H^{-1} V \right)^{\frac{1}{2}} \left( \frac{1}{2} (\theta - \theta_k)^T H (\theta - \theta_k) - \delta \right)$$

$$\nabla_{\theta} \mathcal{L}(\theta, \lambda^*) = -V + \left( \frac{1}{2\delta} V^T H^{-1} V \right)^{\frac{1}{2}} H (\theta - \theta_k) = 0$$

$$\Rightarrow \theta^* = \theta_k + \left( \frac{1}{2\delta} V^T H^{-1} V \right)^{\frac{1}{2}} H^{-1} V$$

$$= \theta_k + \left( \frac{1}{2\delta} (\nabla_{\theta} \mathcal{L}_{\theta_k}(\theta) \big|_{\theta=\theta_k})^T H^{-1} (\nabla_{\theta} \mathcal{L}_{\theta_k}(\theta) \big|_{\theta=\theta_k}) \right)^{\frac{1}{2}} H^{-1} (\nabla_{\theta} \mathcal{L}_{\theta_k}(\theta) \big|_{\theta=\theta_k})$$

$$\Rightarrow \alpha = \left( \frac{1}{2\delta} (\nabla_{\theta} \mathcal{L}_{\theta_k}(\theta) \big|_{\theta=\theta_k})^T H^{-1} (\nabla_{\theta} \mathcal{L}_{\theta_k}(\theta) \big|_{\theta=\theta_k}) \right)^{\frac{1}{2}} \times$$

# Homework 2 Report

## Reinforcement Learning

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April 30, 2023

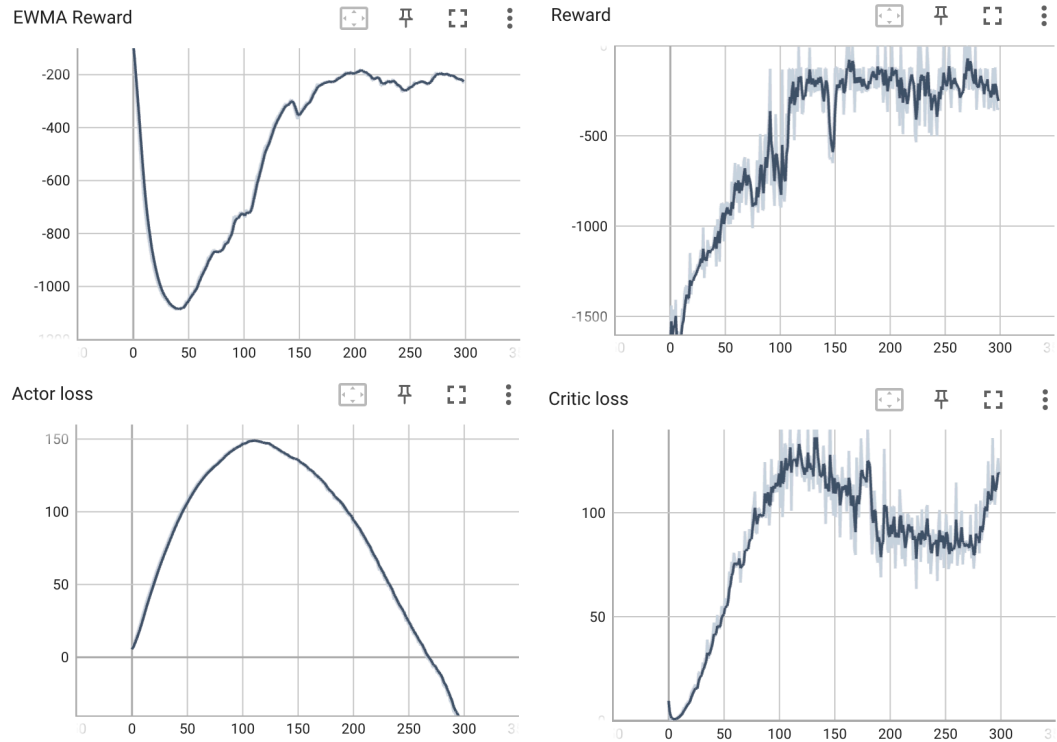
### 1 Experiment of DDPG

#### 1.1 Pendulum-v1

Learning Rate(Actor)	0.0001
Learning Rate(Critic)	0.001
Batch Size	128
Hidden Size	128
Layer Number	1

Table 1: Hyperparameters

Result: Reach well policy in near 300 steps.



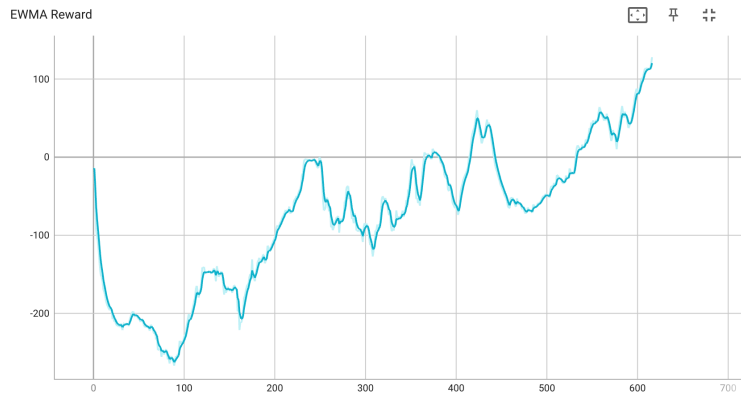
## 1.2 LunarLanderContinuous-v2

Use bayesian optimization to tune the hyper parameters. Reach EWMA reward=120 in 616 steps.

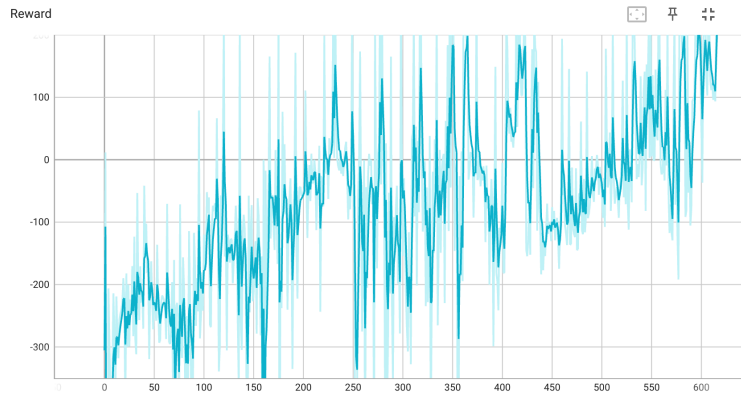
<b>Learning Rate(Actor)</b>	0.008
<b>Learning Rate(Critic)</b>	0.001
<b>Learning Rate decay rate(Actor)</b>	0.85
<b>Learning Rate decay rate(Critic)</b>	0.81
<b>Batch Size</b>	211
<b>Hidden Size</b>	128
<b>Layer Number</b>	2
<b>Noise Scale</b>	0.28

Table 2: Hyperparameters

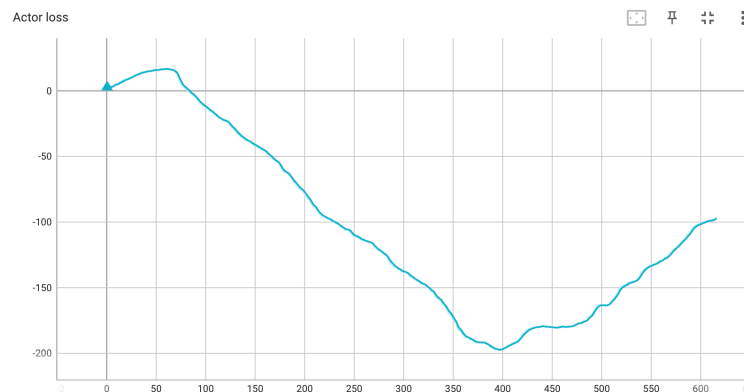
EWMA Reward:



Reward:



### Loss of Actor:



### Loss of Critic:

